DL: Сверточные сети Детектирование объектов

План

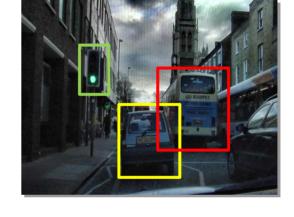
- Семантическая сегментация
- Детектирование
- Извлечение точек
- Трекинг

Детектирование объектов

Исходное изображение



ROI detection

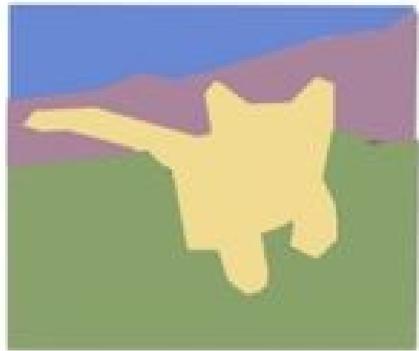


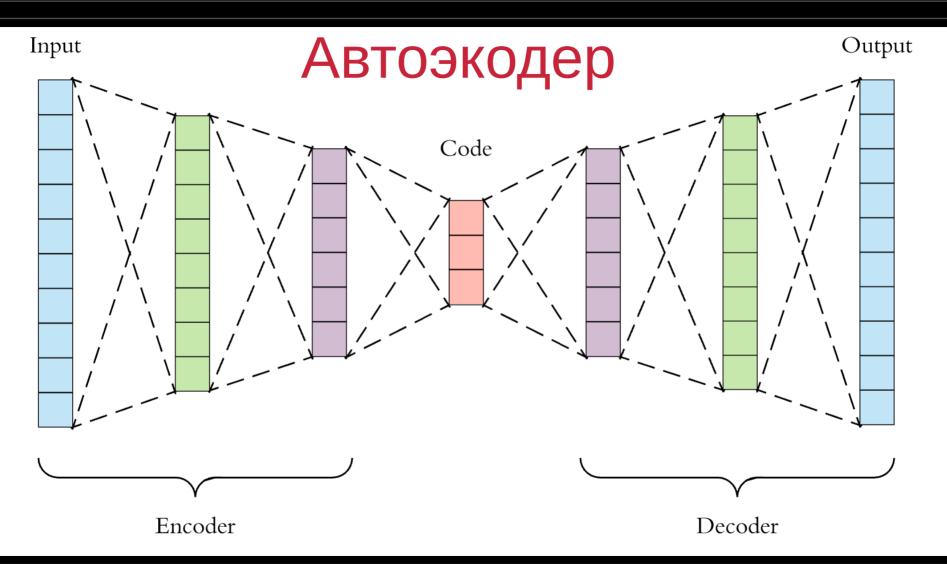
Pixel classification

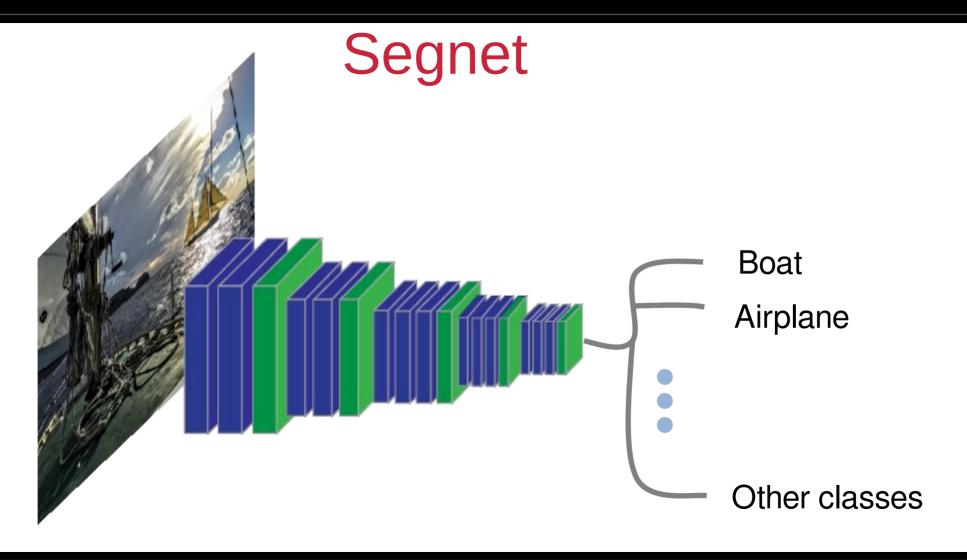


Семантическая сегментация

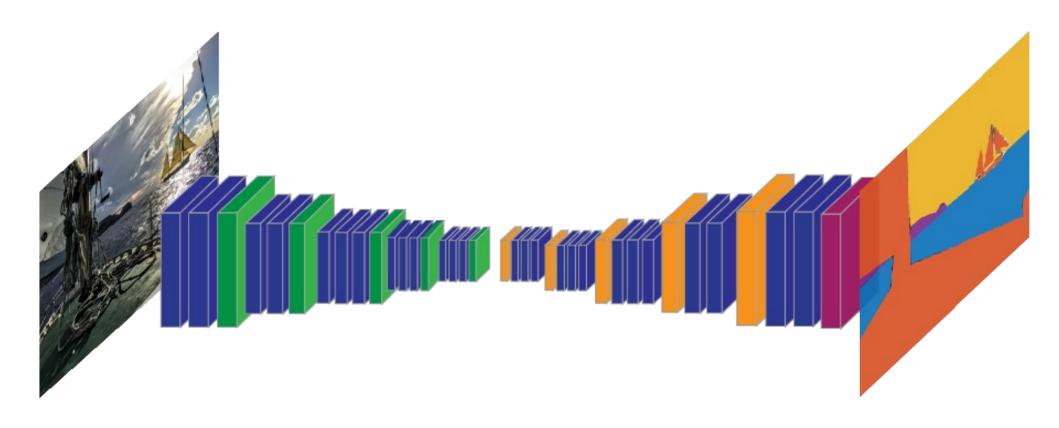




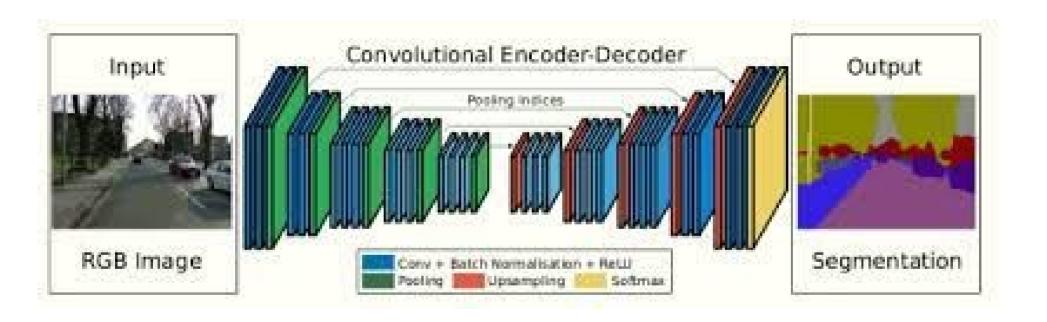




