Vortex Panel Method

Nicholas Richmond

Student ID: 919578115

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EAE 127: Applied Aerodynamics

University of California, Davis

```
In [11]: #standard imports and setups
         import math
         import pandas as pd #type: ignore
         import numpy as np #type: ignore
         import matplotlib.pyplot as plt #type: ignore
         import matplotlib.lines as mlines
         from scipy import integrate
         #Plot all figures in full-size cells, no scroll bars
         %matplotlib inline
         #Disable Python Warning Output
         #(NOTE: Only for production, comment out for debugging)
         import warnings
         warnings.filterwarnings('ignore')
         ### PLOTTING DEFAULTS BOILERPLATE (OPTIONAL) #######################
         #SET DEFAULT FIGURE APPERANCE
         import seaborn as sns #Fancy plotting package #type: ignore
         #No Background fill, legend font scale, frame on legend
         sns.set_theme(style='whitegrid', font_scale=1.5, rc={'legend.frameon': True}
         #Mark ticks with border on all four sides (overrides 'whitegrid')
         sns.set style('ticks')
         #ticks point in
         sns.set style({"xtick.direction": "in","ytick.direction": "in"})
         #fix invisible marker bug
         sns.set_context(rc={'lines.markeredgewidth': 0.1})
         #restore default matplotlib colormap
         mplcolors = ['#1f77b4', '#ff7f0e', '#2ca02c', '#d62728', '#9467bd',
         '#8c564b', '#e377c2', '#7f7f7f', '#bcbd22', '#17becf']
         sns.set palette(mplcolors)
```

```
#Get color cycle for manual colors
colors = sns.color palette()
#SET MATPLOTLIB DEFAULTS
#(call after seaborn, which changes some defaults)
params = {
#FONT SIZES
'axes.labelsize' : 30, #Axis Labels
'axes.titlesize' : 30, #Title
'font.size' : 28, #Textbox
'xtick.labelsize': 22, #Axis tick labels
'ytick.labelsize': 22, #Axis tick labels
'legend.fontsize': 24, #Legend font size
'font.family' : 'serif',
'font.fantasy' : 'xkcd',
'font.sans-serif': 'Helvetica',
'font.monospace' : 'Courier',
#AXIS PROPERTIES
'axes.titlepad' : 2*6.0, #title spacing from axis
'axes.grid' : True, #grid on plot
'figure.figsize' : (8,8), #square plots
'savefig.bbox' : 'tight', #reduce whitespace in saved figures
#LEGEND PROPERTIES
'legend.framealpha': 0.5,
'legend.fancybox' : True,
'legend.frameon' : True,
'legend.numpoints': 1,
'legend.scatterpoints': 1,
'legend.borderpad': 0.1,
'legend.borderaxespad' : 0.1,
'legend.handletextpad' : 0.2,
'legend.handlelength': 1.0,
'legend.labelspacing': 0,
import matplotlib #type:ignore
matplotlib.rcParams.update(params) #update matplotlib defaults, call after
colors = sns.color palette() #color cycle
```

