

Graph 15. Learning with Heterogeneous Graphs (II)

Product Graphs [H Liu & Y Yang. ICML 2015/2016]

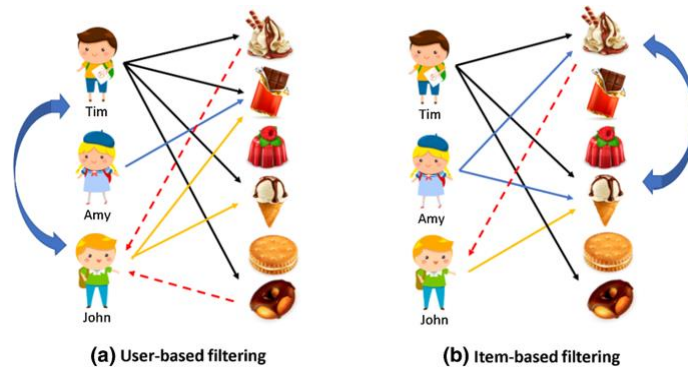
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Motivating Example 1: Recommender System over a Bipartite Graph



Cold Start Issue: Sparse observations on new users/items

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Motivating Example 1 (cont'd)

- **Challenge:** Cold-start issue in recommender systems
- **Remedy:** Using additional information about users and items
 - If user A and user B are friends, they may have similar tastes in watching movies.
 - If movie A and movie B share the same director and/or leading actress, they may be favored by the same user or user group.
- **Graph-based Reasoning**
 - Given a user-user similarity graph (**G1**), an item-item similarity graph (**G2**) and a partially observed bipartite graph (**B**), predict the missing links in B.

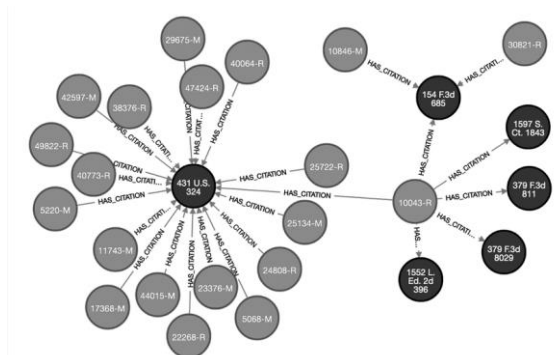
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Motivating Example 2: Publication-related Graphs



Citation Graph (useful for node classification)

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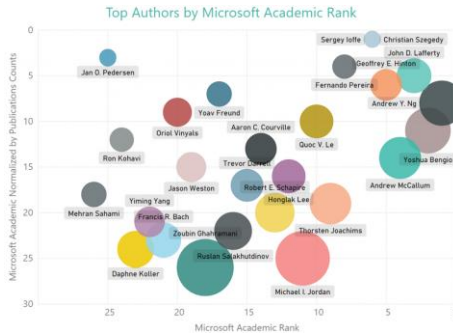
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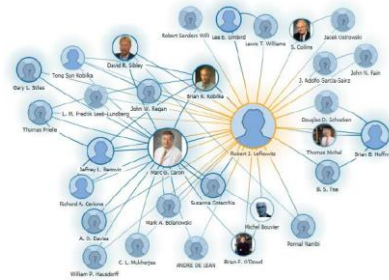
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Motivating Example 2 (cont'd)

Publication-related Graphs



Author-Rank Graph



Co-author Graph

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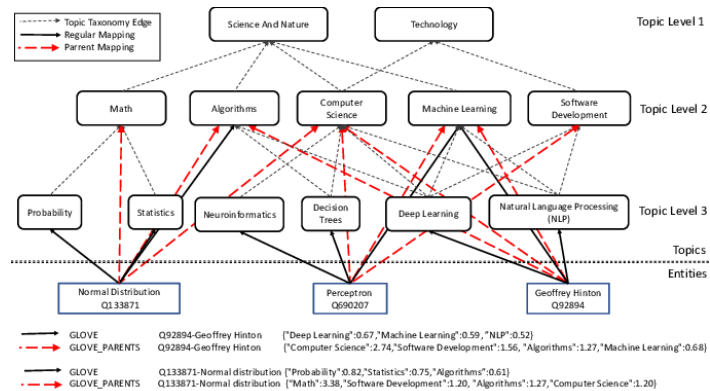
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Motivating Example 2 (cont'd)

