

Adapting Swarm Application

A Systematic and Quantitative Approach

Ben Zhang

December 6, 2019

TerraSwarm Research Center

<https://github.com/nebgnahz/dissertation-talk>

Table of contents

1. Introduction to the Swarm
2. Network Resource Adaptation
3. Compute Resource Adaptation
4. Conclusion and Acknowledgement

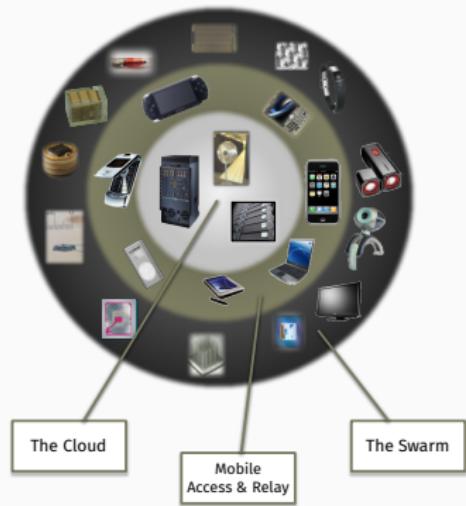
Introduction to the Swarm

The Swarm at the Edge of the Cloud



J. Rabaey, ASPDAC'08

The Swarm at the Edge of the Cloud



Swarm, or

- Internet of Things (IoT)
- Internet of Everything (IoE)
- Industry 4.0
- The Industrial Internet
- TSensors (Trillion Sensors)
- Machine to Machine (M2M)
- Smarter Planet

J. Rabaey, ASPDAC'08

The Swarm at the Edge of the Cloud



J. Rabaey, ASPDAC'08

Swarm, or

- Internet of Things (IoT)
- Internet of Everything (IoE)
- Industry 4.0
- The Industrial Internet
- TSensors (Trillion Sensors)
- Machine to Machine (M2M)
- Smarter Planet



The Swarm at the Edge of the Cloud



J. Rabaey, ASPDAC'08

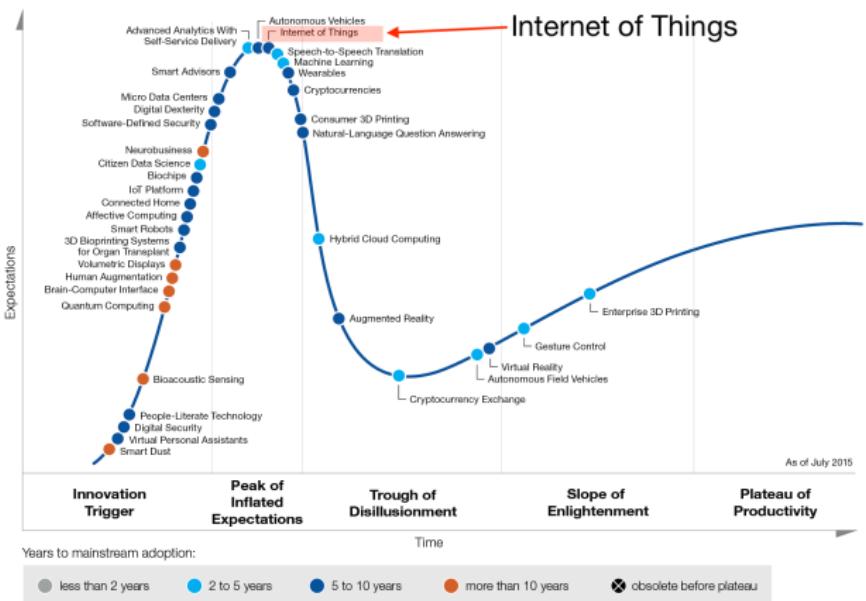
Swarm, or

- Internet of Things (IoT)
- Internet of Everything (IoE)
- Industry 4.0
- The Industrial Internet
- TSensors (Trillion Sensors)
- Machine to Machine (M2M)
- Smarter Planet



Gartner Hype Cycle (2015)

Emerging Technology Hype Cycle

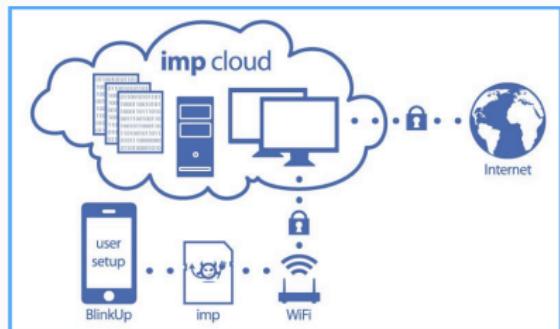


gartner.com/SmarterWithGartner

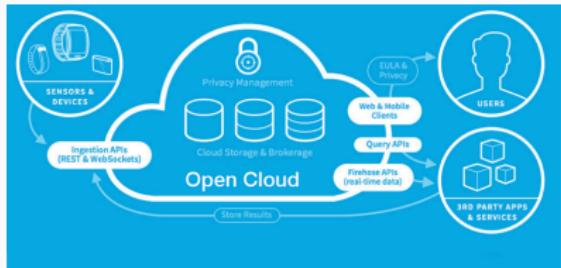
© 2015 Gartner, Inc. and/or its affiliates. All rights reserved.

Gartner

A Cloud-centric Approach



(a) Electric Imp

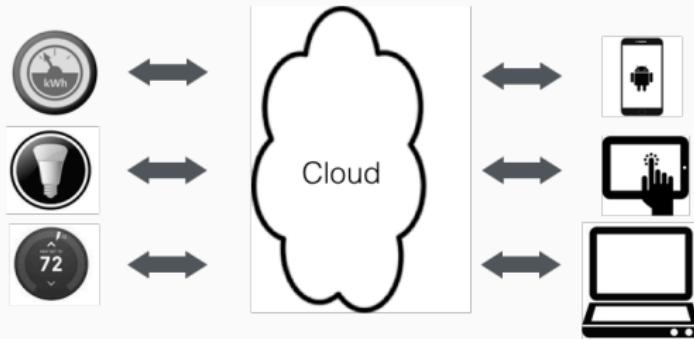


(b) Samsung SAMI

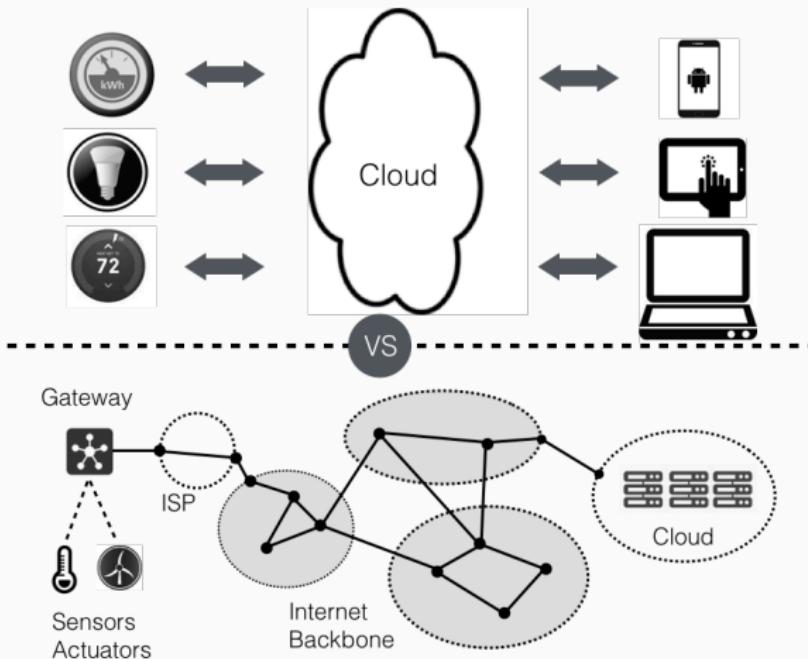


(c) Ninja Sphere

“The Cloud”: Model vs. Reality



“The Cloud”: Model vs. Reality



The Cloud is Not Enough

	Web/IT	Swarm/IoT
Privacy & Security	Open for access	Sensitive data
Scalability	Power law	Billion devices
Interaction Model	Human	Machine
Latency	Variable	Bounded
Bandwidth	Downstream	Upstream
Availability (QoS)	No guarantee	Requirement
Durability Management	Cloud controls	Users control

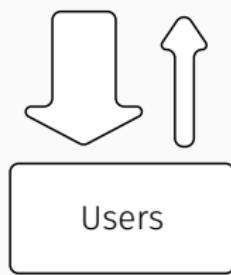
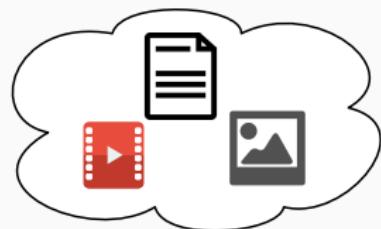
Pitfalls with Today's Approach to IoT [Zhang et al., 2015]

The Cloud is Not Enough

	Web/IT	Swarm/IoT
Privacy & Security	Open for access	Sensitive data
Scalability	Power law	Billion devices
Interaction Model	Human	Machine
Latency	Variable	Bounded
Bandwidth	Downstream	Upstream
Availability (QoS)	No guarantee	Requirement
Durability Management	Cloud controls	Users control

Pitfalls with Today's Approach to IoT [Zhang et al., 2015]

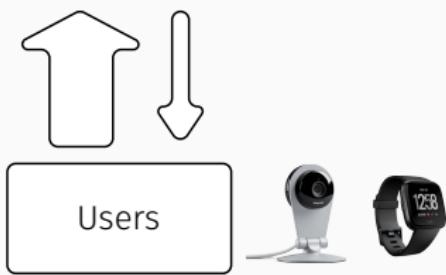
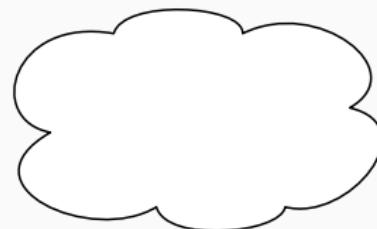
Bandwidth: Downstream vs. Upstream



Downstream

Upstream

Web/IT



Upstream

Downstream

Swarm/IoT

Network Resource Adaptation

Limited Network Resource

Demand

Huge Data Volume at the Edge

Resource

Insufficient WAN Bandwidth

Limited Network Resource

Demand

Huge Data Volume at the Edge

Resource

Insufficient WAN Bandwidth

- Video surveillance, 3 mbps per camera [Amerasinghe, 2009]
- Electrical grid monitoring, 1.4 million data points per second [Andersen and Culler, 2016]
- Machine logs, 25 TB daily at Facebook (2009)

Limited Network Resource

Demand

Huge Data Volume at the Edge

Resource

Insufficient WAN Bandwidth

... *Dropcam*, a WiFi video-streaming camera and associated cloud backend service for storing and watching the resulting video. Dropcam has *the fewest clients* (2,940) Yet, each client uses roughly *2.8 GB* a week and uploads *nearly 19 times more* than they download, implying that Dropcam users do not often watch what they record.

Large-scale Measurements of Wireless Network Behavior

[Biswas et al., 2015]

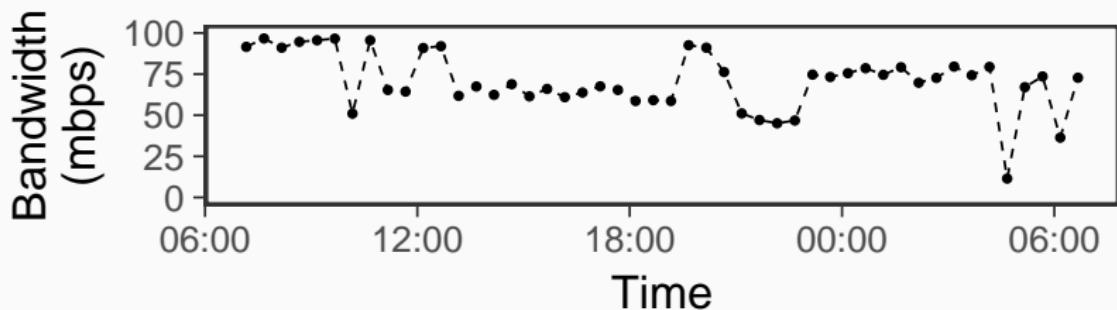
Limited Network Resource

Demand

Huge Data Volume at the Edge

Resource

Insufficient WAN Bandwidth



Bandwidth variations throughout the day between Amazon EC2 sites. Similar scarcity and variation for wireless networks, broadband access networks and cellular networks ([backup slides](#)).

Limited Network Resource

Demand

Huge Data Volume at the Edge

Resource

Insufficient WAN Bandwidth

What about edge processing? (I will cover in the second half of this talk).

But communication is not avoidable.

- Large performance gap between the cloud and the edge (GPU/TPU/ASIC).
- Aggregation is sometimes necessary in applications.
- Last-hop wireless may become the bottleneck.