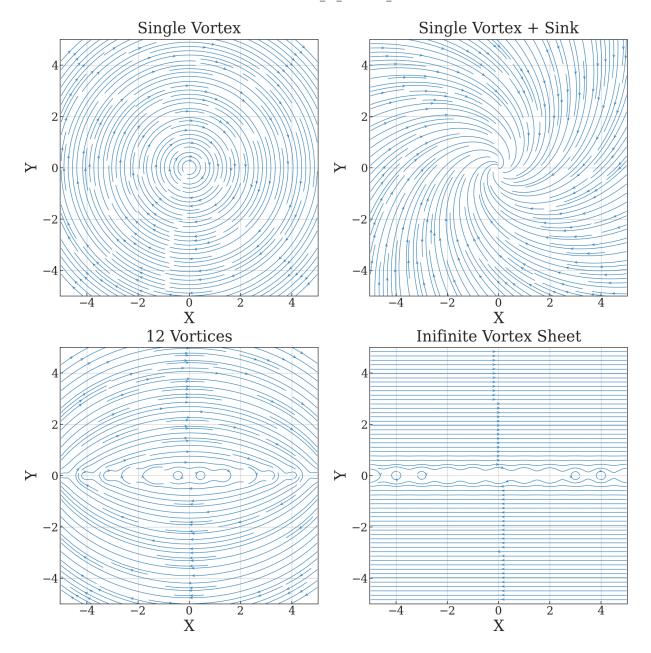
Problem 1: Vortex Potential Flow

This problem asks us to plot a single vortex, 12 vorticies (finite vortex sheet), and an infinite vortex sheet (or, rather, an approximation of one).

```
X, Y = np.meshgrid(x, y)
def get_vortex_velocity(Gamma, xv, yv, X, Y):
    Returns the velocity field generated by a vortex
    Parameters
    Gamma: float
        Strength of the vortex.
    xv: float
        x-coordinate of the vortex.
    yv: float
        y-coordinate of the vortex.
    X: 2D Numpy array of floats
        x-coordinate of the mesh points.
    Y: 2D Numpy array of floats
        y-coordinate of the mesh points.
    Returns
    u: 2D Numpy array of floats
        x-component of the velocity vector field.
    v: 2D Numpy array of floats
        y-component of the velocity vector field.
    # Here, input the equation for u_vortex from the equations above
    u = (Gamma/(2*np.pi))*((Y-yv)/((X-xv)**2 + (Y-yv)**2))
    # Here, input the equation for v_vortex from the equations above
    v = -1 * (Gamma/(2*np.pi)) * ((X-xv)/((X-xv)**2 + (Y-yv)**2))
    return u, v
def get_velocity(strength, xs, ys, X, Y):
    Returns the velocity field generated by a source/sink.
    Parameters
    strength: float
        Strength of the source/sink.
    xs: float
        x-coordinate of the source (or sink).
    ys: float
        y-coordinate of the source (or sink).
    X: 2D Numpy array of floats
        x-coordinate of the mesh points.
    Y: 2D Numpy array of floats
        y-coordinate of the mesh points.
    Returns
    u: 2D Numpy array of floats
        x-component of the velocity vector field.
    v: 2D Numpy array of floats
        y-component of the velocity vector field.
```

```
# Here, input the equation for u_source from the equations above
   u = strength / (2 * np.pi) * (X - xs) / ((X - xs)**2 + (Y - ys)**2)
   # Here, input the equation for v_source from the equations above
   v = strength / (2 * np.pi) * (Y - ys) / ((X - xs)**2 + (Y - ys)**2)
    return u, v
def infinite vortex vel(Gamma, a, X, Y):
   Parameters
    a: float
       Spacing between the vortices
   X: 2D Numpy array of floats
       x-coordinate of the mesh points.
   Y: 2D Numpy array of floats
        y-coordinate of the mesh points.
   Returns
   u: 2D Numpy array of floats
        x-component of the velocity vector field.
   v: 2D Numpy array of floats
       y-component of the velocity vector field.
   # Here, input the equation for u_vortex from the equations above
   u = (Gamma/(2*a)) * (np.sinh(2*np.pi*Y/a)) / (np.cosh(2*np.pi*Y/a) - np.
   # Here, input the equation for v_vortex from the equations above
   v = -1* (Gamma/(2*a)) * (np.sin(2*np.pi*X/a)) / (np.cosh(2*np.pi*Y/a) -
    return u, v
vortStrength = 5
sstrength = -5
uVort, vVort = get vortex velocity(vortStrength,0,0,X,Y)
uSink, vSink = get_velocity(sstrength,0,0,X,Y)
uInfVort, vInfVort = infinite_vortex_vel(vortStrength,1,X,Y)
plt.figure(figsize=(20,20))
plt.subplot(2,2,1)
plt.title("Single Vortex")
plt.xlabel("X")
plt.ylabel("Y")
plt.streamplot(X, Y, uVort, vVort, density=2, linewidth=1, arrowsize=1, arro
plt.axis("equal")
plt.subplot(2,2,2)
plt.title("Single Vortex + Sink")
plt.xlabel("X")
plt.ylabel("Y")
plt.streamplot(X, Y, uVort + uSink, vVort + vSink, density=2, linewidth=1, a
```

```
plt.axis("equal")
sum uVort = 0
sum_vVort = 0
nVortices = 12 #Number of vortices we want to plot
for xLoc in np.linspace(-5,5,nVortices):
    u, v = get_vortex_velocity(vortStrength,xLoc,0,X,Y)
    sum uVort += u
   sum_vVort += v
plt.subplot(2,2,3)
plt.title("12 Vortices")
plt.xlabel("X")
plt.ylabel("Y")
plt.streamplot(X, Y, sum_uVort, sum_vVort, density=2, linewidth=1, arrowsize
plt.axis("equal");
plt.subplot(2,2,4)
plt.title("Inifinite Vortex Sheet")
plt.xlabel("X")
plt.ylabel("Y")
plt.streamplot(X, Y, uInfVort, vInfVort, density=2, linewidth=1, arrowsize=1
plt.axis("equal");
```



The first graph is of a vortex only, and is the basis for the rest of the plots. The second plot dipicts a source and a sink superimposed. The last two polots are of a finite sheet of 12 vorticies and of an infinite sheet approximation. The difference is that the finite sheet plot has edges, and from farther away the flow will look more and more like a single vortex. From close up, however, the flow appears to move to the right when above the x-axis, and to the left when below the x-axis. The infinite sheet approximation is a mathematical representation of an infinite sheet and displays the same left-right behavior as the finite sheet, but this time everywhere. As an approximation, it is still not perfect when close to the x-axis. By adjusting the spacing (closer spacing) and quantity of vorticies (more vortices total), we could make the finite sheet more closely approximate an infinite vortex sheet.

