Name:

## Homework 1 Due 9 Feb 2021

1. Composites material properties are usually calibrated in the material coordinate system, with the base vectors denoted as  $a_i$ . To carry out analysis, we usually have to set up problem coordinate system denoted as  $e_i$ . In the most general case, the material coordinate system can be obtained through three consecutive rotations from the problem coordinate system. Let us assume we rotate  $e_i$  about  $e_1$  by  $\theta_1$  to become  $e_i'$ . This is followed by a rotation of  $e_i'$  about  $e_2'$  by  $\theta_2$  to become  $e_i''$ . Finally, we rotate rotate  $e_i''$  about  $e_3''$  by  $\theta_3$  to give  $a_i$ . Find the effective total direction cosine matrix  $Q_{ij}$  such that  $a_i = Q_{ij}e_j$ .

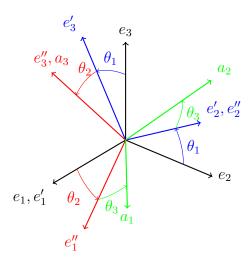


Figure 1: Illustration of rotations described in Problem 1

2. Consider a unidirectional fiber-reinforced composite as a linearly elastic, orthotropic material with

Property	Value
$E_1$	20 Mpsi
$E_2$	1.4 Mpsi
$E_3$	2.5 Mpsi
$G_{12}$	0.8 Mpsi
$G_{13}$	2.0 Mpsi
$G_{23}$	1.5 Mpsi
$ u_{12}$	0.2
$ u_{13}$	0.3
$\nu_{23}$	0.25

Where the 1-direction is in the fiber direction, the 2-direction is normal to the fibers in the plane, and the 3-direction is normal to the plane. Four 45° laminae are used to make a box beam (45° refers to the rotation about the outward normal at each wall). Compute the 6x6 stiffness matrix for each wall of the box beam in the global coordinate system. The cross-section of the box is shown in Figure 2.

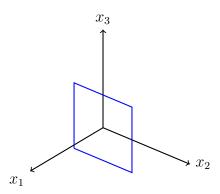


Figure 2: Cross-section of box beam for Problem 2

3. A plate mechanician uses an atypical arrangement of the stress and strain tensors in vector form. His preferred format is

$$\sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{22} & \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix}^T$$

$$\epsilon = \begin{bmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{22} & \epsilon_{13} & \epsilon_{23} & \epsilon_{33} \end{bmatrix}^T$$

- (a) Find the rotation matrices for  $R_{\sigma}$  and  $R_{\epsilon}$  for a general direction cosine matrix.
- (b) Verify that  $(R_{\epsilon})^{-1} = R_{\sigma}$  for the direction cosine matrix in Problem 1 with  $\theta_1 = 20^{\circ}$ ,  $\theta_2 = 45^{\circ}$ , and  $\theta_3 = 60^{\circ}$ .
- (c) Compute the new 6x6 stiffness matrix (C') for the left wall of the box beam in this new notation.
- (d) Compare C' with the original stiffness matrix in the left wall, C and verify that  $C' = BCB^T$  where

why is this the case?