Fidelity vs. Freshness

When the network resource is not sufficient:

- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss

Fidelity vs. Freshness

When the network resource is not sufficient:

- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal

Fidelity vs. Freshness

When the network resource is not sufficient:

- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal
 - JetStream [Rabkin et al., 2014] uses manual policy
 - “if bandwidth is insufficient, switch to sending images at 75% fidelity, then 50% if still not enough”

Fidelity vs. Freshness

When the network resource is not sufficient:

- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal
- Application-specific optimizations don't generalize

Fidelity vs. Freshness

When the network resource is not sufficient:

- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal
- Application-specific optimizations don't generalize
 - Video streaming often aims at Quality of Experience (limited degradation dimension, e.g. maintain 25FPS)
 - For object detection, resolution matters more than FPS

Fidelity vs. Freshness

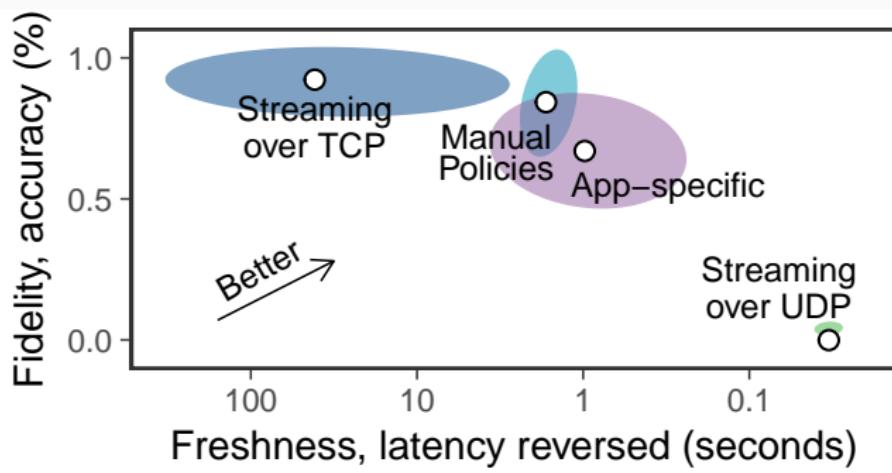
When the network resource is not sufficient:

- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal
- Application-specific optimizations don't generalize

Fidelity vs. Freshness

When the network resource is not sufficient:

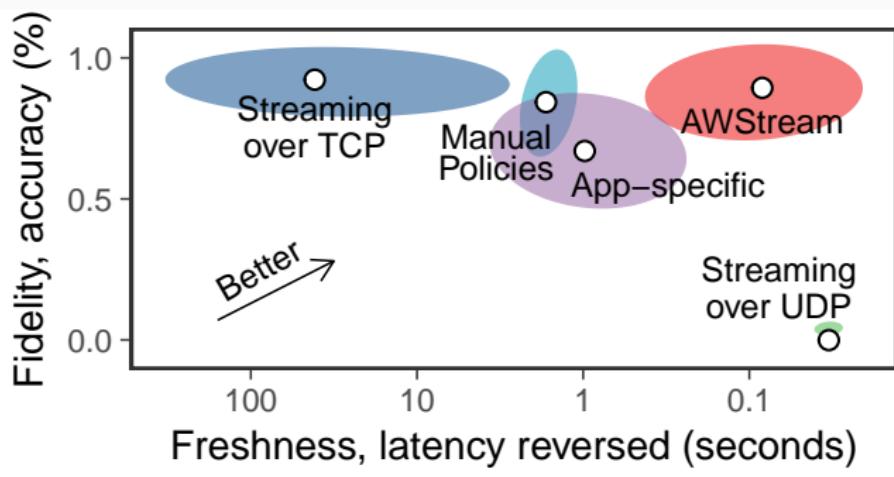
- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal
- Application-specific optimizations don't generalize



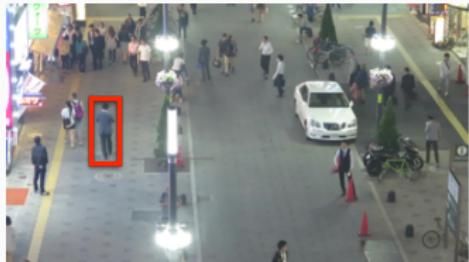
Fidelity vs. Freshness

When the network resource is not sufficient:

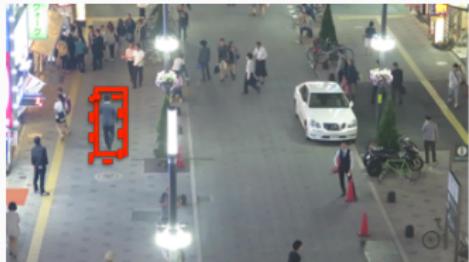
- TCP ensures data delivery, but hurts latency
- UDP sends as fast as possible, uncontrolled packet loss
- Manual policies (developer heuristics) are sub-optimal
- Application-specific optimizations don't generalize



Application-specific Optimizations Don't Generalize

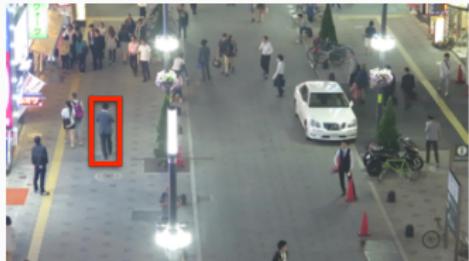


t=0s, small target in far-field views

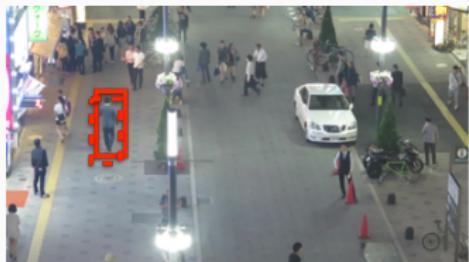


t=1s, small difference

Application-specific Optimizations Don't Generalize



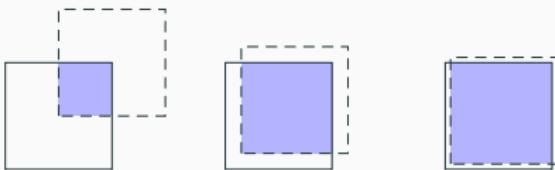
t=0s, small target in far-field views



t=1s, small difference

Positive if intersection over union (IOU)
larger than 0.5.

$$\text{IOU} = \frac{\text{Area of Intersection}}{\text{Area of Union}}$$

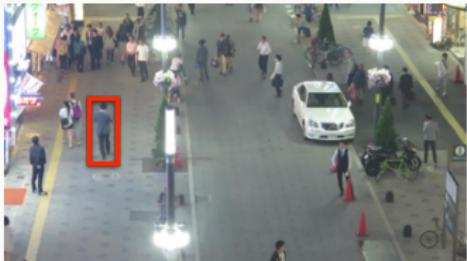


(a) IOU=0.14

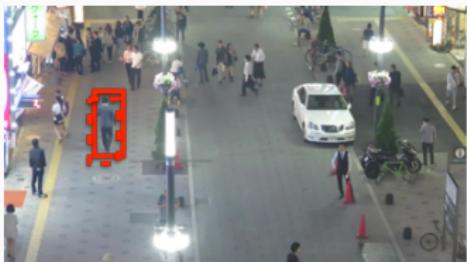
(b) IOU=0.57

(c) IOU=0.82

Application-specific Optimizations Don't Generalize



t=0s, small target in far-field views



t=1s, small difference

F1 score is the harmonic mean of precision and recall, ranging from 0 to 1:

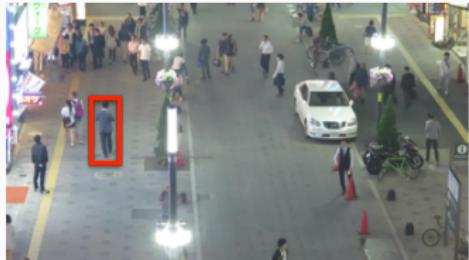
	P	N
Y	True Positive	False Positive
N	False Negative	True Negative

$$\text{Precision} = \frac{\text{true positive}}{\text{all positive}}$$

$$\text{Recall} = \frac{\text{true positive}}{\text{all detection}}$$

$$F1 = \frac{2}{\frac{1}{\text{Recall}} + \frac{1}{\text{Precision}}}$$

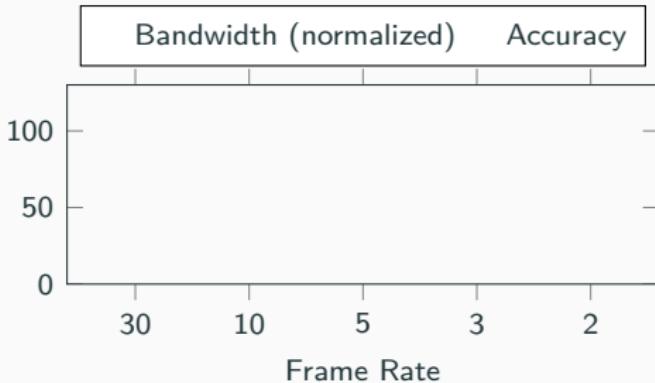
Application-specific Optimizations Don't Generalize



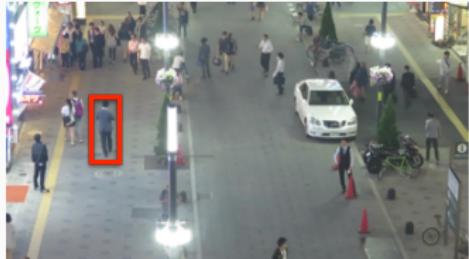
$t=0s$, small target in far-field views



$t=1s$, small difference



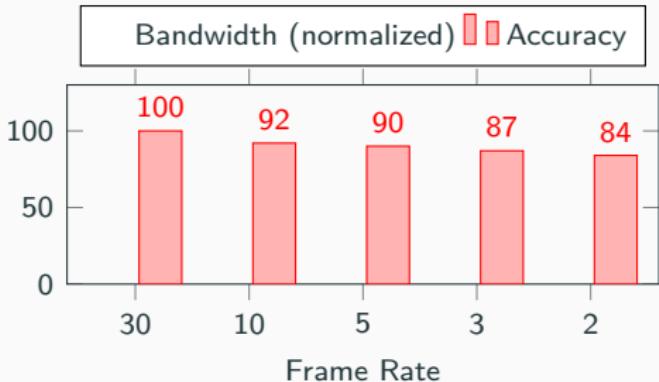
Application-specific Optimizations Don't Generalize



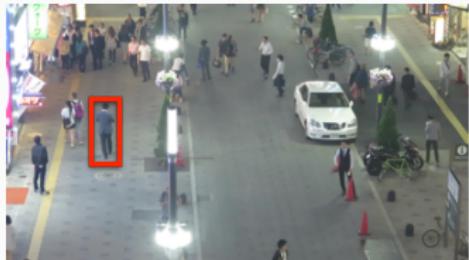
t=0s, small target in far-field views



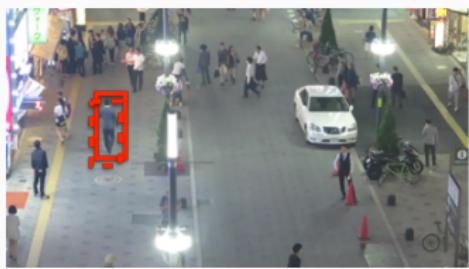
t=1s, small difference



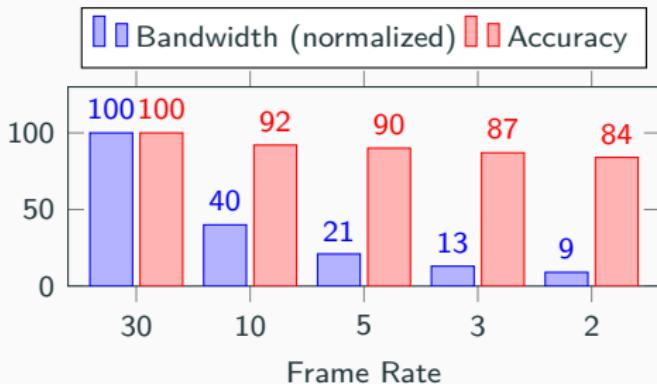
Application-specific Optimizations Don't Generalize



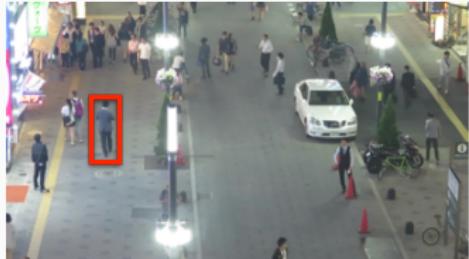
t=0s, small target in far-field views



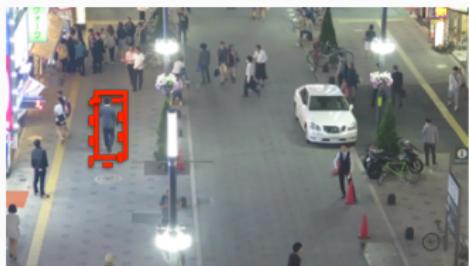
t=1s, small difference



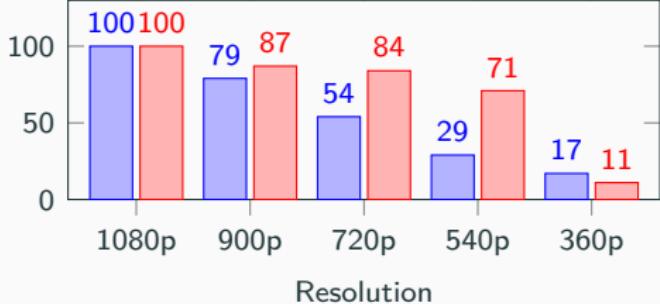
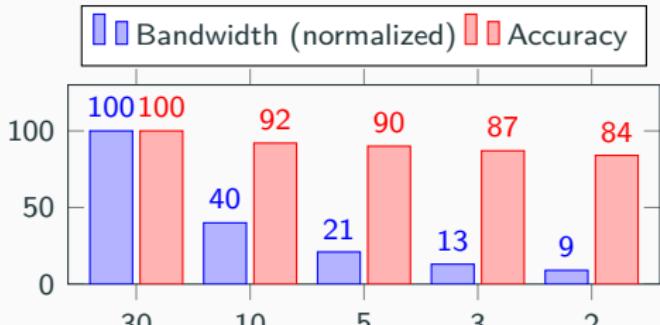
Application-specific Optimizations Don't Generalize



