```
makeJac:=proc(f)
local N, jac;
N:=LinearAlgebra:-Dimension(f);
jac:=VectorCalculus:-Jacobian(f,[seq(y[i],i=1..N)]);
unapply(jac,y);
end proc;
> Newton:=proc(f,y0,makeJac,tol,maxiter)
#global
local N,dy,Jac,F,yold,ynew,Err,iter;
N:=LinearAlgebra:-Dimension(f);
F:=unapply(f,y);
Jac:=makeJac(f);
yold:=y0;
dy:=LinearAlgebra:-LinearSolve(-Jac(yold),F(yold));
ynew:=yold+dy;
yold:=ynew;
Err:=10;
iter:=1;
while Err>tol and iter < maxiter do
iter:=iter+1;
dy:=LinearAlgebra:-LinearSolve(-Jac(yold),F(yold));
ynew:=yold+dy;
Err:=LinearAlgebra:-Norm(yold-ynew);
yold:=ynew;
end;
#[Err,ynew,iter];
ynew;
end proc;
makeJac := prod(f)
                                             end proc
local N, jac;
   N := LinearAlgebra:-Dimension(f);
   jac := VectorCalculus :- Jacobian(f, [seq(y[i], i = 1 .. N)]);
   unapply(jac, y)
```

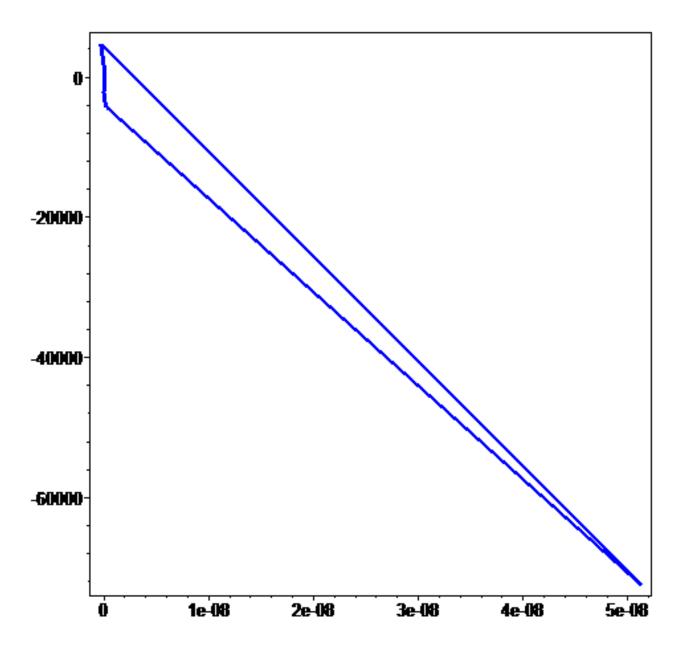
```
Newton := prod(f, y0, makeJac, tol, maxiter)
local N, dy, Jac, F, yold, ynew, Err, iter;
     N := LinearAlgebra:-Dimension(f);
     F := \operatorname{unapply}(f, y);
     Jac := makeJac(f);
     yold := y0;
     dy := LinearAlgebra:-LinearSolve(-Jac(yold), F(yold));
     ynew := yold + dy;
     yold := ynew;
     Err := 10:
     iter := 1;
     while tol < Err and iter < maxiter do
          iter := iter + 1:
          dy := LinearAlgebra:-LinearSolve(-Jac(yold), F(yold));
          ynew := yold + dy;
          Err := LinearAlgebra:-Norm(yold - ynew);
          vold := vnew
     end do:
     ynew
end proc
> eq1:=y[1]^2+y[2]^2+y[1]*y[2]-3;
eq2:=y[2]*y[2]+2*y[2]^2-2*(y[1]+y[2])-2;
eqns:=Vector(2,[eq1,eq2]);
y0:=Vector(2,[1.0,1.0]);
Newton(eqns,y0,makeJac,1e-6,50);
                                    eq1 := y_1^2 + y_1 y_2 + y_2^2 - 3
                                   eq2 := 3 y_2^2 - 2 y_1 - 2 y_2 - 2
                                 eqns := \begin{bmatrix} y_1^2 + y_1 y_2 + y_2^2 - 3 \\ 3 y_2^2 - 2 y_1 - 2 y_2 - 2 \end{bmatrix}
                                           y0 := \begin{bmatrix} 1.0 \\ 1.0 \end{bmatrix}
                                     [0.537841544434349]
1.39932526923185
>######################### P4 Stability #######################
> restart;
> Digits:=15;
```

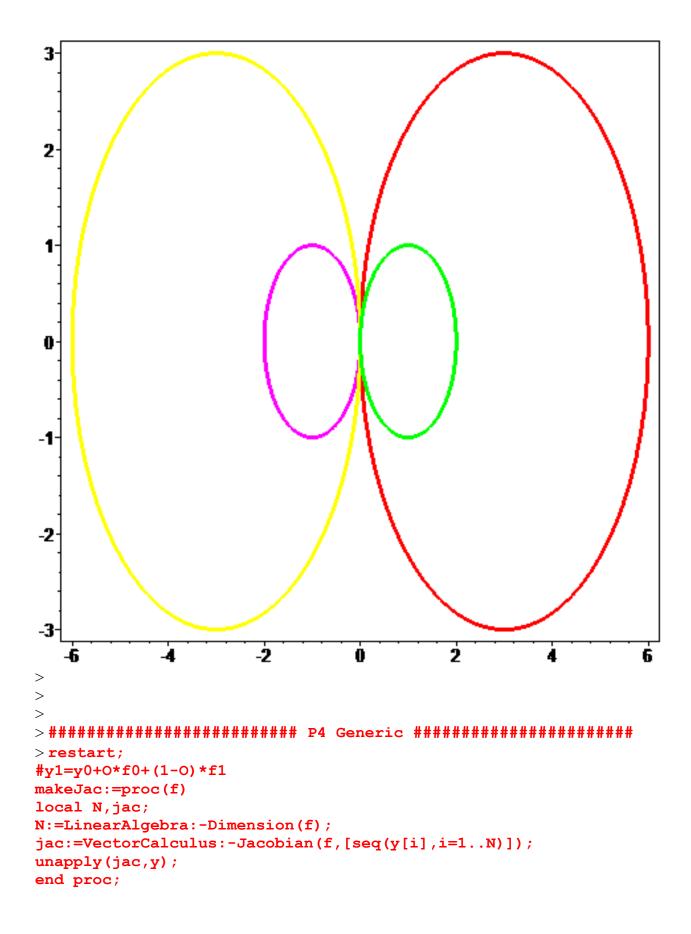
```
Digits := 15
```

```
> #dy/dt=lambda*y
eq4:=Y[1]=Y[0]+h*(O*lambda*Y[0]+(1-O)*lambda*Y[1]);
                                   eq4 := Y_1 = Y_0 + h(O\lambda Y_0 + (1 - O)\lambda Y_1)
> cons:=solve({eq4}, {Y[1]});
                                          cons := { Y_1 = \frac{Y_0 \left( O h \lambda + 1 \right)}{O h \lambda - h \lambda + 1} }
> Y[0]:=1;
eqz:=Y[1]=subs(cons,Y[1]);
                                                           Y_0 := 1
                                             eqz := Y_1 = \frac{Oh\lambda + 1}{Oh\lambda - h\lambda + 1}