Publication-related Graphs



Topic Graph

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Motivating Example 2 (cont'd)

- **Challenge:** Discover the missing ones in publication records
- **Intuitions**
 - If authors A and B had many joint publications in the past, they may have shared interests in future publications.
 - If authors A and B have overlapped a lot on research topics, they are likely to attend the same conferences.
- **Graph-based Reasoning**
 - Given a co-author graph (G_1), a citation graph (G_2), a conference-conference topic-overlap graph (G_3), and a set of observed **multi-relational patterns** (author-topic-conference tuples), predict the tuples which are missing or likely to happen in the future.

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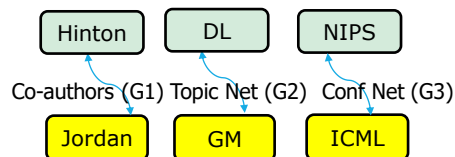
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Generalizing from Link Prediction (Example 1) to Multi-relational Prediction (Example 2)

▪ k-tuples (in a knowledge graph)

E.g., Author-Topic-Conference tuples ($k=3$)



▪ Graph-based prediction Task

- Given a training set of semantically valid tuples and graphs G_1, G_2, G_3, \dots in addition, predict the unobserved semantically valid tuples.

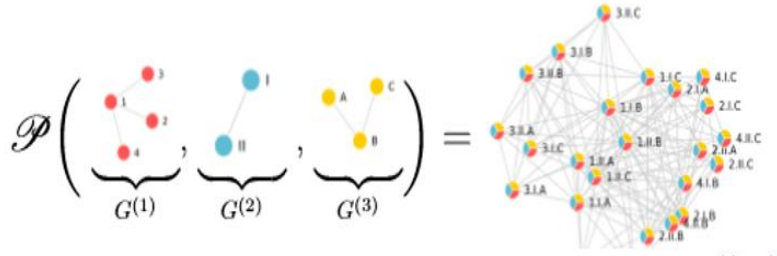
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Product Graph Construction



- Each node in \mathcal{P} is a tuple with one node from each input graph.
- Each edge in \mathcal{P} combines the edge strengths in input graphs as
 - Soft AND (Tensor Product):** If **all** the corresponding links from tuple A to tuple B are strong, then the combined link from A to B in \mathcal{P} is strong (multiplicative);
 - Soft OR (Cartesian Product):** If **any** of the corresponding links from tuple A to tuple B are strong, then the combined link from A to B in \mathcal{P} is strong (additive).

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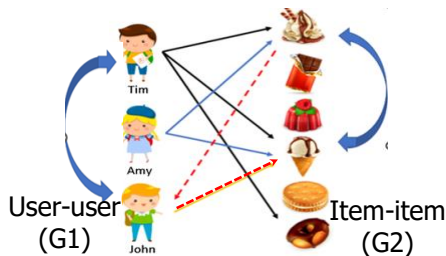
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use soft
And/or
to build
the links.

