

Graph-based Machine Learning

Analogy for Knowledge Base Completion

(H Liu et al. ICML 2017)

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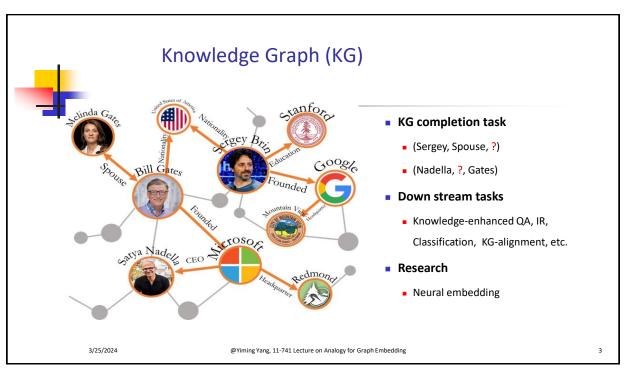


Outline

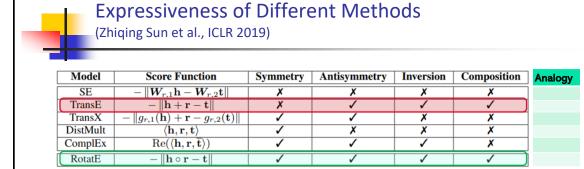
- Recap of KG completion methods (previous lecture)
- Analogy Modeling (Hanxiao Liu, et al., ICML 2017)

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- What method is missing above?
- How the above methods related to KE-GCN?

 $-log\sigma(y \mathbf{h}^T W_r \mathbf{t})$

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Analogy

(ICML'2017)

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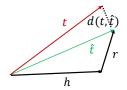
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Recap of TransE (Bordels et al., NIPS 2013)

- Learning a real vector embedding for each entity and relation
- Predicting the missing element in (h, r, ?) by calculating $f(h, r) = h + r \triangleq \hat{t}$
- Minimizing distance $d(t,\hat{t}) = ||t \hat{t}|| = ||h + r t||$ during training (iterative optimization of embedding vectors)



Vector \mathbf{r} is added to vector \mathbf{h} .

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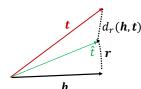
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Recap of RotatE (Zhiqing Sun et al., ICLR 2019)

- Learning a complex vector embedding for each entity and relation
- Predicting the missing element in (h,r,?) by calculating $f(h,r) = h \circ r \triangleq \hat{t}$
- Minimizing distance $d_r(\pmb{h}, \pmb{t}) = \|\pmb{h} \circ \pmb{r} \pmb{t}\|$ during training



r is a unit-length rotation operator

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Important Types of KG Relations

- Symmetric (h and t) (H Liu, ICML 2017)
 - $\phi(h, r, t) = \phi(t, r, h)$, e.g., marriage, divorce
- Antisymmetric (h and t) (H Liu, ICML 2017)
 - $\phi(h, r, t) \gg \phi(t, r, h)$, e.g., a-parent-of
- Inversive (r and r') (H Liu, ICML 2017)
 - $\phi(h,r,t) = \phi(h,r',t)$, e.g., hypernym (r) vs. hyponym (r')
- Compositive (or "transitive") (r and r') (Z Sun, ICLR 2019)
 - $\phi(a,r,b) \times \phi(b,r',c) = \phi(a,r \circ r',c)$, e.g., my mother's husband is my father
- Commutative (r and r'): $r \circ r' = r' \circ r$ (H Liu, ICML 2017)
 - $\phi(a,r\circ r',d)=\phi(a,r'\circ r,d)$, e.g., king to queen as man to women