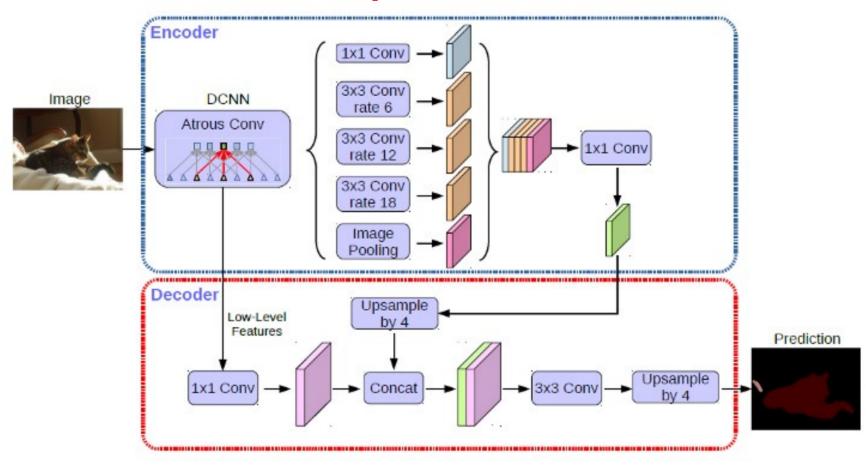
Segnet



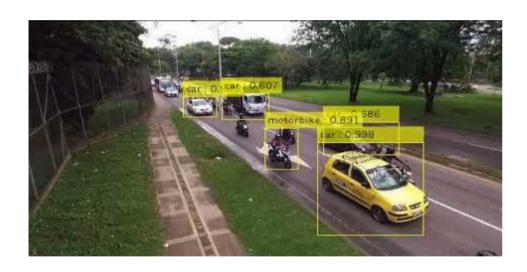
Unet

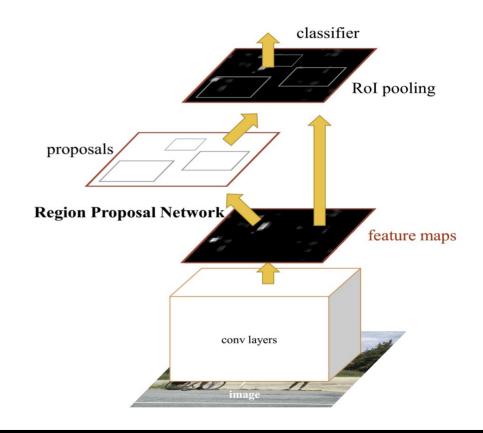


DeepLabv3

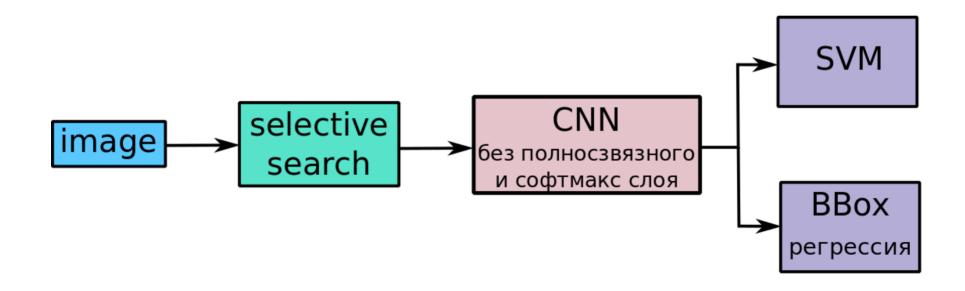


Детектирование объектов