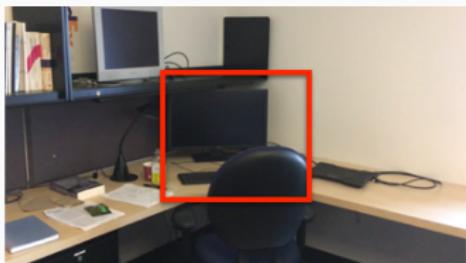
t=0s, small target in far-field views



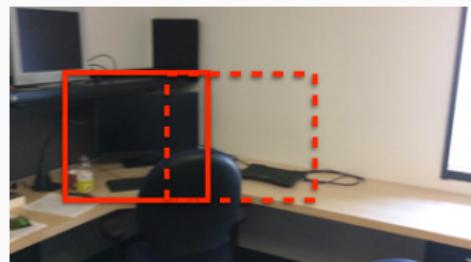
t=1s, small difference



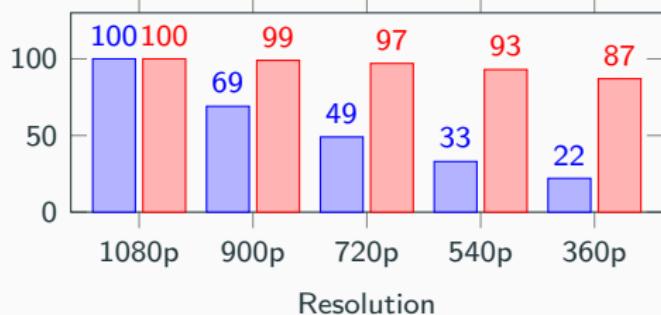
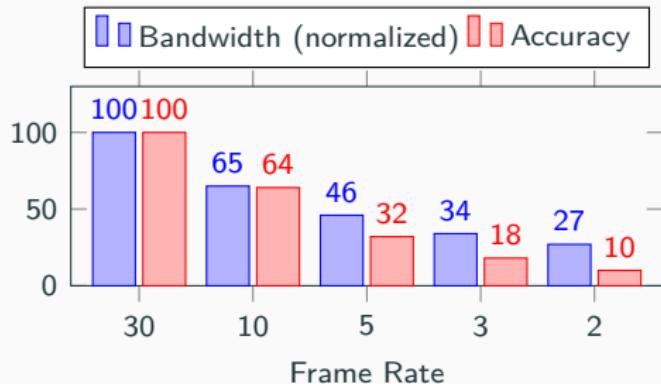
Application-specific Optimizations Don't Generalize



t=0s, nearby and large targets



t=1s, large difference



Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

Challenges:

1. Application-specific optimizations don't generalize.

Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

Challenges:

1. Application-specific optimizations don't generalize.
2. It requires expertise and manual work to explore multidimensional adaptation.

Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

Challenges:

1. Application-specific optimizations don't generalize.
2. It requires expertise and manual work to explore multidimensional adaptation.
3. The adaptation happens at the runtime.

Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

Challenges:

1. Application-specific optimizations don't generalize.
 - APIs: maybe operators to express adaptation.
2. It requires expertise and manual work to explore multidimensional adaptation.
3. The adaptation happens at the runtime.

Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

Challenges:

1. Application-specific optimizations don't generalize.
 - APIs: maybe operators to express adaptation.
2. It requires expertise and manual work to explore multidimensional adaptation.
 - Profiling: automatically learn Pareto-optimal strategy with multi-dimensional exploration.
3. The adaptation happens at the runtime.

Making Adaptation Practical is Challenging

Goal

Minimize bandwidth while maximizing application accuracy

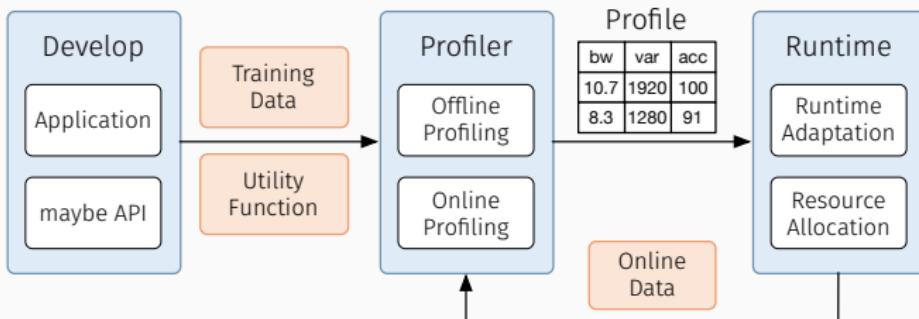
Challenges:

1. Application-specific optimizations don't generalize.
 - APIs: maybe operators to express adaptation.
2. It requires expertise and manual work to explore multidimensional adaptation.
 - Profiling: automatically learn Pareto-optimal strategy with multi-dimensional exploration.
3. The adaptation happens at the runtime.
 - Engineering an adaptation system to balance latency and accuracy.

Making Adaptation Practical is Challenging

Goal

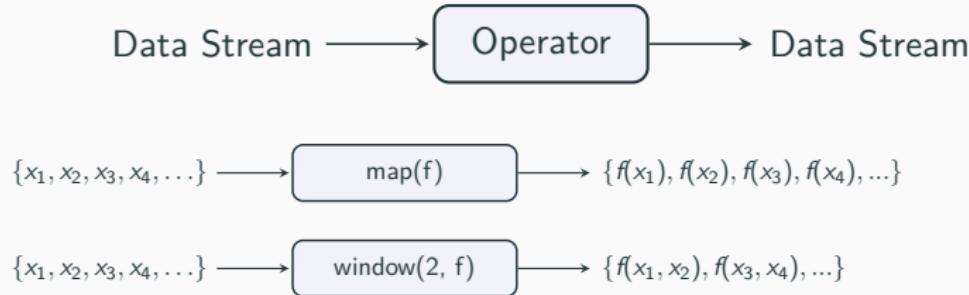
Minimize bandwidth while maximizing application accuracy



(1) Stream Processing APIs



(1) Stream Processing APIs



(1) Stream Processing APIs

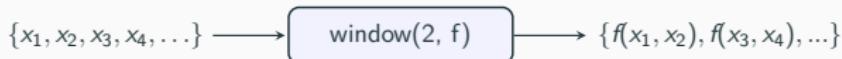


Normal	<i>map</i> ($f: I \Rightarrow O$)	$Stream<I> \Rightarrow Stream<O>$
	<i>skip</i> ($i: Integer$)	$Stream<I> \Rightarrow Stream<I>$
	<i>window</i> ($count: Integer, f: Vec<I> \Rightarrow O$)	$Stream<I> \Rightarrow Stream<O>$

...

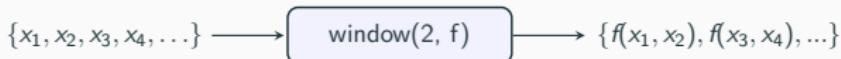
...

(1) Stream Processing APIs



Normal	<i>map</i> ($f: I \Rightarrow O$)	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle O \rangle$
	<i>skip</i> ($i: \text{Integer}$)	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle I \rangle$
	<i>window</i> ($\text{count}: \text{Integer}, f: \text{Vec}\langle I \rangle \Rightarrow O$)	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle O \rangle$

(1) Stream Processing APIs

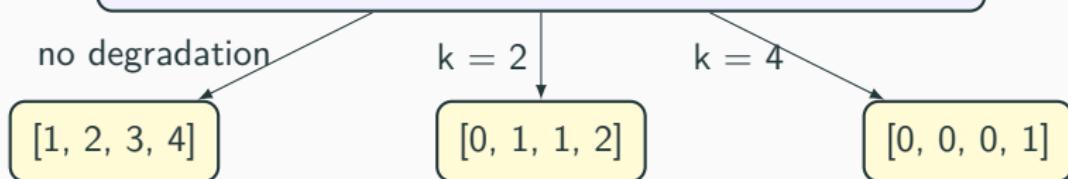


Normal	<code>map (f: I ⇒ O)</code>	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle O \rangle$
	<code>skip (i: Integer)</code>	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle I \rangle$
	<code>window (count: Integer, f: Vec⟨I⟩ ⇒ O)</code>	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle O \rangle$

Adaptation	<code>maybe (knobs: Vec⟨T⟩, f: (T, I) ⇒ I)</code>	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle I \rangle$
	<code>maybe_skip (knobs: Vec⟨Integer⟩)</code>	$\text{Stream}\langle I \rangle \Rightarrow \text{Stream}\langle I \rangle$
	<code>maybe_head (knobs: Vec⟨Integer⟩)</code>	$\text{Stream}\langle \text{Vec}\langle I \rangle \rangle \Rightarrow \text{Stream}\langle \text{Vec}\langle I \rangle \rangle$

`maybe(knobs: Vec<T>, f: (T, I) => I)`

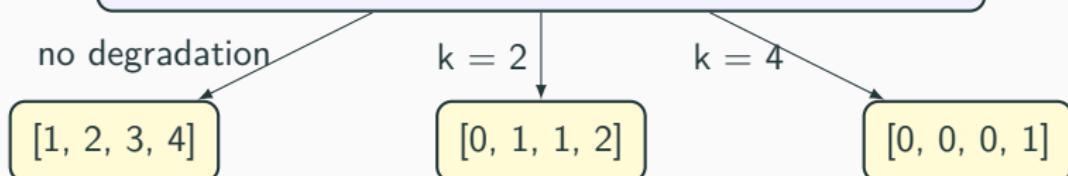
```
let quantized_stream = vec![1, 2, 3, 4].into_stream()
    .maybe(vec![2, 4], |k, val| val / k)
    .collect();
```



Example code in Rust, simplified for presentation.

```
maybe(knobs: Vec<T>, f: (T, I) => I)
```

```
let quantized_stream = vec![1, 2, 3, 4].into_stream()  
.maybe(vec![2, 4], |k, val| val / k)  
.collect();
```



We rewrite the video streaming application as follows,

```
let app = Camera::new((1920, 1080), 30)  
.maybe_downsample(vec![(1600, 900), (1280, 720)])  
.maybe_skip(vec![2, 5])  
.map(|frame| pedestrian_detect(frame))  
.compose();
```

Example code in Rust, simplified for presentation.

(2) Profiling

```
let app = Camera::new((1920, 1080), 30)
    .maybe_downsample(vec![(1600, 900), (1280, 720)])
    .maybe_skip(vec![2, 5])
    .map(|frame| pedestrian_detect(frame))
    .compose();
```

(2) Profiling

```
let app = Camera::new((1920, 1080), 30)
    .maybe_downsample(vec![(1600, 900), (1280, 720)])
    .maybe_skip(vec![2, 5])
    .map(|frame| pedestrian_detect(frame))
    .compose();
```

Training Data

(2) Profiling

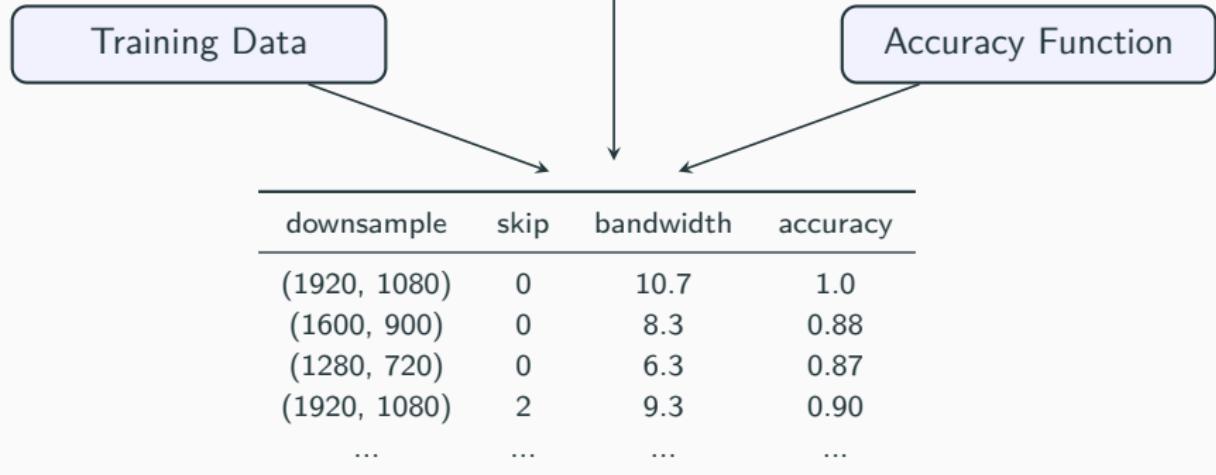
```
let app = Camera::new((1920, 1080), 30)
    .maybe_downsample(vec![(1600, 900), (1280, 720)])
    .maybe_skip(vec![2, 5])
    .map(|frame| pedestrian_detect(frame))
    .compose();
```

