## Exam 1 Equation Sheet

$$\delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

$$\delta_{ij}a_j = a_i$$

$$\delta_{ij}a_{ij} = a_{ii}$$

$$\epsilon_{ijk} = \begin{cases} 1 & \text{if } ijk \text{ is an even permutation of } 1,2,3 \\ -1 & \text{if } ijk \text{ is an odd permutation of } 1,2,3 \\ 0 & \text{otherwise} \end{cases}$$

$$Q_{ij} = \cos(x'_i, x_j)$$

$$v'_i = Q_{im}v_m$$

$$\sigma'_{ij} = Q_{im}Q_{jn}\sigma_{mn}$$

$$\text{div}(v_i) = \text{tr}(\nabla v_i)$$

$$\nabla v_i = \begin{bmatrix} v_{r,r} & \frac{1}{r}(v_{r,\theta} - v_{\theta}) & v_{r,z} \\ v_{\theta,r} & \frac{v_{\theta,\theta} + v_r}{r} & v_{\theta,\theta} \\ v_{\theta,r} & \frac{v_{\theta,\theta} + v_r}{r} & v_{\theta,z} \\ v_{\phi,r} & \frac{v_{\theta,\theta} + v_r}{r} & \frac{v_{\theta,\theta} - v_{\phi}}{r\sin\theta} - \frac{v_{\phi}}{r} \\ v_{\theta,r} & \frac{v_{\theta,\theta} + v_r}{r\sin\theta} + v_{r+}v_{\theta}\cot\theta \end{bmatrix}$$

$$\frac{D\Theta(X_i, t)}{Dt} = \begin{pmatrix} \partial \hat{\Theta} \\ \partial t \end{pmatrix}_{X_i - fixed}$$

$$\frac{D\Theta(x_i, t)}{Dt} = \begin{pmatrix} D\tilde{\Theta} \\ Dt \end{pmatrix}_{X_i - fixed} = \begin{pmatrix} \partial \hat{\Theta} \\ \partial t \end{pmatrix} \frac{\partial x_i}{\partial t} + \begin{pmatrix} \partial \tilde{\Theta} \\ \partial t \end{pmatrix}_{x_i - fixed}$$

$$F_{ij} = x_{i,j} = \delta_{ij} + u_{i,j} = R_{im}U_{mj} = V_{im}R_{mj}$$

$$C_{ij} = F_{mi}F_{mj}$$

$$\rho v_{i,i} + \frac{D}{Dt}\rho = 0$$