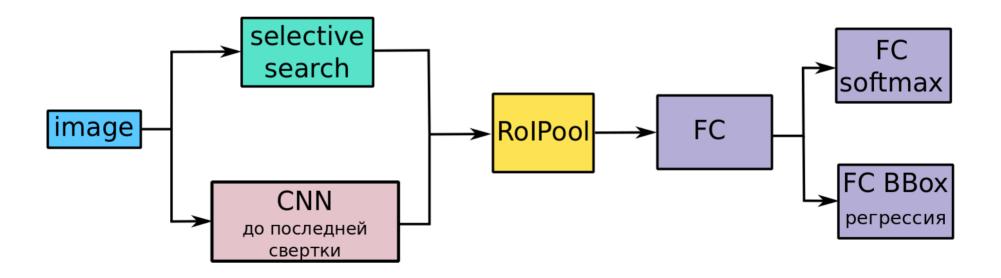




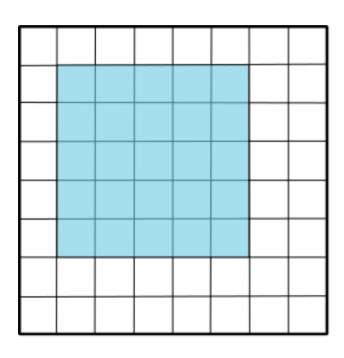
Детектирование объектов: R-CNN

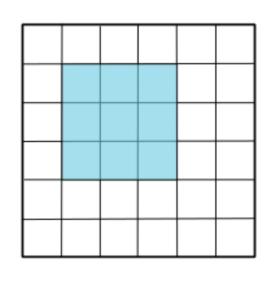


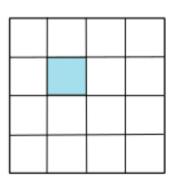
Детектирование объектов: Fast R-CNN



