

April 9, 2020

- The exponential of a matrix (7.7)
- Complex valued solutions (end of 7.4.,  
7.6)
- Method of Variation of Parameters (7.9) ← Today and next  
class

### The exponential

$$e^x = \sum_{n=0}^{\infty} \frac{1}{n!} x^n \quad (x \text{ a real variable})$$

$$n! = n(n-1)(n-2)\dots \cdot 1 \quad 0! = 1, 1! = 1 \dots$$

$$\begin{aligned} (e^x)' &= \sum_{n=0}^{\infty} \frac{1}{n!} (x^n)' \\ &= \sum_{n=0}^{\infty} \frac{n}{n!} x^{n-1} \quad \left( \frac{n}{n!} = \frac{n}{n(n-1)\dots 1} = \frac{1}{(n-1)!} \right) \\ &= \sum_{n=1}^{\infty} \frac{1}{(n-1)!} x^{n-1} \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} x^n = e^x \end{aligned}$$

EXERCISE: Check without using the chain rule  
that  $(e^{\lambda x})' = \lambda e^{\lambda x}$

To compute the exponential of  $x$ , we require

- Taking powers of  $x$
- Adding such powers of  $x$  (multiple by  $\frac{1}{n!}$ )
- Taking limits

$$e^x = \lim_{N \rightarrow \infty} \sum_{n=0}^N \frac{1}{n!} x^n$$

Each of these things can be done with a square matrix  $A$ :

- Powers of  $A$ :  $A^0 = I, A^1, A^2, \dots$

- We can add them up

$$\sum_{k=0}^N \frac{1}{k!} A^k = I + A + \frac{1}{2} A^2 + \frac{1}{6} A^3 + \dots + \dots + \frac{1}{N!} A^N$$

- $\lim_{N \rightarrow \infty} \sum_{k=0}^N \frac{1}{k!} A^k$

Definition: The exponential of a square matrix  $A$ , denoted  $e^A$ , is the matrix given by

$$e^A = \sum_{k=0}^{\infty} \frac{1}{k!} A^k$$

Properties of  $e^A$  (properties of  $e^x$  for all  $x$ )

$$\begin{aligned} \textcircled{1} \quad e^x &\neq 0 \\ \textcircled{2} \quad e^0 &= I \\ \textcircled{3} \quad (e^x)^t &= e^x \end{aligned}$$

$\textcircled{1}$  If  $A$  and  $B$  are matrices which commute (meaning  $AB = BA$ )

then 
$$e^{A+B} = e^A \cdot e^B = e^B \cdot e^A$$

(one can check that this is true manipulating the powers when defining  $e^{A+B}$ :  $\sum_{k=0}^{\infty} \frac{1}{k!} (A+B)^k$  ← A good exercise!)

$\textcircled{2}$  If  $A = 0$  ( $A = \begin{pmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & 0 \end{pmatrix}$ ) then

$$e^A = I = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & 1 \\ 0 & 0 & \dots & 1 \end{pmatrix}$$

(why? well if  $A=0$ , then  $A^k=0$  for all powers  $k$ , so

$$e^A = I + 0 + \frac{1}{2}0 + \frac{1}{6}0 + \dots \\ = I.)$$

③ If  $A$  is a diagonal matrix, then so

is  $e^A$ .  
 $A = \begin{pmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_2 & & & \\ \vdots & & \lambda_3 & & \\ 0 & & \dots & 0 & \lambda_n \end{pmatrix}$

Note  $A^k$  is simply the diagonal matrix where the entries of  $A$  are raised to the  $k$ -th power

$$A = \begin{pmatrix} \lambda_1^k & 0 & 0 & \dots & 0 \\ 0 & \lambda_2^k & & & \\ \vdots & & \lambda_3^k & & \\ 0 & & \dots & 0 & \lambda_n^k \end{pmatrix}$$