Vortex Panel Method

Problem 2 is focused on creating a vortex panel method to improve upon our previous method: the source panel method. Now, by imposing the Kutta condition, we can create an airfoil panel approximation that is capable of estimating lift.

```
In [13]: #define each of the functions
         class Panel:
             Here, we are creating a panel object and all its necessary information.
             def __init__(self, xa, ya, xb, yb):
                 Initialization of the panel.
                 Here, we write a specific piece of code to be run everytime we creat
                 will be run every time that we create a new panel.
                 Our code needs to calculate the center point of the panel, the lengt
                 Our code also needs to make space for the source strength, tangentia
                 (which we will define for a specific panel later)
                 Parameters:
                 xa: float
                     x - coordinate of the first end point
                 ya: float
                     y - coordinate of the first end point
                 xb: float
                     x - coordinate of the second end point
                 yb: float
                     y - coordinate of the second end point
                 xc: float
                     x - coordinate of the center point of the panel
                 yc: float
                     y - coordinate of the center point of the panel
                 length: float
                     length of the panel
                 beta: float
                     orientation/angle of the panel
                 These parameters are not defined until later. We set them equal to z
                 sigma: float
                     source sheet strength
                 vt: float
                     velocity tangential to the panel
                 cp: float
                     pressure coefficient
                 0.00
                 self.xa, self.ya = xa, ya
                                                      # Defines the first end point
                 self.xb, self.yb = xb, yb
                                                      # Defines the second end point
```

```
# Defining center point and panel parameters
       # You will need to define these yourself:
                                                           # Control po
        self.xc, self.yc = (xa + xb) / 2, (ya + yb) / 2
        self.length = math.sqrt((xb - xa)**2 + (yb - ya)**2)
                                                                # Length of
       # For the orientation of the panel (angle between x axis and the uni
       if xb - xa <= 0:
            self.beta = math.acos((yb - ya) / self.length)
        elif xb - xa > 0:
            self.beta = math.pi + math.acos(-(yb - ya) / self.length)
       # Location of the panel (we will use this later when we expand our a
       if self.beta <= math.pi:</pre>
            self.loc = 'upper'
        else:
            self.loc = 'lower'
        # Will need a value for theta
        self.theta = math.atan2(self.yc, self.xc)
       # We also need 3 more parameters, sigma, vt for tangential velocity,
       # Create these and set the equal to zero for now
        self.sigma = 0.0
        self.vt = 0.0
        self.cp = 0.0
def define panels(x, y, N=40):
   Discretizes the geometry into panels using the 'circle mapping' method.
   Parameters
   x: 1D array of floats
       x-coordinate of the points defining the geometry.
   y: 1D array of floats
       y-coordinate of the points defining the geometry.
   N: integer, optional
       Number of panels;
       default: 40.
   Returns
    panels: 1D Numpy array of Panel objects
       The discretization of the geometry into panels.
   R = (x.max() - x.min()) / 2
                                               # Radius of the circle, base
   x_{\text{center}} = (x_{\text{max}}() + x_{\text{min}}()) / 2
# X coordinate of center of
   x \text{ circle} = x \text{ center} + R * np.cos(np.linspace(0.0, 2 * math.pi, N + 1))
   # Here we define the x coordinates of the circle
   x_{ends} = np.copy(x_{circle})
                                               # projection of the x-coord
   y_ends = np.empty_like(x_ends)
                                               # initialization of the y-co
   x, y = np.append(x, x[0]), np.append(y, y[0]) # extend arrays using num
```

```
# computes the y-coordinate of end-points
    I = 0
    for i in range(N):
        while I < len(x) - 1:
            if (x[I] \leftarrow x_{ends}[i] \leftarrow x[I+1]) or (x[I+1] \leftarrow x_{ends}[i] \leftarrow
            else:
                I += 1
        a = (y[I + 1] - y[I]) / (x[I + 1] - x[I])
        b = y[I + 1] - a * x[I + 1]
        y = nds[i] = a * x = nds[i] + b
        #print(i)
        #print(I)
    x \text{ ends}[N] = x \text{ ends}[0]
    y_{ends}[N] = y_{ends}[0]
    panels = np.empty(N, dtype=object)
    for i in range(N):
        panels[i] = Panel(x_ends[i], y_ends[i], x_ends[i + 1], y_ends[i + 1]
    return panels
def vortex_integral_normal(p_i, p_j):
    Evaluates the contribution of a source-panel at the center-point of anot
    in the normal direction.
    Parameters:
    p i: Panel object
        Panel on which the contribution is calculated.
    p j: Panel object
        Panel from which the contribution is calculated.
    def integrand(s):
