

Vector-valued Gaussian Processes

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I. Overview of Gaussian Processes

Gaussian processes generalize the multivariate Gaussian dist. and can describe probability distributions over functions. [1]

i. Multivariate Gaussian Distribution

$$\begin{split} \boldsymbol{z} \in \mathbb{R}^N \sim \mathcal{N}_N(\boldsymbol{\mu}, \boldsymbol{\Sigma}) \ \boldsymbol{z}_i \sim \mathcal{N}(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_{ii}) \\ \boldsymbol{\mu} \in \mathbb{R}^N = (\boldsymbol{\mu}_1, \boldsymbol{\mu}_2, ..., \boldsymbol{\mu}_N)^\top = (\mathbb{E}(\boldsymbol{z}_1), \mathbb{E}(\boldsymbol{z}_2), ..., \mathbb{E}(\boldsymbol{z}_N))^\top \\ \boldsymbol{\Sigma} \in \mathbb{R}^{N \times N} = \mathbb{E} \Big((\boldsymbol{z} - \boldsymbol{\mu}) (\boldsymbol{z} - \boldsymbol{\mu})^\top \Big) = \left[\operatorname{cov}(\boldsymbol{z}_i, \boldsymbol{z}_j) \right]_{i, j = 1}^N \end{split}$$

ii. Gaussian Processes (GPs)

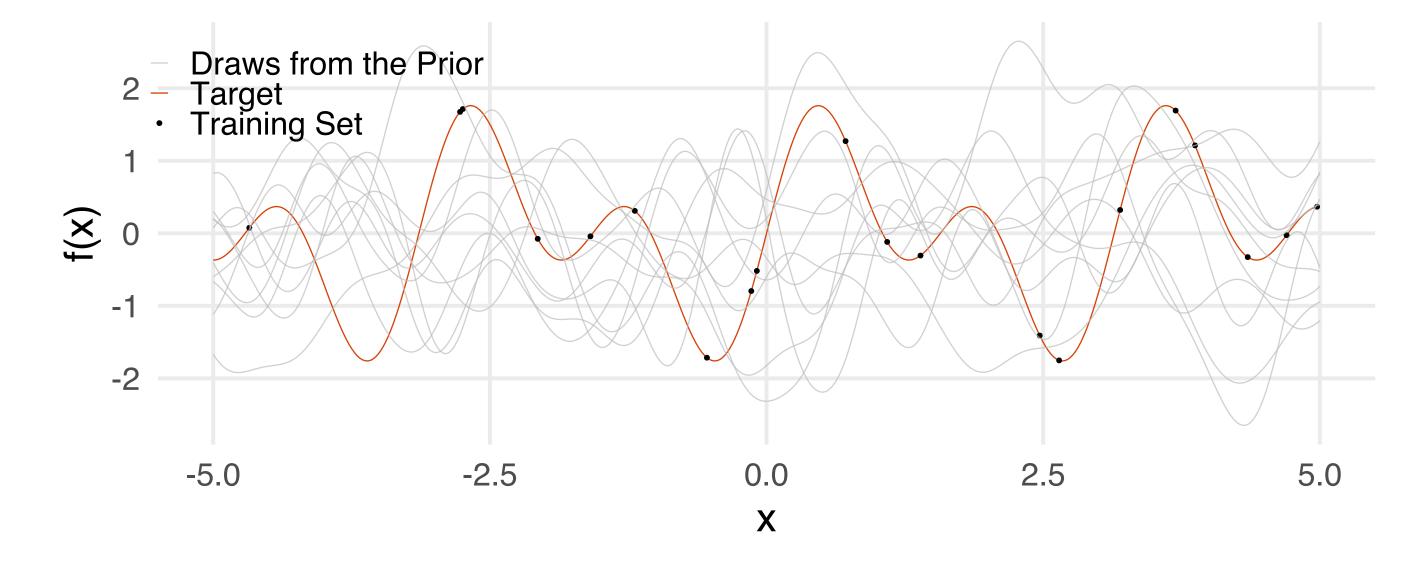
- GP: an uncountably infinite collection of random variables; any finite sample is a draw from a MV Gaussian distribution.
- GPs fully specified by mean and covariance (kernel) functions.
- The covariance function k must produce a positive semi-definite matrix.
- Squared exponential kernel, $k: \mathbb{R}^p \times \mathbb{R}^p \to \mathbb{R}$:

$$k(x, x') = \alpha^2 \exp\left(-\frac{1}{2\rho^2} \|x - x'\|^2\right).$$
 (2)

