

Chapter 4

AC Circuits

Me

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Outlines

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 - Impedance $v_e = Zi_e$
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- 4 Power in AC
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 - Examples

$$v(t) = V_{\max} \cos(\omega t + \theta) = \sqrt{2} V_{rms} \cos(\omega t + \theta)$$

$$i(t) = I_{\max} \cos(\omega t + \phi) = \sqrt{2} I_{rms} \cos(\omega t + \phi)$$

Euler's(/oiler/) formula $e^{jx} = \cos x + j \sin x$, leads to

$$v(t) = \operatorname{Re}[V_{\max} \cos(\omega t + \theta) + j V_{\max} \sin(\omega t + \theta)]$$

$$= \operatorname{Re}[V_{\max} e^{j(\omega t + \theta)}] = \operatorname{Re}[\sqrt{2} V_{rms} e^{j(\omega t + \theta)}]$$

$$= \operatorname{Re}[v_e(t)]$$

$$i(t) = \operatorname{Re}[I_{\max} \cos(\omega t + \phi) + j I_{\max} \sin(\omega t + \phi)]$$

$$= \operatorname{Re}[I_{\max} e^{j(\omega t + \phi)}] = \operatorname{Re}[\sqrt{2} I_{rms} e^{j(\omega t + \phi)}]$$

$$= \operatorname{Re}[i_e(t)]$$

- $v(t) = \operatorname{Re}[v_e(t)], \quad i(t) = \operatorname{Re}[i_e(t)]$

- $j\omega e^{j\omega t} = \frac{d}{dt} e^{j\omega t}, \quad \frac{1}{j\omega} e^{j\omega t} = \int_{-\infty}^t e^{j\omega t} dt.$

Impedance $v_e = Zi_e$

- Resistors (Ohm's law) $v_e(t) = i_e(t)R = Z_R i_e$
- Inductors (Henry's law)

$$\begin{aligned}v_e(t) &= L \frac{di_e(t)}{dt} = L \frac{d}{dt}(I_{max} e^{j(\omega t + \phi)}) \\&= (j\omega L) I_{max} e^{j(\omega t + \phi)} = \underline{j\omega L} i_e = Z_L i_e\end{aligned}$$

- Capacitors (Faraday's law)

$$\begin{aligned}v_e(t) &= \frac{1}{C} \int_{-\infty}^t i_e(\tau) d\tau = \frac{1}{C} \int_{-\infty}^t I_{max} e^{j(\omega \tau + \phi)} d\tau \\&= \left(\frac{1}{j\omega C}\right) I_{max} e^{j(\omega t + \phi)} = \underline{\frac{1}{j\omega C}} i_e = Z_C i_e\end{aligned}$$

Summary

$$\begin{array}{l|l} V_{\max} \cos(\omega t + \theta) = v(t) & \text{Re}[v_e(t)] = \text{Re}[V_{\max} e^{j(\omega t + \theta)}] \\ I_{\max} \cos(\omega t + \phi) = i(t) & \text{Re}[i_e(t)] = \text{Re}[I_{\max} e^{j(\omega t + \phi)}] \end{array}$$

Only magnitudes and angles are kept

$$\bar{V} =$$

$$V_{rms} e^{j\theta} = \frac{V_{\max}}{\sqrt{2}} e^{j\theta}$$

$$\bar{I} =$$

$$I_{rms} e^{j\phi} = \frac{I_{\max}}{\sqrt{2}} e^{j\phi}$$

$$\bar{Z} = \frac{\bar{V}}{\bar{I}} = \frac{V_{rms} e^{j\theta}}{I_{rms} e^{j\phi}} = \frac{V_{rms} \angle \theta}{I_{rms} \angle \phi} = \frac{V_{rms}}{I_{rms}} \angle \theta - \phi = Z \angle \theta_z$$

