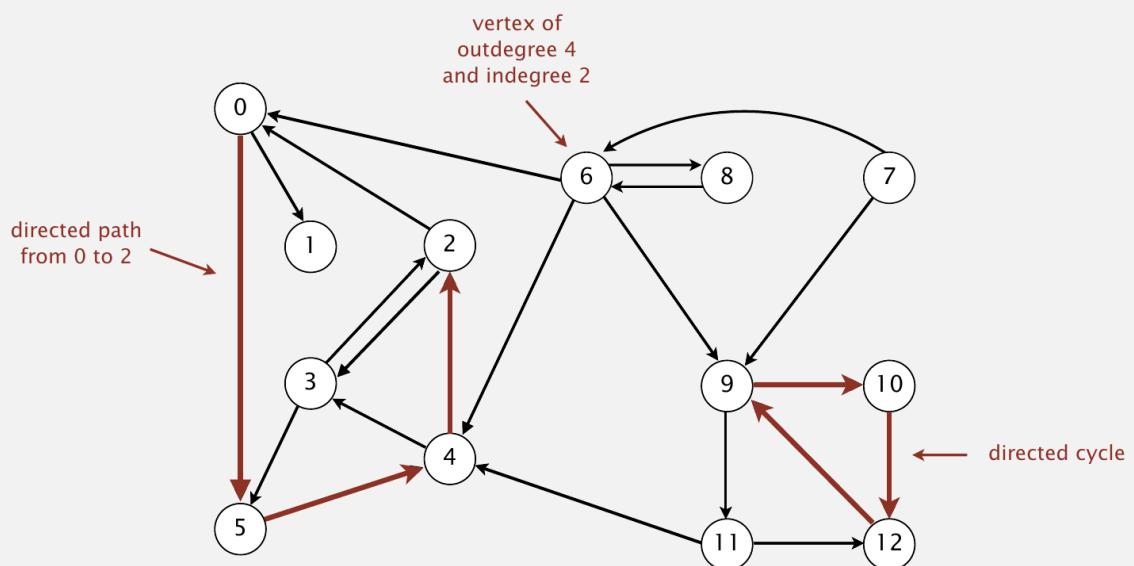


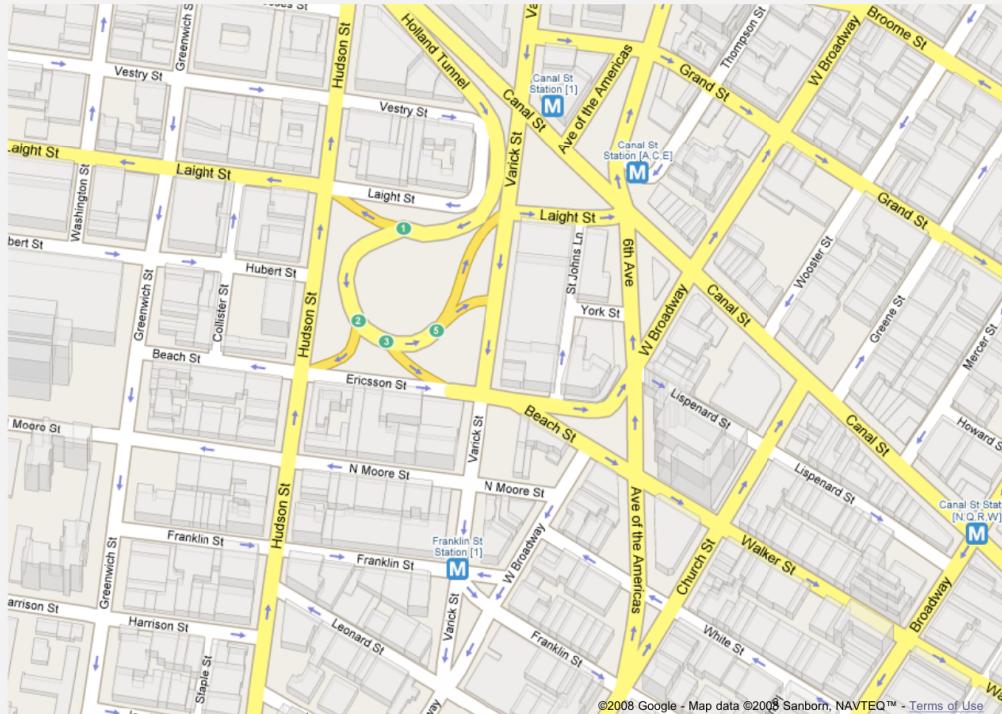
Directed graphs

Digraph. Set of vertices connected pairwise by **directed** edges.



Road network

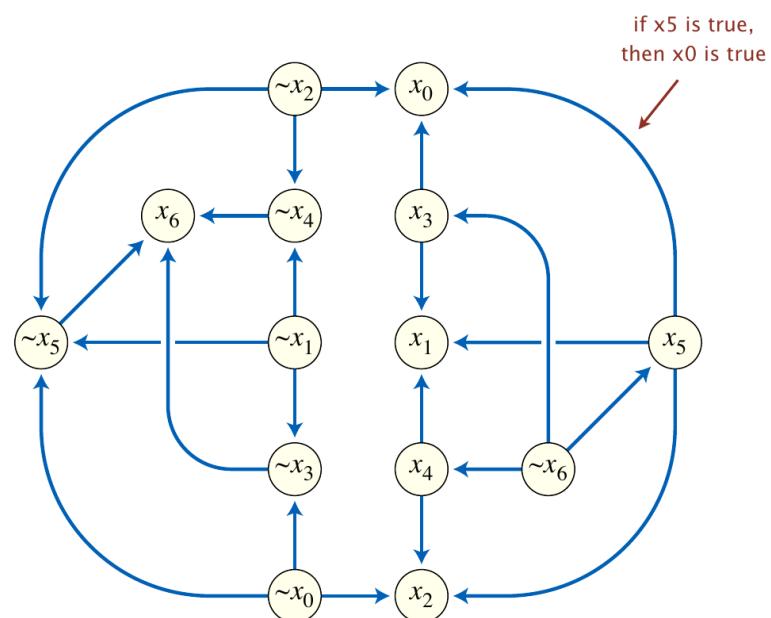
Vertex = intersection; edge = one-way street.



4

Implication graph

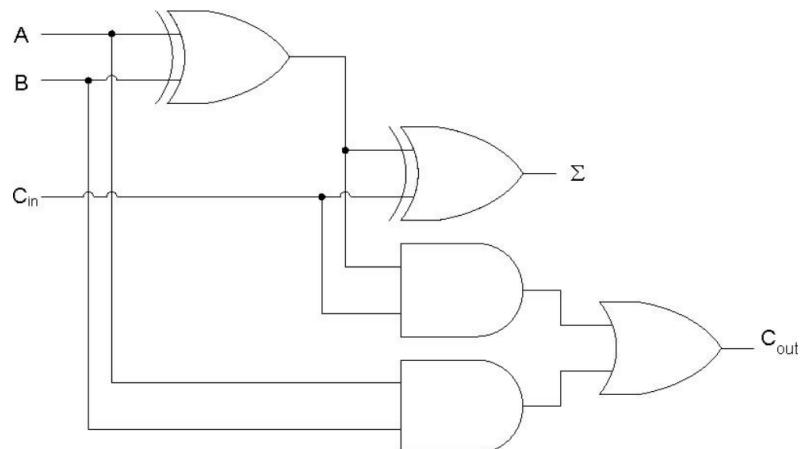
Vertex = variable; edge = logical implication.



7

Combinational circuit

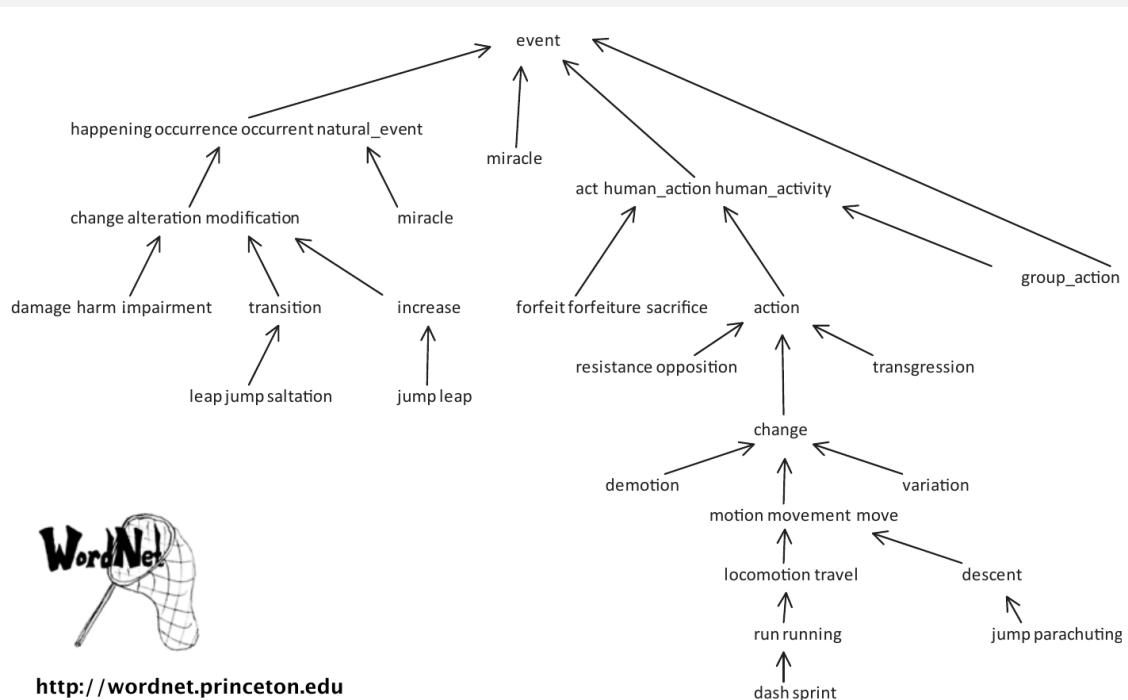
Vertex = logical gate; edge = wire.



