

5374 Fall '22

Numerical Linear Algebra

Lecture 24

Today

* More on the SVD

(low rank approximation, compression, dimensionality reduction)

Remarks on the SVD (continued)

4. The sup norm of A and the SVD

Let A be $m \times n$, recall

$$\|A\| := \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

Claim : If $A = U \Sigma V^T$, then

$$\|A\| = \sigma_1$$

Proof

Observe: If

$$\Sigma = \begin{pmatrix} \sigma_1 & 0 & \dots & 0 & \dots & 0 \\ 0 & \sigma_2 & & & & \\ \vdots & & \ddots & & & \\ 0 & & & \sigma_r & 0 & \dots \end{pmatrix} \begin{matrix} n \\ m \end{matrix}$$

($r \leq \min(m, n)$)

Then given $x \in \mathbb{R}^n$,

$$\begin{aligned}
 \|\Sigma x\|_2 &= \left\| \begin{pmatrix} \sigma_1 x_1 \\ \sigma_2 x_2 \\ \vdots \\ \sigma_n x_n \end{pmatrix} \right\|_2 \\
 &= \sqrt{(\sigma_1 x_1)^2 + \dots + (\sigma_n x_n)^2} \\
 &= \sqrt{\sigma_1^2 x_1^2 + \dots + \sigma_n^2 x_n^2}, \quad \text{since } \sigma_1^2 \geq \sigma_n^2 \quad \forall n \\
 &\leq \sqrt{\sigma_1^2 (x_1^2 + \dots + x_n^2)} \\
 &= \sigma_1 \|x\|_2
 \end{aligned}$$

$$\Rightarrow \frac{\|\Sigma x\|_2}{\|x\|_2} \leq \sigma_1 \quad \forall x \neq 0$$

$$\text{Moreover, } \|\Sigma e_1\|_2 = \left\| \begin{pmatrix} \sigma_1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \right\|_2 = \sigma_1$$

$$\text{Thus } \max_{x \neq 0} \frac{\|\Sigma x\|_2}{\|x\|_2} = \sigma_1$$

The general claim follows from here as follows

(we are going to use that if U, V are orthogonal matrices then $\|Uy\|_2 = \|y\|_2$ and $\|Vx\|_2 = \|x\|_2$ for all $x \in \mathbb{R}^n, y \in \mathbb{R}^m$)

Well,

$$\begin{aligned}
 Av_i &= (U \Sigma V^T) v_i, \quad V^T v_i = e_i \\
 &= U \Sigma e_i = \sigma_i U e_i = \sigma_i u_i
 \end{aligned}$$

$$\Rightarrow \|Av_1\|_2 = \|\sigma_1 u_1\|_2 = \sigma_1 \|u_1\|_2 = \sigma_1$$

$$\Rightarrow (\|u_1\|_2 = 1) \quad \frac{\|Av_1\|_2}{\|v_1\|_2} = \sigma_1$$

On the other hand, take $x \in \mathbb{R}^n$ ($x \neq 0$)

$$\begin{aligned} \frac{\|Ax\|_2}{\|x\|_2} &= \frac{\|(\Sigma V^T)(V^T x)\|_2}{\|x\|_2} \\ &\leq \frac{\|\Sigma\| \cdot \|V^T x\|_2}{\|x\|_2} \quad \left(\|V^T x\|_2 = \|x\|_2 \right) \\ &\leq \|\Sigma\| \end{aligned}$$

Next, let again $x \in \mathbb{R}^n$ ($x \neq 0$)

$$\frac{\|V(\Sigma x)\|_2}{\|x\|_2} = \frac{\|\Sigma x\|_2}{\|x\|_2} \quad \left(\text{since } \|Vy\|_2 = \|y\|_2 \right)$$

$$\leq \sigma_1$$

$$\Rightarrow \|V\Sigma\| \leq \sigma_1$$

Thus $\|A\| = \sigma_1$

5. Observe that if

$$A = U \Sigma V^T \quad (A \text{ is } n \times n, \text{ invertible})$$

Then

$$\begin{aligned} A^{-1} &= (U \Sigma V^T)^{-1} \\ &= (V^T)^{-1} \Sigma^{-1} U^{-1} \\ &= V \Sigma^{-1} U^T \end{aligned}$$