> eqz:=subs(lambda=z/h,Y[1]=theta,eqz);
                                                eqz := \theta = \frac{Oz + 1}{Oz - z + 1}
> z2:=solve(eqz,z);
                                                 z2 := -\frac{\theta - 1}{\Omega \theta - \Omega - \theta}
> z2:=subs(theta=exp(I*phi),z2);
zz2:=unapply(z2,0);
zz2(1);
zz2(0);
zz2(1/2);
                                             z2 := -\frac{e^{(\phi I)} - 1}{Ce^{(\phi I)} - Ce^{(\phi I)}}
                                         zz2 := O \rightarrow -\frac{e^{(\phi I)} - 1}{O e^{(\phi I)} - O - e^{(\phi I)}}
                                                         e^{(\phi I)} - 1
                                                        \frac{e^{(\phi I)}-1}{e^{(\phi I)}}
                                                    -\frac{e^{(\phi I)}-1}{-\frac{1}{2}e^{(\phi I)}-\frac{1}{2}}
```

> with(plots):
p1:=complexplot(zz2(0),phi=0..2\*Pi,thickness=3,axes=boxed,color=
green):

```
p2:=complexplot(zz2(1/3),phi=0..2*Pi,thickness=3,axes=boxed,colo
r=red):
p3:=complexplot(zz2(1/2),phi=0..2*Pi,thickness=3,axes=boxed,colo
r=blue):
p4:=complexplot(zz2(2/3),phi=0..2*Pi,thickness=3,axes=boxed,colo
r=yellow):
p5:=complexplot(zz2(1),phi=0..2*Pi,thickness=3,axes=boxed,color=
magenta):
#display({p1});
#display({p1});
#display({p2});
display({p3});
#display({p3});
#display({p4});
#display({p5});
display({p1,p2,p4,p5});
```





```
makeJacN:=proc(f)
local N, jac;
N:=LinearAlgebra:-Dimension(f);
jac:=VectorCalculus:-Jacobian(f,[seq(y[i],i=1..N)]);
end proc;
Newton:=proc(f,y0,makeJac,tol,maxiter)
#global
local N,dy,Jac,F,yold,ynew,Err,iter;
N:=LinearAlgebra:-Dimension(f);
F:=unapply(f,y);
Jac:=makeJac(f);
yold:=y0;
dy:=LinearAlgebra:-LinearSolve(-Jac(yold),F(yold));
ynew:=yold+dy;
yold:=ynew;
Err:=10;
iter:=1;
while Err>tol and iter < maxiter do
iter:=iter+1;
dy:=LinearAlgebra:-LinearSolve(-Jac(yold),F(yold));
ynew:=yold+dy;
Err:=LinearAlgebra:-Norm(yold-ynew);
yold:=ynew;
end;
#[Err,ynew,iter];
ynew;
end proc;
makeJac := proq(f)
                                                  end proc
local N, jac;
    N := LinearAlgebra:-Dimension(f);
    jac := VectorCalculus :- Jacobian(f, [seq(y[i], i = 1 .. N)]);
    unapply(jac, y)
             makeJacN := proq(f)
             local N, jac;
                N := LinearAlgebra:-Dimension(f);
                jac := VectorCalculus :- Jacobian(f, [seq(y[i], i = 1 .. N)])
             end proc
```

```
Newton := prod(f, y0, makeJac, tol, maxiter)
local N, dy, Jac, F, yold, ynew, Err, iter;
    N := LinearAlgebra:-Dimension(f);
    F := \operatorname{unapply}(f, y);
    Jac := makeJac(f);
    yold := y0;
    dy := LinearAlgebra:-LinearSolve(-Jac(yold), F(yold));
    ynew := yold + dy;
    yold := ynew;
    Err := 10;
    iter := 1;