8

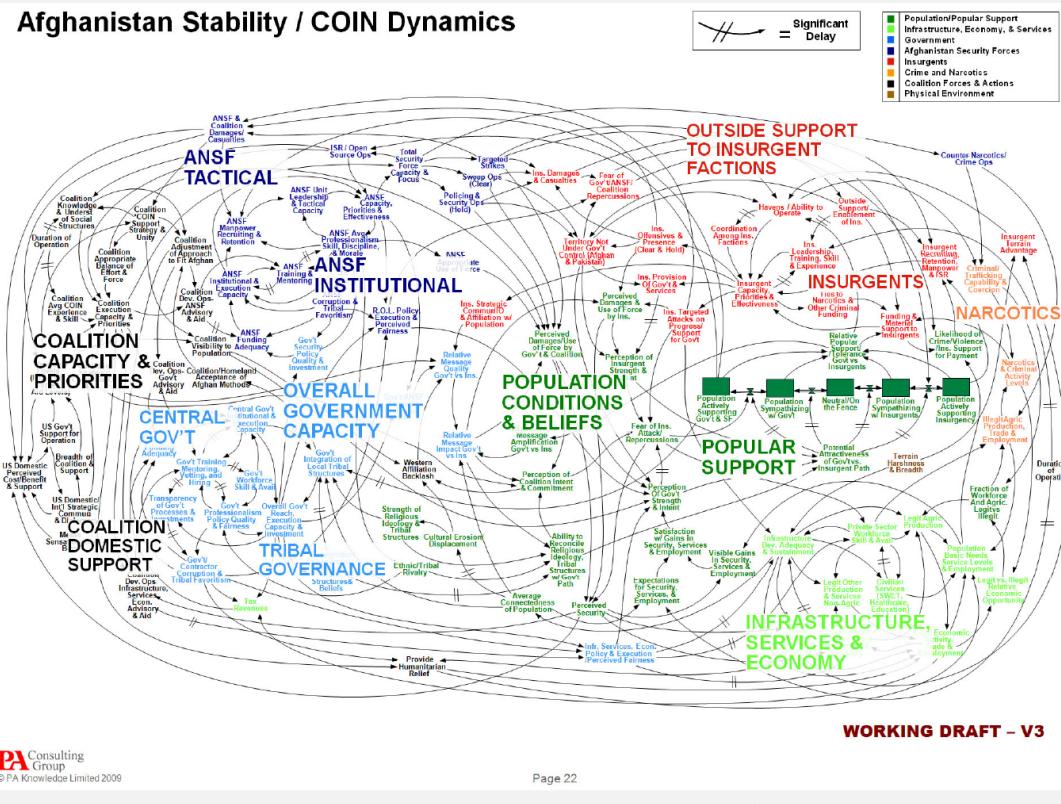
WordNet graph

Vertex = synset; edge = hypernym relationship.



9

The McChrystal Afghanistan PowerPoint slide



<http://www.guardian.co.uk/news/datablog/2010/apr/29/mccrystal-afghanistan-powerpoint-slide>

10

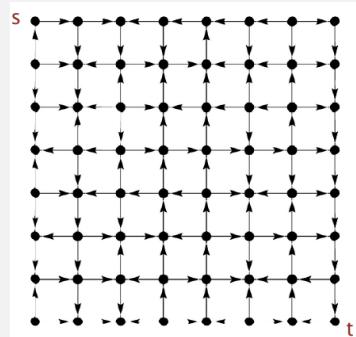
Digraph applications

| digraph | vertex | directed edge |
|-----------------------|---------------------|----------------------------|
| transportation | street intersection | one-way street |
| web | web page | hyperlink |
| food web | species | predator-prey relationship |
| WordNet | synset | hypernym |
| scheduling | task | precedence constraint |
| financial | bank | transaction |
| cell phone | person | placed call |
| infectious disease | person | infection |
| game | board position | legal move |
| citation | journal article | citation |
| object graph | object | pointer |
| inheritance hierarchy | class | inherits from |
| control flow | code block | jump |

11

Some digraph problems

Path. Is there a directed path from s to t ?



Shortest path. What is the shortest directed path from s to t ?

Topological sort. Can you draw a digraph so that all edges point upwards?

Strong connectivity. Is there a directed path between all pairs of vertices?

Transitive closure. For which vertices v and w is there a path from v to w ?

PageRank. What is the importance of a web page?

12

ROBERT SEDGEWICK | KEVIN WAYNE
<http://algs4.cs.princeton.edu>

4.2 DIRECTED GRAPHS

- ▶ *introduction*
- ▶ *digraph API*
- ▶ *digraph search*
- ▶ *topological sort*
- ▶ *strong components*

Digraph API

| | |
|---|--|
| <code>public class Digraph</code> | |
| <code> Digraph(int V)</code> | <i>create an empty digraph with V vertices</i> |
| <code> Digraph(In in)</code> | <i>create a digraph from input stream</i> |
| <code> void addEdge(int v, int w)</code> | <i>add a directed edge v→w</i> |
| <code> Iterable<Integer> adj(int v)</code> | <i>vertices pointing from v</i> |
| <code> int V()</code> | <i>number of vertices</i> |
| <code> int E()</code> | <i>number of edges</i> |
| <code> Digraph reverse()</code> | <i>reverse of this digraph</i> |
| <code> String toString()</code> | <i>string representation</i> |

```
In in = new In(args[0]);
Digraph G = new Digraph(in);           ← read digraph from
                                         input stream

for (int v = 0; v < G.V(); v++)
    for (int w : G.adj(v))
        StdOut.println(v + "->" + w);   ← print out each
                                         edge (once)
```

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Digraph API

tinyDG.txt

V → 13
E ← 22
4 2
2 3
3 2
6 0
0 1
2 0
11 12
12 9
9 10
9 11
7 9
10 12
11 4
4 3
3 5
6 8
8 6
:

```
% java Digraph tinyDG.txt
0->5
0->1
2->0
2->3
3->5
3->2
4->3
4->2
5->4
5->12
:
11->4
11->12
12->9
```

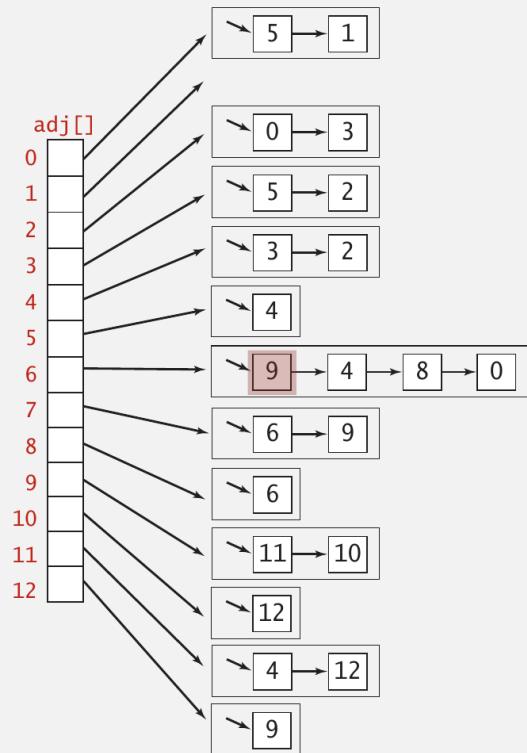
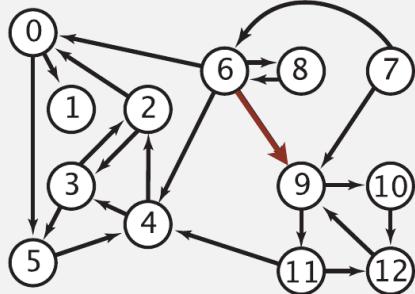
```
In in = new In(args[0]);
Digraph G = new Digraph(in);           ← read digraph from
                                         input stream

for (int v = 0; v < G.V(); v++)
    for (int w : G.adj(v))
        StdOut.println(v + "->" + w);   ← print out each
                                         edge (once)
```

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Adjacency-lists digraph representation

Maintain vertex-indexed array of lists.



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Adjacency-lists graph representation (review): Java implementation

```
public class Graph
{
    private final int V;
    private final Bag<Integer>[] adj; ← adjacency lists

    public Graph(int V)
    {
        this.V = V;
        adj = (Bag<Integer>[]) new Bag[V];
        for (int v = 0; v < V; v++)
            adj[v] = new Bag<Integer>(); ← create empty graph with V vertices

    }

    public void addEdge(int v, int w)
    {
        adj[v].add(w);
        adj[w].add(v); ← add edge v-w
    }

    public Iterable<Integer> adj(int v)
    { return adj[v]; } ← iterator for vertices
}
```

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Adjacency-lists digraph representation: Java implementation

```

public class Digraph
{
    private final int V;
    private final Bag<Integer>[] adj; ← adjacency lists

    public Digraph(int V)
    {
        this.V = V;
        adj = (Bag<Integer>[]) new Bag[V];
        for (int v = 0; v < V; v++)
            adj[v] = new Bag<Integer>();
    }

    public void addEdge(int v, int w) ← add edge v→w
    {
        adj[v].add(w);
    }

    public Iterable<Integer> adj(int v) ← iterator for vertices
    {   return adj[v]; } ← pointing from v
}

```

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Digraph representations

In practice. Use adjacency-lists representation.

