

5374 Fall '22

Numerical Linear Algebra

Lecture 14

QR decomposition continued  
Least squares problems.

Last time we reviewed the Gram-Schmidt process and saw how given a basis

$$a_1, \dots, a_n$$

we can produce an orthonormal basis

$$q_1, \dots, q_n$$

by

$$(r_{11} = \|a_1\|_2)$$

$$r_{11} q_1 = a_1$$

$$r_{22} q_2 = a_2 - (a_2, q_1) q_1$$

$\vdots$

$$r_{kk} q_k = a_k - \sum_{j=1}^{k-1} (a_k, q_j) q_j$$

$\hookleftarrow$

$$r_{kk} = \|a_k - \sum_{j=1}^{k-1} (a_k, q_j) q_j\|_2$$

Clearly this is an iterative procedure where  $q_k$  is built from  $a_k$  and  $q_1, \dots, q_{k-1}$ .

From the construction it follows that

$$\text{span}[a_1, \dots, a_n] = \text{span}[q_1, \dots, q_n]$$

$$n=1, 2, \dots, n$$

and  $(q_i, q_j) = \delta_{ij}$ . Moreover,

$$a_1 = r_{11} q_1$$

$$a_2 = (a_2, q_1) q_1 + r_{22} q_2$$

$\vdots$

$$a_n = (a_n, q_1) q_1 + \dots + (a_n, q_{n-1}) q_{n-1} + r_{nn} q_n$$

Let's define  $r_{ij}$  (for  $i \neq j$ ) by

$$r_{ij} = \begin{cases} (a_j, q_i) & \text{if } i < j \\ 0 & \text{if } i > j \end{cases}$$

In this notation

$$a_1 = r_{11} q_1$$

$$a_2 = r_{12} q_1 + r_{22} q_2$$

$\vdots$

$$a_n = r_{1n} q_1 + \dots + r_{nn} q_n$$

$\vdots$

$$a_n = r_{1n} q_1 + \dots + r_{nn} q_n$$

This  $n$  vector equation can be expressed as a single matrix equation

$$\begin{pmatrix} a_1 & | & \dots & | & a_n \end{pmatrix} = \begin{pmatrix} q_1 & | & \dots & | & q_n \end{pmatrix} \begin{pmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & r_{22} & & r_{2n} \\ \vdots & 0 & \ddots & \vdots \\ 0 & \vdots & & 0 r_{nn} \end{pmatrix}$$

If  $A$  is an arbitrary  $n \times n$  invertible matrix, we can apply the above process to the column of  $A$  ( $a_1, \dots, a_n$ ) and obtain  $n$  orthonormal vectors ( $q_1, \dots, q_n$ ) and coefficients  $r_{ij}$  such that if we define  $Q$  and  $R$  by

$$Q = \begin{pmatrix} q_1 & | & \dots & | & q_n \end{pmatrix}$$

$$R = \begin{pmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & \ddots & & \vdots \\ \vdots & & 0 & r_{nn} \end{pmatrix}$$

Then

$$A = QR$$

This proves any invertible matrix admits a  $QR$  decomposition.

## A detour on projection

A  $n \times n$  matrix  $P$  is said to be idempotent if

$$P^2 = P$$

A projector or projection operator is a symmetric idempotent operator, i.e.  $P$  such that

$$P^2 = P, \quad P^t = P$$

Examples :

①  $A = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

② let  $q \in \mathbb{R}^n$  be a unit vector, and consider

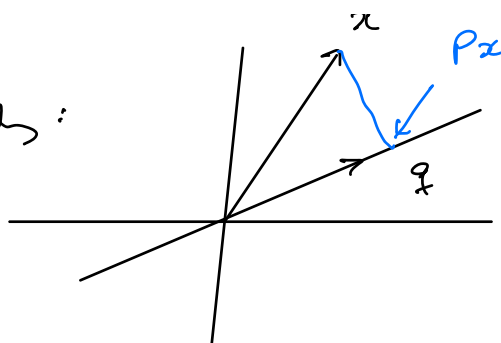
$$P = q \otimes q$$

$$(P_{ij} = q_i q_j)$$

$$Px = (q, x) q \quad (*)$$

It's easy to check from  $(*)$  that  $P^2 = P$

Geometrically:



$$\begin{aligned} P(Px) &= P((q, x)q) \\ &= (q, x) Pq \\ &= (q, x)q \quad (Pq = q) \end{aligned}$$

The example in ① corresponds to

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

③ If  $q_1, \dots, q_n$  are an orthonormal family of vectors ( $1 \leq k \leq n$ ), let

$$P = q_1 \otimes q_1 + q_2 \otimes q_2 + \dots + q_n \otimes q_n$$

Clearly  $P^t = P$

$$\begin{aligned} (P^t &= (q_1 \otimes q_1)^t + \dots + (q_n \otimes q_n)^t \\ &= q_1 \otimes q_1 + \dots + q_n \otimes q_n) \end{aligned}$$

$$Px = (q_1, x)q_1 + \dots + (q_n, x)q_n$$

In particular ,

$$P q_i = (q_1, q_i) q_1 + \dots + (q_k, q_i) q_k$$

Since  $(q_i, q_j) = \delta_{ij}$ , the above reduces to

$$P q_i = (q_i, q_i) q_i = q_i$$

$\Rightarrow$  if  $x$  is a linear comb of  $q_1, \dots, q_k$  then

$$P x = x.$$

$$\Rightarrow P^2 = P.$$

so  $P$  is the orthogonal projection onto the space spanned by  $q_1, \dots, q_k$ .