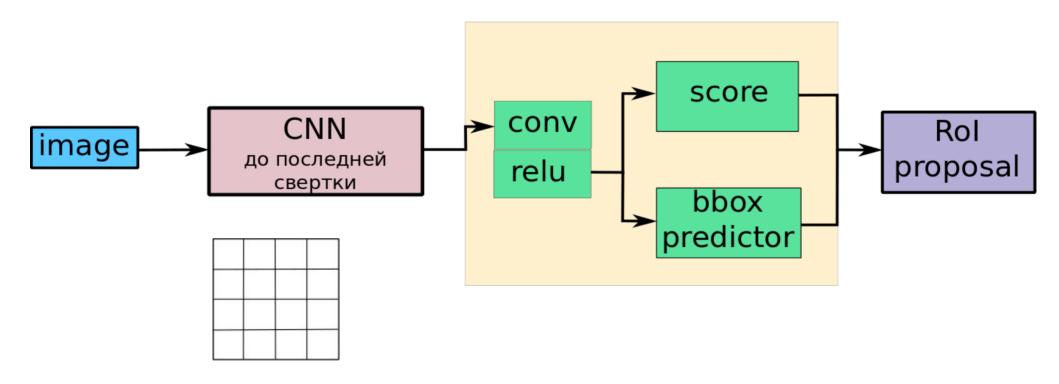
Fast R-CNN: Roi Pooling



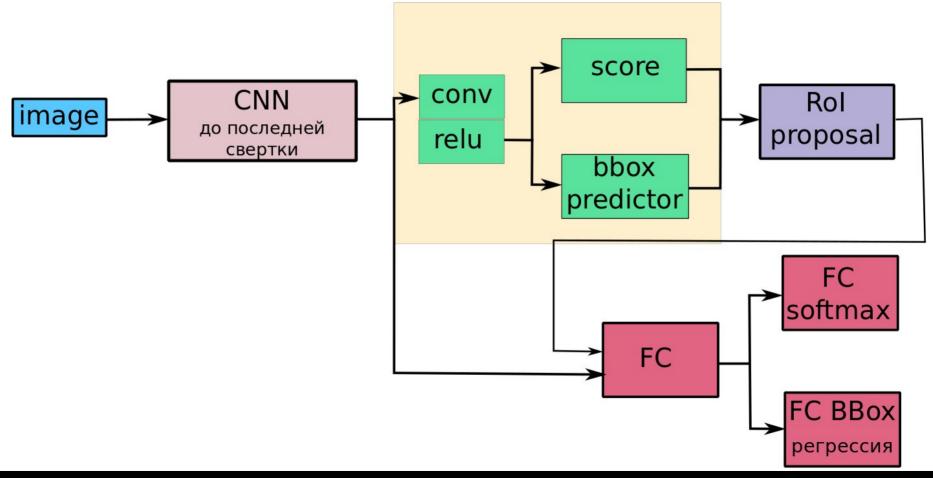


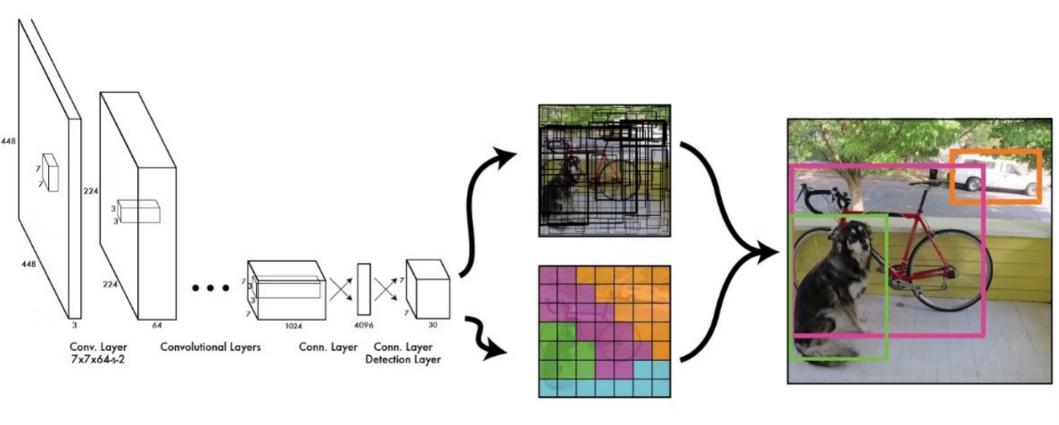


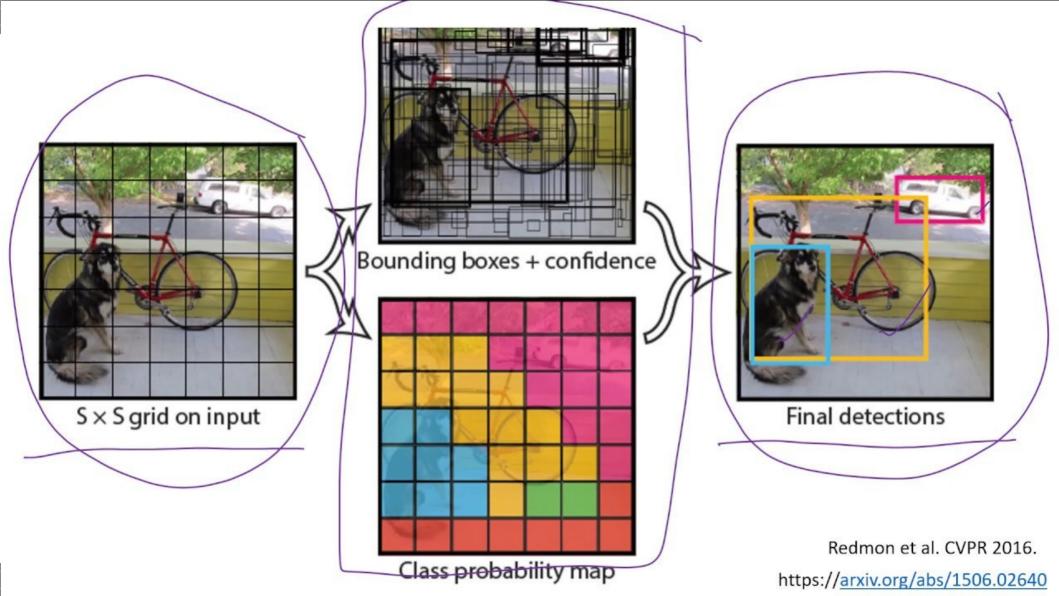
Детектирование объектов: Faster R-CNN