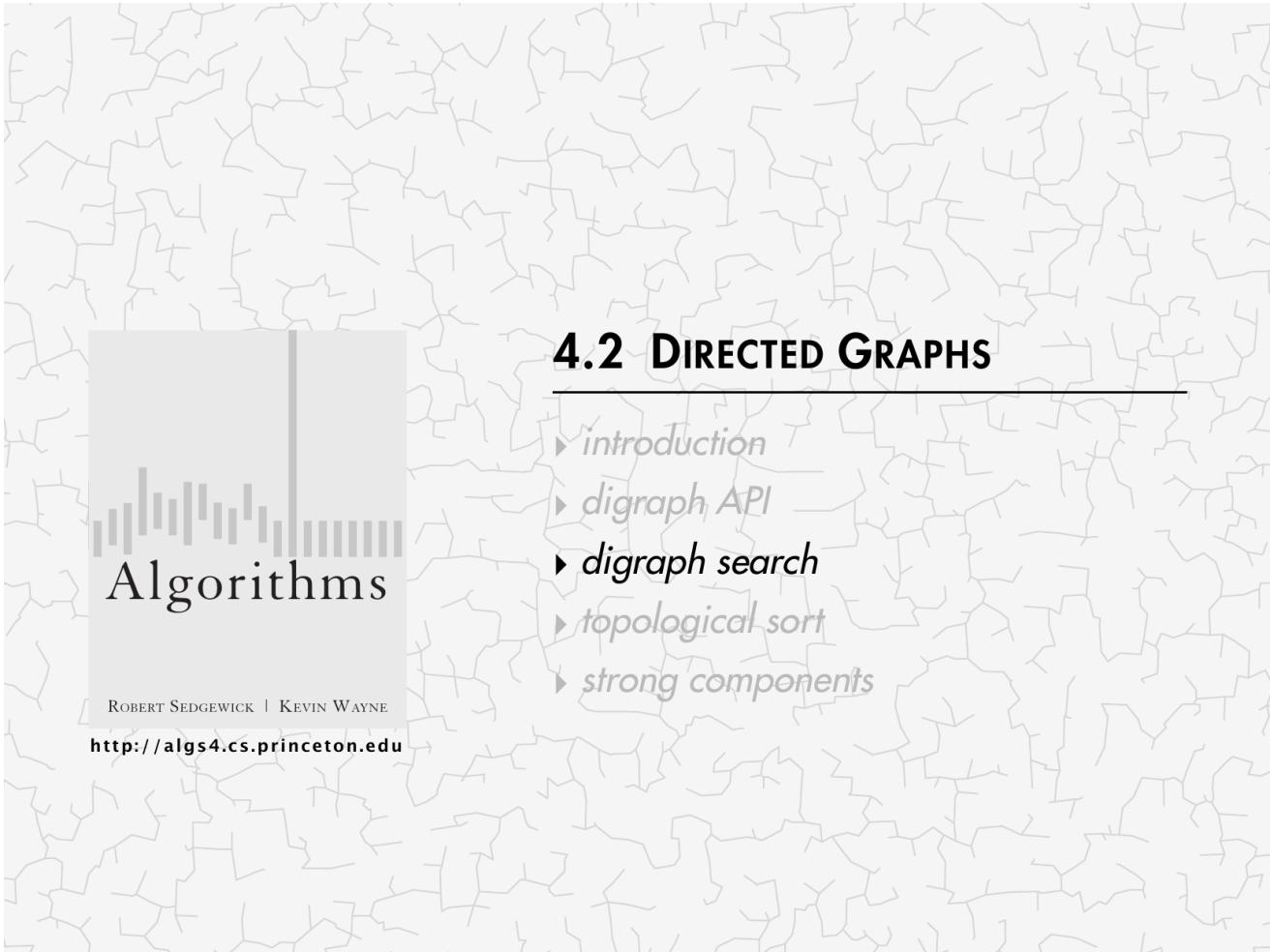
- Algorithms based on iterating over vertices pointing from v .
- Real-world digraphs tend to be sparse.

huge number of vertices,
small average vertex degree

| representation | space | insert edge from v to w | edge from v to w ? | iterate over vertices pointing from v ? |
|------------------|---------|--------------------------------|---------------------------|--|
| list of edges | E | 1 | E | E |
| adjacency matrix | V^2 | 1^\dagger | 1 | V |
| adjacency lists | $E + V$ | 1 | $\text{outdegree}(v)$ | $\text{outdegree}(v)$ |

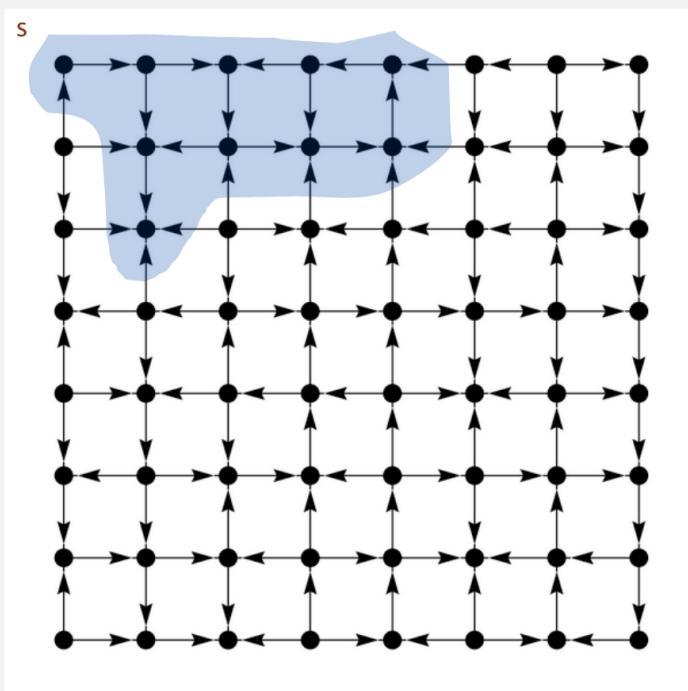
\dagger disallows parallel edges

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Reachability

Problem. Find all vertices reachable from s along a directed path.



Depth-first search in digraphs

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- DFS is a **digraph** algorithm.

DFS (to visit a vertex v)

Mark v as visited.

Recursively visit all unmarked
vertices w pointing from v .

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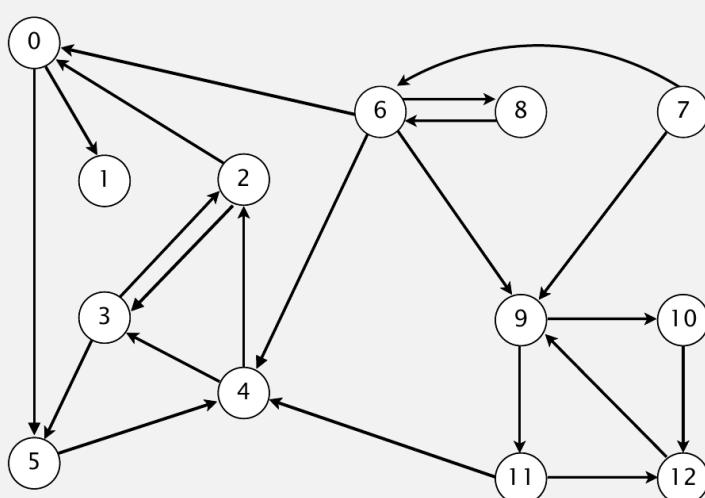
Depth-first search demo

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v .



4→2
2→3
3→2
6→0
0→1
2→0
11→12
12→9
9→10
9→11
8→9
10→12
11→4
4→3
3→5
6→8
8→6
5→4
0→5
6→4
6→9
7→6



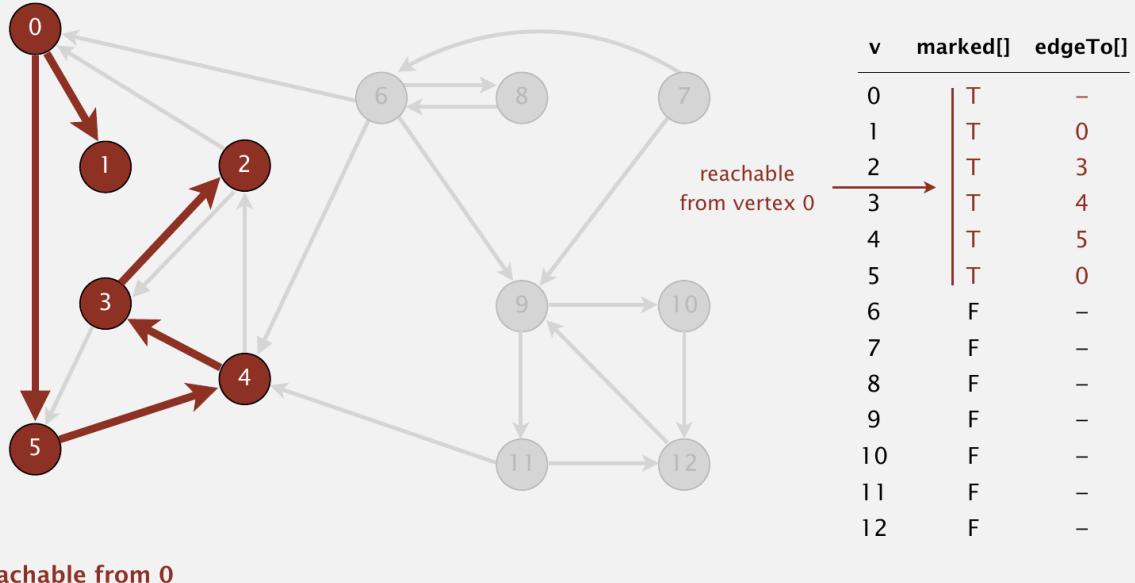
a **directed** graph

25

Depth-first search demo

To visit a vertex v :

- Mark vertex v as visited.
- Recursively visit all unmarked vertices pointing from v .



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Depth-first search (in undirected graphs)

Recall code for **undirected** graphs.

```
public class DepthFirstSearch
{
    private boolean[] marked;

    public DepthFirstSearch(Graph G, int s)
    {
        marked = new boolean[G.V()];
        dfs(G, s);
    }

    private void dfs(Graph G, int v)
    {
        marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w]) dfs(G, w);
    }

    public boolean visited(int v)
    { return marked[v]; }
}
```

Annotations from right to left:

- true if path to s
- constructor marks vertices connected to s
- recursive DFS does the work
- client can ask whether any vertex is connected to s

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Depth-first search (in directed graphs)

Code for **directed** graphs identical to undirected one.