Training Data

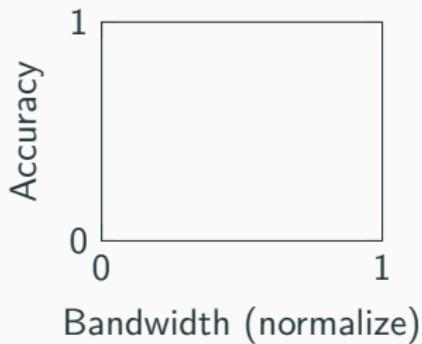
Accuracy Function

(2) Profiling

```
let app = Camera::new((1920, 1080), 30)
    .maybe_downsample(vec![(1600, 900), (1280, 720)])
    .maybe_skip(vec![2, 5])
    .map(|frame| pedestrian_detect(frame))
    .compose();
```

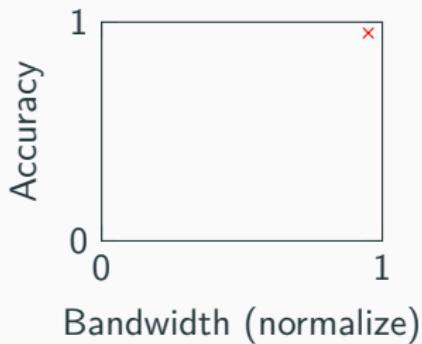


Profile: Pareto-optimal Strategy



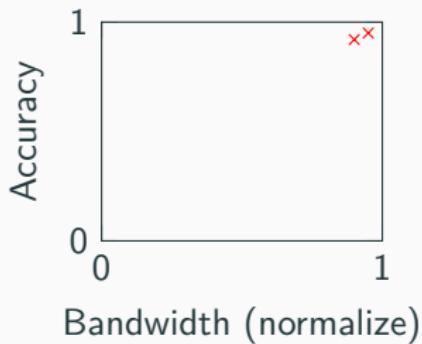
Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy



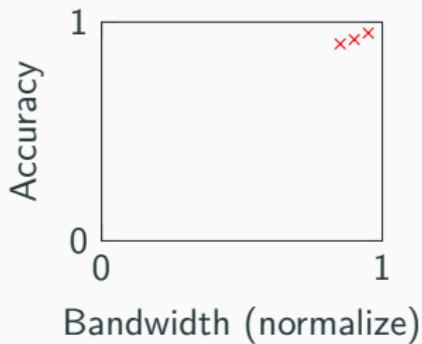
Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy



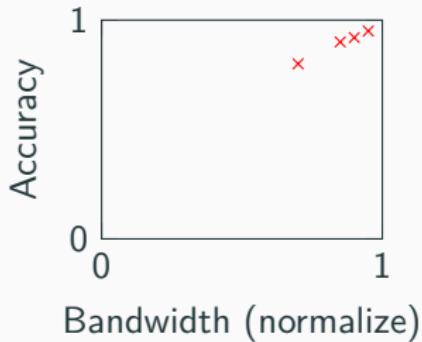
Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy



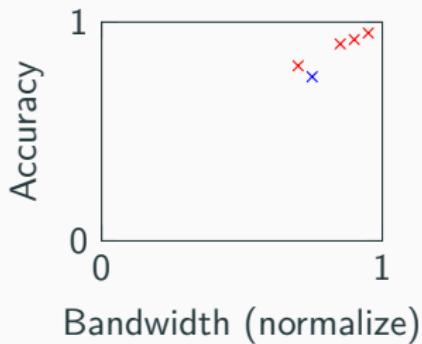
Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy



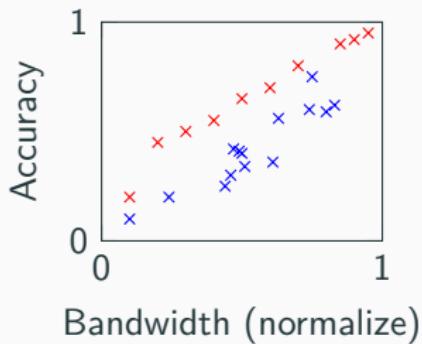
Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy



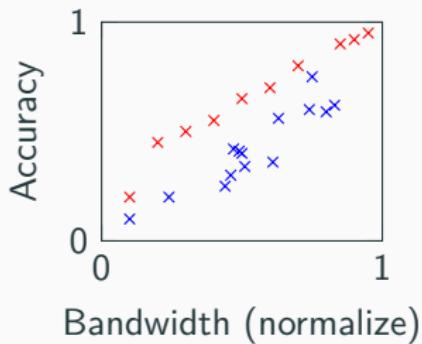
Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy



Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

Profile: Pareto-optimal Strategy

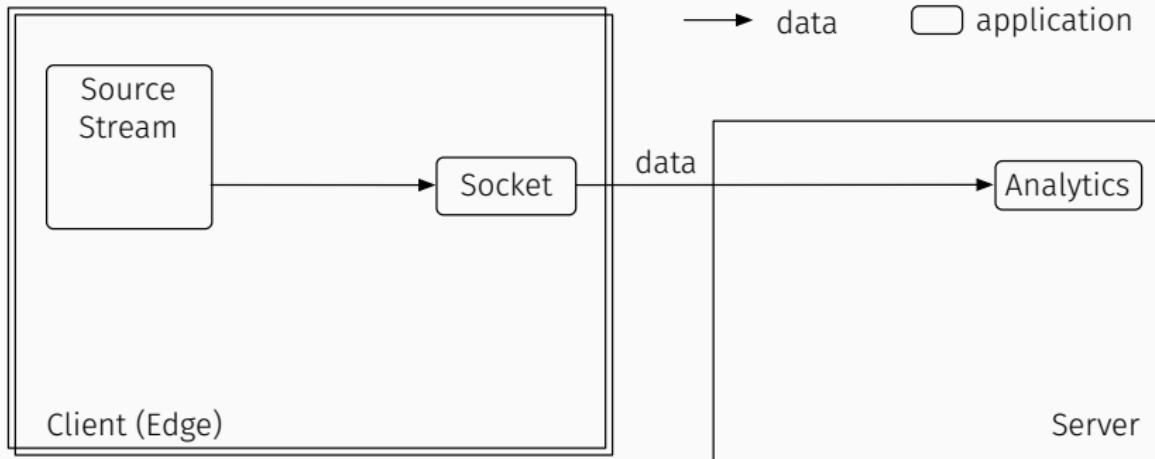


Symbol	Description
n	number of degradation operations
k_i	the i -th degradation knob
$c = [k_1, k_2, \dots k_n]$	one specific configuration
\mathbb{C}	the set of all configurations
$B(c)$	bandwidth requirement for c
$A(c)$	accuracy measure for c
\mathbb{P}	Pareto-optimal set

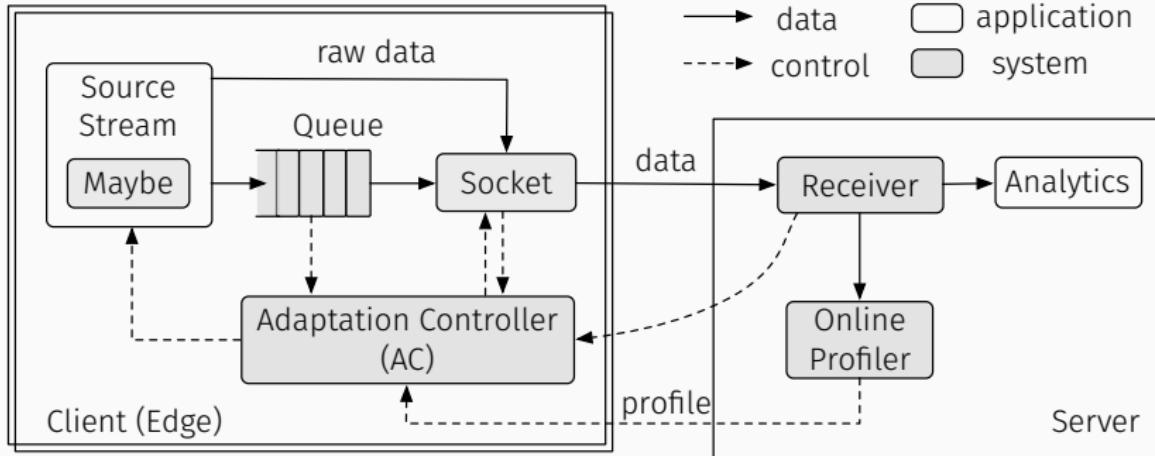
$$\mathbb{P} = \{c \in \mathbb{C} : \underbrace{\{c' \in \mathbb{C} : B(c') < B(c), A(c') > A(c)\}}_{\text{set of better configurations } c'} = \emptyset\}$$

See red markers in the figure.

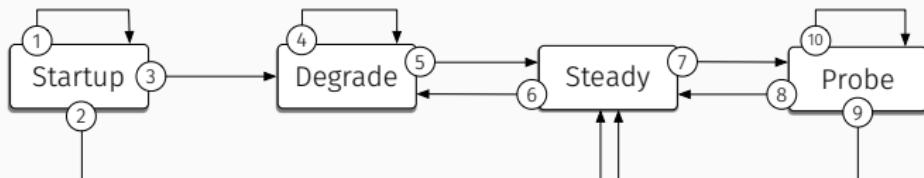
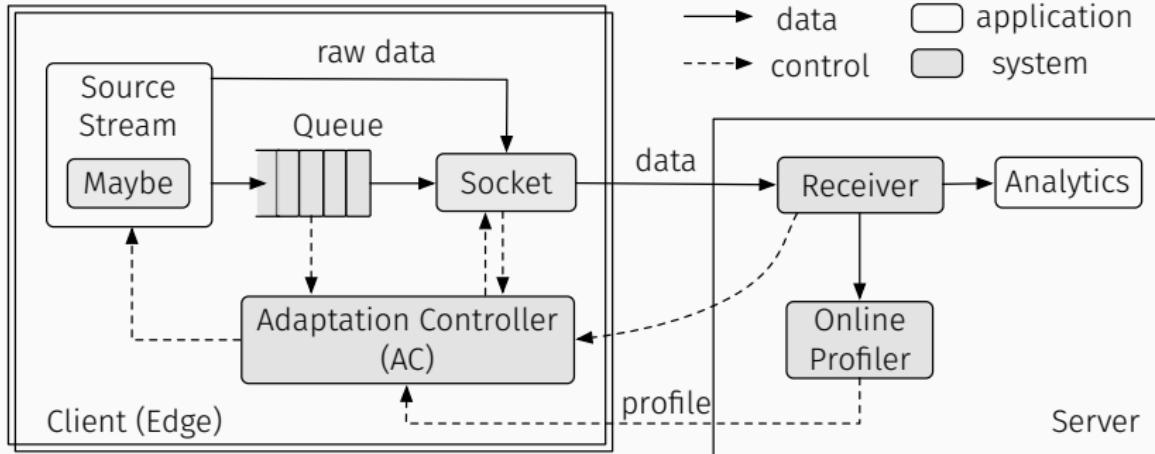
(3) Runtime Adaptation



(3) Runtime Adaptation



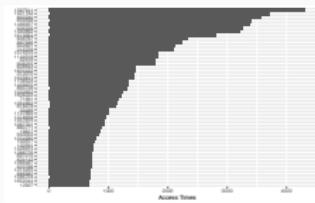
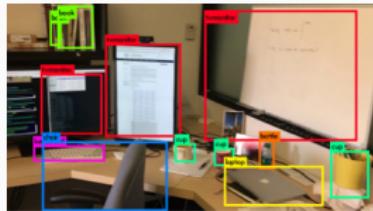
(3) Runtime Adaptation



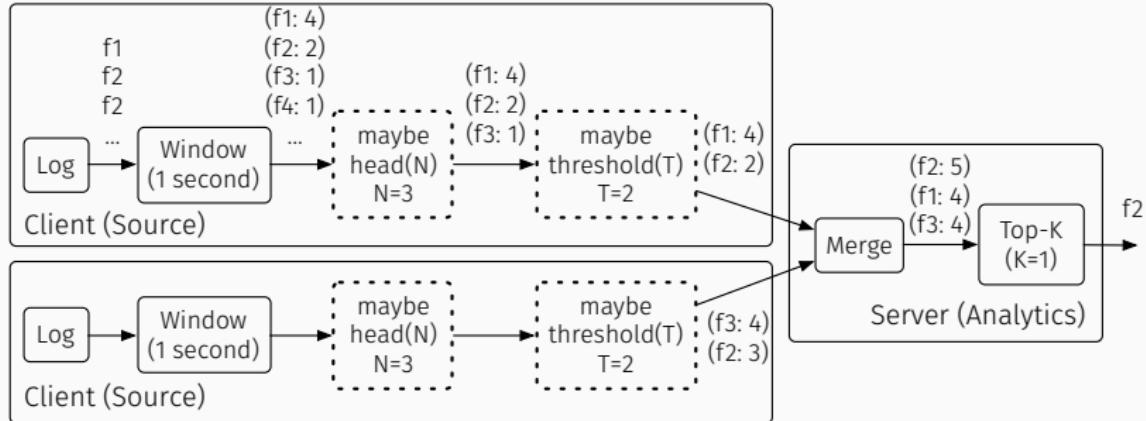
Adaptation Controller State Machine. We introduce Probe phase to conservatively change adaptation level. For details, please see the paper/thesis.