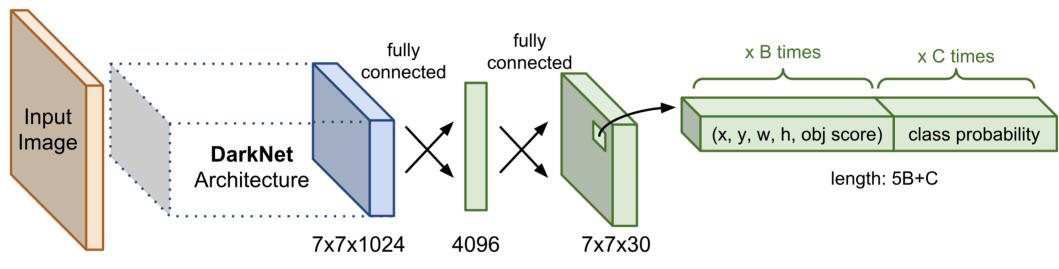


Детектирование объектов: Faster R-CNN

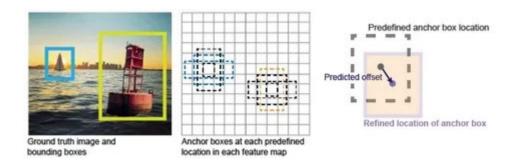


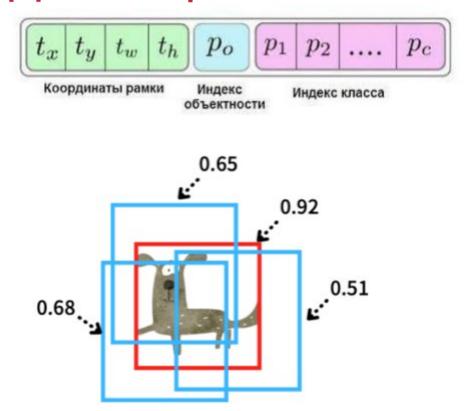


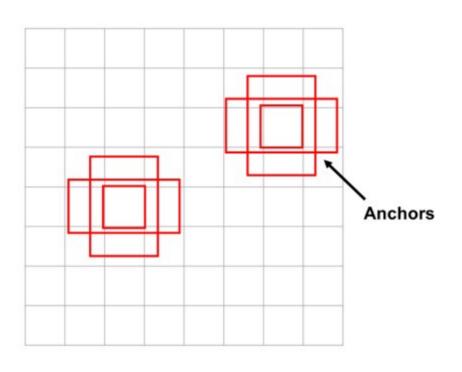


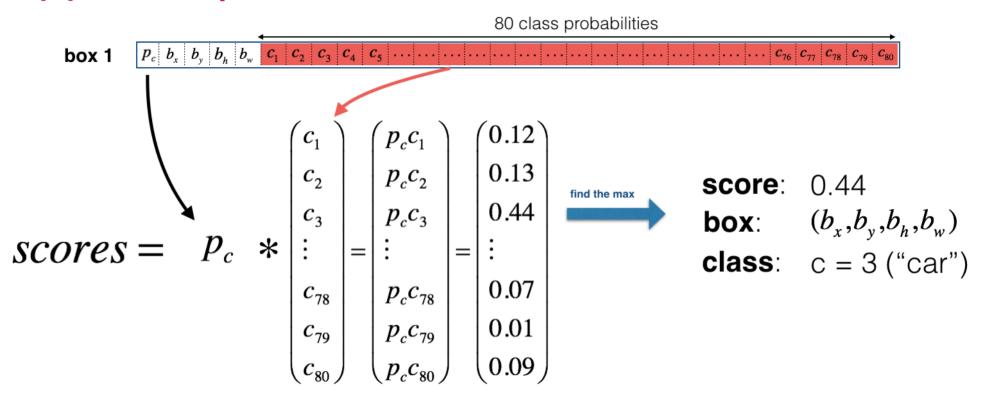