• α and ρ are *hyperparameters* (chosen, or estimated from data)

II. Gaussian Process Regression – Univariate y

Have:
$$\boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^{N}, \boldsymbol{x}_{*} \in \mathbb{R}^{M}$$
 Want: $\boldsymbol{y} = f(\boldsymbol{x})$
Prior: $f \sim \mathcal{GP}(\boldsymbol{0}, k)$ $\boldsymbol{y}_{*} \sim \mathcal{N}_{M}(\boldsymbol{0}, k(\boldsymbol{x}_{*}, \boldsymbol{x}_{*}))$ (3)
 $k(\boldsymbol{x}_{*}, \boldsymbol{x}_{*}) \in \mathbb{R}^{M \times M} = \left[k(\boldsymbol{x}_{*i}, \boldsymbol{x}_{*j})\right]_{i,j=1}^{M}$.

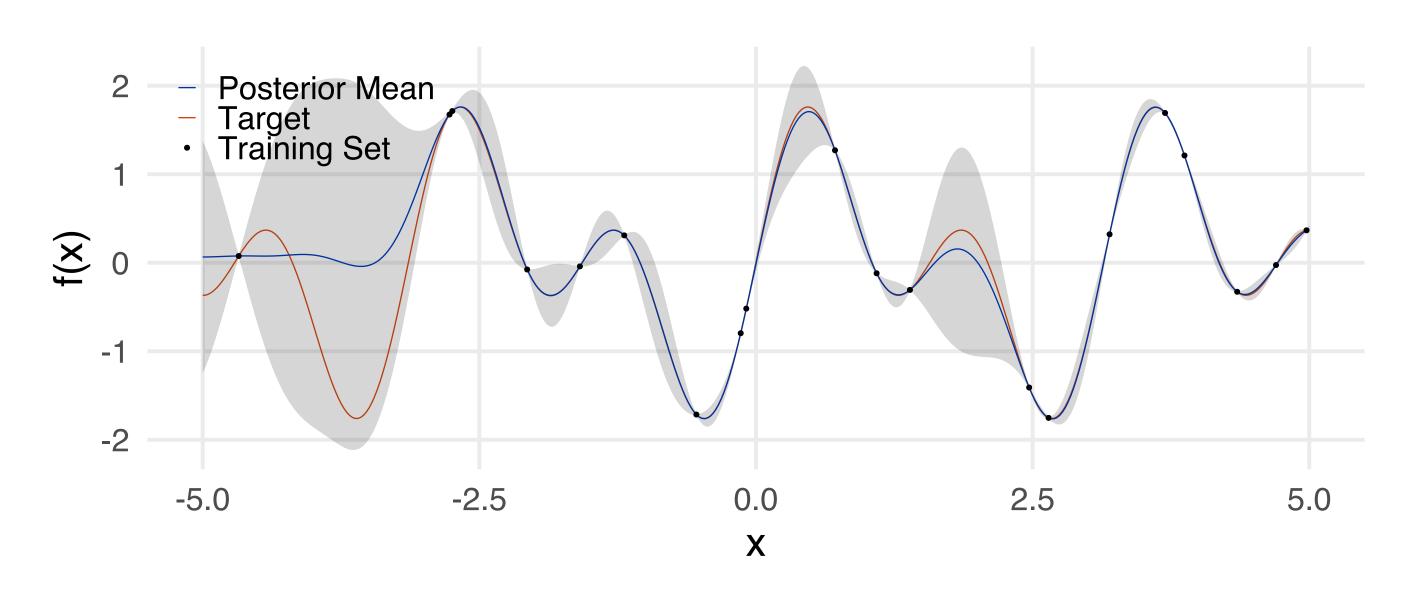


Posterior:
$$\mathbf{y}_* \mid \mathbf{x}, \mathbf{y}, \mathbf{x}_* \sim \mathcal{N}_M (\hat{\mu}, \hat{\Sigma})$$

$$\hat{\mu} \in \mathbb{R}^M = k(\mathbf{x}_*, \mathbf{x}) k(\mathbf{x}, \mathbf{x})^{-1} \mathbf{y}$$

$$\hat{\Sigma} \in \mathbb{R}^{M \times M} = k(\mathbf{x}_*, \mathbf{x}_*) - k(\mathbf{x}_*, \mathbf{x}) k(\mathbf{x}, \mathbf{x})^{-1} k(\mathbf{x}_*, \mathbf{x})^{\top}$$