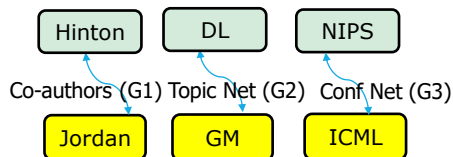
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Combine Evidence in Tuple Predictions

Ex 1. Link Prediction (k=2)



Ex 2. Triplet Prediction (k=3)



- Soft AND** (Tensor Product) or **Soft OR** (Cartesian Product)

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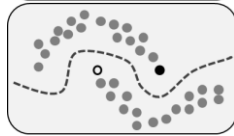
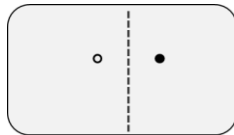
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Recap: SSL for Classification

- With or without Semi-Supervised Learning (SSL)



(from Wikipedia)

- Conventional SVM

$$\min_f \mathcal{L}_o(f) + c \|f\|_K^2$$

- Laplacian SVM

$$\min_f \mathcal{L}_o(f) + c_1 \|f\|_K^2 + c_2 \frac{l}{(l+u)^2} f^T L f$$

- Smoothness Penalty:** $f^T L f$ forces well-connected nodes to have similar scores in f .

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Our Objective for Optimization

- Define our objective as

$$\min_f l_o(f) + C f^T A^{-1} f$$

where $f \in \mathbb{R}^n$ consists of the system-assigned scores to nodes in \mathcal{P} .

- Term $f^T A^{-1} f$ means to assume a Gaussian prior for f

$$f \sim N(0, A), \quad \log P(f) \propto -f^T A^{-1} f$$

- Minimizing $f^T A^{-1} f$ is equivalent to maximizing the log-likelihood of the system-predicted scores based on the Gaussian prior.

- Intuition:** we want similar scores to nearby nodes based on MD distance (instead of Euclidian distance).

is proportional

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Related Concept: Mahalanobis Distance (MD)

https://en.wikipedia.org/wiki/Mahalanobis_distance

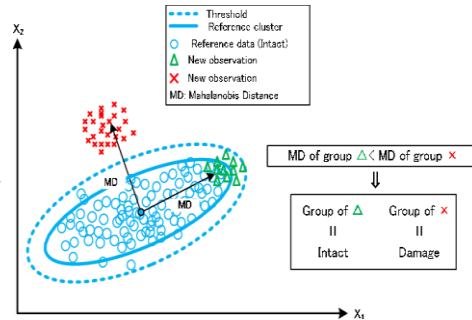
MD Definitions:

$$d(x, y) = \sqrt{(x - y)^T \Sigma^{-1} (x - y)}$$



$$d(x, \mu) = \sqrt{(x - \mu)^T \Sigma^{-1} (x - \mu)}$$

where Σ is the covariance matrix of some underlying Gaussian distribution.



https://www.researchgate.net/profile/Chul_Woo_Kim/pub668639590088740@1536427509947/Concept-of-Mahalanobis-distance-MD.png/figure/fig7/AS:

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Two Basic Product Graphs

Let $v = (v_1, v_2, \dots, v_J)$ and $v' = (v'_1, v'_2, \dots, v'_J)$ are two nodes in \mathcal{P}_{\otimes} .

- **Tensor Product** (mimicking **SOFT AND**)

$$\mathcal{P}_{\otimes} = G_1 \otimes G_2 \cdots \otimes G_J; \quad A_{\otimes}(v, v') = \prod_{i=1}^J A_{G_i}(v_i, v'_i)$$

- link weight $A_{\otimes}(v, v')$ is strong iff $A_{G_i}(v_i, v'_i)$ is strong for **all** G 's.

- **Cartesian Product** (mimicking **SOFT OR**).

$$\mathcal{P}_{\oplus} = G_1 \oplus G_2 \cdots \oplus G_J; \quad A_{\oplus}(v, v') = \sum_{j=1}^J A_{G_j}(v_j, v'_j)$$

- link weight $A_{\oplus}(v, v')$ is strong iff $A_{G_j}(v_j, v'_j)$ is strong for **any** G 's.