[substitute Digraph for Graph]

```
public class DirectedDFS
{
    private boolean[] marked; ← true if path from s

    public DirectedDFS(Digraph G, int s)
    {
        marked = new boolean[G.V()];
        dfs(G, s); ← constructor marks
    } ← vertices reachable from s

    private void dfs(Digraph G, int v) ← recursive DFS does the work
    {
        marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w]) dfs(G, w);
    }

    public boolean visited(int v) ← client can ask whether any
    { return marked[v]; } ← vertex is reachable from s
}
```

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Reachability application: program control-flow analysis

Every program is a digraph.

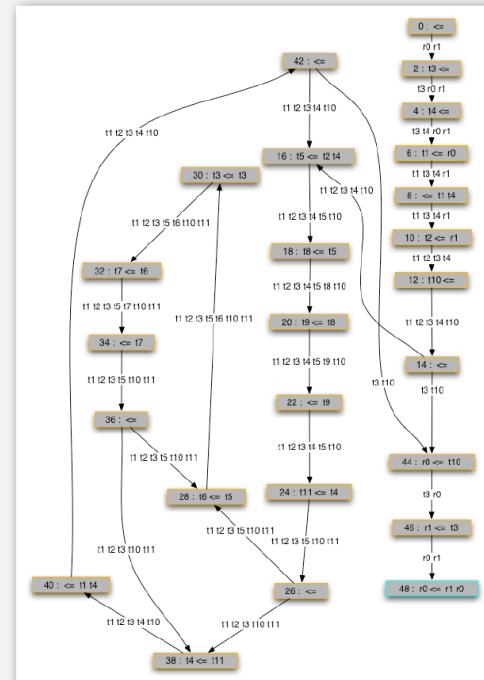
- Vertex = basic block of instructions (straight-line program).
- Edge = jump.

Dead-code elimination.

Find (and remove) unreachable code.

Infinite-loop detection.

Determine whether exit is unreachable.



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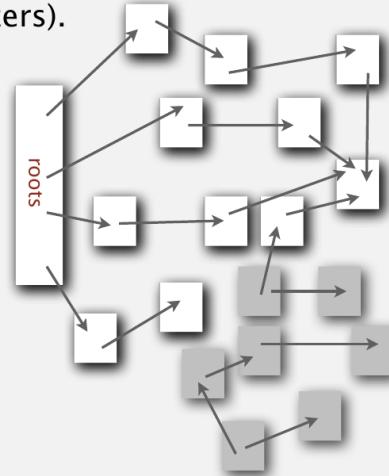
Reachability application: mark-sweep garbage collector

Every data structure is a digraph.

- Vertex = object.
- Edge = reference.

Roots. Objects known to be directly accessible by program (e.g., stack).

Reachable objects. Objects indirectly accessible by program (starting at a root and following a chain of pointers).



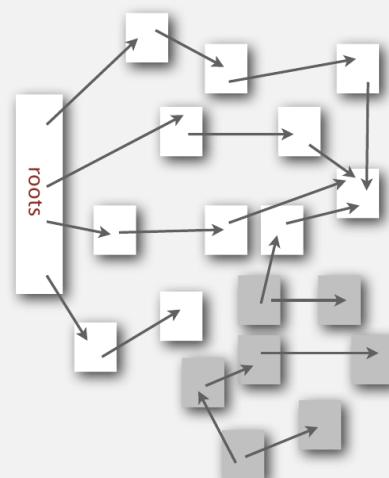
30

Reachability application: mark-sweep garbage collector

Mark-sweep algorithm. [McCarthy, 1960]

- Mark: mark all reachable objects.
- Sweep: if object is unmarked, it is garbage (so add to free list).

Memory cost. Uses 1 extra mark bit per object (plus DFS stack).



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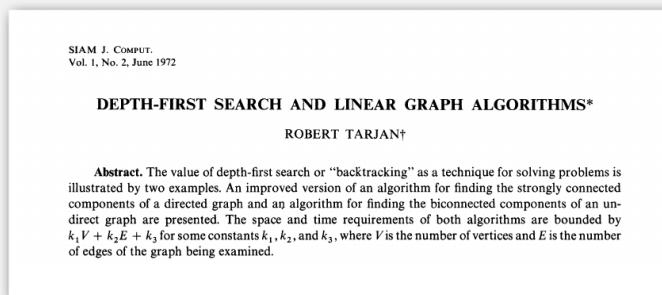
Depth-first search in digraphs summary

DFS enables direct solution of simple digraph problems.

- ✓ • Reachability.
- Path finding.
- Topological sort.
- Directed cycle detection.

Basis for solving difficult digraph problems.

- 2-satisfiability.
- Directed Euler path.
- Strongly-connected components.



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Breadth-first search in digraphs

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- BFS is a **digraph** algorithm.

BFS (from source vertex s)

Put s onto a FIFO queue, and mark s as visited.

Repeat until the queue is empty:

- **remove the least recently added vertex v**
- **for each unmarked vertex pointing from v:**
- add to queue and mark as visited.**

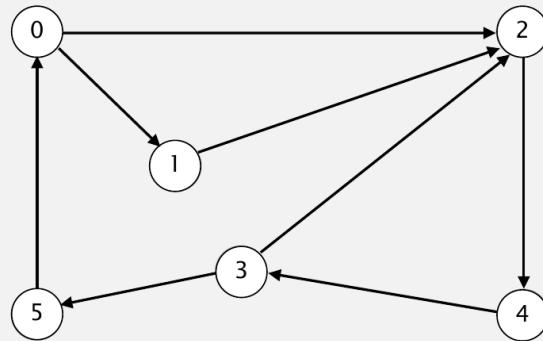
Proposition. BFS computes shortest paths (fewest number of edges) from s to all other vertices in a digraph in time proportional to $E + V$.

33

Directed breadth-first search demo

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices pointing from v and mark them.



tinyDG2.txt

V → 6
E → 8
5 0
2 4
3 2
1 2
0 1
4 3
3 5
0 2

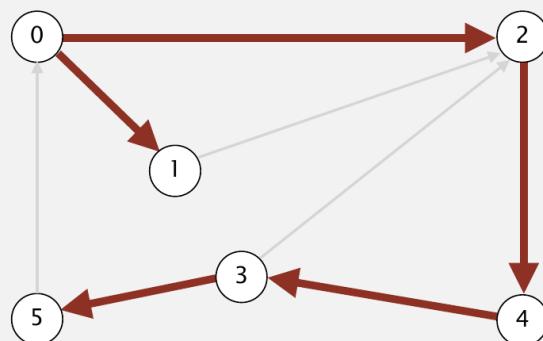
graph G

34

Directed breadth-first search demo

Repeat until queue is empty:

- Remove vertex v from queue.
- Add to queue all unmarked vertices pointing from v and mark them.



| v | edgeTo[] | distTo[] |
|---|----------|----------|
| 0 | - | 0 |
| 1 | 0 | 1 |
| 2 | 0 | 1 |
| 3 | 4 | 3 |
| 4 | 2 | 2 |
| 5 | 3 | 4 |

done

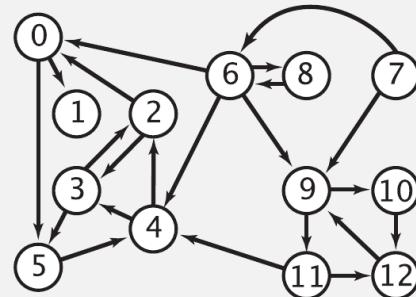
35

Multiple-source shortest paths

Multiple-source shortest paths. Given a digraph and a set of source vertices, find shortest path from any vertex in the set to each other vertex.

Ex. $S = \{1, 7, 10\}$.

- Shortest path to 4 is $7 \rightarrow 6 \rightarrow 4$.
- Shortest path to 5 is $7 \rightarrow 6 \rightarrow 0 \rightarrow 5$.
- Shortest path to 12 is $10 \rightarrow 12$.
- ...



Q. How to implement multi-source shortest paths algorithm?

A. Use BFS, but initialize by enqueueing all source vertices.

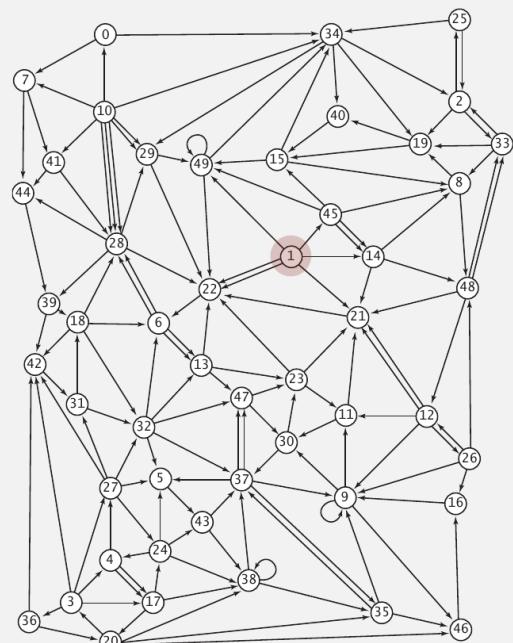
36

Breadth-first search in digraphs application: web crawler

Goal. Crawl web, starting from some root web page, say www.princeton.edu.

Solution. [BFS with implicit digraph]

- Choose root web page as source s .
- Maintain a Queue of websites to explore.
- Maintain a SET of discovered websites.
- Dequeue the next website and enqueue websites to which it links
(provided you haven't done so before).