    while tol < Err and iter < maxiter do
         iter := iter + 1:
         dy := LinearAlgebra:-LinearSolve(-Jac(yold), F(yold));
         ynew := yold + dy;
         Err := LinearAlgebra:-Norm(yold - ynew);
         yold := ynew
    end do:
    ynew
end proc
>f:=Vector(2,[-y[1]^2,y[1]^2-y[2]]);
y00:=Vector(2,[1.0,0.0]);
                                     f \coloneqq \begin{bmatrix} -y_1^2 \\ y_1^2 - y_2 \end{bmatrix}
                                     y00 := \begin{bmatrix} 1.0 \\ 0. \end{bmatrix}
> EulerBDF:=proc(f,y00,tf,N)
local F,YY,h,y0,i;
F:=unapply(h*f+y0-Vector(LinearAlgebra:-
Dimension(f),[seq(y[i],i=1..LinearAlgebra:-
Dimension(f))]),y0,h);
h:=tf/N;
YY[0] := y00;
YY[1]:=Newton(F(y00,h),y00,makeJac,1e-6,50); #print(YY[1]);
for i from 2 to N do
YY[i] := Newton(F(YY[i-1],h),YY[i-1],makeJac,1e-6,50);
[seq([i*h,YY[i]],i=0..N)];#for printing all the values
YY[N];
```

```
end proc;
EulerBDF := prod(f, y00, tf, N)
local F, YY, h, y0, i;
    F := \text{unapply}(h \times f + y0 - \text{Vector}(LinearAlgebra:-Dimension}(f)),
        [seq(y[i], i = 1 .. LinearAlgebra:-Dimension(f))]), y0, h);
    h := tf/N;
    YY[0] := y00;
    YY[1] := Newton(F(y00, h), y00, makeJac, 0.1*10^{-5}, 50);
    for i from 2 to N do
        YY[i] := Newton(F(YY[i-1], h), YY[i-1], makeJac, 0.1*10^(-5), 50)
    end do:
    [seq([i \times h, YY[i]], i = 0...N)];
    YY[N]
end proc
> EulerBDF(f,y00,1,10); # used for comparison
                              [0.516493908066555]
                              0.268870124077736
> ThetaMethod: =proc(f, y00, tf, N, O)
local F,YY,h,y0,i;
ff:=unapply(f,y);
F:=unapply (hh* (OO*ff(y0)+(1-OO)*f)+y0-Vector(LinearAlgebra:-
Dimension(f),[seq(y[i],i=1..LinearAlgebra:-
Dimension(f))]),y0,hh,00);
h:=tf/N;
YY[0] := y00;
YY[1] := Newton(F(y00,h,O),y00,makeJac,1e-6,50); #print(YY[1]);
for i from 2 to N do
YY[i] := Newton(F(YY[i-1],h,O),YY[i-1],makeJac,1e-6,50);
#[seq([i*h,YY[i]],i=0..N)];#for printing all the values
YY[N];
end proc;
Warning, `ff` is implicitly declared local to procedure `ThetaMethod`
```

```
ThetaMethod := proc(f, y00, tf, N, O)
 local F, YY, h, y0, i, ff;
               ff := \text{unapply}(f, y);
                F := \text{unapply}(hh \times (OO \times ff(yO) + (1 - OO) \times f) + yO - \text{Vector}(yO) + yO - \text{Vector}(yO)
                              LinearAlgebra:-Dimension(f),
                              [seq(y[i], i = 1 .. LinearAlgebra:-Dimension(f))]), y0, hh, OO);
                h := tf/N;
                YY[0] := y00;
                YY[1] := Newton(F(y00, h, O), y00, makeJac, 0.1*10^{-5}, 50);
                for i from 2 to N do
                              YY[i] := Newton(F(YY[i-1], h, O), YY[i-1], makeJac, 0.1*10^(-5), 50)
                end do;
                YY[N]
  end proc