        return (((p_i.xc - (p_j.xa - np.sin(p_j.beta)*s)) * (np.sin(p_i.beta
                  (p i.yc - (p j.ya + np.cos(p j.beta)*s)) * (np.cos(p i.beta)
                 ((p_i.xc - (p_j.xa - np.sin(p_j.beta)*s))**2 +
                  (p_i.yc - (p_j.ya + np.cos(p_j.beta)*s))**2))
    return integrate.quad(integrand, 0.0, p_j.length)[0]
def source integral normal(p i, p j):
    0.00
    Evaluates the contribution of a source-panel at the center-point of anot
    in the normal direction.
    Parameters:
    p_i: Panel object
        Panel on which the contribution is calculated.
    p j: Panel object
        Panel from which the contribution is calculated.
    ## Fill in the equation below for the function integrand
    def integrand(s):
```

```
return (((p_i.xc - (p_j.xa - math.sin(p_j.beta) * s)) * math.cos(p_i
                 (p_i.yc - (p_j.ya + math.cos(p_j.beta) * s)) * math.sin(p_i)
                ((p_i.xc - (p_j.xa - math.sin(p_j.beta) * s))**2 +
                 (p_i.yc - (p_j.ya + math.cos(p_j.beta) * s))**2))
    return integrate.quad(integrand, 0.0, p_j.length)[0]
def analyze panels(panels, uinf, alpha):
   Here, we write some code to analyze our panels after they have been crea
   Creates a source influence matrix [A]
   Input: an array of panels created using the Panel function (panels) and
   0.00
   Num = len(panels)
   A s = np.empty((Num, Num), dtype = float)
   A_v = np.empty((Num, Num), dtype = float)
   np.fill diagonal(A s, 0.5)
        # Whenever we have i = j, we have sigma(i)/2 or sigma(i)*0.5. Thus,
       # The diagonal of a matrix means i = j i.e (1,1), (2,2), etc etc.
       # Remember that this represents how much a source panel conributes t
   np.fill_diagonal(A_v, 0.0)
        # Here, we have the same thing, but for vortex contributions on norm
   # Create the source influence matrix [A_s] of the linear system
   # This represents how much a source panel contributes to OTHER panels no
   for i, p i in enumerate(panels):
        for j, p_j in enumerate(panels):
            if i != j:
                A_s[i,j] = (0.5/np.pi) * source_integral_normal(p_i, p_j)
                # Here, we create a matrix called A s to hold the source con
                # Make sure that you change this to use our new functions ra
   # Create the vortex influence matrix [A v]
   for i, p_i in enumerate(panels):
       for j, p_j in enumerate(panels):
            if i != j:
                A_v[i,j] = (-1 * 0.5/np.pi) * vortex_integral_normal(p_i,p_j)
                # Here, we create a matrix called A s to hold the source cor
                # Make sure that you change this to use our new functions ra
   A s norm = A s
   A \vee norm = A \vee
   # Kutta Condition:
   # First, lets create an array to hold all of our values.
   # This array should be of length N + 1 (the number of panels + 1)
   Kutta = np.empty(A_s.shape[0] + 1, dtype=float)
   # Next, we would like all the elements of our Kutta array (except the la
   # to be equal to the first and last values of our vortex contribution ma
```

```
Kutta[:-1] = A_v[0, :] + A_v[-1, :]
# Finally, we make the last element of our Kutta array equal to the sum
# all the last elements of our source contribution matrix.
Kutta[-1] = - np.sum(A_s[0, :] + A_s[-1, :])
A = np.empty((Num+1, Num+1), dtype = float)
# Enter the source contribution matrix
# This takes up all but the last column and all but the last row
# The vortex strength (gamma) and the kutta condition will take this pla
A[:-1, :-1] = A s norm
# Enter the vortex contribution array
# Fills in the last column
A[:-1, -1] = np.sum(A_v_norm, axis = 1)
# Enter the Kutta array
# Fills in the last row
A[-1, :] = Kutta
# Freestream Velocity and Matrix b
# Lets start by creating an empty array b
alpha = np.radians(alpha)
b = np.empty(Num + 1, dtype = float)
for i, panel in enumerate(panels):
    b[i] = - uinf * np.cos(alpha - panel.beta)
# Freestream contribution on the Kutta condition
b[-1] = -uinf * (math.sin(alpha - panels[0].beta) + math.sin(alpha - panels[0].beta)
# Here we solve for the Strength sigma
Strengths = np.linalg.solve(A,b)
for i, panel in enumerate(panels):
    panel.sigma = Strengths[i]
# The very last value in our strength array is the value gamma, or the d
gamma = Strengths[-1]
# Now tht we know what our source panel strengths are, as well as our vo
# In order to computer the tangential velocity at each panel. We use a r
# Computing Tangential Velocity
A_t = np.empty((panels.size, panels.size+1), dtype = float)
A t[:, :-1] = A v
A_t[:, -1] = -np.sum(A_s, axis = 1)
b t = uinf * np.sin([alpha - panel.beta for panel in panels])
vortex_strengths = np.append([panel.sigma for panel in panels], gamma)
```

```
tan_vel = np.dot(A_t, vortex_strengths) + b_t
    for i, panel in enumerate(panels):
        panel.vt = tan_vel[i]
    # Finally, we need to compute the pressure coefficient.
    for panel in panels:
        panel.cp = 1 - (panel.vt/uinf)**2
    accuracy = sum([panel.sigma * panel.length for panel in panels])
    print('sum of singularity strengths: {:0.6f}'.format(accuracy))
    return panels
uinf = 2.2 \# m/s
rho = 1.2 \# kg/m^3
chord = 1.2 \# m
mu = 1.591736e-5 #N*s/m^2 --> This part was interpolated to metric since we
alphaDeg = 8
alpha = alphaDeg*np.pi/180
Re = uinf * chord * rho/ mu
print("Reynolds number to be used in analysis: {:.3g}".format(Re))
```

