MSP432P4xx Arduino Pin Map Table

	40-pin header for MSP432P4xx	CDTO	ADC	DWW	Carial	CDT	TOC	DCLV	Note
pin#	full name		ADC	PWM	Serial	5P1	I2C	RSLK	Note
1 20	3.3V GND	+3V3 GND							
22	GND	GND							
21	5V	+5V0							
16	RST	RST							
18	P3.0/PM_UCA2STE	P3.0		PWM1		CS(x)			
3	P3.2/PM_UCA2RXD/PM_UCA2SOMI	P3.2			PVD(1)	POCI(x)			
4	P3.3/PM_UCA2SIMO/PM_UCA2TXD	P3.3				PICO(x)			
32 ¹	P3.5/PM_UCB2CLK	P3.5		PWM1	TAD(1)	SCLK(1)		SRV 1	Avoid on P4111 board (LCD)
11 ¹	P3.6/PM_UCB2SDA/PM_UCB2SIMO	P3.6		PWM1			SDA(v)	MOTOR_R_SLP_PIN	Avoid on P4111 board (LCD)
31 ¹	P3.7/PM UCB2SCL/PM UCB2SOMI	P3.7		PWM1				MOTOR_L_SLP_PIN	Avoid on P4111 board (LCD)
7	P1.5/UCB0CLK	P1.5		I AALIT		SCLK	SCL(X)	MOTOR_E_SET_TIV	Avoid on 14111 board (ECD)
15	P1.6/UCB0SDA/UCB0SIMO	P1.6				PICO	SDA(1)		
14	P1.7/UCB0SCL/UCB0SOMI	P1.7				POCI	SCL(1)		
10	P6.4/UCB1SDA/UCB1SIMO/C1.3	P6.4					SDA		
9	P6.5/UCB1SCL/UCB1SOMI/C1.2	P6.5				POCI(x)			
36	P6.6/TA2.3/UCB3SDA/UCB3SIMO/C1.1	P6.6		PWM2		PICO(x)			
35	P6.7/TA2.4/UCB3SCL/UCB3SOMI/C1.0	P6.7		PWM2		POCI(x)			
17	P5.7/TA2.2/C1.6/VREF-	P5.7		PWM2		. 0 01(X)	CCL(X)	SRV 2	
37	P5.6/TA2.1/C1.7/VREF+	P5.6		PWM2				5	
30	P5.5/A0	P5.5	Α0					MOTOR_R_DIR_PIN	
29	P5.4/A1	P5.4	A1					MOTOR_L_DIR_PIN	
12	P5.2/A3	P5.2	А3					ENCODER_ELB_PIN	
33	P5.1/A4	P5.1	A4						
13	P5.0/A5	P5.0	A5					ENCODER_ERB_PIN	
28	P4.7/A6	P4.7	A6					BP_SW_PIN_0	
8	P4.6/A7	P4.6	Α7					BP_SW_PIN_1	
27	P4.5/A8	P4.5	A8					BP_SW_PIN_2	
26	P4.4/A9/HSMCLK/SVMHOUT	P4.4	A9						
6	P4.3/A10/MCLK/RTCCLK	P4.3	A10					BP_SW_PIN_3	
25	P4.2/A11/TA2CLK/ACLK	P4.2	A11					BP_SW_PIN_4	
5	P4.1/A12	P4.1	A12						
24	P4.0/A13	P4.0	A13					BP_SW_PIN_5	
23	P6.1/A14	P6.1	A14					SHRP_DIST_C_PIN	
2	P6.0/A15	P6.0	A15						
40	P2.7/PM_TA0.4	P2.7		PWM1				MOTOR_L_PWM_PIN	
39	P2.6/PM_TA0.3	P2.6		PWM1				MOTOR_R_PWM_PIN	
19	P2.5/PM_TA0.2	P2.5		PWM1					
38	P2.4/PM_TA0.1	P2.4		PWM1				SRV_0	
34	P2.3/PM_UCA1SIMO/PM_UCA1TXD	P2.3		PWM1	TXD(2)	PICO(x)			

Function descriptions

GPIO digitalRead(), digitalWrite()

Digital inputs or outputs

ADC analogRead()

Analog input

PWM analogWrite()

Pulse-width modulated output. Supports :

up to 8 PWM1 outputs up to 4 PWM2 outputs

Serial Serial, Serial1, Serial2, Serial3²

UART serial communication

SPI, SPI1

SPI serial communication

I2C Wire, Wire1

I2C serial communication

Pins used by TI RSLK robotics kit. These pins should not be used for alternate

functions on the RSLK robot.

Pins connected to on-board components.