448x448x3



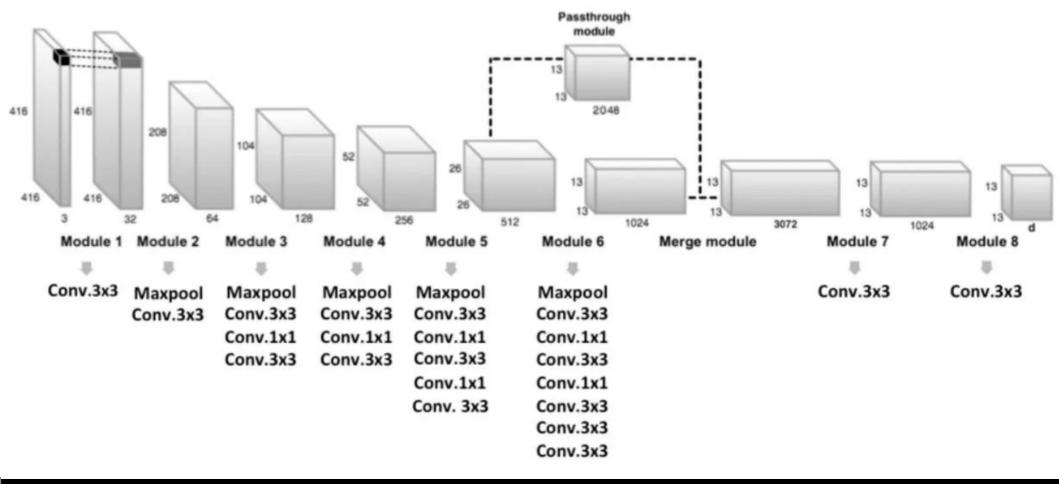


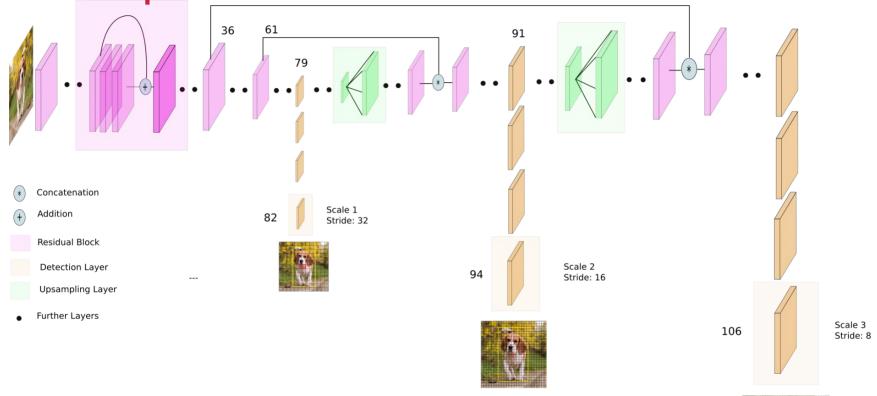




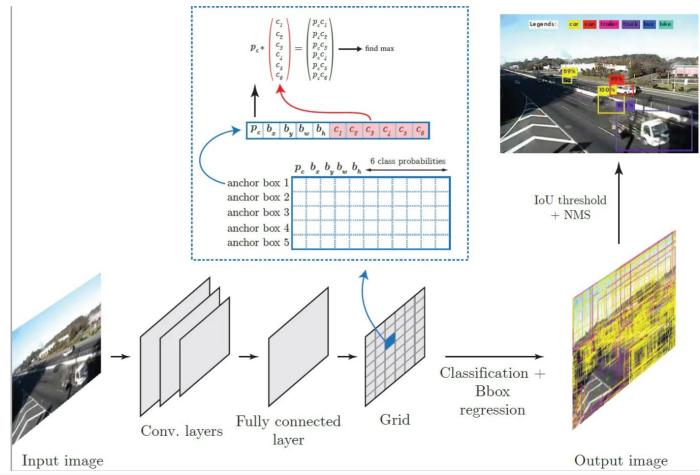
the box (b_x, b_y, b_h, b_w) has detected c = 3 ("car") with probability score: 0.44