$k(\boldsymbol{x}, \boldsymbol{x}) \in \mathbb{R}^{N \times N} = \left[k(x_i, x_j) \right]_{i,j=1}^{N}$ $k(\boldsymbol{x}_*, \boldsymbol{x}) \in \mathbb{R}^{M \times N} = \left[k(x_{*i}, x_j) \right]_{i,j=1}^{M,N}.$ (5)



III. Multioutput GPR – Vector-valued y

- Velocity fields: $m{X}, m{Y} \in \mathbb{R}^{N imes 2}, \ m{y} \in \mathbb{R}^{2N} = \mathrm{vec}(Y), \ m{X}_* \in \mathbb{R}^{M imes 2}$
- Intrinsic Coregionalization Model (ICM) [2], [3]

$$y_{*} \mid \boldsymbol{X}, \boldsymbol{y}, \boldsymbol{X}_{*} \sim \mathcal{N}_{2M}(\hat{\mu}, \hat{\Sigma})$$

$$\hat{\mu} \in \mathbb{R}^{2M} = K_{\boldsymbol{X}_{*}\boldsymbol{X}}K_{\boldsymbol{X}\boldsymbol{X}}^{-1}\boldsymbol{y}$$

$$\hat{\Sigma} \in \mathbb{R}^{2M \times 2M} = K_{\boldsymbol{X}_{*}\boldsymbol{X}_{*}} - K_{\boldsymbol{X}_{*}\boldsymbol{X}}K_{\boldsymbol{X}\boldsymbol{X}}^{-1}K_{\boldsymbol{X}_{*}\boldsymbol{X}}^{\top}$$

$$K_{\boldsymbol{X}\boldsymbol{X}} \in \mathbb{R}^{2N \times 2N} = B \otimes k(\boldsymbol{X}, \boldsymbol{X})$$

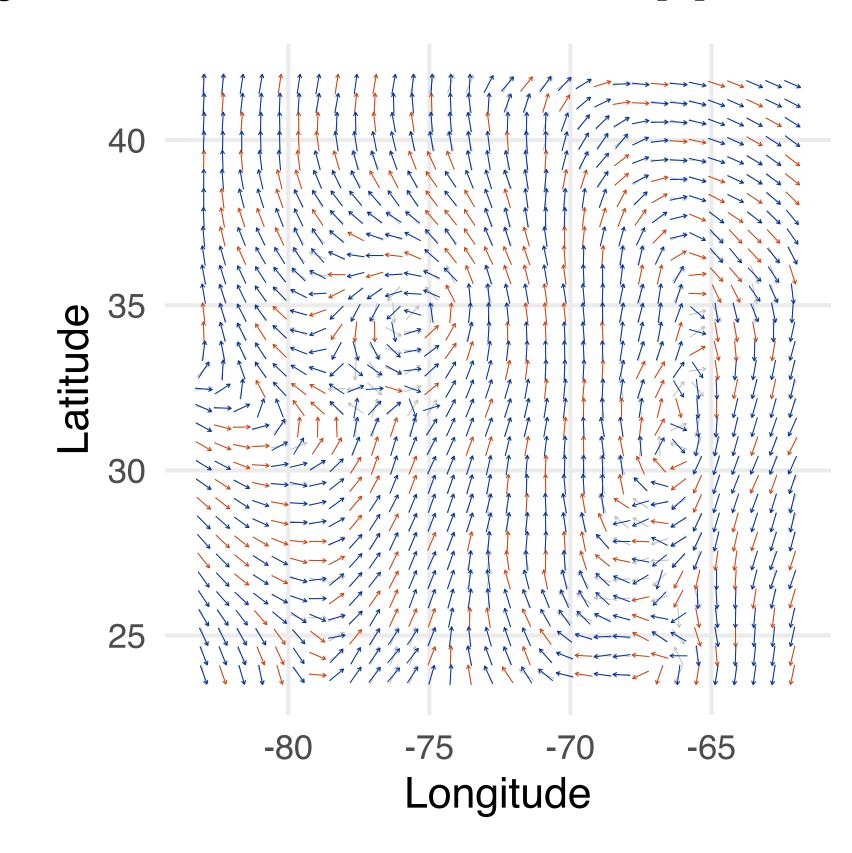
$$K_{\boldsymbol{X}_{*}\boldsymbol{X}} \in \mathbb{R}^{2M \times 2N} = B \otimes k(\boldsymbol{X}_{*}, \boldsymbol{X})$$