These pins should not be used for alternate functions unless appropriate jumpers are removed.

¹ Do not use with MSP432P4111. These pins used by on-board LCD.

² Serial3 only available on MSP432P401R

Additional on-board pins											
pin#	full name	GPIO	ADC PWM	Serial	SPI	I2C	Alt Arduino Name	Note			
73	P1.1/UCA0CLK	P1.1			SCLK(x)		PUSH1				
74	P1.4/UCB0STE	P1.4			CS		PUSH2				
75	P2.0/PM_UCA1STE	P2.0	PWM1		CS(x)		RED_LED				
76	P2.1/PM_UCA1CLK	P2.1	PWM1		SCLK(x)		GREEN_LED				
77	P2.2/PM_UCA1RXD/PM_UCA1SOMI	P2.2	PWM1	RXD(2)	POCI(x)		BLUE_LED				
78	P1.0/UCA0STE	P1.0			CS(x)		LED1 (BUILTIN_LED)				
RXD	P1.2/UCA0RXD/UCA0SOMI	P1.2		RXD	POCI(x)		Serial (USB cable)				
TXD	P1.3/UCA0TXD/UCA0SIMO	P1.3		TXD	PICO(x)		Serial (USB cable)				

pin#	full name	GPIO	ADC PWM	Serial	SPI	I2C	RSLK	Note
41	P8.5/A20	P8.5	A20				LED_FR_PIN	
42	P9.0/A17	P9.0	A17				SHRP_DIST_R_PIN	
43	P8.4/A21	P8.4	A21				SRV_FB0	
44	P8.2/A23/TA3.2	P8.2	A23				SRV_FB2	
45	P9.2/TA3.3	P9.2					QTR_EMITTER_PIN_ODD	
46	P6.2/UCB1STE/C1.5	P6.2			CS(x)			
47	P7.3/PM_TA0.0	P7.3	PWM1				QTR_3	
48	P7.1/PM_C0OUT/PM_TA0CLK/R13	P7.1	PWM1				QTR_1	
49	P9.4/UCA3STE	P9.4			CS(x)		LCD_CS	
50	P9.6/UCA3RXD/UCA3SOMI	P9.6		RXD(3)	POCI(x)		LCD_DC	
51	P8.0/TA1.0/UCB3STE/C0.1	P8.0			CS(x)		LED_FL_PIN	
52	P7.4/PM_TA1.4/C0.5	P7.4	PWM1				QTR_4	
53	P7.6/PM_TA1.2/C0.3	P7.6	PWM1				QTR_6	
54	P10.0/UCB3STE	P10.0			CS(x)			
55	P10.2/UCB3SDA/UCB3SIMO	P10.2			PICO(x)	SDA(x)		
56	P10.4/TA3.0/C0.7	P10.4					ENCODER_ERA_PIN	
57	P8.6/A19	P8.6	A19				LED_BL_PIN	
58	P8.7/A18	P8.7	A18				LED_BR_PIN	
59	P9.1/A16	P9.1	A16				SHRP_DIST_L_PIN	
60	P8.3/A22/TA3CLK	P8.3	A22				SRV_FB1	
61	P5.3/A2	P5.3	A2				QTR_EMITTER_PIN_EVEN	
62	P9.3/TA3.4	P9.3					LCD_RST	
63	P6.3/UCB1CLK/C1.4	P6.3			SCLK(x)			
64	P7.2/PM_C1OUT/PM_TA1CLK/R23	P7.2	PWM1				QTR_2	
65	P7.0/PM_DMAE0/PM_SMCLK/R03	P7.0	PWM1				QTR_0	
66	P9.5/UCA3CLK	P9.5			SCLK(x)		LCD_SCLK	
67	P9.7/UCA3TXD/UCA3SIMO	P9.7		TXD(3)	PICO(x)		LCD_MOSI	
68	P7.5/PM_TA1.3/C0.4	P7.5	PWM1				QTR_5	
69	P7.7/PM_TA1.1/C0.2	P7.7	PWM1				QTR_7	
70	P10.1/UCB3CLK	P10.1			SCLK(x)			
71	P10.3/UCB3SCL/UCB3SOMI	P10.3			POCI(x)	SCL(x)		
72	P10.5/TA3.1/C0.6	P10.5					ENCODER_ELA_PIN	

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up to 4 PWM2 outputs

Serial Serial, Serial1, Serial2, Serial3

UART serial communication

SPI, SPI1

SPI serial communication

I2C Wire, Wire1

removed.

I2C serial communication

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functions on the RSLK robot.

Pins connected to on-board components.

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- Do not use with MSP432P4111. These pins used by on-board LCD.
- ² Serial3 only available on MSP432P401R