$$\Rightarrow \|A^{-1}\| = \frac{1}{\sigma_n}$$

In particular, if the singular values of A are $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n > 0$, then

$$\text{cond}(A) = \frac{\sigma_1}{\sigma_n}$$

6. If A is symmetric, then the singular values of A are the absolute values of the eigenvalues of A .

7. Other things that follow from the SVD is

the determinant (up to a sign) because
(A is $n \times n$)

$$\det A = \underbrace{(\det U)}_{(\pm 1)} (\det \Sigma) \underbrace{(\det V^T)}_{(\pm 1)}$$

$$\Rightarrow \det A = \pm \prod_{k=1}^n \sigma_k$$

$$|\det A| = \prod_{k=1}^n \sigma_k$$

8. Let A have exactly r non-zero singular values, i.e. the singular values of A are s.v.

$$\sigma_1 \geq \sigma_2 \geq \sigma_3 \geq \dots \geq \sigma_r > 0$$

and either $r = \min(m, n)$ or $\sigma_{r+1} = 0$

The number r is exactly the rank of A .

Low Rank Approximation

An alternative way of writing the SVD is, if r is the rank of A , then
 $(\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0)$

$$A = \sigma_1 u_1 \otimes v_1 + \sigma_2 u_2 \otimes v_2 + \dots + \sigma_r u_r \otimes v_r$$

$$(\text{Recall: } (x \otimes y)z = (z, y)x)$$

where u_1, \dots, u_m and v_1, \dots, v_n represent the column vectors

of U and V .

Observe: $\text{Im}(A) = \text{span}\{u_1, \dots, u_r\}$

$$\text{Ker}(A) = \text{span}\{v_{r+1}, \dots, v_n\}$$

Every matrix of rank-1 can be written in the form

$$x \otimes y$$

where x, y are non-zero vectors. If $y \in \mathbb{R}^n$, $x \in \mathbb{R}^m$ the matrix will be $m \times n$.

Another way of stating the SVD is that any matrix of rank r is equal to the sum of exactly r rank-1 matrices generated by orthogonal vectors:

$$A = \sigma_1 u_1 \otimes v_1 + \dots + \sigma_r u_r \otimes v_r$$

Since $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$, The first term ^{tend to} have more influence than the latter ones

Pictorially a matrix A of the form

$$A = 1000 u_1 \otimes v_1 + 1000 u_2 \otimes v_2 + 100 u_3 \otimes v_3 \\ + (0.0001) u_4 \otimes v_4 + \dots + (0.0001) u_{1000} \otimes v_{1000}$$

This would be a matrix of rank 1000 where the smallest 997 singular values are very small, and thus, in certain contexts, it might make sense to approximate A with

$$A \approx_3 1000 u_1 \otimes v_1 + 1000 u_2 \otimes v_2 + 1000 u_3 \otimes v_3$$

which is a rank-3 matrix.

There is a theorem justifying how this provides the best possible low rank approximation

Theorem : Let A be a $m \times n$ matrix with SVD given by :

$$A = \sigma_1 u_1 \otimes v_1 + \dots + \sigma_r u_r \otimes v_r \quad (\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0)$$

For every $l = 1, 2, \dots, r$ define

$$A_l = \sigma_1 u_1 \otimes v_1 + \dots + \sigma_l u_l \otimes v_l$$

Then A_l is the best l -rank approximation to A as measured in the $\|\cdot\|_{Fr}$ and $\|\cdot\|_{op}$ norm of A ; that is

$$\left(\downarrow \|A\|_{op} = \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2} \right)$$

$$\|A - A_l\|_{Fr} = \min \{ \|A - B\|_{Fr} \mid \text{rank}(B) = l \}$$

$$\|A - A_l\|_{op} = \min \{ \|A - B\|_{op} \mid \text{rank}(B) = l \}$$