Summary

$$V_{\max} \cos(\omega t + \theta) = v(t)$$

$$I_{\max} \cos(\omega t + \phi) = i(t)$$

$$\frac{d \cos \omega t}{dt} = -\omega \sin \omega t$$

$$\operatorname{Re}[v_e(t)] = \operatorname{Re}[V_{\max} e^{j(\omega t + \theta)}]$$

$$\operatorname{Re}[i_e(t)] = \operatorname{Re}[I_{\max} e^{j(\omega t + \phi)}]$$

$$\frac{e^{j\omega t}}{dt} = j\omega e^{j\omega t}$$

Only magnitudes and angles are kept

$$\bar{V} =$$

$$V_{rms} e^{j\theta} = \frac{V_{\max}}{\sqrt{2}} e^{j\theta}$$

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$$\frac{d \cos \omega t}{dt} = -\omega \sin \omega t$$

$$\int \cos \omega t dt = \frac{\sin \omega t}{\omega}$$

$$\operatorname{Re}[v_e(t)] = \operatorname{Re}[V_{\max} e^{j(\omega t + \theta)}]$$

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$$\frac{e^{j\omega t}}{dt} = j\omega e^{j\omega t}$$

$$\int e^{j\omega t} dt = \frac{e^{j\omega t}}{j\omega}$$

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$$\frac{d \cos \omega t}{dt} = -\omega \sin \omega t$$

$$\int \cos \omega t dt = \frac{\sin \omega t}{\omega}$$

Computationally hard

$$\operatorname{Re}[v_e(t)] = \operatorname{Re}[V_{\max} e^{j(\omega t + \theta)}]$$

$$\operatorname{Re}[i_e(t)] = \operatorname{Re}[I_{\max} e^{j(\omega t + \phi)}]$$

$$\frac{e^{j\omega t}}{dt} = j\omega e^{j\omega t}$$

$$\int e^{j\omega t} dt = \frac{e^{j\omega t}}{j\omega}$$

Algebraic Ohm's law ($v_e = Zi_e$)

Only magnitudes and angles are kept

$$\bar{V} =$$

$$V_{rms} e^{j\theta} = \frac{V_{\max}}{\sqrt{2}} e^{j\theta}$$

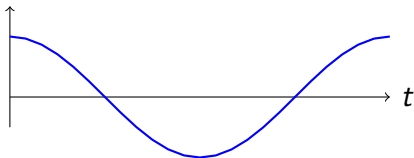
$$\bar{I} =$$

$$I_{rms} e^{j\phi} = \frac{I_{\max}}{\sqrt{2}} e^{j\phi}$$

$$\bar{Z} = \frac{\bar{V}}{\bar{I}} = \frac{V_{rms} e^{j\theta}}{I_{rms} e^{j\phi}} = \frac{V_{rms} \angle \theta}{I_{rms} \angle \phi} = \frac{V_{rms}}{I_{rms}} \angle \theta - \phi = Z \angle \theta_z$$

Time domain and Phasor domain

$$v(t) = \cos \omega t$$



$$\cos(\omega t + \theta) = \text{Re}[e^{j(\omega t + \theta)}]$$

A $\cos \omega t$ function is converted into a rotating vector by Euler

Example 4.2

$$v(t) = 170 \cos(377t - 40^\circ) V \longleftrightarrow \bar{V} = 170 \angle -40^\circ$$

$$i(t) = 10 \sin(1000t + 20^\circ) A \longleftrightarrow \bar{I} = 10 \angle -70^\circ$$

$$\bar{V} = 86.3 \angle 26^\circ V \longleftrightarrow v(t) = 86.3 \cos(\omega t + 26^\circ) V$$

where $\sin(z) = \cos(z - 90^\circ)$. And more examples to practice.

Summary

$$R, j\omega L, \frac{1}{j\omega C}$$

↑ Phasor $M \angle \theta$

$$R, j\omega L, \frac{1}{j\omega C}$$

$$\Downarrow e^{j(\omega t + \theta)}$$

↑ Euler $e^{j(\omega t + \theta)}$

$$\Downarrow \text{Re}(e^{j(\omega t + \theta)})$$

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$$\Downarrow \operatorname{Re}(e^{j(\omega t + \theta)})$$

Sinusoidal Input

→ Differential eqn.

→

Sinusoidal Output

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Summary

$$R, j\omega L, \frac{1}{j\omega C}$$

\Uparrow Phasor $M \angle \theta$

Exponential Input \rightarrow

\Uparrow Euler $e^{j(\omega t + \theta)}$

Sinusoidal Input \rightarrow

$R, j\omega L, \frac{1}{j\omega C}$
 $\rightarrow \bar{Z}$, Algebraic eqn.

\rightarrow Differential eqn.