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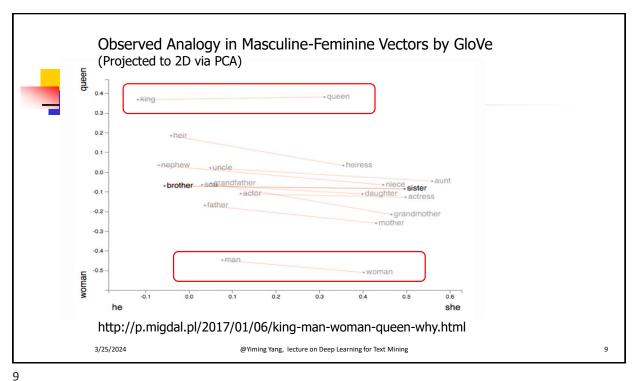


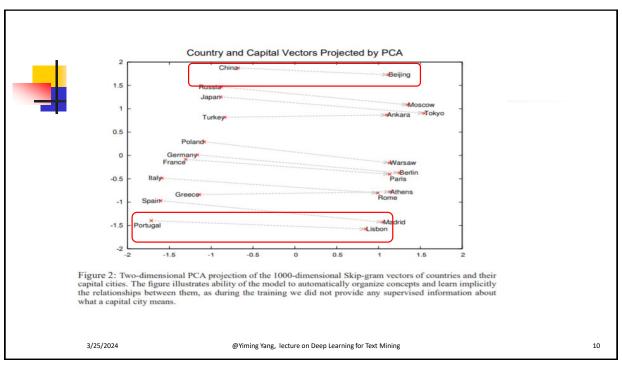
Outline

- Recap of KG completion methods (previous lecture)
- Analogical inference for multi-relational embeddings (H Liu, et al., ICML 2017)
 - Mathematical modeling of analogy with differentiable optimization
 - A unified framework subsuming several representative methods
 - Fast algorithm for linear scalability

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Geometric Property of Analogy

 If two systems form an analogy, then understanding one of them would help the understanding of the other.

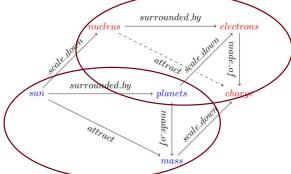


Figure: Solar System (red) v.s. Rutherford-Bohr Model (blue).

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Notation

- Triplet (s, r, o) is any subject-relation-object (or head-relation-tail) combinations;
- Labeled training set $\mathcal{D} = \{((s, r, o), y)\}$ with $y = \pm 1$ as the labels (positive vs. negative);
- Vectors $v_s \in \mathbb{R}^d$ and $v_o \in \mathbb{R}^d$ are the learned embeddings for s and o, respectively;
- Matric $W_r \in \mathbb{R}^{d \times d}$ is the learned embedding of relation r;
- Boldfaced v is the collection of the vector embeddings for all entities in D;
- Boldfaced \mathbf{W} is the collection of the matrix embeddings for all relations in \mathcal{D} .

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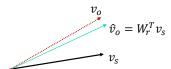
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Treating Relation as a Linear Translation Operator

• Linear transformation (via W_r^T) from v_s to v_o



• For each semantically valid triplet (s, r, o), we want

$$W_r^T v_s = \hat{v}_o \approx v_o \tag{1}$$

Scoring Function (higher is better):

$$\phi(s,r,o) = \langle W_r^T v_s, v_o \rangle = v_s^T W_r v_o = v_0^T W_r^T v_s$$
 (2)

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Constrained Optimization

$$\min_{v,W} \mathbb{E}_{((s,r,o),y)\in\mathcal{D}} l(\phi_{v,W}(s,r,o),y)$$
 (3)

$$s.t. W_r W_r^T = W_r^T W_r, \forall r (4)$$

$$W_r W_{r,} = W_{r,} W_{r,} \ \forall r, r' \tag{5}$$

- Formula (4) restricts the matrices to be in the normality family;
- Formula (5) restricts the matrices to have the commutative property;
- Together they define the desirable properties of relations.

