### AE 760AA: Micromechanics and multiscale modeling

Lecture 7 - Physical measurements

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#### schedule

- Feb 13 Physical measurements (HW2 Due)
- Feb 18 Variational Calculus
- Feb 20 Variational Calculus
- Feb 25 Bounds and Boundary Conditions

### outline

- review
- measuring orientation

## review

### checking transformations

- Follow the procedure **here**
- This gives a way to systematically check whether your rotations are correct
- You can check any coordinate transformation as long as you know the unit vectors of your primed coordinate system in the global coordinates

$$x = [Q^T]x'$$

#### common homework errors

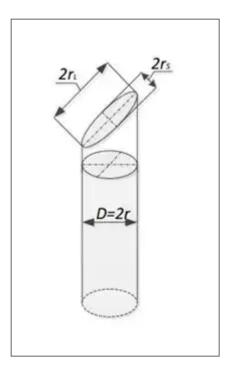
- Some people had rotations about an axis with zeros along the diagonal
- This is possible with successive rotations, but for a rotation about one of the three axes, you should always have one term along the diagonal equal to 1
- When calculating stiffness in Problem 2, most students had some unexpected behavior
- All four walls had same  $x_1$  component of fibers, you should have gotten  $C_{11}$  the same for all 4 walls
- $C_{22}$  or  $C_{33}$  should have also been equal to  $C_{11}$ , depending on the wall

# measuring orientation

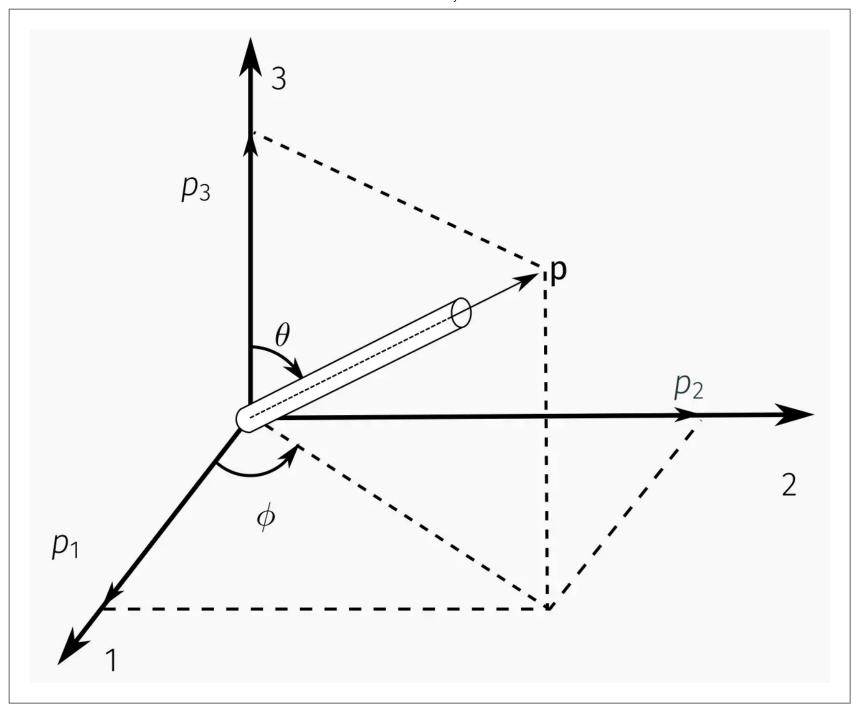
### measuring orientation

- In micromechanics (and most places where multi-scale modeling would be used), measuring local orientations can be difficult
- For composites, these are some common techniques
  - Microscopy (some ambiguity in orientation tensor)
  - Serial sectioned microscopy (eliminates ambiguity, very expensive)
  - CT-scanning (only gives approximate measure)
  - Micro CT-scanning (only for very small parts)

- Cylindrical fiber intersects cutting plane at some angle
- After cutting and polishing, this leaves an ellipse
- By measuring the ellipse, we can calculate the angle between it and the cutting plane
- Microscopy can also be used to measure volume fraction, void content, and fiber spacing