Q. Why not use DFS?

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Bare-bones web crawler: Java implementation

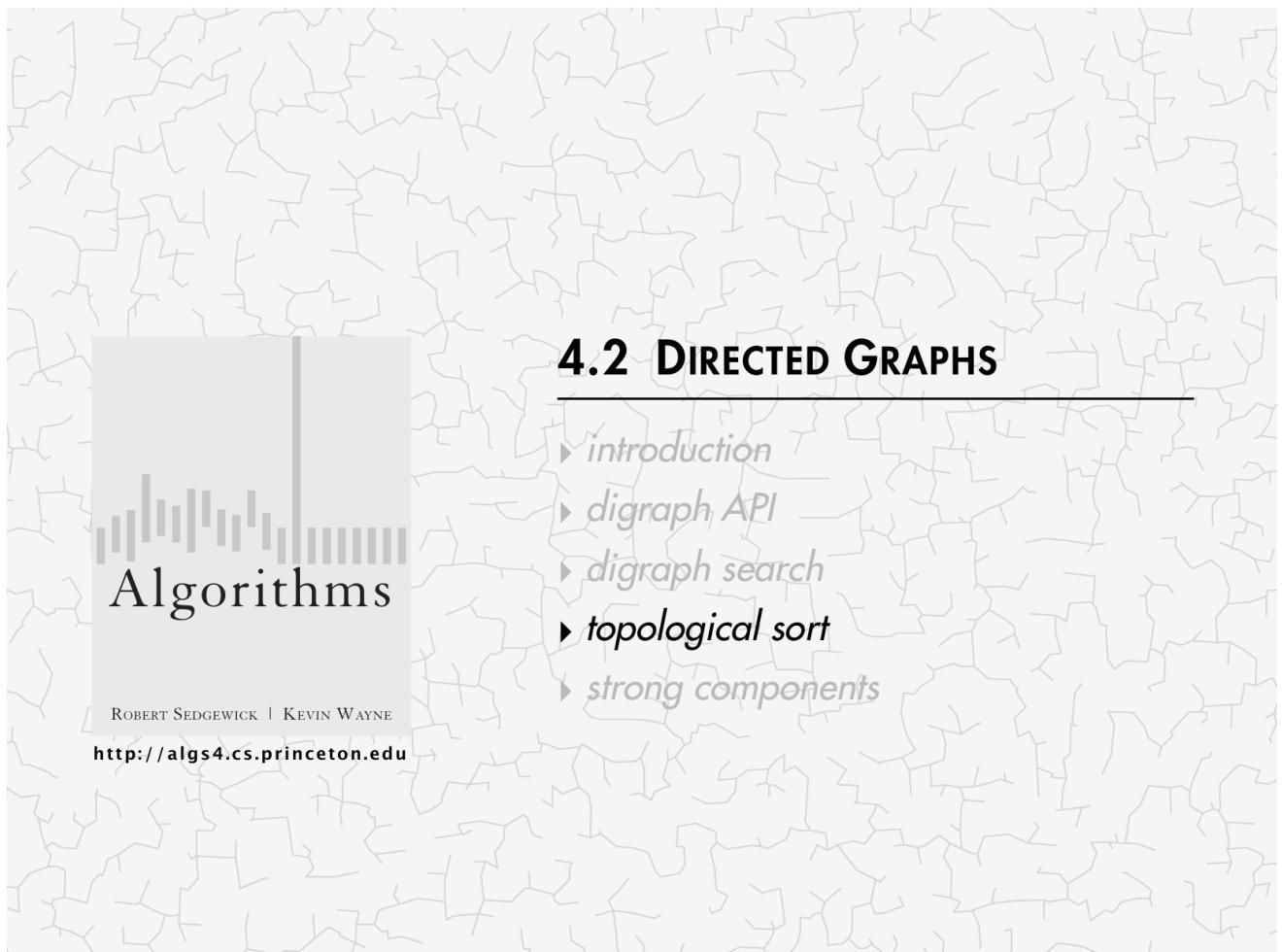
```
Queue<String> queue = new Queue<String>(); ← queue of websites to crawl
SET<String> marked = new SET<String>(); ← set of marked websites

String root = "http://www.princeton.edu";
queue.enqueue(root);
marked.add(root); ← start crawling from root website

while (!queue.isEmpty())
{
    String v = queue.dequeue();
    StdOut.println(v);
    In in = new In(v);
    String input = in.readAll();

    String regexp = "http://(\w+\.\w+)*(\w+)";
    Pattern pattern = Pattern.compile(regexp);
    Matcher matcher = pattern.matcher(input); ← use regular expression to find all URLs
    while (matcher.find())
    {
        String w = matcher.group();
        if (!marked.contains(w)) ← if unmarked, mark it and put
        {
            marked.add(w);
            queue.enqueue(w); ← on the queue
        }
    }
}
```

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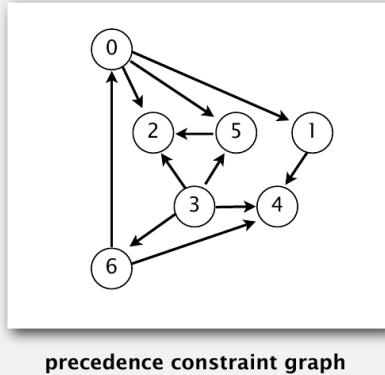
Precedence scheduling

Goal. Given a set of tasks to be completed with precedence constraints, in which order should we schedule the tasks?

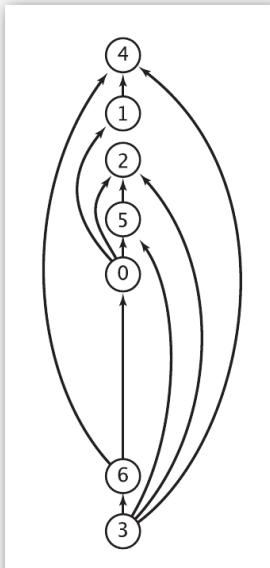
Digraph model. vertex = task; edge = precedence constraint.

- 0. Algorithms
- 1. Complexity Theory
- 2. Artificial Intelligence
- 3. Intro to CS
- 4. Cryptography
- 5. Scientific Computing
- 6. Advanced Programming

tasks



precedence constraint graph



feasible schedule

41

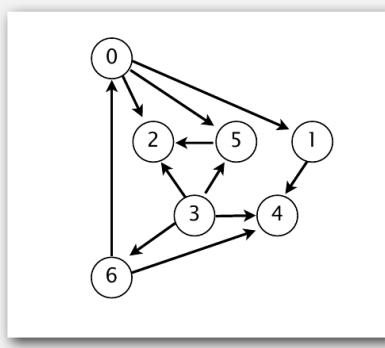
Topological sort

DAG. Directed acyclic graph.

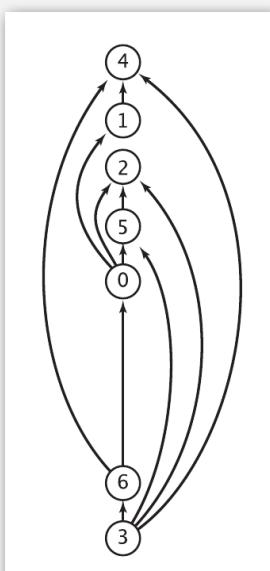
Topological sort. Redraw DAG so all edges point upwards.

- | | |
|-----|-----|
| 0→5 | 0→2 |
| 0→1 | 3→6 |
| 3→5 | 3→4 |
| 5→2 | 6→4 |
| 6→0 | 3→2 |
| 1→4 | |

directed edges



DAG



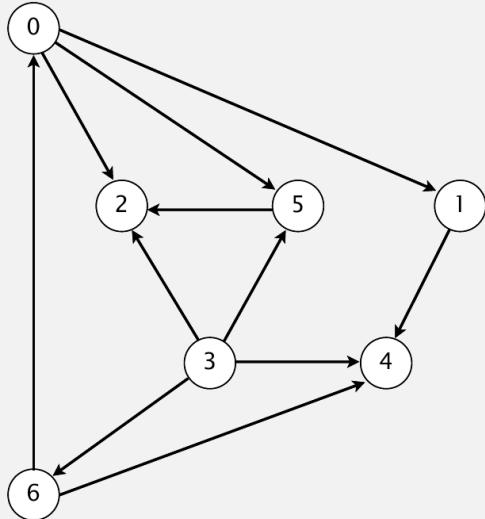
topological order

42

Solution. DFS. What else?

Topological sort demo

- Run depth-first search.
- Return vertices in reverse postorder.



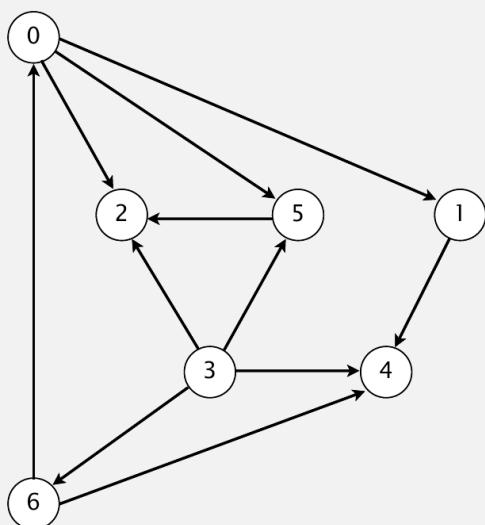
$0 \rightarrow 5$
 $0 \rightarrow 2$
 $0 \rightarrow 1$
 $3 \rightarrow 6$
 $3 \rightarrow 5$
 $3 \rightarrow 4$
 $5 \rightarrow 2$
 $6 \rightarrow 4$
 $6 \rightarrow 0$
 $3 \rightarrow 2$
 $1 \rightarrow 4$

a directed acyclic graph

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Topological sort demo

- Run depth-first search.
- Return vertices in reverse postorder.



postorder
4 1 2 5 0 6 3

topological order
3 6 0 5 2 1 4

done

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Depth-first search order

```

public class DepthFirstOrder
{
    private boolean[] marked;
    private Stack<Integer> reversePost;

    public DepthFirstOrder(Digraph G)
    {
        reversePost = new Stack<Integer>();
        marked = new boolean[G.V()];
        for (int v = 0; v < G.V(); v++)
            if (!marked[v]) dfs(G, v);
    }

    private void dfs(Digraph G, int v)
    {
        marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w]) dfs(G, w);
        reversePost.push(v);
    }

    public Iterable<Integer> reversePost() ← returns all vertices in
    {   return reversePost; } "reverse DFS postorder"
}

```

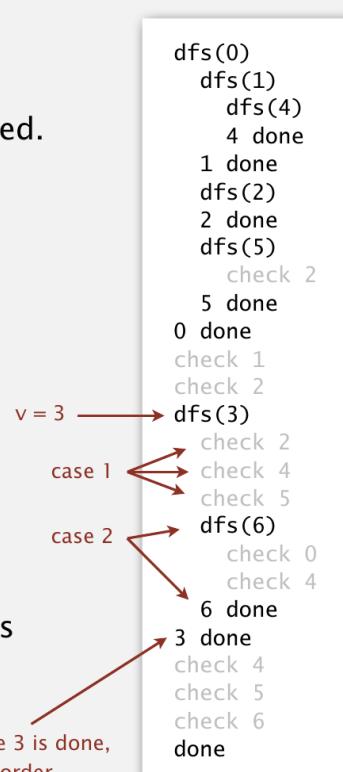
45

Topological sort in a DAG: correctness proof

Proposition. Reverse DFS postorder of a DAG is a topological order.