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Normal Matrices (Formula 4)

• Def. A linear transformation W_r which satisfies

$$W_r^T W_r = W_r W_r^T \tag{4}$$

Properties ("well-behaved")

• Symmetric:
$$W_r = W_r^T$$
 (4a)

 $\phi(s,r,o) = \phi(o,r,s)$ (e.g., r = "is-married-to")

• Anti-symmetric:
$$W_r = -W_r^T$$
 (4b)

$$\phi(s,r,o) = -\phi(o,r,s)$$
 (e.g., "is-parent-of")

"Inversive"
$$\rightarrow$$
 Orthogonal (bijective): $W_r^T W_r = I$ or $W_r^T = W_r^{-1}$ (4c)

- Useful for one-to-one mapping in both directions

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Concrete Example: Parent-child Relationship

• As an anti-symmetric relationship, its embedding should satisfy the equality below

$$W_r = -W_r^T \tag{4b}$$

This yields $\phi(s,r,o) = -\phi(o,r,s)$, which is the definition of anti-symmetric relation.

■ Proof

$$\phi(s,r,o) \stackrel{\text{\tiny def}}{=} \langle W_r^T v_s, v_o \rangle = \langle v_o, W_r^T v_s \rangle = v_o^T W_r^T v_s \quad \text{(dot-product is symmetric)}$$

$$\phi(o,r,s) \stackrel{\text{\tiny def}}{=} \langle W_r^T v_o, v_s \rangle = v_o^T \ W_r v_s = -v_o^T W_r^T v_s \quad \text{(substituting } W_r \text{ by } -W_r^T \text{ in 4b)}$$

 $\phi(s,r,o) = -\phi(o,r,s) \qquad \text{("A is a parent of B."} \to \text{"B is not a parent of A.")}$

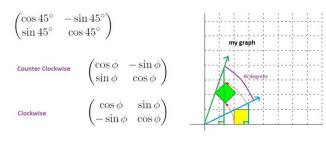
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Bijective vs. "Inversive"

- Orthogonal (bijective): $W_r^T W_r = I$ or $W_r^T = W_r^{-1}$ (4c)
 - Useful for one-to-one mapping in both directions
- Equivalent to the "inversive relationship" (between r1 and r2) in Z Sun ICLR 2019
 - r_1 and r_2 are inverse if and only if $\mathbf{r}_1 \circ r_2 = \mathbf{1}$ or $\mathbf{r}_2 = \overline{\mathbf{r}_1}$ or $\boldsymbol{\theta}_2 = -\boldsymbol{\theta}_1$



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Commutativity (Formula 5)

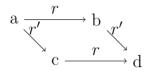
Notice that commutativity is a necessary condition for analogy.

$$W_r W_{r\prime} = W_{r\prime} W_{r\prime}, \quad \forall r, r' \tag{5}$$

Equivalently, we can express this property as

$$r \circ r' = r' \circ r \quad \forall r, r'$$

• Geometrically, r, r' define a parallelogram



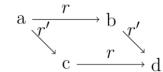
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Concrete Example of Analogical Structure

- Well-known example
 - "man is to king as woman is to queen"
- Abstract notion
 - "a is to b as c is to d"



(4)

• Geometrically, consider that r and r' define a parallelogram, where we have

$$\phi(a, r \circ r', d) = \phi(a, r' \circ r, d)$$

In words, analogy is defined by the commutativity of relations.

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Computational Challenge

$$\min_{v,W} \mathbb{E}_{((s,r,o),y)\in\mathcal{D}} l(\phi_{v,W}(s,r,o),y)$$

s.t.
$$W_rW_r^T = W_r^TW_r$$
, $\forall r$

$$W_r W_{r,l} = W_{r,l} W_{r,l} \quad \forall r, r' \tag{5}$$

- Good news: Our objective is differentiable (supporting gradient descend).
- Bad news: The number of constraints can be very large (quadratic in the # of relations), and each relation has a dense-matrix representation.

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The Remedy?