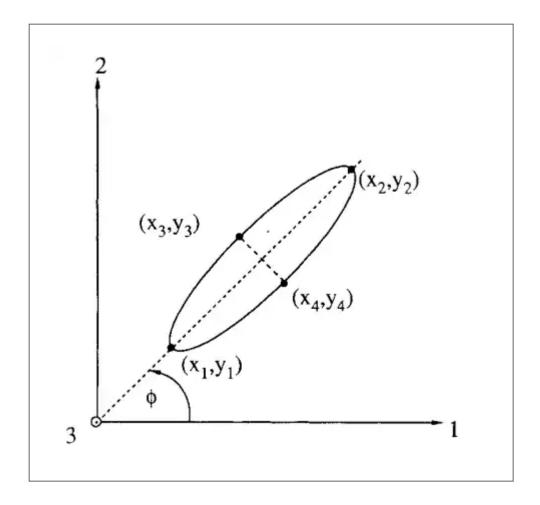
## fiber in spherical coordinates



## fiber direction components

Component	Definition
$p_1$	$\sin  heta \cos \phi$
$p_2$	$\sin  heta \sin \phi$
$p_3$	$\cos \theta$

#### measurements



#### calculations

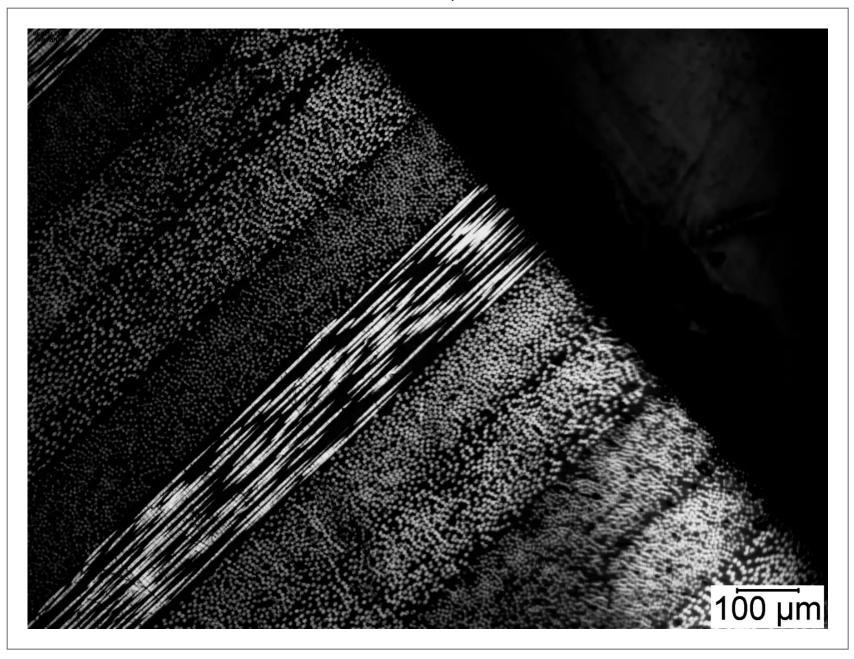
• We find the major (M) and minor (m) axes using

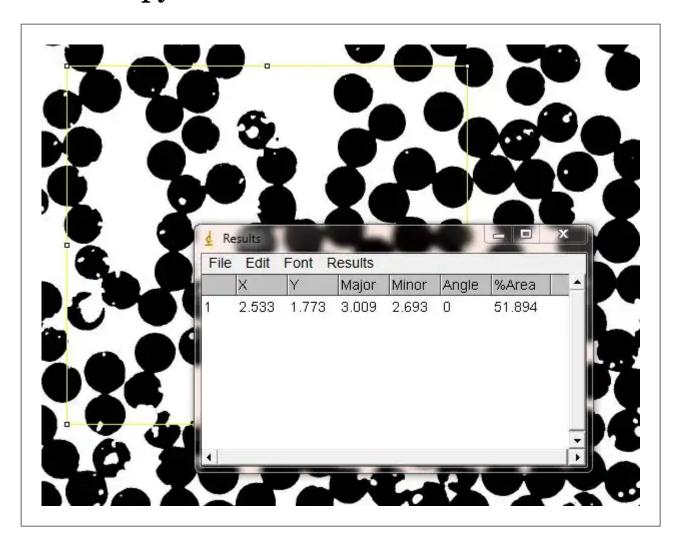
$$m = \sqrt{(x_3 - x_4)^2 + (y_3 - y_4)^2} \ X = x_1 - x_2 \ Y = y_1 - y_2 \ M = \sqrt{X^2 - Y^2}$$