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Enriched Formulation: $A \rightarrow \kappa(A)$

Basic Objective: $\min_f l_o(f) + \lambda f^T A^{-1} f$

Enriched Objective: $\min_f l_o(f) + \lambda f^T \kappa(A)^{-1} f$

Enhancing smoothness via multi-hop propagation:

$\kappa_{rw}(A) = A^k$ for k -step random walk

$\kappa_{von_Neumann}(A) = (I - A)^{-1} = I + A + A^2 + \dots$ for infinite walk

$\kappa_{heat}(A) = e^A = I + A + \frac{1}{2!}A^2 + \frac{1}{3!}A^3 + \dots$ for weight-decayed walk

...

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Spectral Graph Product (SGP)

- Use the eigen-systems of the individual input graphs to construct the eigen-system of \mathcal{P}

- The eigenvectors

$$\{v\} = \{v_i^{(G_1)} \otimes v_j^{(G_2)} \otimes v_k^{(G_3)} \dots\}$$

- The eigenvalues

$$\{\lambda\} = \{\kappa(\lambda_i^{(G_1)}, \lambda_j^{(G_2)}, \lambda_k^{(G_3)}, \dots)\}$$

- The adjacency matrix

$$A_{\kappa} = \sum_{i_1, i_2, \dots, i_j=1}^{n_1, n_2, \dots, n_j} \kappa(\lambda_{i_1}^{(G_1)}, \lambda_{i_2}^{(G_2)}, \lambda_{i_3}^{(G_3)}, \dots) \{v_{i_1}^{(G_1)} \otimes v_{i_2}^{(G_2)} \otimes v_{i_3}^{(G_3)} \dots\}$$

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is the new graph

Different kernels in SGP

- Denote mapping function κ as

$$\kappa: \{\lambda_i^{(G1)}, \lambda_j^{(G2)}, \lambda_k^{(G3)}, \dots\} \rightarrow \mathbb{R}$$

- $\kappa_{\otimes}(\cdot) = \lambda_i^{(G1)} \times \lambda_j^{(G2)} \times \dots$ for $\mathcal{P}_{\otimes} = G_1 \otimes G_2 \otimes \dots$ (Tensor Product)
- $\kappa_{\oplus}(\cdot) = \lambda_i^{(G1)} + \lambda_j^{(G2)} + \dots$ for $\mathcal{P}_{\oplus} = G_1 \oplus G_2 \oplus \dots$ (Cartesian Product)
- For other graph products ... (next slide)

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Different kernel maps in SGP

- k-step Random Walk**

$$\kappa_{rw}(A) \triangleq A^k; \quad \lambda_i \rightarrow \lambda_i^k$$

- Infinite Walk (von Neumann Kernel)**

$$\kappa_{von_Neumann}(A) \triangleq (I - A)^{-1} = I + A + A^2 + \dots; \quad \lambda_i \rightarrow (1 - \lambda_i)^{-1}$$

- Wight-decayed Walk (Heat Diffusion Kernel)**

$$\kappa_{heat}(A) \triangleq e^A = I + A + \frac{1}{2!}A^2 + \frac{1}{3!}A^3 + \dots; \quad \lambda_i \rightarrow e^{\lambda_i}$$

Operator over eigenvalues can be multiplicative (for \mathcal{P}_{\otimes}) or additive (for \mathcal{P}_{\oplus}).

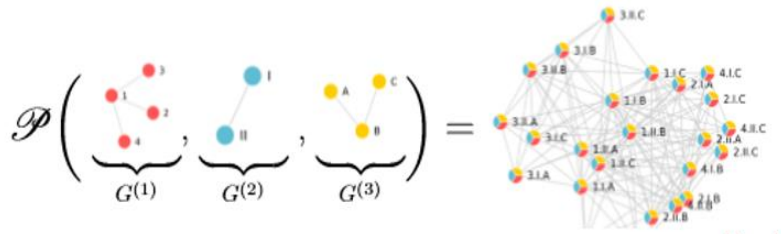
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Computational Tractability?