Applications

Application	Knobs	Accuracy	Dataset
Augmented Reality	resolution frame rate quantization	F1 score [Rijsbergen, 1979]	iPhone video clips training: office (24s) testing: home (246s)
Pedestrian Detection	resolution frame rate quantization	F1 score	MOT16 [Milan et al., 2016] training: MOT16-04 testing: MOT16-03
Log Analysis (Top-K, K=50)	head (N) threshold (T)	Kendall's τ [Abdi, 2007]	SEC.gov logs [DERA, 2016] training: 4 days testing: 16 days



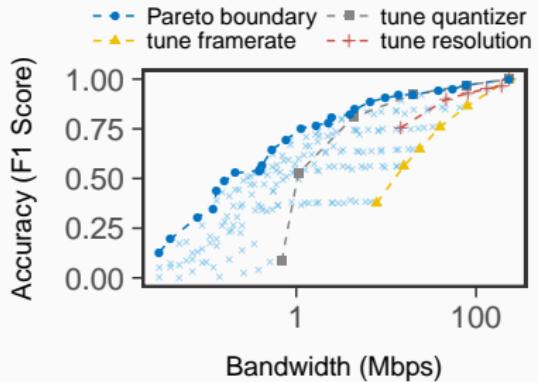
Top-K



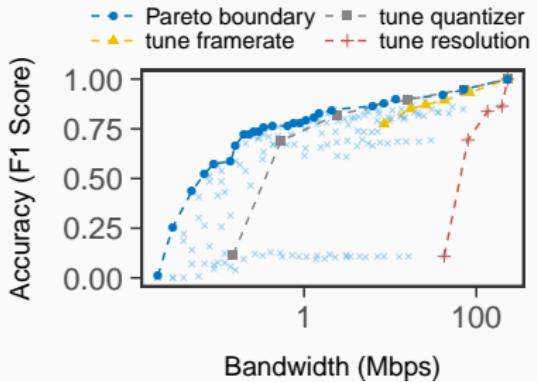
A distributed Top-K application with two degradation operations: **head** and **threshold**. In this example, $f2$, which is not in Top-1 for either client, becomes the global Top-1 after the merge. It would have been purged if the clients use threshold $T=3$, demonstrating degradation that reduces data sizes affects fidelity.

Evaluation: Generated Profiles

(a) Augmented Reality (AR)

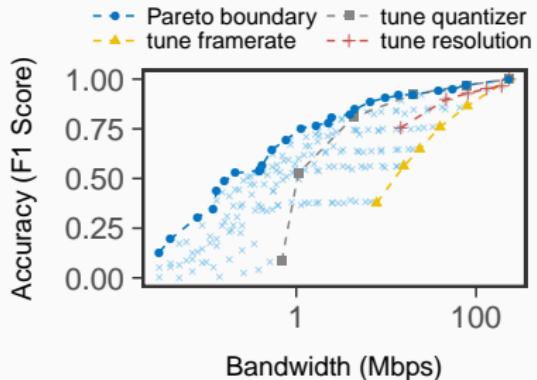


(b) Pedestrian Detection (PD)

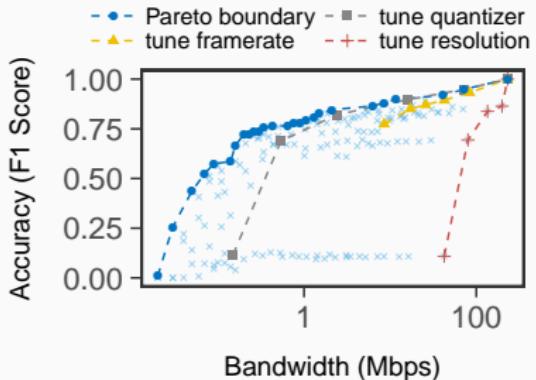


Evaluation: Generated Profiles

(a) Augmented Reality (AR)



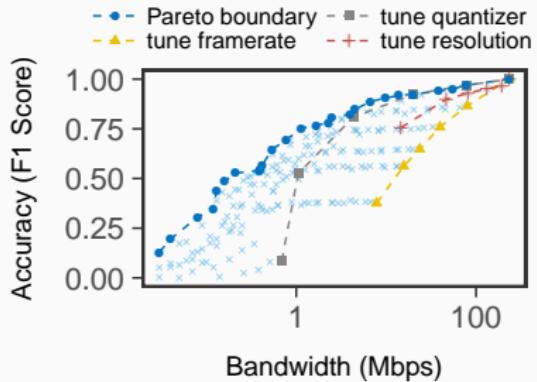
(b) Pedestrian Detection (PD)



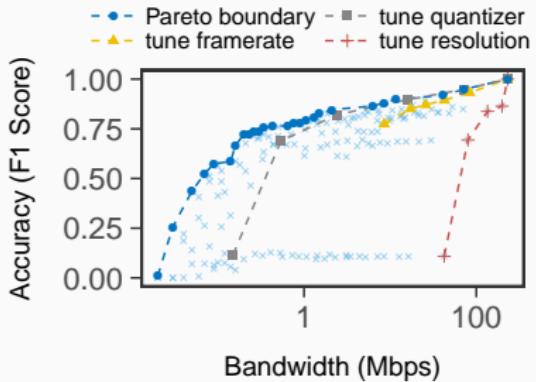
- Optimal strategy is achieved with multiple dimensions; tuning one dimension leads to suboptimal performance.

Evaluation: Generated Profiles

(a) Augmented Reality (AR)



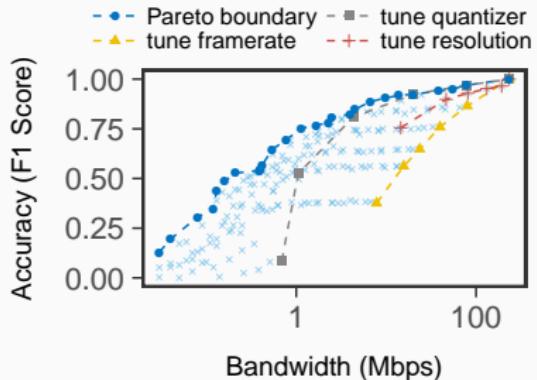
(b) Pedestrian Detection (PD)



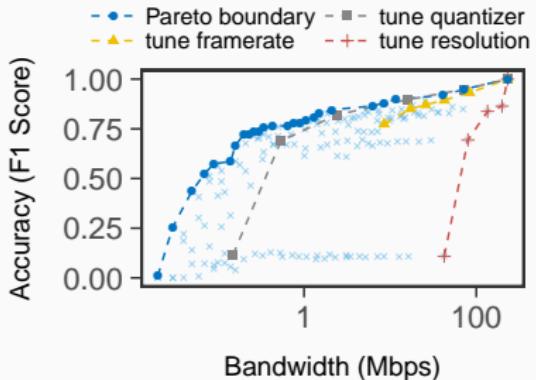
- Optimal strategy is achieved with multiple dimensions; tuning one dimension leads to suboptimal performance.
- For the same application, different dimensions have different impact.

Evaluation: Generated Profiles

(a) Augmented Reality (AR)

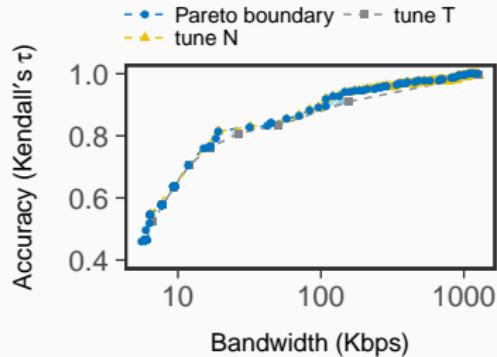


(b) Pedestrian Detection (PD)

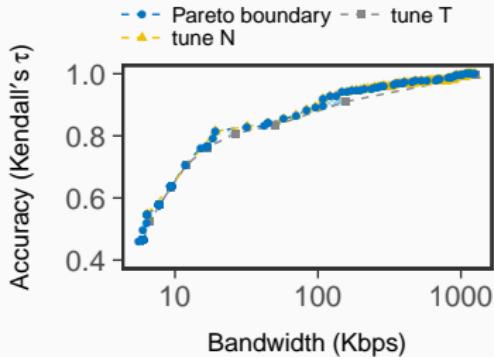


- Optimal strategy is achieved with multiple dimensions; tuning one dimension leads to suboptimal performance.
- For the same application, different dimensions have different impact.
- For different applications, the same dimension has different impact.

Evaluation: Generated Profiles (Top-K)

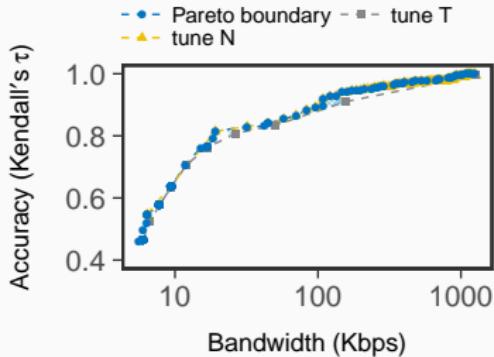


Evaluation: Generated Profiles (Top-K)



- The effect of each dimension is not significantly different.

Evaluation: Generated Profiles (Top-K)



- The effect of each dimension is not significantly different.
- The profile offers quantified effects of degradation.

Evaluation: Runtime Experiment Baselines

Baseline	Description
Streaming over TCP	A non-adaptive approach
Streaming over UDP	A non-adaptive approach, represents RTP/UDP/RTSP video streaming

Evaluation: Runtime Experiment Baselines

Baseline	Description
Streaming over TCP	A non-adaptive approach
Streaming over UDP	A non-adaptive approach, represents RTP/UD-P/RTSP video streaming
JetStream [Rabkin et al., 2014]	Manual Policy: <i>"if bandwidth is insufficient, switch to sending images at 75% fidelity, then 50% if there still isn't enough bandwidth. Beyond that point, reduce the frame rate, but keep the image fidelity."</i>

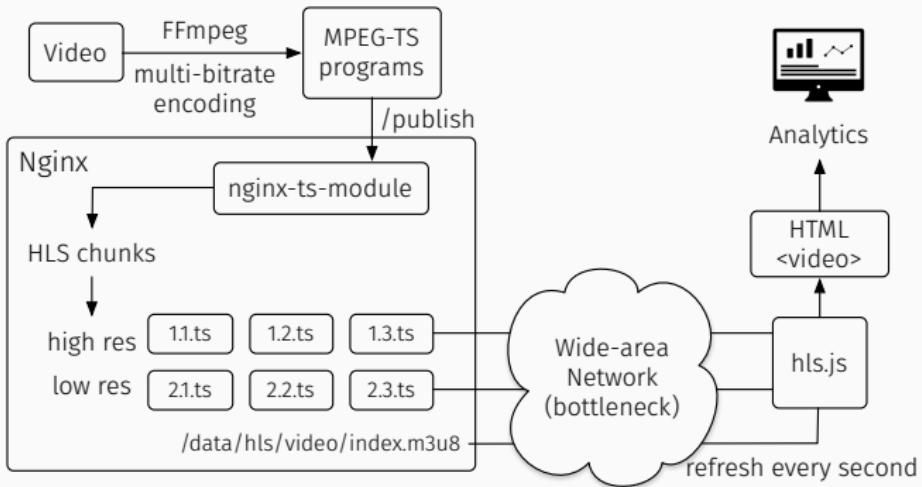
Evaluation: Runtime Experiment Baselines

Baseline	Description
Streaming over TCP	A non-adaptive approach
Streaming over UDP	A non-adaptive approach, represents RTP/UD-P/RTSP video streaming
JetStream [Rabkin et al., 2014]	Manual Policy: <i>"if bandwidth is insufficient, switch to sending images at 75% fidelity, then 50% if there still isn't enough bandwidth. Beyond that point, reduce the frame rate, but keep the image fidelity."</i>
JetStream++	Uses adaptation policy generated by AWStream. JetStream runtime does not probe (hence may oscillate between policies).

Evaluation: Runtime Experiment Baselines

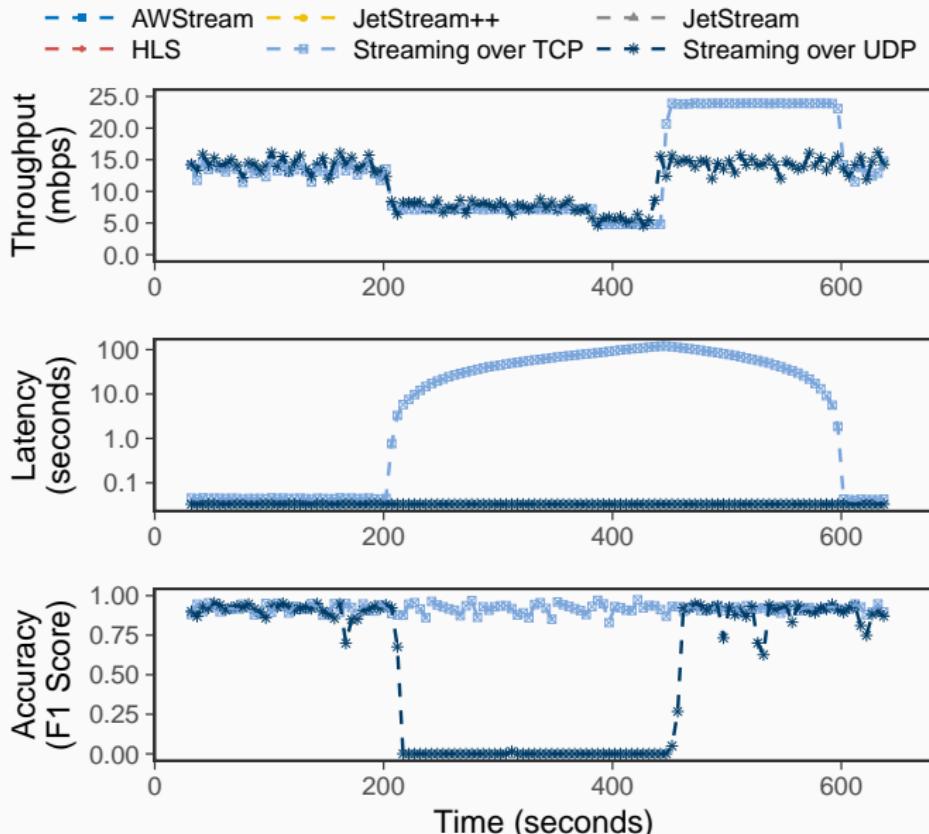
Baseline	Description
Streaming over TCP	A non-adaptive approach
Streaming over UDP	A non-adaptive approach, represents RTP/UD-P/RTSP video streaming
JetStream [Rabkin et al., 2014]	Manual Policy: <i>"if bandwidth is insufficient, switch to sending images at 75% fidelity, then 50% if there still isn't enough bandwidth. Beyond that point, reduce the frame rate, but keep the image fidelity."</i>
JetStream++	Uses adaptation policy generated by AWStream. JetStream runtime does not probe (hence may oscillate between policies).
HLS [Pantos and May, 2016]	HTTP Live Streaming represents popular adaptive video streaming techniques; used for Periscope video stream [Wang et al., 2016].