Then,

$$e^A = \begin{pmatrix} \sum_{k=0}^{\infty} \frac{1}{k!} \lambda_1^k & 0 & 0 & \dots & 0 \\ 0 & \sum_{k=0}^{\infty} \frac{1}{k!} \lambda_2^k & & & \\ \vdots & & \ddots & & \\ 0 & 0 & 0 & \dots & \sum_{k=0}^{\infty} \frac{1}{k!} \lambda_n^k \end{pmatrix} \quad (6)$$

$$= \begin{pmatrix} e^{\lambda_1} & 0 & 0 & \dots & 0 \\ 0 & e^{\lambda_2} & & & \\ \vdots & & \ddots & & \\ 0 & 0 & 0 & \dots & e^{\lambda_n} \end{pmatrix}$$

④ If  $v$  is an eigenvector of the matrix  $A$  with eigenvalue  $\lambda$ , then  $v$  is also an eigenvector of  $e^A$ , but with eigenvalue  $e^\lambda$ .

(why?) If  $v$  is an eigenvector, then

$$\begin{aligned} A^k v &= A^{k-1}(Av) = \lambda A^{k-1}v \\ &= \lambda^2 A^{k-2}v \dots \\ &= \lambda^k v \end{aligned}$$

Then  $e^A v = \sum_{k=0}^{\infty} \frac{1}{k!} A^k v = \sum_{k=0}^{\infty} \frac{1}{k!} \lambda^k v$

$$= \left( \sum_{k=0}^{\infty} \frac{1}{k!} \lambda^k \right) v = e^\lambda v.$$

In particular, if  $v$  is an eigenvector of  $A$  with eigenvalue  $\lambda$ , then

$$e^{tA} v = e^{\lambda t} v$$

This is interesting because we know that  $e^{\lambda t} v$  is a solution of  $\dot{x} = Ax$  when  $v$  is an eigenvector with eigenvalue  $\lambda$ .

Is it the case that for any  $v$ , there

$$e^{tA} v$$

is a solution of  $\dot{x} = Ax$ ?

(5)  $e^{tA}$  as a matrix function has the following property

$$\frac{d}{dt} e^{tA} = Ae^{tA} = e^{tA} A$$

(compare with  $(e^{\lambda t})' = \lambda e^{\lambda t}$ )

(why is this true?)

$$\frac{d}{dt} e^{tA} = \lim_{h \rightarrow 0} \frac{1}{h} (e^{(t+h)A} - e^{tA})$$

Note :  $e^{(t+h)A} = e^{tA+hA} = e^{hA} \cdot e^{tA}$

$$e^{(t+h)A} - e^{tA} = e^{hA} e^{tA} - e^{tA}$$

$$= (e^{hA} - I) e^{tA}$$

Observe :  $e^{hA} = I + hA + h^2 \frac{A^2}{2} + h^3 \frac{A^3}{6} + \dots$

w  $e^{hA} - I = hA + h^2 \frac{A^2}{2} + h^3 \frac{A^3}{6} + \dots$

$\frac{1}{h} (e^{hA} - I) = A + \underbrace{h \frac{A^2}{2} + h^2 \frac{A^3}{6} + \dots}_{\text{thus sum } \rightarrow 0 \text{ when } h \rightarrow 0}$

so

$$\begin{aligned} & \lim_{h \rightarrow 0} \frac{1}{h} (e^{(t+h)A} - e^{tA}) \\ &= \lim_{h \rightarrow 0} \frac{1}{h} (e^{hA} - I) e^{tA} \\ &= A e^{tA} \end{aligned}$$

(6) If  $x_0$  is any initial vector,

then

$$x(t) = e^{tA} x_0 \quad \text{solves}$$

$$\begin{cases} \dot{x} = Ax \\ x(0) = x_0 \end{cases}$$

(why?)

$$\dot{x}(t) = \frac{d}{dt}(e^{tA} x_0)$$

$$\begin{aligned} &= \left( \frac{d}{dt}(e^{tA}) \right) x_0 + e^{tA} \frac{d}{dt} x_0 \\ &\stackrel{\text{(by property 5)}}{=} A e^{tA} x_0 = A(e^{tA} x_0) \\ &= A x(t). \end{aligned}$$

(by property 2)

$$\begin{aligned} x(0) &= e^{0 \cdot A} x_0 \\ &= e^0 x_0 = I x_0 = x_0 \end{aligned}$$

Then it is clear that solving a system  $\dot{x} = Ax$  is the same as finding an expression for  $e^{tA}$ .