- # of nodes in \mathcal{P} is $N = n_1 \times n_2 \times n_3 \dots$
- # of edges is N^2

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Computational Tractability

- We need to solve the problem *without explicitly* constructing \mathcal{A} of \mathcal{P}
- Divide-&-conquer Strategy
 - Solving the *eigen-decomposition* of each graph independently
 - Approximation f via *Low-rank Tensor Decomposition*

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Calculating smoothness penalty

$$A = V\Lambda V^T = \sum_{i=1}^N \lambda_i v_i v_i^T$$

$$A^{-1} = (V^T)^{-1} \Lambda^{-1} V^{-1} = V \Lambda^{-1} V^T = \sum_{i=1}^N \frac{v_i v_i^T}{\lambda_i}$$

$$\kappa(A)^{-1} = \sum_{i=1}^N \frac{v_i v_i^T}{\kappa(\lambda_1, \lambda_2, \dots, \lambda_N)}$$

$$f^T \kappa(A)^{-1} f = \sum_{i=1}^N \frac{f^T v_i v_i^T f}{\kappa(\lambda_1, \lambda_2, \dots, \lambda_N)} = \sum_{i=1}^N \frac{\|f^T v_i\|^2}{\kappa(\lambda_1, \lambda_2, \dots, \lambda_N)}$$

$$= \sum_{i_1, i_2, \dots, i_J=1}^{n_1, n_2, \dots, n_J} \frac{\left(\text{TensorProd} \left(f; v_{i_1}^{(G1)}, v_{i_2}^{(G2)}, \dots, v_{i_J}^{(GJ)} \right) \right)^2}{\kappa \left(\lambda_{i_1}^{(G1)}, \lambda_{i_2}^{(G2)}, \dots, \lambda_{i_J}^{(GJ)} \right)}$$

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Calculating the Smoothness Penalty

$$f^T A^{-1} f = \sum_{i_1, i_2, \dots, i_J=1}^{n_1, n_2, \dots, n_J} \frac{\left(\text{TensorProd} \left(f; v_{i_1}^{(G1)}, v_{i_2}^{(G2)}, \dots, v_{i_J}^{(GJ)} \right) \right)^2}{\kappa \left(\lambda_{i_1}^{(G1)}, \lambda_{i_2}^{(G2)}, \dots, \lambda_{i_J}^{(GJ)} \right)}$$

$$\approx \sum_{i_1, i_2, \dots, i_J=1}^{k_1, k_2, \dots, k_J} \frac{\left(\text{TensorProd} \left(\alpha; v_{i_1}^{(G1)}, v_{i_2}^{(G2)}, \dots, v_{i_J}^{(GJ)} \right) \right)^2}{\kappa \left(\lambda_{i_1}^{(G1)}, \lambda_{i_2}^{(G2)}, \dots, \lambda_{i_J}^{(GJ)} \right)}$$

J-mode Product on the full tensor, taking time of $O \left(\left(\sum_{j=1}^J n_j \right) \prod_{j=1}^J n_j \right)$

J-mode Product on the core tensor with $k_i = d, \forall i$, taking time of $O(d^{J+1})$, $d \ll n_j$

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Low-rank Tensor Approximation

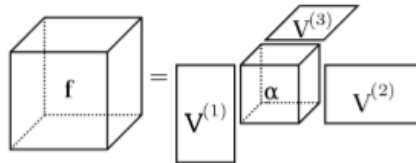


Figure: Tucker Decomposition, where α is the core tensor.

- Tensor algebras are carried out on GPU.

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Smoothing Effect (a simulated example)

Low-rank approx. prunes off the high-volatility factors (eigen-vectors)

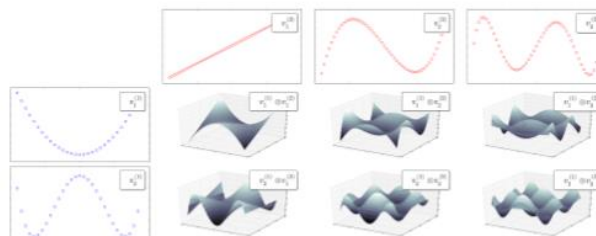


Figure: Eigenvectors of G_1 (blue), G_2 (red) and $\mathcal{P}(G_2)$.