YOLO v3 network Architecture

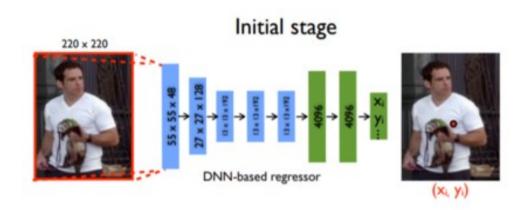


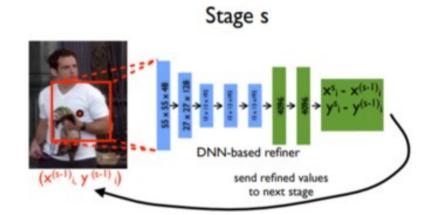
Pose estimation



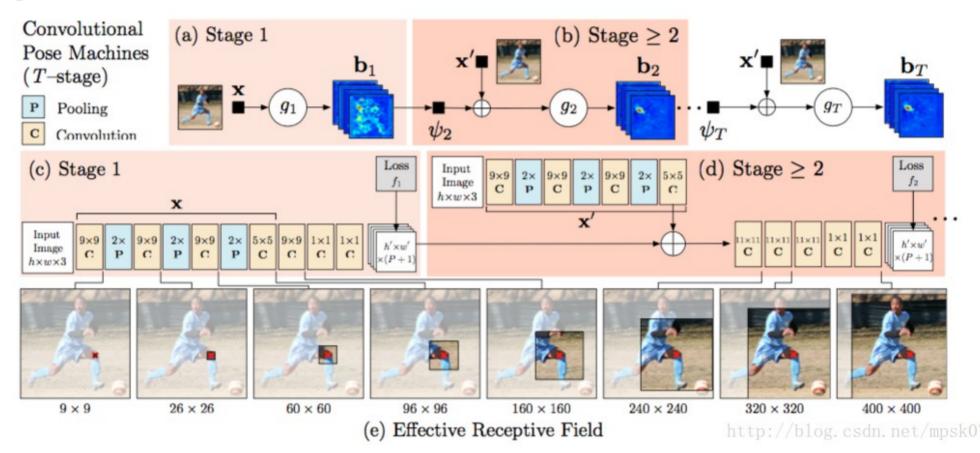
https://nanonets.com/blog/human-pose-estimation-2d-guide/

CPM

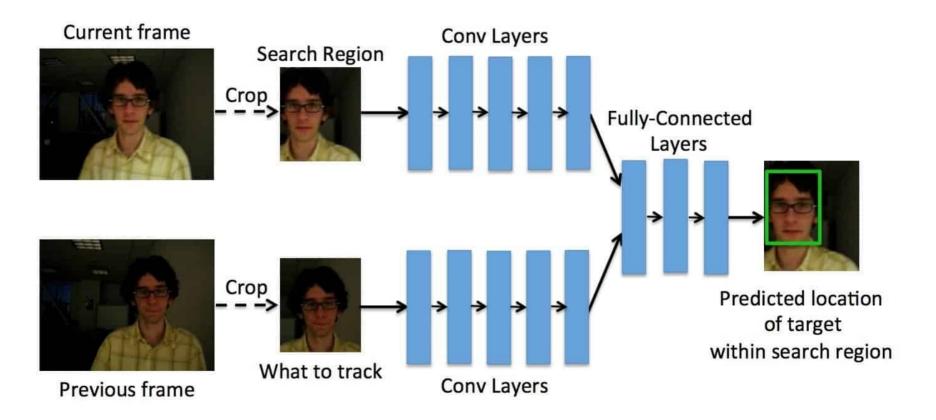




CPM



Трекинг



Трекинг

