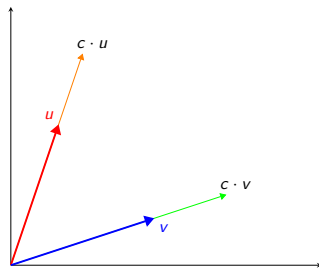
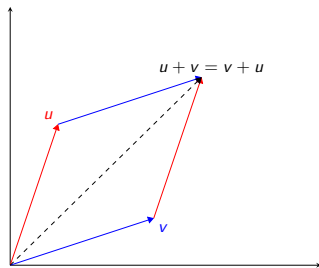


Recitation 1.1: Vector Spaces

TA: Nate Clause

Vector Spaces

- A *vector space* V over a field \mathbb{F} consists of a set of elements, called *vectors* and two operations:



Definition

A *vector space* over a field \mathbb{F} is a set V , along with operations $+$: $V \times V \rightarrow V$ given by $(u, v) \mapsto u + v$ and \cdot : $\mathbb{F} \times V \rightarrow V$ given by $(c, v) \mapsto c \cdot v$, satisfying:

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- (additive identity) $\exists 0 \in V$ such that $0 + v = v + 0 = v$ for all $v \in V$.
- (additive inverse) For all $v \in V$, $\exists (-v) \in V$ such that $v + (-v) = 0$.

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- (multiplication distributes over field addition) For all $a, b \in \mathbb{F}$ and $v \in V$:

$$(a + b) \cdot v = a \cdot v + b \cdot v$$

Vector Space Examples

Common examples of vector spaces include:

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$$\begin{aligned}(u_1, \dots, u_n) + (v_1, \dots, v_n) &:= (u_1 + v_1, \dots, u_n + v_n) \\ c \cdot (v_1, \dots, v_n) &:= (c \cdot v_1, \dots, c \cdot v_n)\end{aligned}$$

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- 3.) Fix a field \mathbb{F} , $V = \mathbb{F}^n$, with $+$ and \cdot defined coordinate-wise as in 2.)
 - Common field: \mathbb{Z}_2 , also denote $\mathbb{Z}/2\mathbb{Z}$. Set is $\{0, 1\}$ and operations are addition modulo 2 and multiplication modulo 2.

Direct Sums

Definition

Let V, W be vector spaces over a field \mathbb{F} . The (external) *direct sum* $V \oplus W$, is a vector space with set $V \times W := \{(v, w) \mid v \in V, w \in W\}$, and operations:

$$(v_1, w_1) + (v_2, w_2) = (v_1 + v_2, w_1 + w_2)$$

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- Example: for \mathbb{F} a field, \mathbb{F}^n is a vector space, with $\mathbb{F}^n = \bigoplus_{i=1}^n \mathbb{F}$.

Basis of a Vector Space

Definition

A *basis* B of a vector space V over a field \mathbb{F} is a subset $B \subseteq V$ satisfying the following:

- 1.) Linear independence: for every finite subset $\{v_1, \dots, v_n\} \subseteq B$, if $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$ for some $c_1, c_2, \dots, c_n \in \mathbb{F}$, then $c_1 = c_2 = \dots = c_n = 0$.

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- 2.) Spanning: for every $v \in V$, there exists $c_1, c_2, \dots, c_n \in \mathbb{F}$ and $v_1, v_2, \dots, v_n \in B$ such that $v = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$.

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Standard example: if $V = \mathbb{F}^n$, then

$\{(1, 0, \dots, 0), (0, 1, 0, \dots, 0), \dots, (0, 0, \dots, 0, 1)\}$ is a basis for V . We denote by e_i the basis element with 1 in coordinate i .

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Linear Subspace

Definition

A subset W of a vector space V over \mathbb{F} is a *linear subspace* if W with the operations of V restricted to W is a vector space over \mathbb{F} . Equivalently, $W \subseteq V$ is a linear subspace if for all $a, b \in \mathbb{F}$ and $u, v \in W$, $au + bv \in W$.

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- If $m \leq n$, then \mathbb{R}^m can be viewed as a linear subspace of \mathbb{R}^n by embedding $(v_1, \dots, v_m) \mapsto (v_1, \dots, v_m, 0, \dots, 0)$.

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- For $W = \{w_1, \dots, w_n\} \subset V$, define

$$\text{span}(W) := \left\{ \sum_{i=1}^n c_i w_i \mid c_i \in \mathbb{F} \right\}.$$

$\text{span}(W)$ is a linear subspace of V .