$\Downarrow e^{j(\omega t + \theta)}$

Exponential Output \rightarrow

$\Downarrow \text{Re}(e^{j(\omega t + \theta)})$

Sinusoidal Output

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Summary

	$R, j\omega L, \frac{1}{j\omega C}$	
Complex input	$\rightarrow \bar{Z}, \text{Algebraic eqn.}$	\rightarrow Complex output
\uparrow Phasor $M \angle \theta$	$R, j\omega L, \frac{1}{j\omega C}$	$\Downarrow e^{j(\omega t + \theta)}$
Exponential Input	$\rightarrow \bar{Z}, \text{Algebraic eqn.}$	\rightarrow Exponential Output
\uparrow Euler $e^{j(\omega t + \theta)}$		$\Downarrow \text{Re}(e^{j(\omega t + \theta)})$
Sinusoidal Input	\rightarrow Differential eqn.	\rightarrow Sinusoidal Output

Resistor, \bar{I}_R and \bar{V}_R are in phase

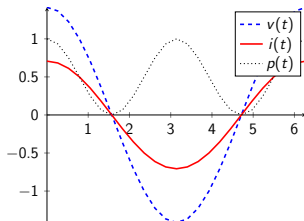
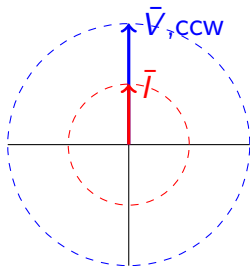
Assumed Form: $v(t) = V_{\max} \cos(\omega t + \theta) = \sqrt{2} V_{\text{rms}} \cos(\omega t + \theta)$

Assume $\theta = 90^\circ$ for voltage. Could be any angle

$$v = iR, i(t) = \frac{V_{\max}}{R} \cos(\omega t + \theta) = I_{\max} \cos(\omega t + 90^\circ)$$



$$p(t) = v(t)i(t) = V_{\max} I_{\max} \cos^2(\omega t)$$



Resistor, \bar{I}_R and \bar{V}_R are in phase

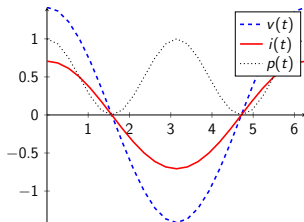
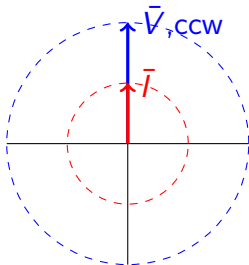
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$$p(t) = v(t)i(t) = V_{\max} I_{\max} \cos^2(\omega t)$$



Inductor, \bar{I}_L lags \bar{V}_L by 90°

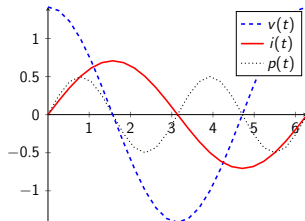
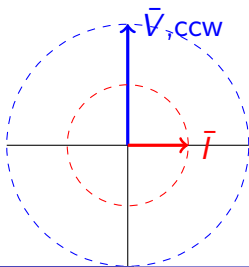
Assumed Form: $v(t) = V_{\max} \cos(\omega t + \theta) = \sqrt{2} V_{\text{rms}} \cos(\omega t + \theta)$

Assume $\theta = 90^\circ$ for voltage. Could be any angle

$$v = i(j\omega L), i(t) = \frac{1}{j\omega L} V_{\max} \cos(\omega t + 90^\circ) = I_{\max} \sin(\omega t)$$



$$p(t) = v(t)i(t) = V_{\max} I_{\max} \cos(\omega t) \sin(\omega t) = \frac{V_{\max} I_{\max}}{2} \sin(2\omega t)$$



Capacitor, \bar{I}_C leads \bar{V}_C by 90°

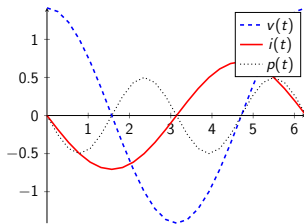
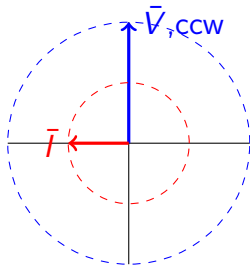
Assumed Form: $v(t) = V_{\max} \cos(\omega t + \theta) = \sqrt{2} V_{\text{rms}} \cos(\omega t + \theta)$