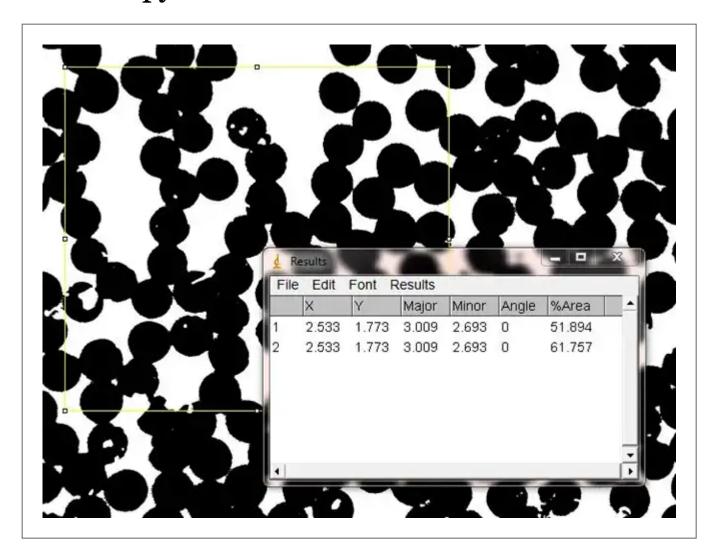
#### orientation tensor

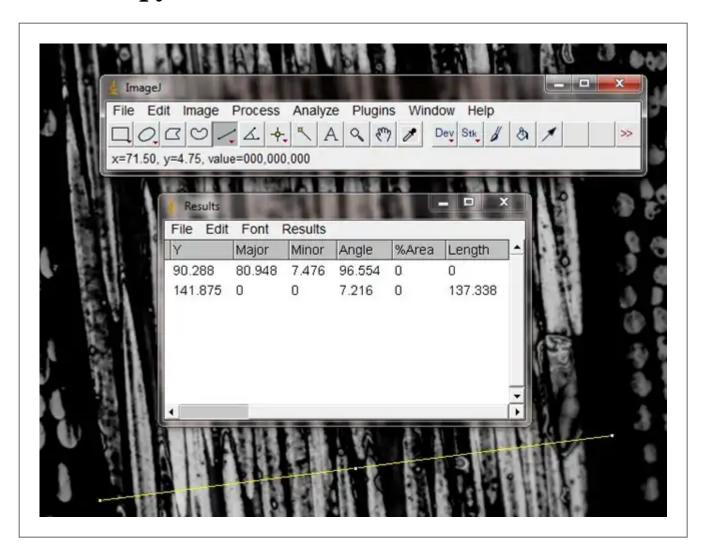
• We can now calculate angles using

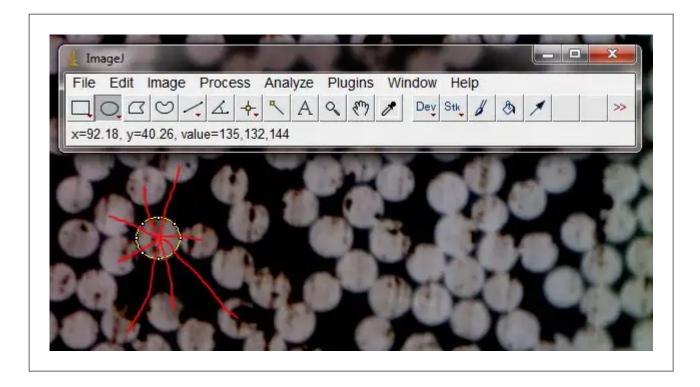
$$\sin\phi = rac{Y}{M}\cos\phi = rac{X}{M}\cos heta = rac{m}{M}\sin heta = \sqrt{1-rac{m^2}{M^2}}$$











#### software

- If you have to do a lot of microscopy measurements, contact Dr. Sharma, he wrote an automated measurement tool
- Otherwise you can use **imageJ**

- Need to account for bias in measurement (more likely to see fibers coming out of plane)
- There is some ambiguity in fiber angle
- Fiber at  $(\phi, \theta)$  is not distinguishable from  $(\phi + \pi, \theta)$
- In the second-order orientation tensor, this affects  $a_{23}$  and  $a_{13}$

### serial sectioning

- Serial sectioning is a method where you continually polish a specimen after photographing it
- After photograph you grind and polish, then photograph and repeat
- Gives the full 3D state of orientation, but is difficult

### **CT Scanning**

- Even if a CT Scan cannot resolve down to fiber resolution, the gradient information can give an idea of fiber orientation
- This method is not very precise
- But it can view the full-field and detect many forms of damage without destroying a part
- At the micro-scale full orientation can be obtained, but this is not practical for large parts