Reynolds number to be used in analysis: 1.99e+05

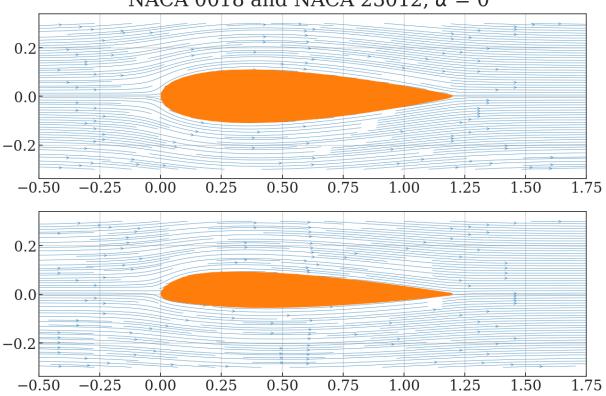
These functions (and the class Panel) are very similar to the last project, and the Panel class is exactly the same. The only difference is that now, the Kutta condition is imposed and a nonzero circulation for panels is allowed. This affects the normal integral functions, which are changed accordingly. They Reynolds number is also calculated to be 1.99×10^5 .

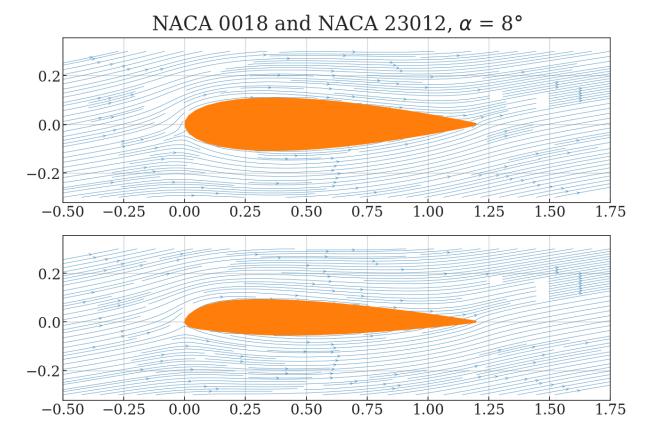
The next section analyzes the panels and creates the flow fields for each of the airfoils and the different angles of attack (0 and 8 degrees) and then creates the streamplots for each scenario.

```
#chord length isn't one, so mulitply everything by the chord lengthx
x0018 *= chord
z0018 *= chord
x23012 *= chord
z23012 *= chord
nPanels = 40
naca0018panelsa0 = define panels(x0018,z0018,nPanels)
naca23012panelsa0 = define_panels(x23012, z23012, nPanels)
naca0018panelsaa = define panels(x0018,z0018,nPanels)
naca23012panelsaa = define panels(x23012,z23012,nPanels)
analyze panels(naca0018panelsa0,uinf,0)
analyze_panels(naca23012panelsa0,uinf,0)
analyze_panels(naca0018panelsaa,uinf,alphaDeg)
analyze panels(naca23012panelsaa,uinf,alphaDeg)
#function from aeropython to get the u and v velocity components in the mesh
def integral(x, y, panel, dxdz, dydz):
   Evaluates the contribution of a panel at one point.
   Parameters
   x: float
       x-coordinate of the target point.
   y: float
       y-coordinate of the target point.
    panel: Panel object
        Source panel which contribution is evaluated.
   dxdz: float
        Derivative of x in the z-direction.
   dydz: float
        Derivative of y in the z-direction.
   Returns
   Integral over the panel of the influence at the given target point.
   def integrand(s):
        return (((x - (panel.xa - math.sin(panel.beta) * s)) * dxdz +
                 (y - (panel.ya + math.cos(panel.beta) * s)) * dydz) /
                ((x - (panel.xa - math.sin(panel.beta) * s))**2 +
                 (y - (panel.ya + math.cos(panel.beta) * s))**2) )
    return integrate.quad(integrand, 0.0, panel.length)[0]
def get_velocity_field(panels, uinf, alpha, X, Y):
    Computes the velocity field on a given 2D mesh.
    Parameters
    panels: 1D array of Panel objects
       The source panels.
```

```
freestream: Freestream object
                 The freestream conditions.
             X: 2D Numpy array of floats
                 x-coordinates of the mesh points.
             Y: 2D Numpy array of floats