Pf. Consider any edge $v \rightarrow w$. When $\text{dfs}(v)$ is called:

- Case 1: $\text{dfs}(w)$ has already been called and returned.
Thus, w was done before v .
- Case 2: $\text{dfs}(w)$ has not yet been called.
 $\text{dfs}(w)$ will get called directly or indirectly by $\text{dfs}(v)$ and will finish before $\text{dfs}(v)$.
Thus, w will be done before v .
- Case 3: $\text{dfs}(w)$ has already been called, but has not yet returned.
Can't happen in a DAG: function call stack contains path from w to v , so $v \rightarrow w$ would complete a cycle.



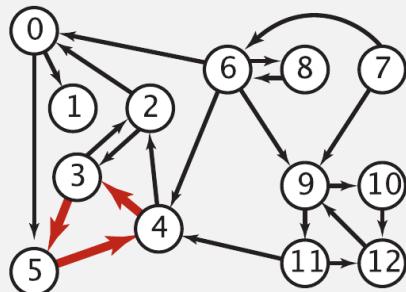
46

Directed cycle detection

Proposition. A digraph has a topological order iff no directed cycle.

Pf.

- If directed cycle, topological order impossible.
- If no directed cycle, DFS-based algorithm finds a topological order.



a digraph with a directed cycle

Goal. Given a digraph, find a directed cycle.

Solution. DFS. What else? See textbook.

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Directed cycle detection application: precedence scheduling

Scheduling. Given a set of tasks to be completed with precedence constraints, in what order should we schedule the tasks?

| PAGE 3 | | | |
|------------------|----------|--|----------|
| DEPARTMENT | COURSE | DESCRIPTION | PREREQS |
| COMPUTER SCIENCE | CPSC 432 | INTERMEDIATE COMPILER DESIGN, WITH A FOCUS ON DEPENDENCY RESOLUTION. | CPSC 432 |

<http://xkcd.com/754>

Remark. A directed cycle implies scheduling problem is infeasible.

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Directed cycle detection application: cyclic inheritance

The Java compiler does cycle detection.

```
public class A extends B
{
    ...
}
```

```
public class B extends C
{
    ...
}
```

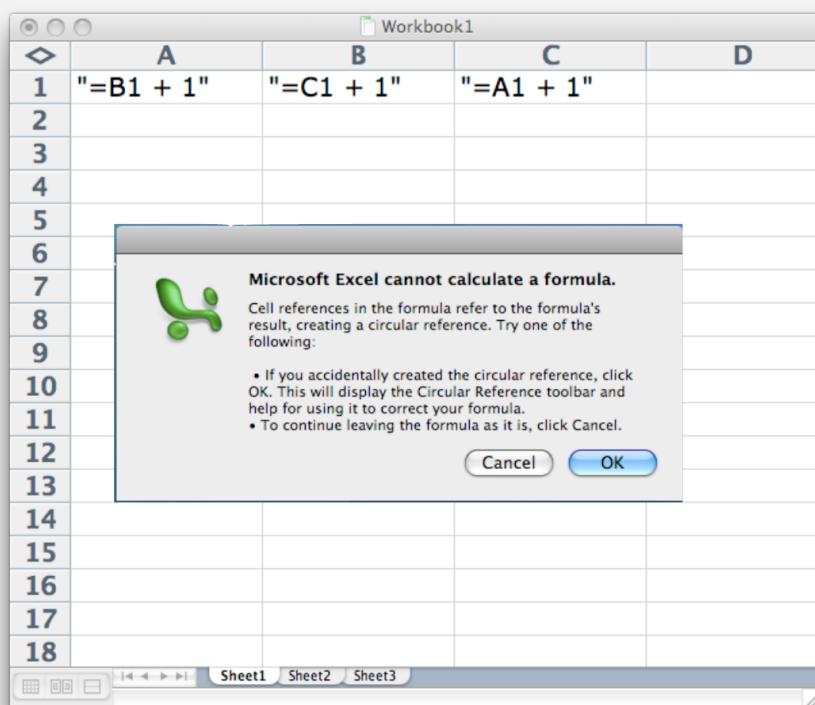
```
public class C extends A
{
    ...
}
```

```
% javac A.java
A.java:1: cyclic inheritance
involving A
public class A extends B { }
^
1 error
```

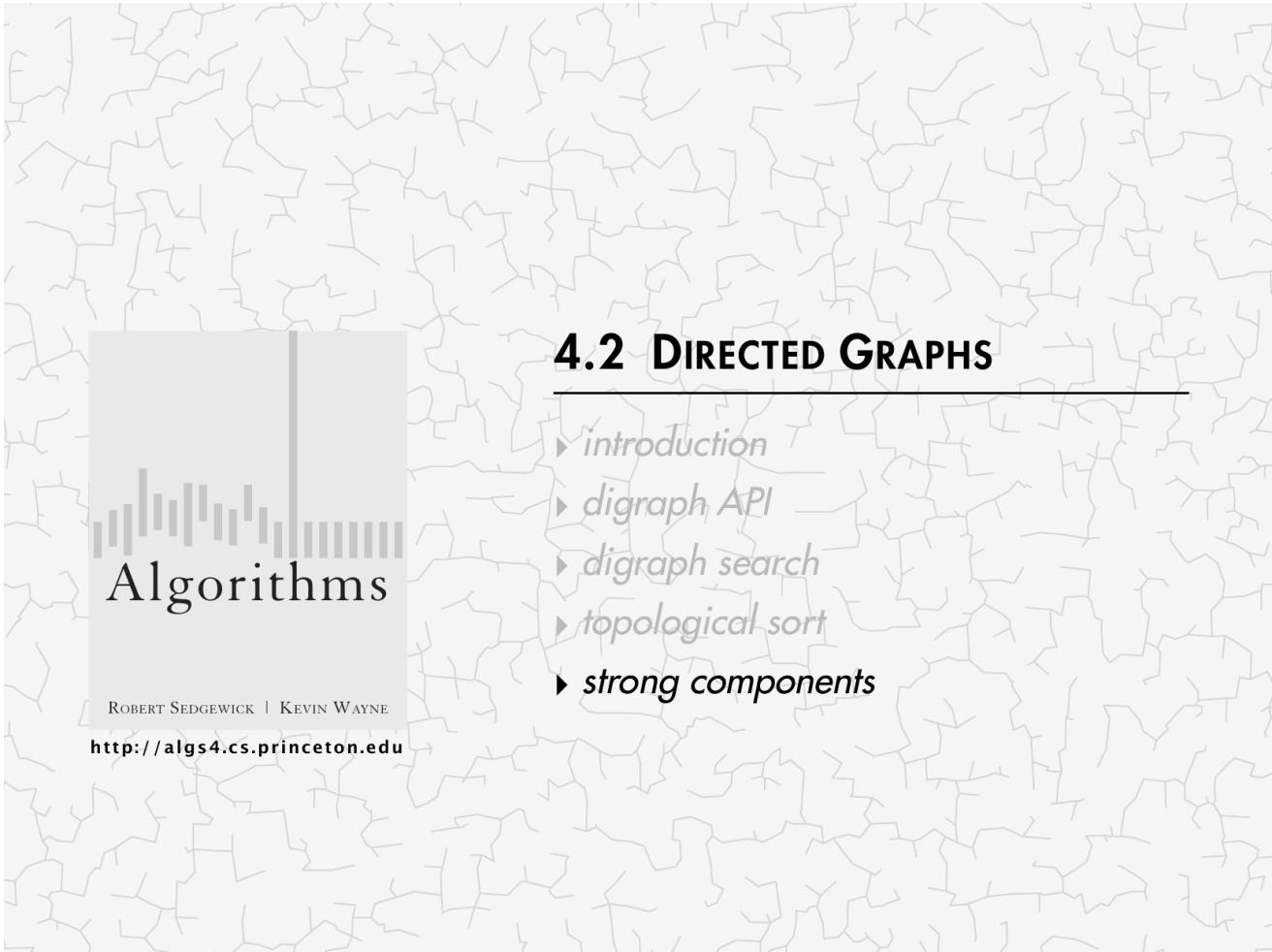
49

Directed cycle detection application: spreadsheet recalculation

Microsoft Excel does cycle detection (and has a circular reference toolbar!)



50



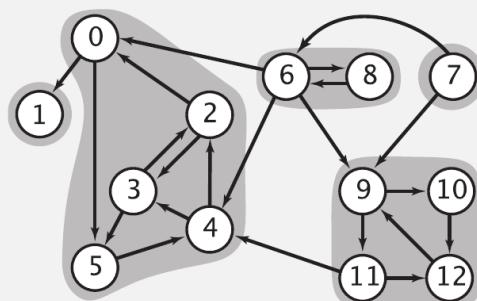
Strongly-connected components

Def. Vertices v and w are **strongly connected** if there is both a directed path from v to w **and** a directed path from w to v .