> ff:=unapply(f,y);
YY[0] := y00;
q:=h*(O*ff(y0)+(1-O)*f)+y0-Vector(LinearAlgebra:-
Dimension(f),[seq(y[i],i=1..LinearAlgebra:-Dimension(f))]);
F:=unapply (hh* (O*ff (y0) + (1-O) *f) +y0-Vector (LinearAlgebra: -
Dimension(f),[seq(y[i],i=1..LinearAlgebra:-
Dimension(f))]),y0,hh,O);
h:=1/10;
YY[1] := Newton(F(y00,h,0.5),y00,makeJac,1e-6,50);
YY[2] := Newton(F(YY[1],h,0.5),YY[1],makeJac,1e-6,50);
>
>
                                ff := y \rightarrow \text{rtable}(1 ... 2, \{1 = -y_1^2, 2 = y_1^2 - y_2^2\}, datatype = anything,
                                             subtype = Vector_{column}, storage = rectangular, order = Fortran\_order)
                                                                                                                            YY_0 := \begin{bmatrix} 1.0 \\ 0. \end{bmatrix}
                                                           q := y0 + \begin{bmatrix} h(-Oy\theta_1^2 - (1-O)y_1^2) - y_1 \\ h(O(y\theta_1^2 - y\theta_2) + (1-O)(y_1^2 - y_2)) - y_2 \end{bmatrix}
```

```
F := (y0, hh, O) \rightarrow y0 + \text{rtable}(1 ... 2, \{1 = hh (-Oy0_1^2 - (1 - O)y_1^2) - y_1,
     2 = hh \left(O\left(y\theta_1^2 - y\theta_2\right) + (1 - O)\left(y_1^2 - y_2\right)\right) - y_2\right\}, datatype = anything,
     subtype = Vector_{column}, storage = rectangular\,, order = Fortran\_order\,)
                                                     h := \frac{1}{10}
                                       YY_1 := \begin{bmatrix} 0.908712114635714 \\ 0.0869408432040815 \end{bmatrix}
                                       YY_2 := \begin{bmatrix} 0.832750554934263 \\ 0.151005105471742 \end{bmatrix}
> i := 0.1;
ThetaMethod(f,y00,1,50,i);
i:=1/3;
ThetaMethod(f,y00,1,50,i);
i:=1/2;
ThetaMethod(f,y00,1,50,i);
i:=2/3;
ThetaMethod(f,y00,1,50,i);
ThetaMethod(f,y00,1,50,i);
                                                     i := 0.1
                                            [0.502741192105351 ]
                                            0.279725647282292
                                                      i := \frac{1}{2}
                                            [0.501129248978697 <sup>-</sup>
                                            0.281000909699360
                                                      i := \frac{1}{2}
                                            0.499974997083022 0.281912177403608
                                                      i := \frac{2}{3}
                                            [0.498818380304596 <sup>-</sup>
                                            0.282823666431601
                                                     i := 1.0
                                            Γ0.496498130899834
                                            0.284647004665424
```