Remark: In general,  $\frac{d}{dt} e^{\int_0^t A(s) ds} \neq A(t) e^{\int_0^t A(s) ds}$

because  $e^{A+B} = e^A \cdot e^B$  only when  $AB = BA$ , which

is hardly true for nature in general. This is why the matrix exponential is of little help for system with time-dependent coefficients

$$\dot{x} = A(t)x$$

except when  $A(s)$  is such that

$$A(t)A(s) = A(s)A(t)$$

for all  $t$  and  $s$

How do we actually find the exponential?  
We already know!

Observation: If  $\Psi(t)$  is a fundamental matrix for the system

$$\dot{x} = Ax$$

then

$$\Psi(t)\Psi(0)^{-1} = e^{tA}$$

So, to compute  $e^{tA}$ , we

- (1) Compute the characteristic polynomial of  $A$
- (2) Find eigenvalues and (necessarily)  $n$  linearly independent eigenvectors  $v_1, \dots, v_n$

③ We form the fundamental matrix

$$\tilde{\Psi}(t) = \begin{pmatrix} e^{\lambda_1 t} v_1 & e^{\lambda_2 t} v_2 & \cdots & e^{\lambda_n t} v_n \end{pmatrix}$$

and then compute  $\tilde{\Psi}(0)^{-1}$  and

then

$$e^{tA} = \tilde{\Psi}(t) \tilde{\Psi}(0)^{-1}$$

Ex Recall our "favorite" equation

$$\dot{x} = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}$$

We found in previous lecture that a fundamental matrix is given by

$$\tilde{\Psi}(t) = \begin{pmatrix} e^{3t} & e^{-t} \\ 2e^{3t} & -2e^{-t} \end{pmatrix}$$

Then

$$e^{t \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}} = \tilde{\Psi}(t) \tilde{\Psi}(0)^{-1}$$

$$= \begin{pmatrix} \frac{1}{2}(e^{3t} + e^{-t}) & \frac{1}{2}(e^{3t} - e^{-t}) \\ e^{3t} - e^{-t} & \frac{1}{2}(e^{3t} - e^{-t}) \end{pmatrix}$$

## Complex Valued Solutions

(end of Sectr 7.4, and all of Sectr 7.5)

A vector function  $\mathbf{x}(t)$  will be called real valued if all the components are real valued functions, and will be called complex valued if all the components are complex.

If  $\mathbf{x}(t)$  is complex valued, we can write it as

$$\mathbf{x}(t) = \mathbf{x}_1(t) + i \mathbf{x}_2(t)$$

where  $\mathbf{x}_1(t)$  and  $\mathbf{x}_2(t)$  are real valued functions.

Ex  $\mathbf{x}(t) = \begin{pmatrix} \cos(t) + i \sin(t) \\ \sin(t) - i \cos(t) \end{pmatrix}$

$$\begin{aligned} \text{Then } \mathbf{x}(t) &= \begin{pmatrix} \cos(t) \\ \sin(t) \end{pmatrix} + \begin{pmatrix} i \sin(t) \\ -i \cos(t) \end{pmatrix} \\ &= \begin{pmatrix} \cos(t) \\ \sin(t) \end{pmatrix} + i \begin{pmatrix} \sin(t) \\ -\cos(t) \end{pmatrix} \end{aligned}$$