Key property. Strong connectivity is an **equivalence relation**:

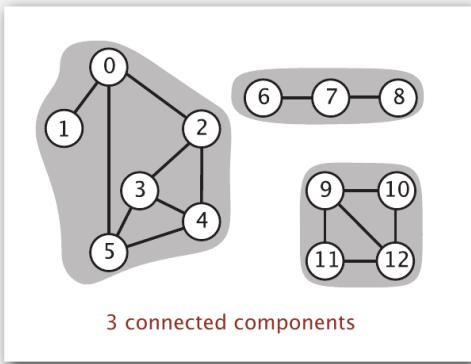
- v is strongly connected to v .
- If v is strongly connected to w , then w is strongly connected to v .
- If v is strongly connected to w and w to x , then v is strongly connected to x .

Def. A **strong component** is a maximal subset of strongly-connected vertices.

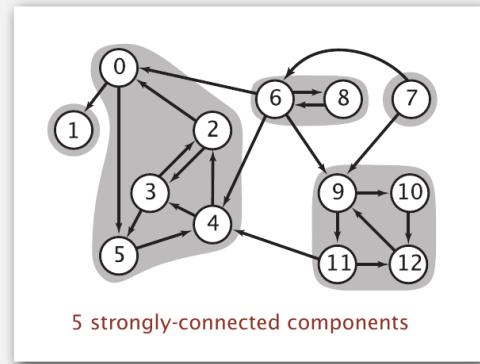


Connected components vs. strongly-connected components

v and w are **connected** if there is a path between v and w



v and w are **strongly connected** if there is both a directed path from v to w and a directed path from w to v



connected component id (easy to compute with DFS)

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
|------|---|---|---|---|---|---|---|---|---|----|----|----|
| cc[] | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 2 | 2 | 2 |

```
public int connected(int v, int w)
{ return cc[v] == cc[w]; }
```

constant-time client connectivity query

strongly-connected component id (how to compute?)

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
|-------|---|---|---|---|---|---|---|---|---|----|----|----|
| scc[] | 1 | 0 | 1 | 1 | 1 | 1 | 3 | 4 | 3 | 2 | 2 | 2 |

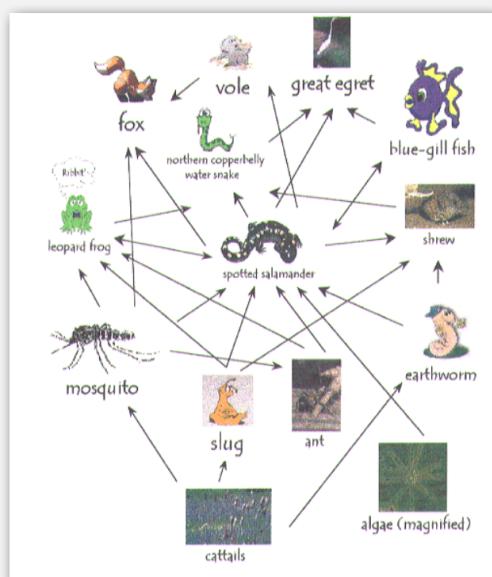
```
public int stronglyConnected(int v, int w)
{ return scc[v] == scc[w]; }
```

constant-time client strong-connectivity query

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Strong component application: ecological food webs

Food web graph. Vertex = species; edge = from producer to consumer.



<http://www.twinkiegroves.district96.k12.il.us/Wetlands/Salamander/SalGraphics/salfoodweb.gif>

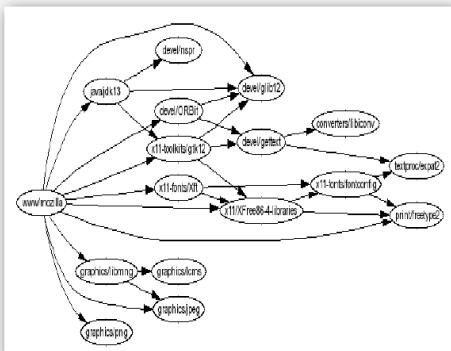
Strong component. Subset of species with common energy flow.

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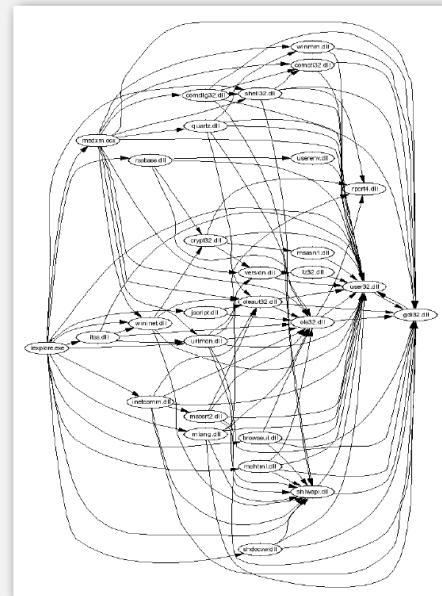
Strong component application: software modules

Software module dependency graph.

- Vertex = software module.
 - Edge: from module to dependency.



Firefox



Internet Explorer

Strong component. Subset of mutually interacting modules.

Approach 1. Package strong components together.

Approach 2. Use to improve design!

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Strong components algorithms: brief history

1960s: Core OR problem.

- Widely studied; some practical algorithms.
 - Complexity not understood.

1972: linear-time DFS algorithm (Tarjan).

- Classic algorithm.
 - Level of difficulty: Algs4++.
 - Demonstrated broad applicability and importance of DFS.

1980s: easy two-pass linear-time algorithm (Kosaraju-Sharir).

- Forgot notes for lecture; developed algorithm in order to teach it!
 - Later found in Russian scientific literature (1972).

1990s: more easy linear-time algorithms.

- Gabow: fixed old OR algorithm.
 - Cheriyan-Mehlhorn: needed one-pass algorithm for LEDA.

Kosaraju-Sharir algorithm: intuition

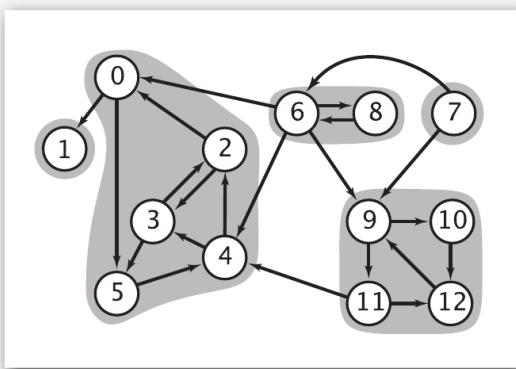
Reverse graph. Strong components in G are same as in G^R .

Kernel DAG. Contract each strong component into a single vertex.

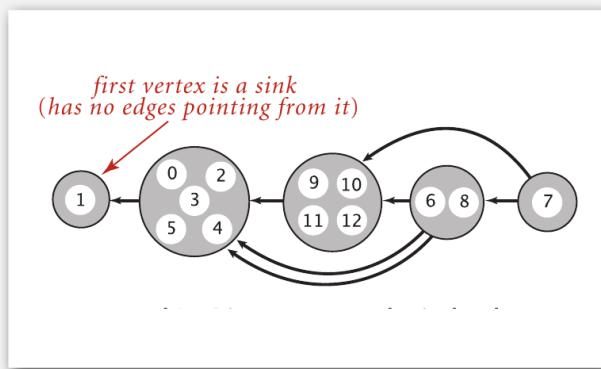
Idea.

- Compute topological order (reverse postorder) in kernel DAG.
- Run DFS, considering vertices in reverse topological order.

how to compute?



digraph G and its strong components



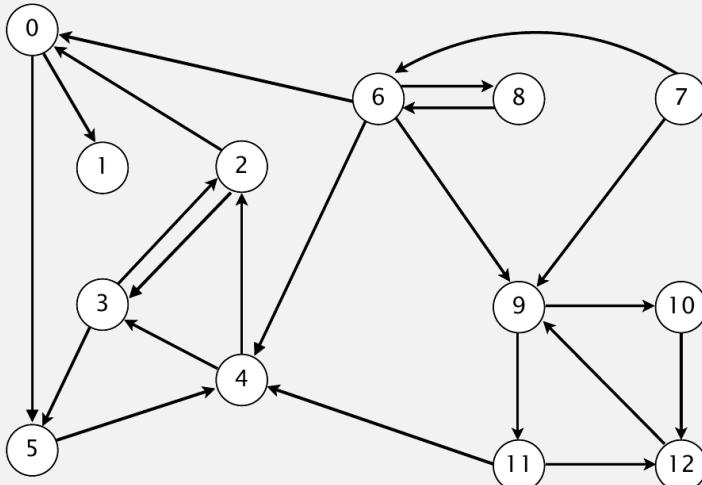
kernel DAG of G (in reverse topological order)

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Kosaraju-Sharir algorithm demo

Phase 1. Compute reverse postorder in G^R .

Phase 2. Run DFS in G , visiting unmarked vertices in reverse postorder of G^R .



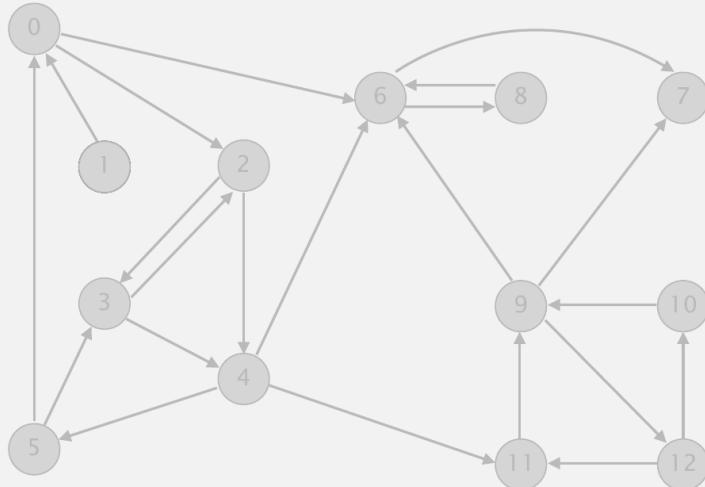
digraph G

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Kosaraju-Sharir algorithm demo

Phase 1. Compute reverse postorder in G^R .