                 y-coordinate of the mesh points.
             Returns
             u: 2D Numpy array of floats
                 x-component of the velocity vector field.
             v: 2D Numpy array of floats
                 y-component of the velocity vector field.
             # freestream contribution
             u = uinf * math.cos(alpha) * np.ones_like(X, dtype=float)
             v = uinf * math.sin(alpha) * np.ones_like(X, dtype=float)
             # add the contribution from each source (superposition powers!!!)
             vec intregral = np.vectorize(integral)
             for panel in panels:
                 u += panel.sigma / (2.0 * math.pi) * vec_intregral(X, Y, panel, 1.0,
                 v += panel.sigma / (2.0 * math.pi) * vec intregral(X, Y, panel, 0.0,
             return u, v
         u0018aa, v0018aa = get_velocity_field(naca0018panelsaa,uinf,alpha,X,Y)
         u23012aa, v23012aa = qet velocity field(naca23012panelsaa,uinf,alpha,X,Y)
         u0018a0, v0018a0 = get_velocity_field(naca0018panelsa0,uinf,0,X,Y)
         u23012a0, v23012a0 = get velocity field(naca23012panelsa0,uinf,0,X,Y)
        sum of singularity strengths: 0.017645
        sum of singularity strengths: 0.013009
        sum of singularity strengths: 0.018362
        sum of singularity strengths: 0.005262
In [15]: #plot everything
         plt.figure(figsize=(15,10))
         plt.subplot(2,1,1)
         plt.title(r"NACA 0018 and NACA 23012, $\alpha$ = 0$\degree$")
         plt.streamplot(X,Y,u0018a0,v0018a0,density=2,linewidth=0.5,arrowsize=1,arrow
         plt.fill([panel.xc for panel in naca0018panelsa0],
                      [panel.yc for panel in naca0018panelsa0],
                     color=colors[1], linestyle='solid', linewidth=2, zorder=2)
         plt.axis("equal");
         plt.subplot(2,1,2)
         plt.streamplot(X,Y,u23012a0,v23012a0,density=2,linewidth=0.5,arrowsize=1,arr
         plt.fill([panel.xc for panel in naca23012panelsa0],
                      [panel.yc for panel in naca23012panelsa0],
                     color=colors[1], linestyle='solid', linewidth=2, zorder=2)
         plt.axis("equal");
         plt.figure(figsize=(15,10))
```

NACA 0018 and NACA 23012, $\alpha = 0^{\circ}$





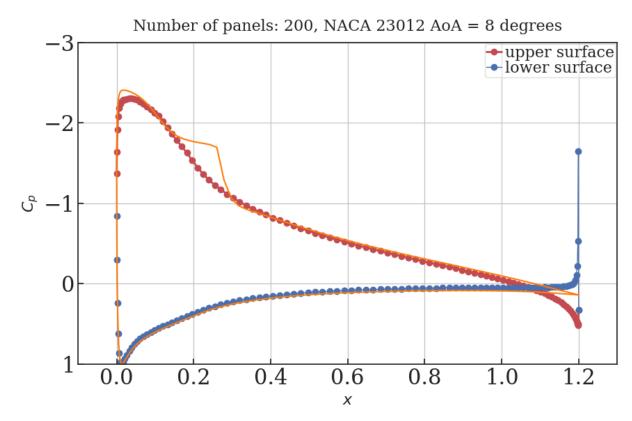
These plots show how the NACA 0018 airfoil and NACA 23012 airfoil behave at different angles of attack. Also, since NACA 23012 is a cambered airfoil, it has a noticeably asymmetric flow around it when compared to the symmetric NACA 0018 airfoil.