Lemma 4.1. (Wilkinson & Wilkinson, 1965) For any real normal matrix A, there exists a real orthogonal matrix Q and a block-diagonal matrix B such that $A = QBQ^{\top}$, where each diagonal block of B is either (1) A real scalar, or (2) A 2-dimensional real matrix in the form of $\begin{bmatrix} x & -y \\ y & x \end{bmatrix}$, where both x, y are real scalars.

The lemma suggests any real normal matrix can be blockdiagonalized into an almost-diagonal canonical form.

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The Magic?

ullet We can rotate the vectors using matrix Q as

$$\forall r, \ \phi(s,r,o) = v_s^T W_r v_o = \underbrace{v_s^T Q^T}_{v_s'} B_r \underbrace{Q v_0}_{v_0'} = v_s'^T B_r v_0'$$

where B_r has 1×1 or 2×2 non-zero diagonal blocks and zero's anywhere else.

Now, we can solve the optimization problem for $\{v'\}$ and $\{B_r\}$ instead of $\{v\}$ and $\{W_r\}$ in the original objective function.

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Replacing dense w_r by sparse w_r'

Original Objective

$$\min_{v,W} \mathbb{E}_{((s,r,o),y)\in\mathcal{D}} l(\phi_{v,W}(s,r,o),y)$$

New Equivalent Objective

$$\min_{v',B} \mathbb{E}_{((s,r,o),y) \in \mathcal{D}} l(\phi_{v',B_r}(s,r,o),y)$$

where each $B_r \in \mathbf{B}$ is a block-diagonal whose block sizes are bounded by 2.

Time/Space Saving

 $O(d^2) \rightarrow O(d)$ where d is the embedding size.

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Implementation Details

Use logistic loss

$$l(\phi(s,r,o),y) = -log\sigma(y\phi(s,r,o))$$
 $y \in \{\pm 1\}$

- Optimization algorithm
 - Asynchronous AdaGrad
- Negative training instances
 - For each valid (s, r, o), generate the negative examples (s', r, o), (s, r', o) and (s, r, o') by corrupting s, r, o, respectively.

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Analogy subsumes other well-known methods

Multiplicative Embedding (DistMult by Yang et al. CoRR 2014)

$$\phi(s,r,o) = \langle v_s, v_r, v_o \rangle$$
 where $v_s, v_r, v_o \in \mathbb{R}^d$

- equivalent to Analogy by setting $W_r \stackrel{\text{def}}{=} diag(v_r)$ as a special case
- Complex Embedding (Complex by Trouillon et al, ICML 2016)

$$\phi(s,r,o) = RealPart(v_s, v_r, \overline{v_o})$$
 where $v_s, v_r, v_o \in \mathbb{C}^d$

where <., ., .> denote the generalized dot-product.

■ The solution can be fully recovered by Analogy with embedding size of 2d because any complex number a+bj is isomorphic to the 2×2 matrix $\begin{pmatrix} a & -b \\ b & a \end{pmatrix}$.

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Analogy subsumes other well-known methods (cont'd)

Holographic Embeddings (HolE by Nickel et al., AAAI 2016)

$$\phi(s,r,o) = \langle v_s, v_r * v_o \rangle$$

where v_s, v_r , $v_o \in \mathbb{R}^d$ and * denotes circular correlation.

This is equivalent to solving

$$\phi(s,r,o) = RealPart(\langle v_s, v_r, \overline{v_o} \rangle)$$

where $v_s, v_r, v_o \in FFT(\mathbb{R}^d) \in \mathbb{C}^d$ are the Fast Fourier Transform of real vectors.

Hence, HolE is a restricted case of Complex and ANALOGY.