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Evaluation

Datasets

Enzyme 445 compounds, 664 proteins.

DBLP 34K authors, 11K papers, 22 venues.

Representative Baselines

TF/GRTF Tensor Factorization/Graph-Regularized TF

NN One-class Nearest Neighbor

RSVM Ranking SVMs

LTKM Low-Rank Tensor Kernel Machines

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State-of-the art (SOTA) Performance

Our method: “TOP” (blue).

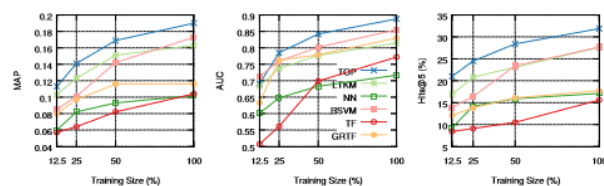
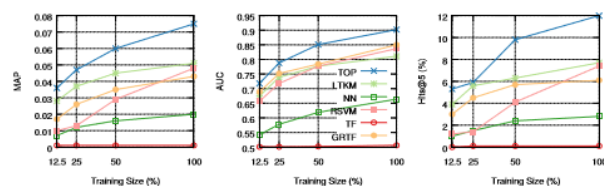


Figure: Performance on Enzyme (above) and DBLP (below).



Enzyme: predicting compound-protein interactions (link prediction)

DBLP: predicting Author-Paper- Conference triplets

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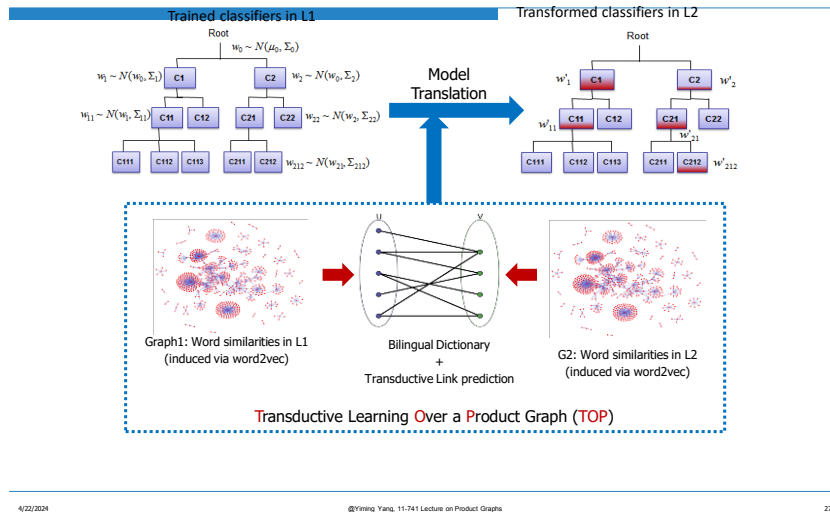
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Cross-Language Topic Model Translation

(R Xu et al., ACL'16)



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Concluding Remarks

- **Challenge in multi-relational prediction**
 - Lack of sufficient labeled training data for link/tuple prediction
- **Remedy**
 - Leveraging heterogeneous graphs to enable SSL
- **Contributions**
 - **Novel unified framework** for integrating heterogeneous types of graph into a product graph
 - **Scalable algorithms** for extreme-scale convex optimization via tensor-based approximation
 - **State-of-the-art performance** on evaluation benchmarks
- **Limitation:** No learning of edge weights; manually specified kernels

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References

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- T. G. Kolda, B. W. Bader. Tensor Decompositions and Applications. *SIAM Review*, Vol. 51, No. 3, pp. 455-500, 2009. <https://doi.org/10.1137/07070111X>