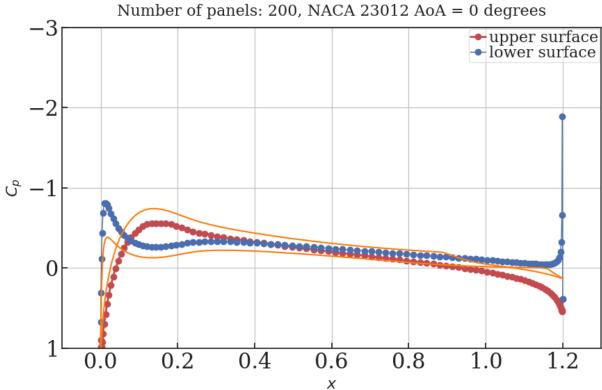
I also compared the pressure distribution graphs, which are plotted next.

```
In [20]: #plot pressure graphs
         nPanels = 200
         naca23012panelsaa = define_panels(x23012,z23012,nPanels)
         analyze_panels(naca23012panelsaa,uinf,alphaDeg)
         naca23012panelsa0 = define_panels(x23012,z23012,nPanels)
         analyze_panels(naca23012panelsa0,uinf,0)
         filename = os.path.join(folder,"naca23012a8V.txt")
         xfoil23012xCpVa8, xfoil23012CpVa8 = np.loadtxt(filename,dtype=float,skiprows
         xfoil23012xCpVa8 *= chord
         filename = os.path.join(folder,"naca23012a0V.txt")
         xfoil23012xCpVa0, xfoil23012CpVa0 = np.loadtxt(filename,dtype=float,skiprows
         xfoil23012xCpVa0 *= chord
         #filename = os.path.join(folder,"naca23012a8.txt")
         #xfoil23012xCpI, xfoil23012CpI = np.loadtxt(filename,dtype=float,skiprows=1,
         #plot for alpha = 8
         plt.figure(figsize=(10, 6))
         plt.grid()
         plt.xlabel('$x$', fontsize=16)
         plt.ylabel('$C_p$', fontsize=16)
         plt.plot([panel.xc for panel in naca23012panelsaa if panel.loc == 'upper'],
                     [panel.cp for panel in naca23012panelsaa if panel.loc == 'upper'
```

```
label='upper surface',
            color='r', linestyle='-', linewidth=2, marker='o', markersize=6)
plt.plot([panel.xc for panel in naca23012panelsaa if panel.loc == 'lower'],
            [panel.cp for panel in naca23012panelsaa if panel.loc == 'lower'
            label= 'lower surface',
            color='b', linestyle='-', linewidth=1, marker='o', markersize=6)
plt.legend(loc='best', prop={'size':16})
plt.xlim(-0.1, 1.3)
plt.ylim(1.0, -3.0)
plt.title('Number of panels: {}, NACA 23012 AoA = 8 degrees'.format(naca2301
plt.plot(xfoil23012xCpVa8,xfoil23012CpVa8,color = colors[1])
plt.grid(True)
#plot for alpha = 0
plt.figure(figsize=(10, 6))
plt.grid()
plt.xlabel('$x$', fontsize=16)
plt.ylabel('$C_p$', fontsize=16)
plt.plot([panel.xc for panel in naca23012panelsa0 if panel.loc == 'upper'],
            [panel.cp for panel in naca23012panelsa0 if panel.loc == 'upper'
            label='upper surface',
            color='r', linestyle='-', linewidth=2, marker='o', markersize=6)
plt.plot([panel.xc for panel in naca23012panelsa0 if panel.loc == 'lower'],
            [panel.cp for panel in naca23012panelsa0 if panel.loc == 'lower'
            label= 'lower surface',
            color='b', linestyle='-', linewidth=1, marker='o', markersize=6)
plt.legend(loc='best', prop={'size':16})
plt.xlim(-0.1, 1.3)
plt.ylim(1.0, -3.0)
plt.title('Number of panels: {}, NACA 23012 AoA = 0 degrees'.format(naca2301
plt.plot(xfoil23012xCpVa0,xfoil23012CpVa0,color = colors[1])
plt.grid(True);
```

sum of singularity strengths: 0.001073
sum of singularity strengths: 0.002827





```
In [17]: #Calculate coefficient of lift
def getClCd():

    upperCp = [p.cp for p in naca23012panelsa0 if p.loc == "upper"]
    lowerCp = [p.cp for p in naca23012panelsa0 if p.loc == "lower"]

    upperX = [p.xa for p in naca23012panelsa0 if p.loc == "upper"]
```

```
lowerX = [p.xa for p in naca23012panelsa0 if p.loc == "lower"]
   z23012up = []
   x23012up = []
   z23012low = []
   x23012low = []
    for i.element in enumerate(z23012):
        if element > 0:
            z23012up = np.append(z23012up.element)
            x23012up = np.append(x23012up,x23012[i])
        else:
            z23012low = np.append(z23012low,element)
            x23012low = np.append(x23012low,x23012[i])
    upperZremapped = np.interp(upperX,x23012up,z23012up)
    lowerZremapped = np.interp(lowerX,x23012low,z23012low)
   CnUpperInt = np.trapz(upperCp,upperX)
   CnLowerInt = np.trapz(lowerCp, lowerX)
   Cn = CnLowerInt - CnUpperInt
   CaUpperInt = np trapz(np multiply(upperCp,np gradient(upperZremapped,upp
   CaLowerInt = np.trapz(np.multiply(lowerCp,np.gradient(lowerZremapped,low
   Ca = CaUpperInt - CaLowerInt
   Cl = Cn*np.cos(alpha) - Ca*np.sin(alpha)
   Cd = Cn*np.sin(alpha) + Ca*np.cos(alpha)
    return Cl, Cd
#DOESN'T WORK, NOT NECESSARY FOR PROJECT, DISREGARD
```

These graphs show the Cp distribution across the NACA 23012 airfoil as calculated using the vortex panel method compared to XFOIL, with the XFOIL plot in orange. For the 8 degree angle of attack plot, our method matches up quite will with XFOIL. The 0 degree angle of attack plots also looks similar to each other, but the magnitudes are a bit off. Additionally, the vortex panel method seems to have a bit of a spike in CP at the end.