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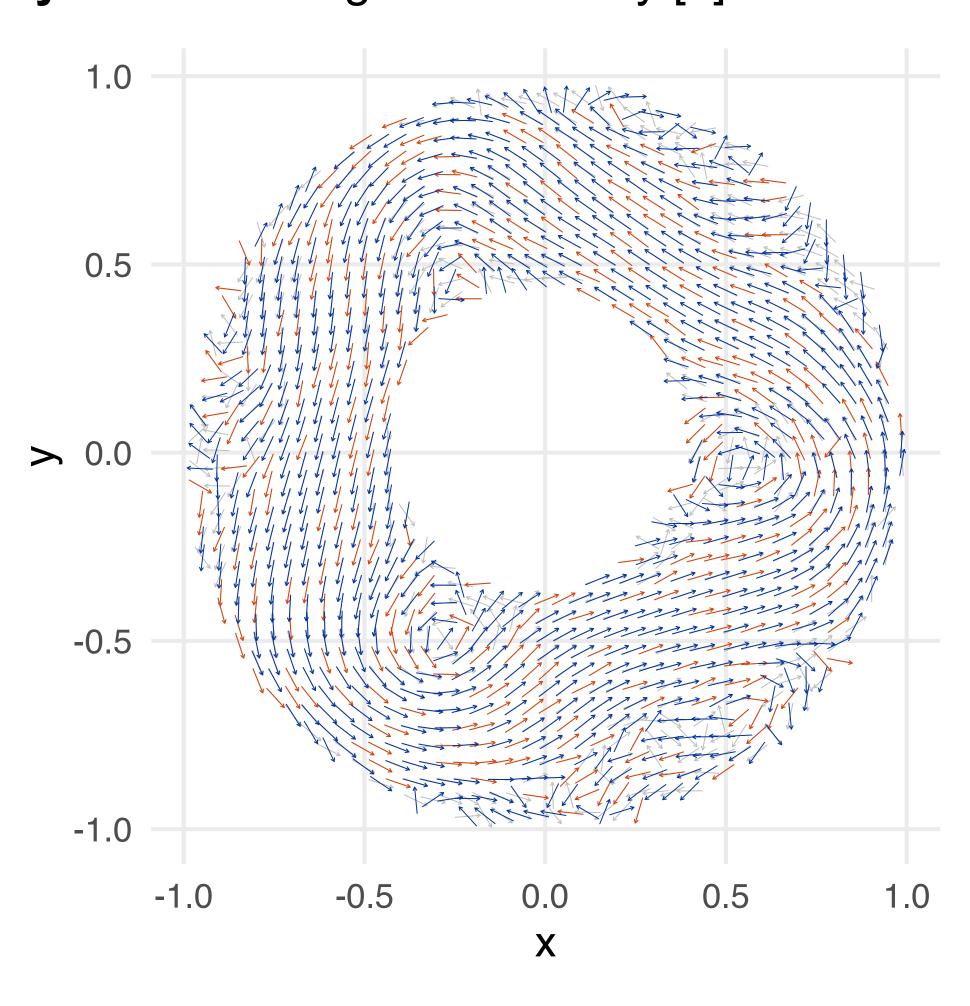
$$B \in \mathbb{R}^{2N \times 2M} = B \otimes k(\boldsymbol{X}_{*}, \boldsymbol{X}_{*})$$

$$(6)$$

Case study: Hurricane Isabel Simulation [4]



Case study: Particle Image Velocimetry [5]



Note: colors reflect sample data, posterior mean, and test points.

Bibliography

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