### Ex (continued)

Let's check that  $\mathbf{x}(t)$  from the previous example is a complex valued solution to the system

$$\dot{x} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} x$$

On one hand

$$\begin{aligned}\dot{x}(t) &= \begin{pmatrix} \frac{d}{dt}(\cos(t)) + i \sin(t) \\ \frac{d}{dt}(\sin(t)) - i \cos(t) \end{pmatrix} \\ &= \begin{pmatrix} -\sin(t) + i \cos(t) \\ \cos(t) + i \sin(t) \end{pmatrix}\end{aligned}$$

on the other hand

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} x = \begin{pmatrix} -(\sin(t) - i \cos(t)) \\ \cos(t) + i \sin(t) \end{pmatrix} \\ = \begin{pmatrix} -\sin(t) + i \cos(t) \\ \cos(t) + i \sin(t) \end{pmatrix}$$

so we note that in this case

$\dot{x} = A x$

It is also easy to check that the following two functions are also solutions to the system

$\begin{pmatrix} \cos(t) \\ \sin(t) \end{pmatrix}$  and  $\begin{pmatrix} \sin(t) \\ -\cos(t) \end{pmatrix}$

but! there are also the real and imaginary parts of  $x(t)$ .

Thus we conclude with the following

Observation: A complex valued function  $x(t)$  is a solution to a differential equation

$$\dot{x} = Ax$$

where A has only real entries if and only if the real and imaginary parts of  $x(t)$  are also solutions.

(symbolically):  $x(t) = x_1(t) + i x_2(t)$ ,  $x_1$  and  $x_2$  real valued solves  $\dot{x} = Ax$  if and only if  $\dot{x}_1 = Ax_1$  and  $\dot{x}_2 = Ax_2$ )

How does this help us? Suppose you have the system for  $t > 0$

$$\dot{x} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}x$$

The characteristic polynomial in this case

is  $P(\lambda) = \lambda^2 + 1$   
and the roots are  $\pm \sqrt{-1}$ , i.e.  $\pm i$ .

This means that a complex valued solution to this system would look like

$$x(t) = e^{it} v ?$$

for some complex constant  $v$ .

## Complex exponential

Let  $z = \alpha + i\beta$  ( $\alpha, \beta$  real numbers)

Then we define

$$e^z = \sum_{k=0}^{\infty} \frac{1}{k!} z^k$$

Properties :

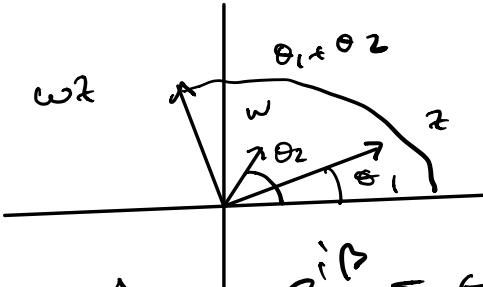
①  $e^{z+w} = e^z \cdot e^w$  for all complex numbers  $z$  and  $w$

② If  $z$  is real, then  $e^z$  is the usual exponential

③  $e^{i\beta} = \cos(\beta) + i \sin(\beta)$ , for real  $\beta$ .

(why? remember as complex multiplication involves rotation)

$$|wz| = |w| |z|$$



The reason why  $e^{i\beta} = \cos(\beta) + i \sin(\beta)$  involves the power series of  $e^x$ ,  $\cos(x)$ ,  $\sin(x)$  and we will discuss that some other time)

EX (let's go back to the system)

$$\dot{x} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} x$$

The eigenvalues are  $i$  and  $-i$ , and  
an eigenvector for  $i$  is

$$v_i = \begin{pmatrix} 1 \\ i \end{pmatrix}$$

so a solution is

$$\begin{aligned} x_i(t) &= e^{it} \begin{pmatrix} 1 \\ i \end{pmatrix} \\ &= \begin{pmatrix} \cos(t) + i \sin(t) \\ (\cos(t) + i \sin(t))i \end{pmatrix} \\ &= \begin{pmatrix} \cos(t) + i \sin(t) \\ -\sin(t) + i \cos(t) \end{pmatrix} \end{aligned}$$

so the complex valued solution we saw  
earlier comes from a complex eigenvector

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• Tomorrow : I will post a video where  
I go over more examples

• Tuesday : we will look at other  
systems like

$$\dot{x} = A(t)x + b(t)$$