

5374 Fall '22

Numerical Linear Algebra

Lecture 20

Today: * Symmetric matrices and eigenvectors

Theorem: If A is a symmetric $n \times n$ matrix then there exists n vectors

$$v_1, \dots, v_n$$

$$\lambda_1, \dots, \lambda_n$$

which are orthonormal and n numbers such that for each $k=1, \dots, n$ we have

$$A v_k = \lambda_k v_k$$

Remarks: In particular, since the $\{v_k\}$ form an orthonormal matrix, given $x \in \mathbb{R}^n$, we have

$$x = (x, v_1) v_1 + \dots + (x, v_n) v_n$$

$$A x = \lambda_1 (x, v_1) v_1 + \dots + \lambda_n (x, v_n) v_n$$

This last equation is the same as saying

$$A x = V D V^t x \quad \forall x \in \mathbb{R}^n$$

where

$$D = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & & \\ \vdots & & \ddots & \\ 0 & & & \lambda_n \end{pmatrix}, \quad V = (v_1 | v_2 | \dots | v_n)$$

In other words, A can be factorized as (note $V^{-1} = V^T$)

$$A = V D V^{-1} \quad (*)$$

In other words, the theorem says any symmetric matrix A is conjugate to a diagonal matrix and the conjugation is done by an orthogonal matrix.

The factorization $(*)$ is sometimes called the eigenvector decomposition of A (even if A is not symmetric and V is not orthogonal).

Exercise: ① Show that if v_1, \dots, v_m are eigenvectors of A ($n \times n$, $n \geq m$) with respective eigenvalues $\lambda_1, \dots, \lambda_m$ all different, then the v_1, \dots, v_m are linearly independent

② Show that if the characteristic polynomial of A ($n \times n$) has n different real roots then A has an eigenvector decomposition

Definition: If A has an eigenvector decomposition, it is said that A is diagonalizable

Remark: Here is another way of thinking about this theorem, and one that naturally extends to infinite dimensions and is important in functional analysis.

Given a matrix A and eigenvalue λ , define

$$E_\lambda = \{ v \in \mathbb{R}^n \mid Av = \lambda v \}$$

and define

$P_\lambda =$ orthogonal projection into E_λ

$$(\text{ie. } P_\lambda^2 = P_\lambda, P_\lambda^* = P_\lambda, \text{Im}(P_\lambda) = E_\lambda)$$

Then the theorem stated earlier can also be stated as follows:

If A is symmetric and A 's set of eigenvalues is $\lambda_1, \dots, \lambda_m$ ($m \leq n$) then, we have

$$A = \lambda_1 P_{\lambda_1} + \lambda_2 P_{\lambda_2} + \dots + \lambda_m P_{\lambda_m}$$

where $I = P_{\lambda_1} + P_{\lambda_2} + \dots + P_{\lambda_m}$
 and $P_{\lambda_k} P_{\lambda_j} = 0$ if $k \neq j$.

Note: In functional analysis, certain linear operators L can be decomposed as

$$L = \int_{\mathbb{R}} \lambda P_{\lambda} d\mu(\lambda)$$

where μ is something called the spectral measure

Remark: All of the above statements have straightforward analogues for Hermitian matrices A , i.e. matrices A with complex entries such that

$$A^* = A$$

Then, the orthogonality is in terms of the usual Hermitian product in \mathbb{C}^n , and "orthogonal matrix" is replaced with "unitary matrix".

Moreover, for such Hermitian matrices, the eigenvalues are all real.

Proof of the eigenvalue decomposition for symmetric matrices

Lemma: Let A be symmetric with two eigenvectors v_1, v_2 with different eigenvalues λ_1, λ_2 . THEN $v_1 \perp v_2$. In other words, the spaces E_{λ_1} and E_{λ_2} are orthogonal to each other.

Proof : $(Av_1, v_2) = \lambda_1 (v_1, v_2)$
 $(v_1, Av_2) = \lambda_2 (v_1, v_2)$

Since A is symmetric, $(Av_1, v_2) = (v_1, Av_2)$

$$\Rightarrow \lambda_1 (v_1, v_2) = \lambda_2 (v_1, v_2)$$

$$(\lambda_1 - \lambda_2) (v_1, v_2) = 0$$

$$\Rightarrow (v_1, v_2) = 0 \quad (\text{since } \lambda_1 - \lambda_2 \neq 0)$$



This shows how the symmetry of A guarantees the orthonormality of the eventual eigenvector basis.

