TPkppv

```
load data app
xa=x;
Sa=S;
% set d'aprentissage
load data test
% X et S \overline{d}e data test -> set de test
xkppv=x;
Skppv = ones(length(S), 1);
Sproto = Skppv;
%image
m = 300;
im = reshape(x(m,:),28,28)';
figure(1)
image (255*ones (28,28) -im);
colormap(gray)
S (m)
taille ap = length(Sa)
taille test = length(S)
% classe 1:10 k = nombre de classe
% classe equirepartie?
k = 10:
for i=1:k
 Ti = mean(Sa==i)
endfor
% oui
%%algo des kppv
% k classe , q voisin
[n c] = size(x);
[l _] = size(xa);
for q = 1:5
 for i = 1:n
  Temp1 = zeros(1,1);
  for z = 1:1
   Temp1(z) = (xa(z,:)-x(i,:))*(xa(z,:)-x(i,:))';
  endfor
  %%recherche des k ppv pour distance euclidienne
  % Temp1 (j) contient distance au carr\hat{\mathbf{Q}} entre xa(j,:) et x(i,:)
  [_,indice] = sort(Temp1);
 % sort trie par ordre croissant met dans d les valeur et dans indice les indices
 % correspondants
 % selection des q voisin les plus proche
  selectkvois = indice(1:q);
  % selection des classe auxquelle les q ppv appartienne
  Clkppv = Sa(selectkvois);
  %calcul frequence classe des q ppv
  temp3 = zeros(1,k);
  for j=1:k
   temp3(j) = mean(Clkppv==j);
  endfor
  % affectation ( classe la plus frequente parmis les q ppv )
  [\_Cl] = max(temp3);
  \overline{Skppv(i)} = Cl;
 endfor
% calcul erreur
erreur = sum(Skppv~=S);
taux_erreur = erreur/length(S)
% matrice de confusion
M conf = zeros(k);
\overline{\text{for}} ii = 1:k
  %element de classe i
  indclassei = find(S==ii);
  for jj = 1:k
    % element de classe i classer en j
    classerj = find(Skppv(indclassei)==jj);
    %coef i j de la matrice de confusion
    M_conf(ii,jj) = length(classerj);
  endfor
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endfor
q=q
M conf
endfor
% il y a 4 donnee de classe 6 qui ont ete classee 1 ont les affichent
%image de qq confusion
%comparaison avec un bien classer
ind1 = find(S==6);
class1 = find(Skppv(ind1) == 1);
xprint = x(ind1,:);
for i = 1:length(class1)
 colormap(gray)
 figure(i+10)
 im1 = reshape(xprint(class1(i),:),28,28)';
 image(255*ones(28,28)-im1);
endfor
% le 1 est reconnaissable par un trait 'long' et
%les six classe 1 ont cette caracteristique
% construction des prototype ( 2*moyenne)
Proto = zeros(k,c);
for i = 1:k
 indcli = find(Sa==i);
 Proto(i,:) = mean(2*xa(indcli,:));
 colormap(gray)
 figure(i+10)
 im1 = reshape(Proto(i,:),28,28)';
 image(255*ones(28,28)-im1);
for i = 1:n
 Temp1 = zeros(1,1);
  % calcul distance au carr ventre Prototype de classe z et x(i,:)
 for z = 1:k
   Temp1(z) = (Proto(z,:)-x(i,:))*(Proto(z,:)-x(i,:))';
  % Temp1 (j) contient distance au carr\hat{\boldsymbol{\varrho}} entre Proto(j,:) et x(i,:)
 %%recherche du ppv pour distance euclidienne
  [ ,indice] = sort(Temp1);
  \overline{\text{clppv}} = \text{Sa(indice(1))}
 Sproto(i) = clppv;
endfor
% calcul erreur
erreur = sum(Sproto~=S);
taux erreur = erreur/length(S);
% il y a surement une erreur car le prototype de type 3 est toujours le plus proche
  ans = 2
  taille_ap = 1000
  taille_{test} = 300
  Ti = \overline{0.11600}

Ti = 0.099000
  Ti = 0.093000
  Ti = 0.10500
  Ti = 0.092000
  Ti = 0.094000
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  Ti = 0.087000
  Ti = 0.10000
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  taux_erreur = 0.15333
  q = 1
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