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Evaluation Results (Hanxiao Liu et al., ICML 2017)

- Use Mean Reciprocal Rank (MRR) and Hits@k as the metrics
- Benchmark datasets of FreeBase-15K and WordNet-18

	WN18			FB15K				
Models	MRR (filt.)	MRR (raw)	Hits@1 (filt.)	Hits@3 (filt.)	MRR (filt.)	MRR (raw)	Hits@1 (filt.)	Hits@3 (filt.)
RESCAL	89.0	60.3	84.2	90.4	35.4	18.9	23.5	40.9
TransE	45.4	33.5	8.9	82.3	38.0	22.1	23.1	47.2
DistMult HolE ComplEx	82.2 93.8 94.1	53.2 61.6 58.7	72.8 93.0 93.6	$91.4 \\ 94.5 \\ 94.5$	65.4 52.4 69.2	$24.2 \\ 23.2 \\ 24.2$	54.6 40.2 59.9	73.3 61.3 75.9
Our ANALOGY	94.2	65.7	93.9	94.4	72.5	25.3	64.6	78.5

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Merged Results of ICML 2017 (H Liu) & ICLR 2019 (Z Sun)

Let's focus on Mean Reciprocal Rank (MRR) only

Models	WN18 (2017)	WN18 (2019)	FB15k (2017)	FB15k (2019)
RESCAL	89	-	-	-
TransE	45.4	49.5	38.0	46.3
DistMult	82.2	79.7	65.4	79.8
HolE	93.8	93.8	52.4	52.4
ComplEx	94.1	94.1	69.2	69.2
ANALOGY	94.2	-	72.5	
ConvE	-	94.3		65.7
RotatE	-	94.9		79.9

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Concluding Remarks

- Analogy can be formulated geometrically in a real vector space, supporting differentiable optimization of KG embedding with linear scalability.
- It provides a unified framework for several representative KG embedding methods.
- Limitation: Cannot model compositional relations? (we omit detailed discussion)
- Connection/difference from KE-GCN
 - All the KG completion methods are designed without consideration of downstream tasks, but KE-GCN is.

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KG-embedding Methods vs. KE-GCN

KG-embedding methods (e.g., Analogy)

$$\min_{v,W} \mathbb{E}_{((s,r,o),y)\in\mathcal{D}} l(\phi_{v,W}(s,r,o),y)$$

KE-GCN for multi-class classification

$$\mathcal{L} = -\sum_{(\boldsymbol{X}_{i}, \boldsymbol{Y}_{i}) \in \mathcal{D}_{l}} \sum_{j=1}^{K} \boldsymbol{Y}_{ij} \ln \hat{Y}_{ij}$$

KE-GCN for cross-language KG Alignment

$$\mathcal{L} = -\sum_{(u,v)\in S} \sum_{(u',v')\in S'} [\|h_u - h_v\|_1 - \|h_{u'} - h_{v'}\|_1 + \gamma]$$

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Is the winning method for KG-completion necessarily be the best choice for down-stream tasks?

Table 11: Entity classification accuracy results over 5 different runs on AM and WN datasets by incorporating different knowledge graph embedding methods into our model.

KE-GCN (X)	AM	WN
X = TransE	91.2 ± 0.2	57.8 ± 0.5
X = TransH	90.5 ± 0.3	57.4 ± 0.3
X = DistMult	89.5 ± 0.4	56.4 ± 0.1
X = TransD	90.1 ± 0.2	57.1 ± 0.2
X = RotatE	90.6 ± 0.4	56.6 ± 0.3
X = QuatE	91.0 ± 0.4	56.9 ± 0.3

Table 4: Knowledge graph entity alignment results over 5 different runs on $\rm DBP_{ZH-EN}$ by incorporating different knowledge graph embedding methods into our model.