A vortex panel method is capable of producing lift because of the Kutta lift condition, which has a circulation term contained within it. It is not possible to produce lift unless there is some source of circulation; for us, a vortex. In real life, the flow around an airfoil can be mathematically modeled as a combination of sources, sinks, and vortices, where the vortices are responsible for lift. Computationally, the source vorticies factor in to the tangential and normal contributions for each panel, which in turn will affect the overall fluid stream.

```
Cd4412Re3 = 0.00632
Cl23012Re3 = 0.6794
Cd23012Re3 = 0.00645
Cl2412Re9 = 0.7996
Cd2412Re9 = 0.00628
Cl4412Re9 = 1.0368
Cd4412Re9 = 0.00607
Cl23012Re9 = 0.6994
Cd23012Re9 = 0.00539
#Lift and Drag calculations:
def getLift(Cl,rho,c,v):
    return (Cl/2) * c * rho * v**2
def getDrag(Cd, rho, c, v):
    return (Cd/2) * c * rho * v**2
rho = 2.0481e-3 \#slugs/ft^3
mu = 3.636e-7 \#lb * s/ft^2
c = 7 \#ft
re1 = 3e6
re2 = 9e6
v1 = re1/(rho*c/mu)
v2 = re2/(rho*c/mu)
L2412Re3 = getLift(Cl2412Re3, rho, c, v1)
D2412Re3 = getDrag(Cd2412Re3, rho, c, v1)
L4412Re3 = getLift(Cl4412Re3, rho, c, v1)
D4412Re3 = getDrag(Cd4412Re3, rho, c, v1)
L23012Re3 = getLift(Cl23012Re3, rho, c, v1)
D23012Re3 = getDrag(Cd23012Re3, rho, c, v1)
L2412Re9 = getLift(Cl2412Re9, rho, c, v2)
D2412Re9 = getDrag(Cd2412Re9, rho, c, v2)
L4412Re9 = getLift(Cl4412Re9, rho, c, v2)
D4412Re9 = getDrag(Cd4412Re9, rho, c, v2)
L23012Re9 = getLift(Cl23012Re9, rho, c, v2)
D23012Re9 = getDrag(Cd23012Re9, rho, c, v2)
def printLD(liftforce, dragforce, airfoil):
    print("-----
    print("Lift of {}: {:.4g} lbf".format(airfoil, liftforce))
    print("Drag of {}: {:.4g} lbf".format(airfoil,dragforce))
printLD(L2412Re3,D2412Re3,"NACA 2412, 3e6")
printLD(L4412Re3,D4412Re3,"NACA 4412, 3e6")
```

```
printLD(L23012Re3,D23012Re3,"NACA 23012, 3e6")
printLD(L2412Re9,D2412Re9,"NACA 2412, 9e6")
printLD(L4412Re9,D4412Re9,"NACA 4412, 9e6")
printLD(L23012Re9,D23012Re9,"NACA 23012, 9e6")
```

Lift of NACA 2412, 3e6: 33.48 lbf
Drag of NACA 2412, 3e6: 0.2809 lbf

Lift of NACA 4412, 3e6: 42.93 lbf
Drag of NACA 4412, 3e6: 0.2623 lbf

Lift of NACA 23012, 3e6: 28.19 lbf
Drag of NACA 23012, 3e6: 0.2677 lbf

Lift of NACA 2412, 9e6: 298.6 lbf
Drag of NACA 2412, 9e6: 2.345 lbf

Lift of NACA 4412, 9e6: 387.2 lbf
Drag of NACA 4412, 9e6: 2.267 lbf

Lift of NACA 23012, 9e6: 2.267 lbf

Lift of NACA 23012, 9e6: 261.2 lbf
Drag of NACA 23012, 9e6: 2.013 lbf

For finding the maximum L/D, I iterated over different angles of attack in xfoil by hand to see where the highest L/D was for each airfoil.

NACA 2412: MAx L/D ≈ 135.61 at an angle of attack of \approx 7.95\degree\newline NACA 4412: Max L/D ≈ 173.42 at an angle of attack of \approx 4.75\degree\newline NACA 23012: Max L/D ≈ 155.89 at an angle of attack of \approx 8.05\degree\newline