Evaluation: Runtime Experiment Baselines

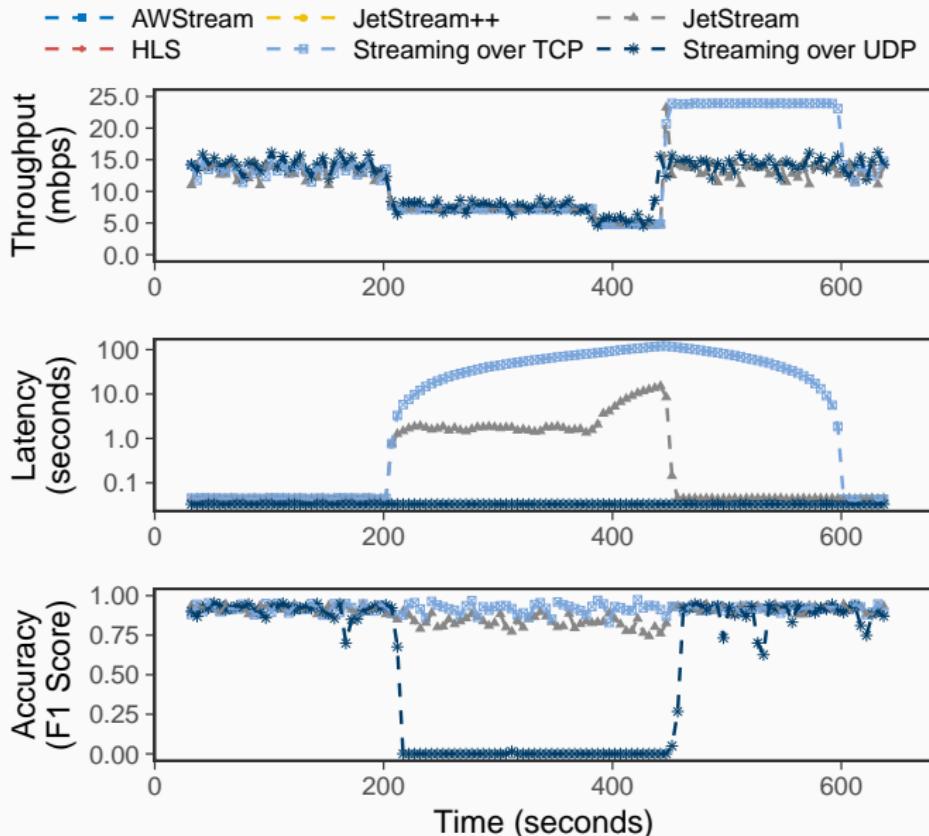


HTTP Live Streaming (HLS) architecture: designed for live video viewing and relying on buffering at the viewing side.

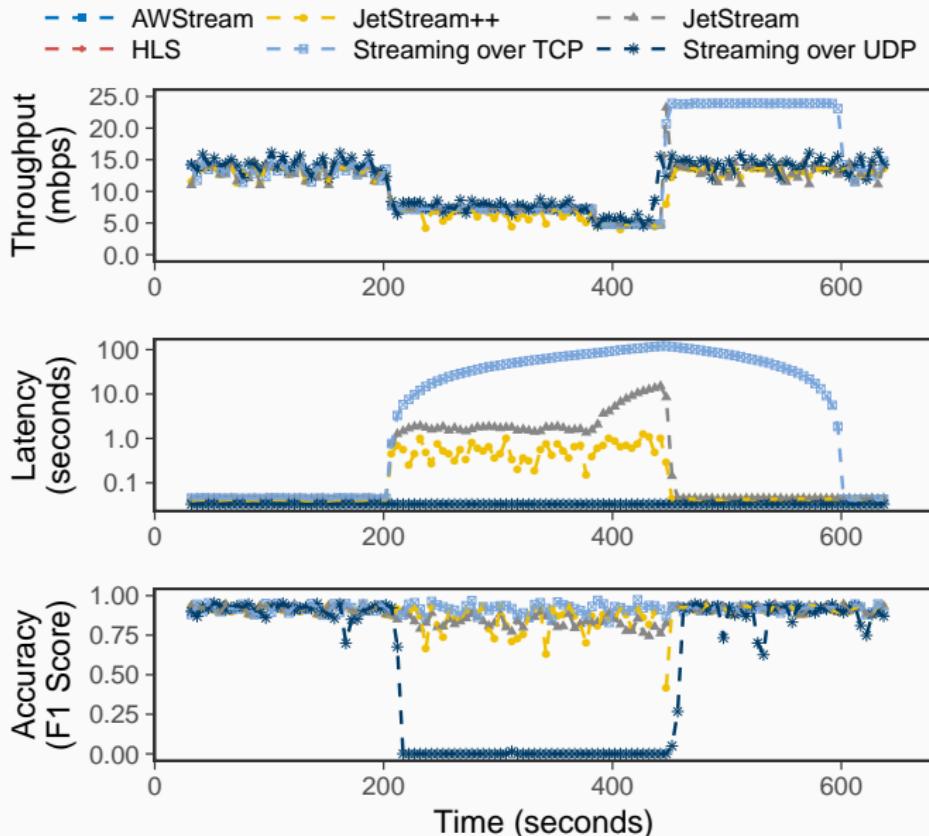
Evaluation: Runtime Performance



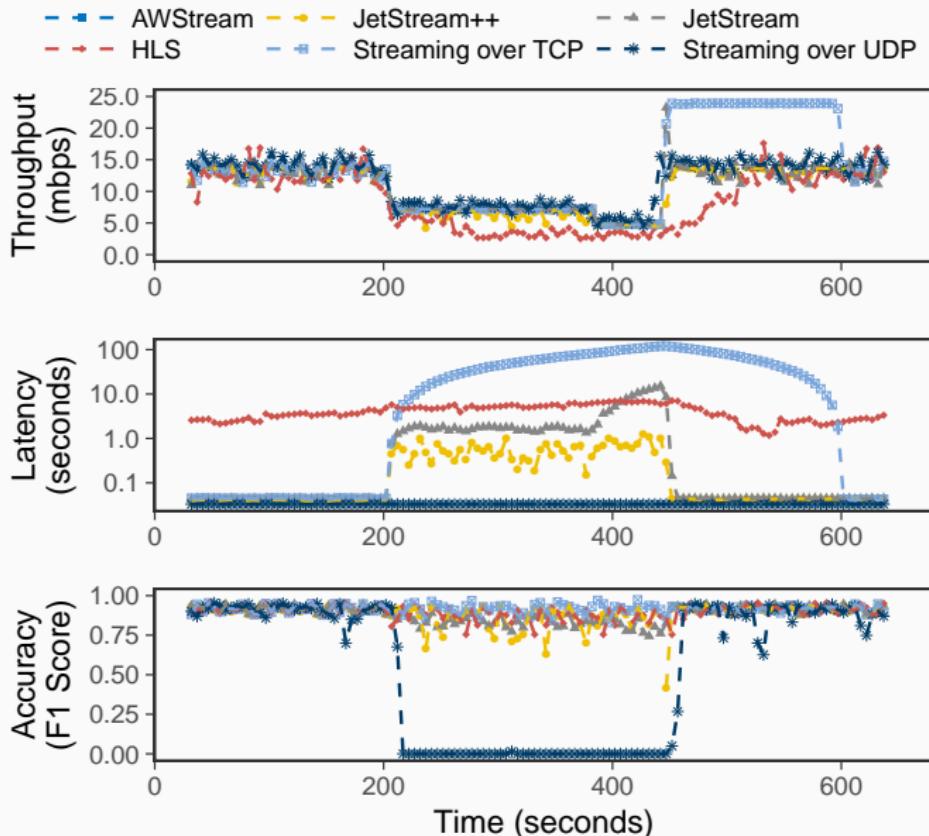
Evaluation: Runtime Performance



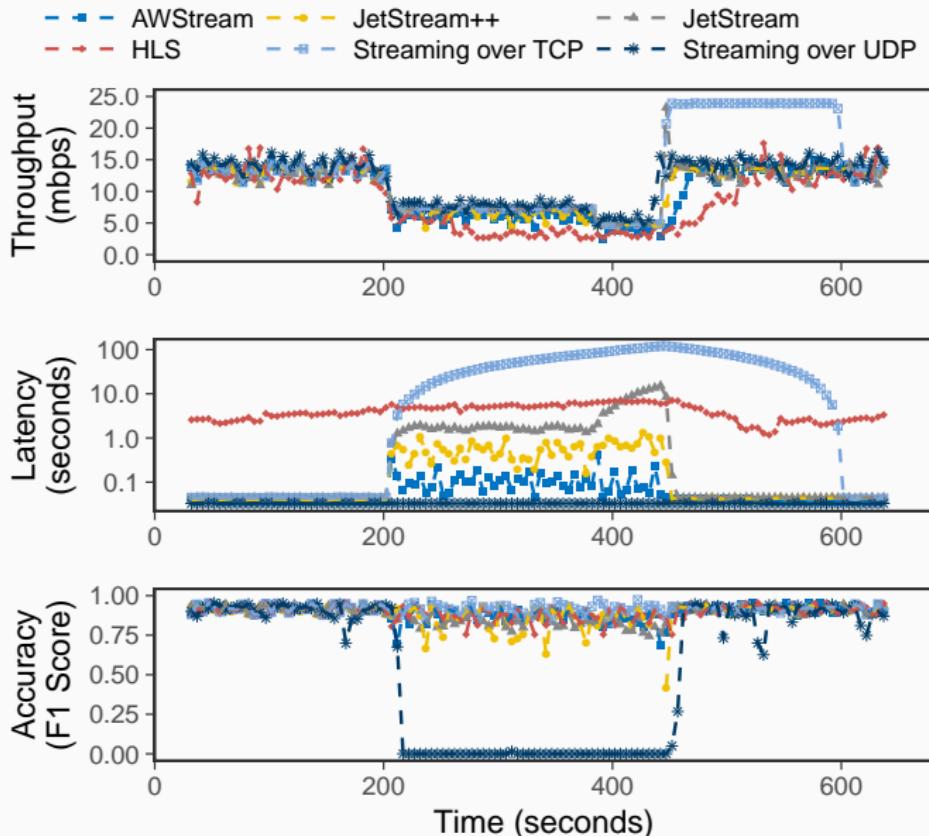
Evaluation: Runtime Performance



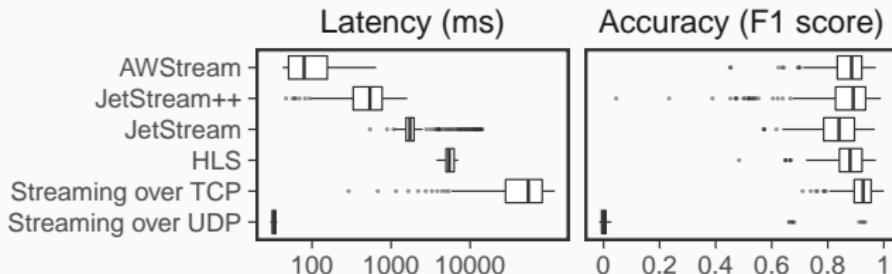
Evaluation: Runtime Performance



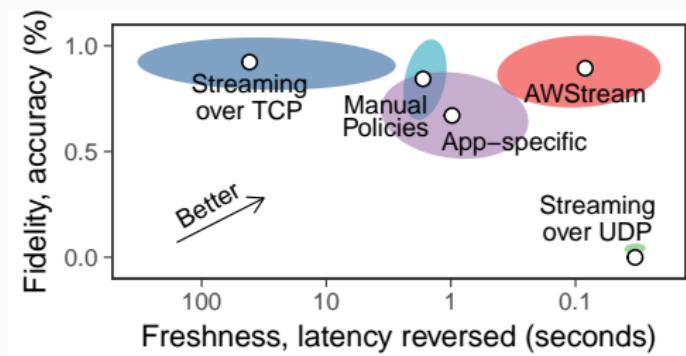
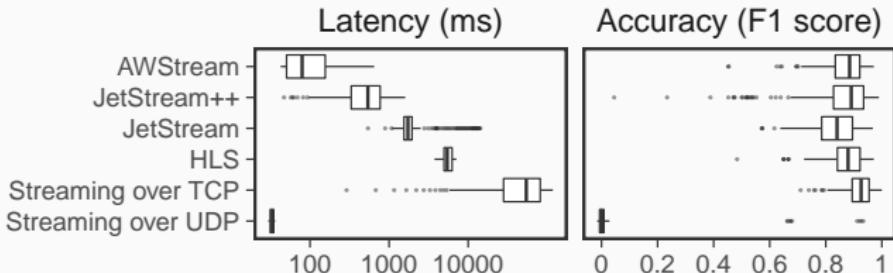
Evaluation: Runtime Performance