KE-GCN (X)	MRR	H@1	H@10
X = TransE	0.648 ± 0.003	54.3 ± 0.3	83.4 ± 0.3
X = TransH	0.650 ± 0.003	54.3 ± 0.4	84.4 ± 0.3
X = DistMult	0.621 ± 0.003	52.0 ± 0.4	80.3 ± 0.4
X = TransD	0.635 ± 0.003	53.1 ± 0.3	82.7 ± 0.4
X = RotatE	0.653 ± 0.004	54.9 ± 0.4	83.8 ± 0.4
X = QuatE	$\boldsymbol{0.664 \pm 0.004}$	$\textbf{56.2} \pm \textbf{0.4}$	84.2 ± 0.4

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KE-GCN uses KG-embedding methods as building blocks

Node embedding at each layer

$$\boldsymbol{h}_{v}^{(k+1)} = \sigma_{ent} \left(W_{0}^{(k)} \; \boldsymbol{h}_{v}^{(k)} + \sum_{(u,r) \in N_{in}(v)} W_{1}^{(k)} \frac{\partial f_{in} \left(\boldsymbol{h}_{u}^{(k)}, \boldsymbol{h}_{r}^{(k)}, \boldsymbol{h}_{v}^{(k)}\right)}{\partial \boldsymbol{h}_{v}^{(k)}} + \sum_{(u,r) \in N_{out}(v)} W_{2}^{(k)} \frac{\partial f_{out} \left(\boldsymbol{h}_{u}^{(k)}, \boldsymbol{h}_{r}^{(k)}, \boldsymbol{h}_{v}^{(k)}\right)}{\partial \boldsymbol{h}_{v}^{(k)}} \right)$$

• For example, we can define f_{in} as

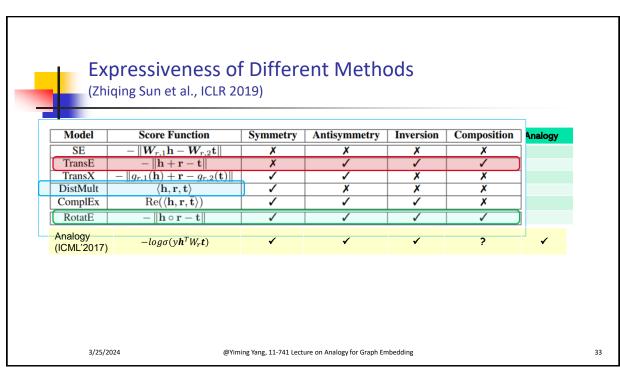
$$f_{in}\left(\pmb{h}_{u}^{(k)}, \pmb{h}_{r}^{(k)}, \pmb{h}_{v}^{(k)}\right) \triangleq \pmb{h}_{u}^{(k)} \cdot \pmb{h}_{r}^{(k)} \cdot \pmb{h}_{v}^{(k)} \triangleq \sum_{i=1}^{d} h_{ui}^{(k)} \; h_{ri}^{(k)} \; h_{vi}^{(k)} \in \mathbb{R}$$

$$\frac{\partial f_{in}(h_u^{(k)},h_r^{(k)},h_v^{(k)})}{\partial \boldsymbol{h}_r^{(k)}} = \boldsymbol{h}_u^{(k)} \circ \boldsymbol{h}_r^{(k)} \in \mathbb{R}^d \qquad (\circ \text{ is the Hadamard product})$$

- Instead of directly aggregating neighbor vector $\mathbf{h}_u^{(k)} \in N_{in}(v)$, we aggregate after it's "convoluted" by $\mathbf{h}_r^{(k)}$.
- In other words, the neighborhood signal passing is "conditioned on" edge embeddings for $(u,r) \in N_{in}(v)$.
- We can replace $f = \left(\mathbf{h}_u^{(k)} \cdot \mathbf{h}_r^{(k)} \cdot \mathbf{h}_v^{(k)} \right)$ above by any function $\phi\left(\mathbf{h}_u^{(k)}, \mathbf{h}_r^{(k)}, \mathbf{h}_v^{(k)} \right)$ in a KG-embedding method.

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 Hanxiao Liu, Yuexin Wu, Yiming Yang. Analogical inference for multi-relational embeddings. ICML 2017.

 Zhiqing Sun, Zhi-hone Deng, Jian-yun Nie, Jian Tang. RotatE: Knowledge Graph Embedding by Relational Rotation in Complex Space. ICLR 2019.

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