The problem we may face when doing an eigenvector decomposition is: not enough eigenvectors exist to span \mathbb{R}^n .

Example : Let

$$A = \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$$

The matrix has exactly one eigenvalue, λ , which is a double root of the characteristic polynomial of A . However,

$$\begin{aligned} E_\lambda &= \{ v \in \mathbb{R}^2 \mid Av = \lambda v \} \\ &= \text{span}\left[\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right] \neq \mathbb{R}^2 \end{aligned}$$

Definition : A subspace $V \subseteq \mathbb{R}^n$ is said to be stable with respect to a matrix A if $V \in \mathcal{V} \Rightarrow AV \in \mathcal{V}$.
(AKA, invariant)

Lemma : Let A be symmetric and $V \subseteq \mathbb{R}^n$ a subspace stable under A . ^{$V \neq \{0\}$} Then there exists an eigenvector of A in V .

Proof : It's a variational proof. You consider

$$f(x) := \frac{1}{2} (Ax, x) \quad \forall x \in \mathbb{R}^n$$

It's gradient is $\nabla f(x) = Ax$ (This uses the symmetry of A , in general, if A is not symmetric

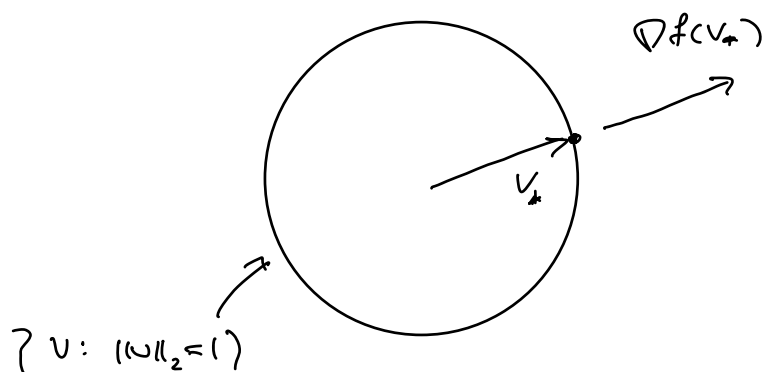
$$\nabla f(x) = \left(\frac{1}{2} A + \frac{1}{2} A^T \right) x$$

Consider f restricted to the following set:

$$\{x \in \mathbb{R}^n \mid \|x\|_2 = 1 \text{ and } x \in V\}$$

This set is compact, and so f restricted to it achieves a maximum and a minimum.

Let V_* be an element of the set where the minimum of $f(x)$ is achieved.



So the gradient $\nabla f(V_*)$ must be parallel to V_* , or rather there must be $\alpha \in \mathbb{R}$ s.t.

$$\nabla f(V_*) = \alpha V_*$$

i.e.

$$AV_* = \alpha V_*$$

Since $\|V_*\|_2 = 1$, $V_* \neq 0$ so V_* is an eigenvector of A in V .

□

Now we combine the lemmas and finish the proof of the theorem:

We will construct an orthonormal basis of eigenvectors for A .

Step 1: \mathbb{R}^n is not $\{0\}$ and is stable under A , so by the last lemma there exists a unit vector, which we call v_1 , and $\lambda_1 \in \mathbb{R}$ s.t.

$$Av_1 = \lambda_1 v_1$$

Step 2: Suppose you have constructed k orthonormal eigenvectors v_1, \dots, v_k ($k \geq 1$), if $k = n$, you are done. If not, then $k < n$, and then we consider

$$V = \{x \in \mathbb{R}^n \mid (x, v_j) = 0 \text{ for } j=1, \dots, k\}$$

Since $k < n$, V is not the null subspace. I claim V is stable under A :

let $x \in V$, then $(x, v_j) = 0 \quad \forall j=1, \dots, k$,
let's show $Ax \in V$. Indeed,

$$\begin{aligned} (Ax, v_j) &= (x, Av_j) = (x, \lambda_j v_j) = \lambda_j (x, v_j) \\ &= 0 \end{aligned}$$

so $(Ax, v_j) = 0$ for $j=1, \dots, k$, and Ax also lies in V .

So V is stable, and not null, so by the last lemma there is a unit eigenvector of A in V , we call it v_{k+1} .

We repeat Step 2 until it hits $k=n$, and we are done.