Assume $\theta = 90^\circ$ for voltage. Could be any angle

$$v = i\left(\frac{1}{j\omega C}\right), i(t) = j\omega C V_{\max} \cos(\omega t + 90^\circ) = -I_{\max} \sin(\omega t)$$

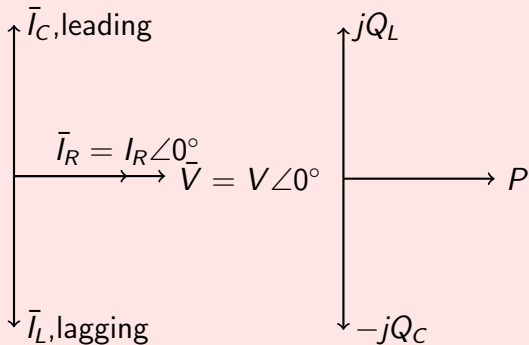


$$p(t) = v(t)i(t) = -V_{\max} I_{\max} \cos(\omega t) \sin(\omega t) = -\frac{V_{\max} I_{\max}}{2} \sin(2\omega t)$$



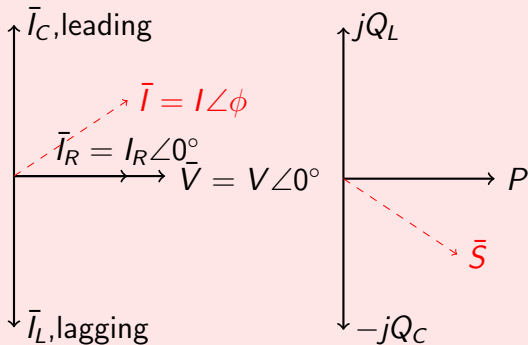
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Summary



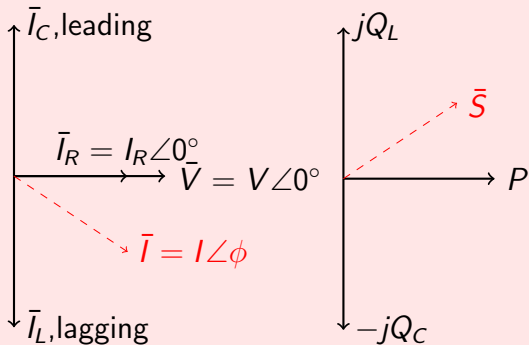
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Summary



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Summary



We have discussed the special cases for R, L and C. How about a more general case? Say, combination of RLC.

Instantaneous power

$$\begin{aligned} p(t) &= V_{\max} \cos(\omega t + \theta) I_{\max} \cos(\omega t + \phi) \\ &= V_{rms} I_{rms} \cos(\theta - \phi) \{1 + \cos(2\omega t + 2\phi)\} \\ &\quad + V_{rms} I_{rms} \sin(\theta - \phi) \sin(2\omega t + 2\phi) \end{aligned}$$

Average real/reactive power

$$P_{ave} = \frac{1}{2\pi} \int_0^{2\pi} p(\tau) d\tau = V_{rms} I_{rms} \cos(\theta - \phi) \text{ W}$$

$$Q_{ave} = \frac{1}{2\pi} \int_0^{2\pi} p(\tau) d\tau = 0 \text{ VAR}$$

Complex power

$$p(t) = V_{rms} I_{rms} \cos(\theta - \phi) \{1 + \cos(2\omega t + 2\phi)\} \\ + V_{rms} I_{rms} \sin(\theta - \phi) \sin(2\omega t + 2\phi)$$

$$\bar{S} = P + jQ = \bar{V} \bar{I}^* = (V_{rms} \angle \theta) (I_{rms} \angle \phi)^* = V_{rms} I_{rms} \angle (\theta - \phi) \\ = V_{rms} I_{rms} \cos(\theta - \phi) + j V_{rms} I_{rms} \sin(\theta - \phi)$$