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As it turns out, these are all the projectors

(P is non)

Lemma: Let  $P$  be a projector, then  
 $\forall x \in \mathbb{R}^n$  we can write  $x$  uniquely  
 as a sum  

$$x = x_p + x_0$$

where

$$x_p \in \text{Im}(P), \quad x_0 \in \text{Ker}(P)$$

Proof: Let  $x_p = Px$ ,  
 $x_0 = x - Px$

Clearly,  $x_p \in \text{Im}(P)$ ,  $x = x_p + x_0$ ,  
 but,

$$\begin{aligned} Px_0 &= Px - P^2x \\ &= Px - Px = 0 \end{aligned}$$

so  $x_0 \in \text{Ker}(P)$ . □

In particular, if  $P$  is a projector, we  
 can select an orthonormal basis of  $\mathbb{R}^n$ ,  
 $q_1, \dots, q_n$ , and we will have

$$P = q_1 \otimes q_1 + \dots + q_r \otimes q_r$$

This defines a 1-1 correspondence between

subspaces of  $\mathbb{R}^n$  and projectors; and here  $\text{tr}(P)$  is equal to the dimension of the corresponding subspace.

## Projectors and more general QR decompositions

A remark about Gram-Schmidt.

If  $a_1, \dots, a_n$  are some linearly independent family of vectors in  $\mathbb{R}^m$  (so  $m \geq n$ ) we can apply the Gram-Schmidt process and obtain  $n$  orthonormal vectors

$$q_1, \dots, q_n$$

and coefficients  $r_{ij}$  ( $i, j = 1, \dots, n$ ) such that

$$a_1 = r_{11} q_1$$

$$a_2 = r_{12} q_1 + r_{22} q_2$$

$$\vdots$$

$$a_n = r_{1n} q_1 + \dots + r_{nn} q_n$$

Define

$$Q = (q_1 \mid \dots \mid q_n)$$



this is a  $m \times n$  matrix, and define

$$R = \begin{pmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & r_{22} & & \\ \vdots & & \ddots & \\ 0 & \dots & & r_{nn} \end{pmatrix}$$

Then

$$A = Q R$$

$m \times n$        $n \times n$        $n \times n$

Sometimes this is also called "the reduced QR decomposition" (see Trefethen and Bau)

When  $m > n$ ,  $Q$  cannot be orthogonal, since it is a rectangular matrix.

But, what do we get from

$$\underbrace{Q Q^T}_{m \times m} \quad \text{and} \quad \underbrace{Q^T Q}_{n \times n}$$

$\uparrow$        $\uparrow$

$$\begin{pmatrix} 1 & 0 & \dots & 0 & & \\ \vdots & \vdots & & \vdots & & \\ 0 & & & 0 & \dots & 0 \end{pmatrix} \quad \begin{pmatrix} 1 & & & & \\ & \ddots & & & \\ & & 1 & & \\ & & & 0 & \dots & 0 \end{pmatrix}$$

$n$        $m-n$

$I_{n \times n}$

Observation: let  $q_1, \dots, q_k$  be orthonormal vectors in  $\mathbb{R}^n$  ( $k \leq n$ ) and set  $P$  as the projector onto the subspace spanned by them. let

$$Q = (q_1 | \dots | q_k) \quad (n \times k)$$

Then  $P = QQ^T$ , why?

If  $x \in \mathbb{R}^n$ , then

$$Px = (q_1, x) q_1 + \dots + (q_k, x) q_k$$

(thanks to the orthonormality of the  $q_i$ 's)

but

$$(q_1, x) q_1 + \dots + (q_k, x) q_k$$

$$= \begin{pmatrix} q_1 & \dots & q_k \end{pmatrix} \begin{pmatrix} (q_1, x) \\ \vdots \\ (q_k, x) \end{pmatrix}$$

$$= (q_1 \dots q_k) \begin{pmatrix} q_1^T \\ \vdots \\ q_k^T \end{pmatrix} x = QQ^T x$$

## Least Square Problems

If  $n < m$ , the equation

$$Ax = b \quad \left( \begin{array}{l} A \text{ is } n \times n \\ b \text{ is in } \mathbb{R}^m \end{array} \right)$$

hardly ever has a solution, since it only covers by definition those  $b$ 's with  $b \in \text{Im}(A)$

and this is a small part of  $\mathbb{R}^m$ .

A problem that always has some solution is "find  $x$  so that  $Ax$  is as close as possible to  $b$ "

$$\begin{array}{l} \text{minimize} \quad \|Ax - b\| \\ x \in \mathbb{R}^n \end{array}$$

The nature of this minimization problem depends drastically on the choice of norm we use. The most popular choices are  $\|\cdot\|_1$ ,  $\|\cdot\|_\infty$ , and  $\|\cdot\|_2$ , the latter being the absolutely most studied and used one.

This is a linear algebra class, and we will only study  $\|\cdot\| = \|\cdot\|_2$ .

In this case the problem is written as

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad \|Ax - b\|_2^2$$

and this is a sum of squares:

$$\|Ax - b\|_2^2 = \sum_{i=1}^m \left( \sum_{j=1}^n a_{ij}x_j - b_i \right)^2$$

so we call it the least squares problem.

Let us use the following notation

$$f(x) = \frac{1}{2} \|Ax - b\|_2^2$$

next class we will study  $\nabla f(x)$ ,  $D^2 f(x)$

$$\nabla f(x) = A^t(Ax - b), \quad D^2 f(x) = A^t A$$

(what about 1-D!  $f(x) = \frac{1}{2}(ax - b)^2$ ,  $a, b \in \mathbb{R}$ )