Evaluation: Runtime Performance



Evaluation: Runtime Performance



Compute Resource Adaptation

Edge Computing: Fog/Cloudlet/Swarmbox & New Infrastructure

Edge Computing: Fog/Cloudlet/Swarmbox & New Infrastructure



Cisco Fog Computing [Bonomi et al., 2012]



Cloudlet [Satyanarayanan et al., 2009]

Edge Computing: Fog/Cloudlet/Swarmbox & New Infrastructure



Cisco Fog Computing [Bonomi et al., 2012]



Cloudlet [Satyanarayanan et al., 2009]



Philips Hue Hub



SmartThings



Smartphones



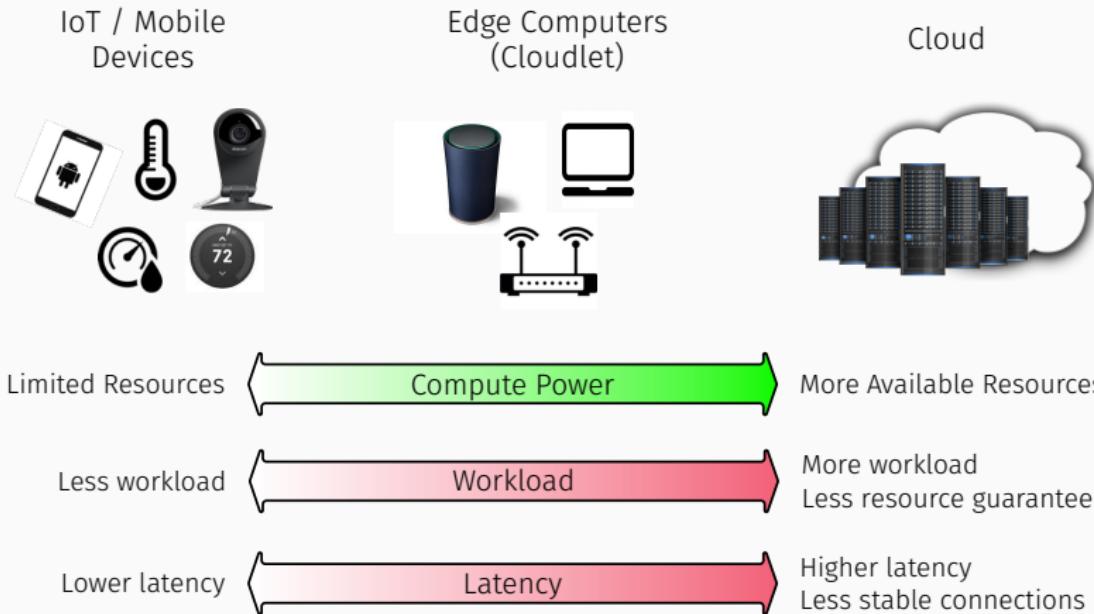
Google onHub



SwarmBox
Intel NUC

Many Gateways

Heterogeneous Environment



Heterogeneous Environment

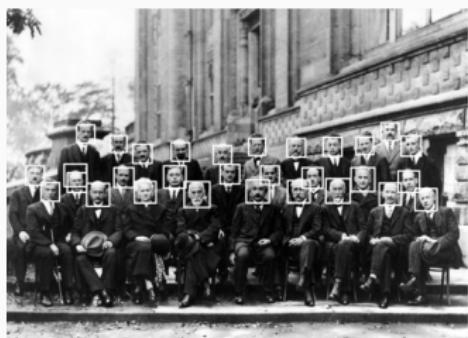
IoT / Mobile Devices



Edge Computers (Cloudlet)



Cloud



RPi Model B	Macbook Model A1502	Workstation Xeon E5-1620
4105	544	346

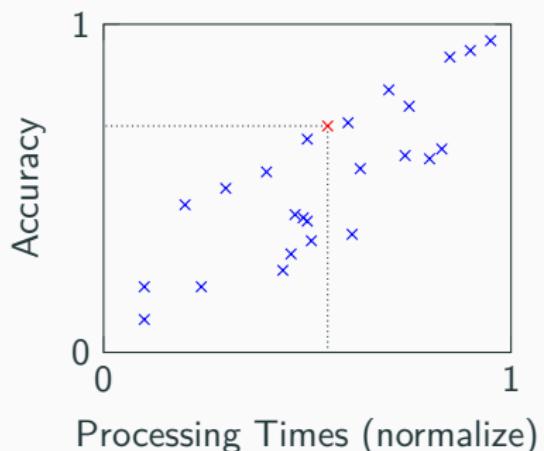
Processing times (ms) on different platforms.

Accuracy and Processing Times Tradeoff

Adaptation

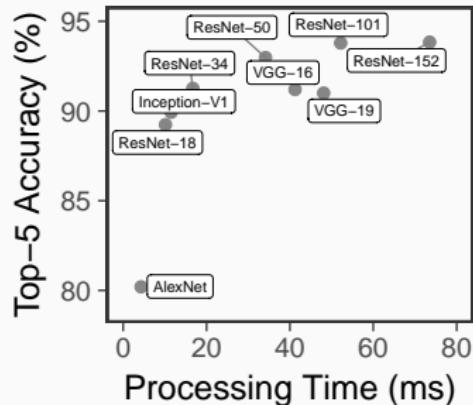
Different algorithm and parameters affect the accuracy and processing times.

Within the tradeoff space, select appropriate algorithm and parameters to meet bounded response time goal.



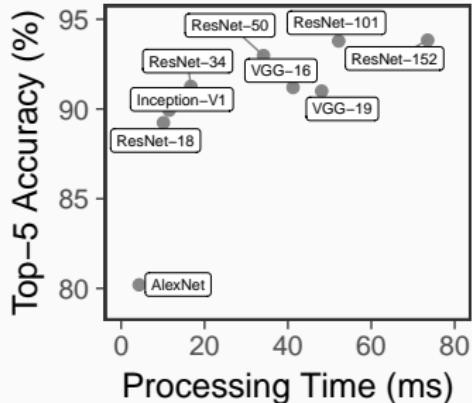
Accuracy and Processing Times Tradeoff

Accuracy and Processing Times Tradeoff

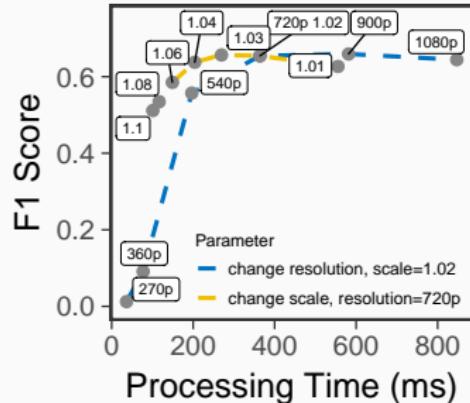


- (a) Benchmarks for popular convolutional neural network (CNN) models. Data source:
[https://github.com/jcjohnson/
cnn-benchmarks](https://github.com/jcjohnson/cnn-benchmarks).

Accuracy and Processing Times Tradeoff



(a) Benchmarks for popular convolutional neural network (CNN) models. Data source: <https://github.com/jcjohnson/cnn-benchmarks>.



(b) Benchmarks for Viola Jones face detection when changing different parameters (see explanation on the next slide).

detectMultiScale in Viola-Jones (or CascadeClassifier)

The OpenCV implementation of
Viola-
Jones [Viola and Jones, 2001] has
three parameters,

Image Source: pyimagesearch.

detectMultiScale in Viola-Jones (or CascadeClassifier)

The OpenCV implementation of Viola-

Jones [Viola and Jones, 2001] has three parameters,

- **scale**: how much the image size is reduced at each image scale.
- **min_size**: minimum detectable object size.

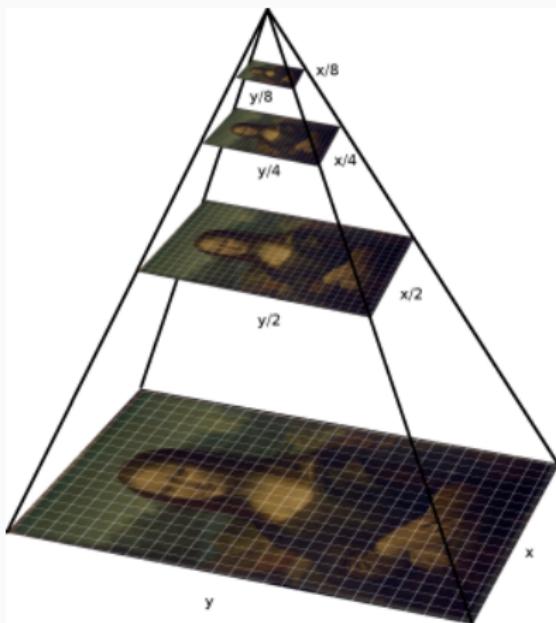


Image Source: pyimagesearch.

`detectMultiScale` in Viola-Jones (or CascadeClassifier)

The OpenCV implementation of Viola-

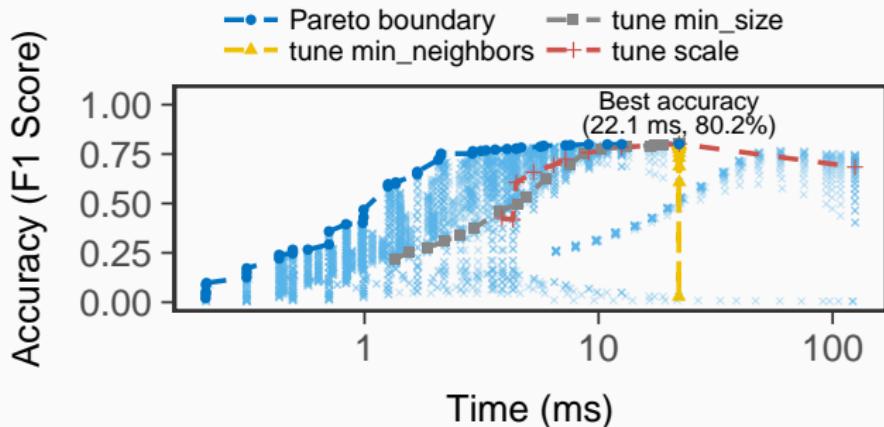
Jones [Viola and Jones, 2001] has three parameters,

- `scale`: how much the image size is reduced at each image scale.
- `min_size`: minimum detectable object size.
- `min_neighbors`: how many neighbors each candidate rectangle should have to retain it.



Image Source: Stack Overflow.

Exhaustive Search is Too Expensive



- scale: how much image size is reduced at each image scale.
- min_size: minimum detectable object size.
- min_neighbors: how many neighbors each candidate rectangle should have to retain it.

`detectMultiScale` in Histogram of Oriented Gradients (HOG)

```
pub struct HogParams {  
    pub win_size: Size2i,  
    pub block_size: Size2i,  
    pub block_stride: Size2i,  
    pub cell_size: Size2i,  
    pub nbins: c_int,  
    pub win_sigma: f64,  
    pub l2hys_threshold: f64,  
    pub gamma_correction: bool,  
    pub nlevels: usize,  
    pub hit_threshold: f64,  
    pub win_stride: Size2i,  
    pub padding: Size2i,  
    pub scale: f64,  
    pub group_threshold: c_int,  
    pub use_meanshift_grouping: bool,  
    pub final_threshold: f64,  
}
```



Image Source: learnopencv.com.

Challenges in Adapting Computation

Goal

Adapt computation to different platforms

Challenges in Adapting Computation

Goal

Adapt computation to different platforms

Challenges:

1. Large parameter space
2. Heterogeneous capabilities (and not available when profiling)

Challenges in Adapting Computation

Goal

Adapt computation to different platforms

Challenges:

1. Large parameter space
 - Previous approaches use random search or coordinate/greedy approach
 - We propose **Bayesian Optimization (BO)** for profiling
2. Heterogeneous capabilities (and not available when profiling)

Challenges in Adapting Computation

Goal

Adapt computation to different platforms

Challenges:

1. Large parameter space
 - Previous approaches use random search or coordinate/greedy approach
 - We propose **Bayesian Optimization (BO)** for profiling
2. Heterogeneous capabilities (and not available when profiling)
 - **Profile transfer:** refine existing Pareto-optimal points

Bayesian Optimization 101

Bayesian optimization approximate black-box functions with proxy functions and iteratively proposes new sample point in the large parameter space. Effective for,

Bayesian Optimization 101

Bayesian optimization approximate black-box functions with proxy functions and iteratively proposes new sample point in the large parameter space. Effective for,

- Evaluating each sample is expensive.
- The objective is a black-box.
- The evaluation can be noisy.

Bayesian Optimization 101

Bayesian optimization approximate black-box functions with proxy functions and iteratively proposes new sample point in the large parameter space. Effective for,

- Evaluating each sample is expensive.
- The objective is a black-box.
- The evaluation can be noisy.

Gaining attraction beyond ML scope:

- CherryPick [Alipourfard et al., 2017]
finds the best cloud configurations
for big data analytics.
- Google optimize chocolate chip
cookies recipes [Solnik et al., 2017].

Bayesian Optimization 101

Bayesian optimization approximate black-box functions with proxy functions and iteratively proposes new sample point in the large parameter space. Effective for,

- Evaluating each sample is expensive.
- The objective is a black-box.
- The evaluation can be noisy.