Since $\bar{V} = \bar{I} \bar{Z}$ (Ohm's law in AC), we have

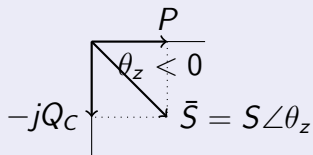
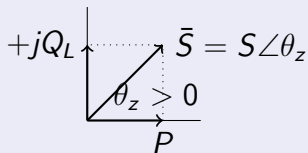
$$\bar{S} = P + jQ = \bar{V} \bar{I}^* = (\bar{I} \bar{Z}) \bar{I}^* = I_{rms}^2 (R + jX) = I_{rms}^2 R + j I_{rms}^2 X \\ = \bar{V} \left(\frac{\bar{V}}{\bar{Z}} \right)^* = \frac{V_{rms}^2}{R - jX} = \frac{V_{rms}^2 R}{Z^2} + j \frac{V_{rms}^2 X}{Z^2}$$

If $X = 0$, it becomes a DC formula.

Apparent power

$$S = V_{rms} I_{rms} = \frac{V_{max}}{\sqrt{2}} \frac{I_{max}}{\sqrt{2}} = \frac{1}{2} V_{max} I_{max}$$

Power triangle



$$P = V_{rms} I_{rms} \cos(\theta - \phi) = I_{rms}^2 R = V_{rms}^2 R / Z^2$$

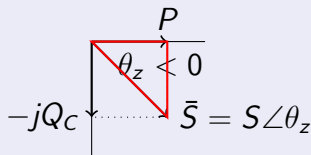
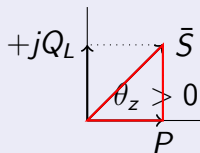
$$Q = V_{rms} I_{rms} \sin(\theta - \phi) = I_{rms}^2 X = V_{rms}^2 X / Z^2$$

$$\theta_z = \theta - \phi = \cos^{-1} pf$$

Apparent power

$$S = V_{rms} I_{rms} = \frac{V_{max}}{\sqrt{2}} \frac{I_{max}}{\sqrt{2}} = \frac{1}{2} V_{max} I_{max}$$

Power triangle



$$P = V_{rms} I_{rms} \cos(\theta - \phi) = I_{rms}^2 R = V_{rms}^2 R / Z^2$$

$$Q = V_{rms} I_{rms} \sin(\theta - \phi) = I_{rms}^2 X = V_{rms}^2 X / Z^2$$

$$\theta_z = \theta - \phi = \cos^{-1} pf$$

Leading/Lagging power factor

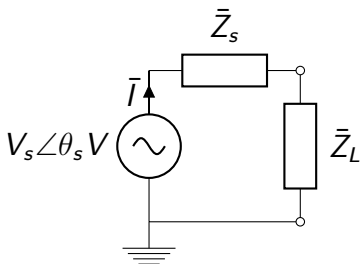
Based on the analysis in the previous page, it is clear that the power factor is the cosine value of the impedance angle θ_z .

$\bar{Z} = R + jX = R + j\left(\omega L - \frac{1}{\omega C}\right) = \sqrt{R^2 + X^2} \angle \tan^{-1} \frac{\omega L - \frac{1}{\omega C}}{R}$. For a pure resistor network: $X = 0$, $\theta_z = 0$, $pf = \cos \theta_z = 1$, pointing to the right.

For a pure inductor network: $X = L$, $\theta_z > 0$, $pf = \cos \theta_z < 1$, pointing upward.

For a pure capacitor network: $X = C$, $\theta_z < 0$, $pf = \cos \theta_z < 1$, pointing downward.

To maximize the power received at the load end.



which implies that

$$\bar{Z}_L = R_L + jX_L = R_s - jX_s = \bar{Z}_s^*$$

$$P_L = I^2 R_L = \frac{V_{s,rms}^2}{4R_s} = \frac{V_{s,max}^2}{8R_s}$$

$$\bar{I} = \frac{\bar{V}_s}{\bar{Z}_s + \bar{Z}_L} = \frac{V_s \angle \theta_s}{(R_s + R_L) + j(X_s + X_L)}$$

$$I = \frac{V_s}{\sqrt{(R_s + R_L)^2 + (X_s + X_L)^2}}$$

$$P_L = I^2 R_L = \frac{V_s^2 R_L}{(R_s + R_L)^2 + (X_s + X_L)^2}$$

$$\frac{\partial P_L}{\partial X_L} = 0 \Rightarrow X_L = -X_s$$

$$\frac{\partial P_L}{\partial R_L} = 0 \Rightarrow R_L = R_s$$