1 0 2 4 5 3 11 9 12 10 6 7 8



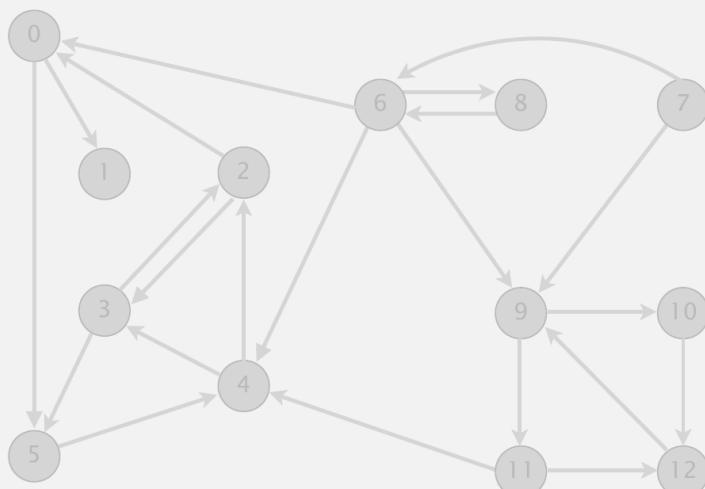
reverse digraph G^R

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Kosaraju-Sharir algorithm demo

Phase 2. Run DFS in G , visiting unmarked vertices in reverse postorder of G^R .

1 0 2 4 5 3 11 9 12 10 6 7 8



| v | scc[] |
|----|-------|
| 0 | 1 |
| 1 | 0 |
| 2 | 1 |
| 3 | 1 |
| 4 | 1 |
| 5 | 1 |
| 6 | 3 |
| 7 | 4 |
| 8 | 3 |
| 9 | 2 |
| 10 | 2 |
| 11 | 2 |
| 12 | 2 |

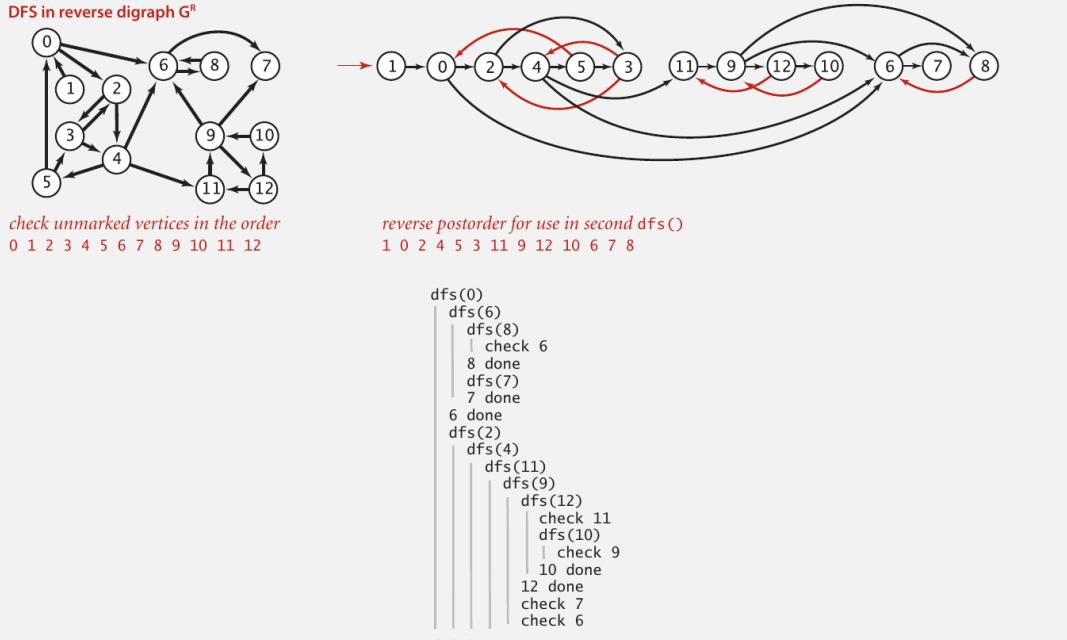
done

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Kosaraju-Sharir algorithm

Simple (but mysterious) algorithm for computing strong components.

- Phase 1: run DFS on G^R to compute reverse postorder.
- Phase 2: run DFS on G , considering vertices in order given by first DFS.

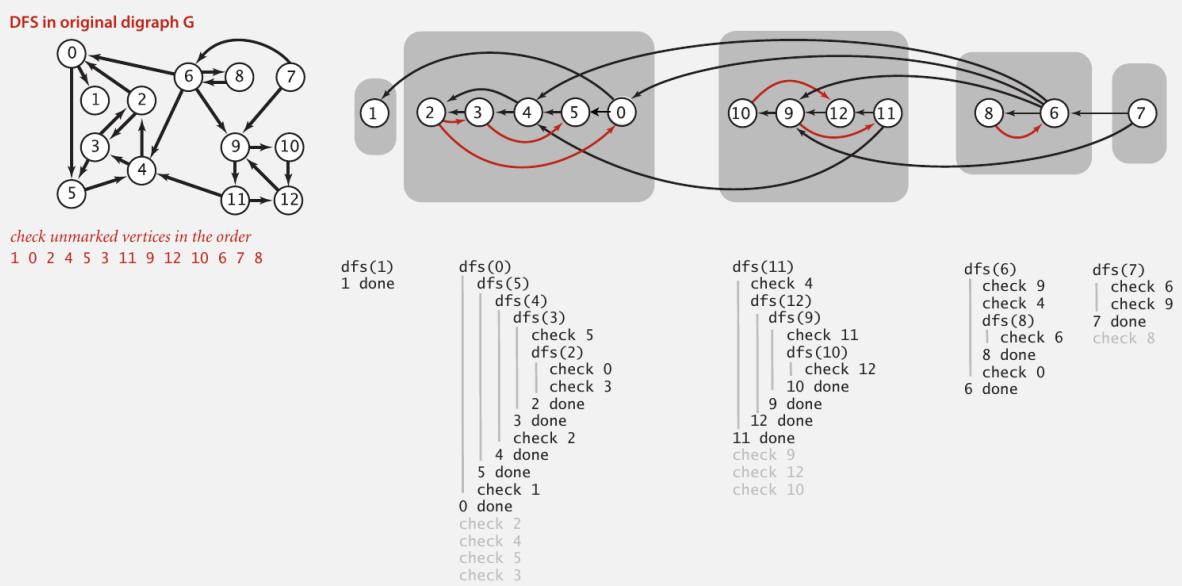


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Kosaraju-Sharir algorithm

Simple (but mysterious) algorithm for computing strong components.

- Phase 1: run DFS on G^R to compute reverse postorder.
- Phase 2: run DFS on G , considering vertices in order given by first DFS.



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Kosaraju-Sharir algorithm

Proposition. Kosaraju-Sharir algorithm computes the strong components of a digraph in time proportional to $E + V$.

Pf.

- Running time: bottleneck is running DFS twice (and computing G^R).
- Correctness: tricky, see textbook (2nd printing).
- Implementation: easy!

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Connected components in an undirected graph (with DFS)

```
public class CC
{
    private boolean marked[];
    private int[] id;
    private int count;

    public CC(Graph G)
    {
        marked = new boolean[G.V()];
        id = new int[G.V()];

        for (int v = 0; v < G.V(); v++)
        {
            if (!marked[v])
            {
                dfs(G, v);
                count++;
            }
        }
    }

    private void dfs(Graph G, int v)
    {
        marked[v] = true;
        id[v] = count;
        for (int w : G.adj(v))
            if (!marked[w])
                dfs(G, w);
    }

    public boolean connected(int v, int w)
    { return id[v] == id[w]; }
}
```

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Strong components in a digraph (with two DFSs)

```
public class KosarajuSharirSCC
{
    private boolean marked[];
    private int[] id;
    private int count;

    public KosarajuSharirSCC(Digraph G)
    {
        marked = new boolean[G.V()];
        id = new int[G.V()];
        DepthFirstOrder dfs = new DepthFirstOrder(G.reverse());
        for (int v : dfs.reversePost())
        {
            if (!marked[v])
            {
                dfs(G, v);
                count++;
            }
        }
    }

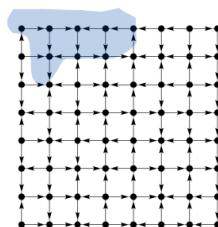
    private void dfs(Digraph G, int v)
    {
        marked[v] = true;
        id[v] = count;
        for (int w : G.adj(v))
            if (!marked[w])
                dfs(G, w);
    }

    public boolean stronglyConnected(int v, int w)
    {
        return id[v] == id[w];
    }
}
```

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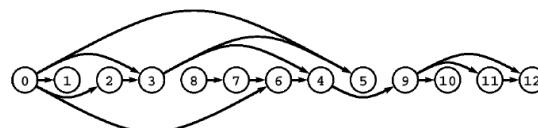
Digraph-processing summary: algorithms of the day

single-source
reachability
in a digraph



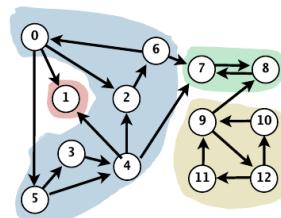
DFS

topological sort
in a DAG



DFS

strong
components
in a digraph



Kosaraju-Sharir
DFS (twice)

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