Gaining attraction beyond ML scope:

- CherryPick [Alipourfard et al., 2017] finds the best cloud configurations for big data analytics.
- Google optimize chocolate chip cookies recipes [Solnik et al., 2017].

Chocolate chip and cardamom cookie

INGREDIENTS

Tapioca starch	1/2 cup + 2 TBSP
Brown rice flour	1/2 cup
Be sugar	3/4 cup + 15 TBSP
Cardamom	2 tsp
Flaxseed meal	15 TBSP
Sorghum flour	1/4 cup
Raw sugar	1/4 cup
Xanthan gum	15 TBSP
Sea salt	1.5 tsp
baking soda	1 tsp
Chocolate chips	1 cup
water	3/4 cup
sunflower oil	3/4 cup

DIRECTIONS

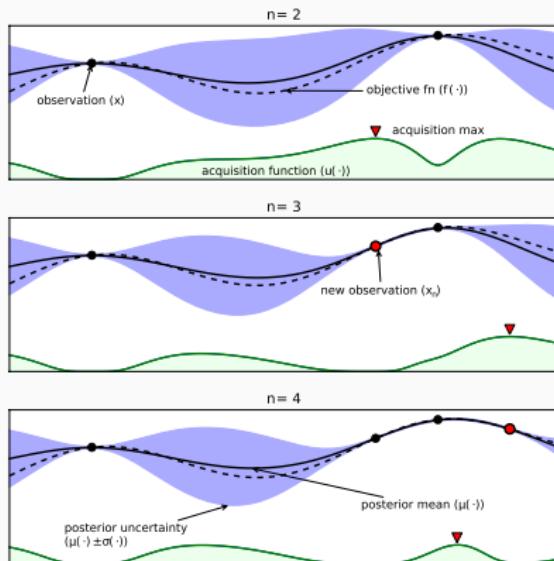
Combine all the dry ingredients except the chocolate chips in a bowl and mix well.

In another bowl, combine all the wet ingredients, and then add to the dry ingredients and mix enough to combine.

Add the chocolate chips and fold in until just mixed. Using a large spoon, drop on parchment lined sheet pan and bake at 350° for about 12 minutes.

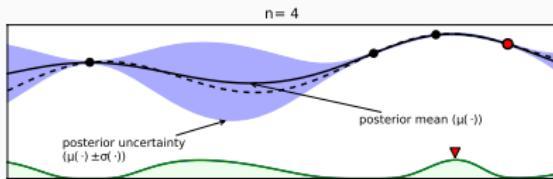
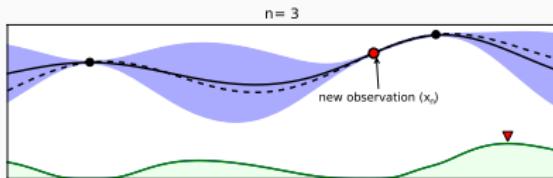
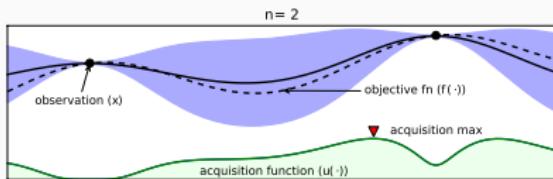
GLUTEN FREE GOAT
BAKERY & CAFE

Bayesian Optimization (Illustrated)

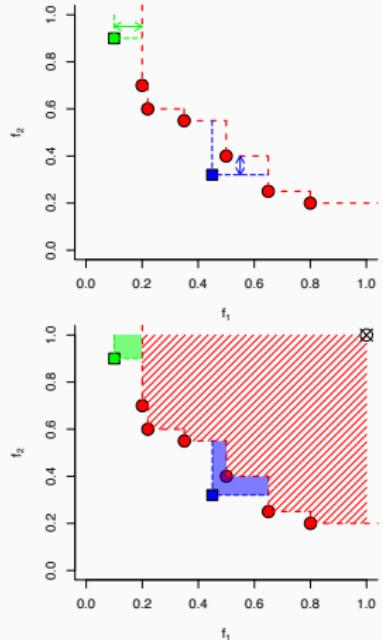


Acquisition function evaluates the utility of candidate points for the next evaluation of f , balancing a high objective (exploitation) and high uncertainty (exploration) [Shahriari et al., 2016]

Bayesian Optimization (Illustrated)



Acquisition function evaluates the utility of candidate points for the next evaluation of f , balancing a high objective (exploitation) and high uncertainty (exploration) [Shahriari et al., 2016]



For two-objective optimization, utility gain is based on additive-epsilon (top) or hypervolume (bottom) [Binois and Picheny, 2018]

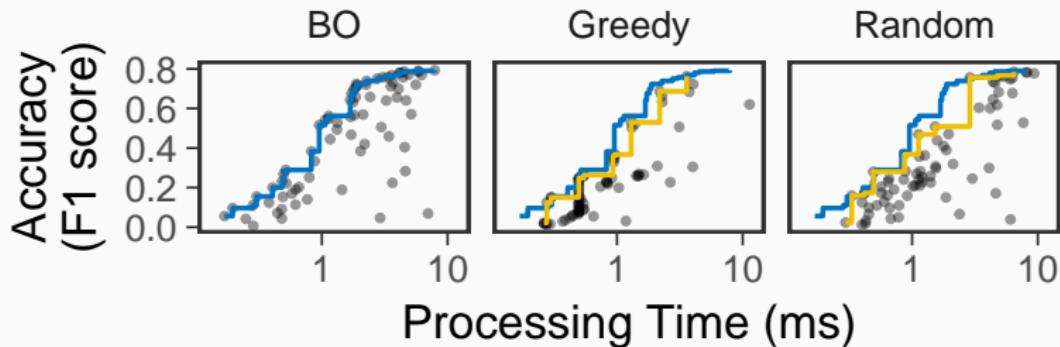
Bayesian Optimization For Performance Modeling

We use PESMO² [[Hernández-Lobato et al., 2016](#)] and compare it with two baselines: (1) greedy/coordinate search; (2) random search.

²A Python package based on [Spearmint](#). It chooses evaluation points to maximally reduce the entropy of the posterior distribution over the Pareto set.

Bayesian Optimization For Performance Modeling

We use PESMO² [Hernández-Lobato et al., 2016] and compare it with two baselines: (1) greedy/coordinate search; (2) random search.



BO evaluates 50 configurations and recommends 29 configurations as the Pareto-optimal boundary (the blue line). Greedy and Random find sub-optimal Pareto configurations with a budget of 80 evaluations (the yellow line in each figure).

²A Python package based on [Spearmint](#). It chooses evaluation points to maximally reduce the entropy of the posterior distribution over the Pareto set.

Profile Transfer (without re-running the entire BO)

We make the following observations:

Profile Transfer (without re-running the entire BO)

We make the following observations:

- Accuracy remains for a given algorithm/parameter.

Profile Transfer (without re-running the entire BO)

We make the following observations:

- Accuracy remains for a given algorithm/parameter.
- Processing time order is preserved
 - More expensive algorithms/parameters remain the same across platforms.

Profile Transfer (without re-running the entire BO)

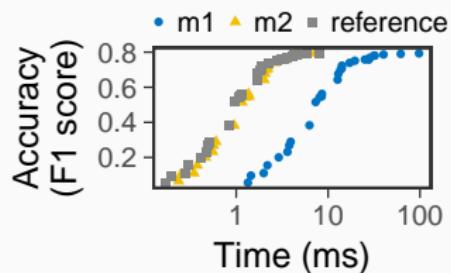
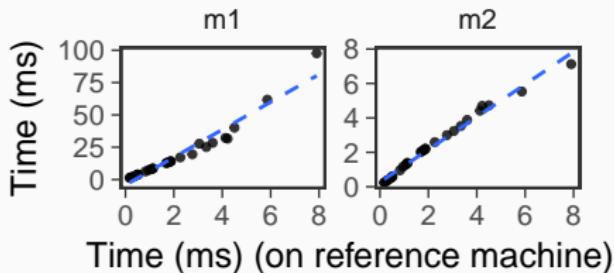
We make the following observations:

- Accuracy remains for a given algorithm/parameter.
- Processing time order is preserved
 - More expensive algorithms/parameters remain the same across platforms.
- The “Pareto-optimal” is horizontally stretched/compressed.

Profile Transfer (without re-running the entire BO)

We make the following observations:

- Accuracy remains for a given algorithm/parameter.
- Processing time order is preserved
 - More expensive algorithms/parameters remain the same across platforms.
- The “Pareto-optimal” is horizontally stretched/compressed.



(Left) Empirically, processing times follows a linear approximation. (Right) Stretched/compressed profile. See paper for details.

Conclusion and Acknowledgement

Summary and Contributions

Summary and Contributions

- Swarm/IoT has huge potentials but also challenges

Summary and Contributions

- Swarm/IoT has huge potentials but also challenges
- Network resource adaptation
 - Addresses scarce and variable WAN bandwidth
 - Tradeoff between application accuracy and data size demand

Summary and Contributions

- Swarm/IoT has huge potentials but also challenges
- Network resource adaptation
 - Addresses scarce and variable WAN bandwidth
 - Tradeoff between application accuracy and data size demand
- Compute resource adaptation
 - Addresses heterogeneous platforms and large parameter space
 - Tradeoff between application accuracy and processing times

Summary and Contributions

- Swarm/IoT has huge potentials but also challenges
- Network resource adaptation
 - Addresses scarce and variable WAN bandwidth
 - Tradeoff between application accuracy and data size demand
- Compute resource adaptation
 - Addresses heterogeneous platforms and large parameter space
 - Tradeoff between application accuracy and processing times
- Overall, a systematic and quantitative approach for adaptation

Current (other) and Future Work

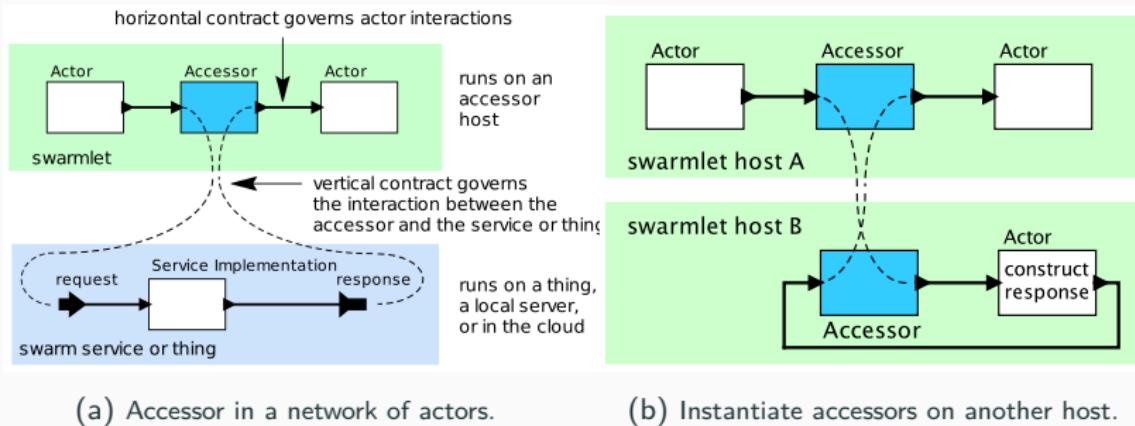
TerraSwarm Vision

TerraSwarm applications are characterized by their ability to **dynamically recruit** resources such as sensors and data from the cloud, aggregate and use that information to make or aid decisions.

Current (other) and Future Work

TerraSwarm Vision

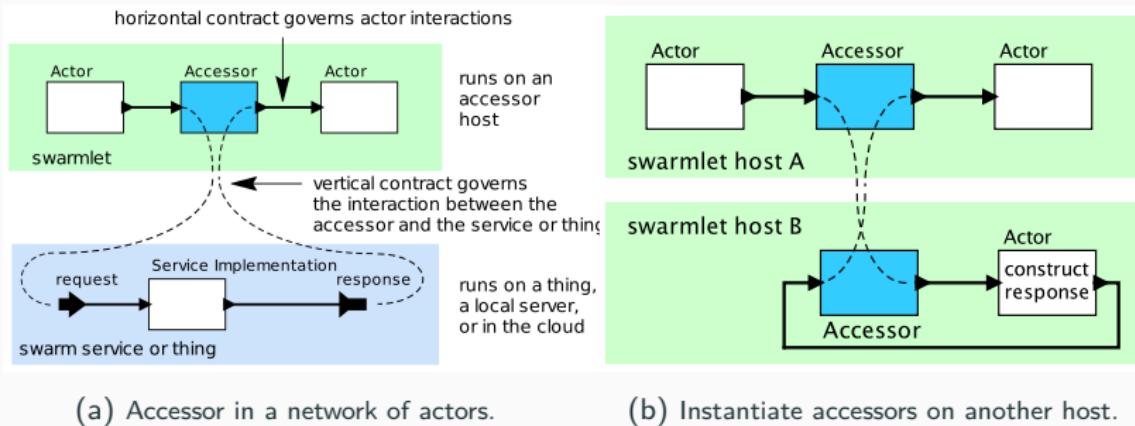
TerraSwarm applications are characterized by their ability to **dynamically recruit** resources such as sensors and data from the cloud, aggregate and use that information to make or aid decisions.



Current (other) and Future Work

TerraSwarm Vision

TerraSwarm applications are characterized by their ability to **dynamically recruit** resources such as sensors and data from the cloud, aggregate and use that information to make or aid decisions.



Work in progress with Marten and Andrés. Maybe checkout Marten's dissertation talk in the future :)

Acknowledgment



Prof. Edward Lee



Prof. John Wawrynek



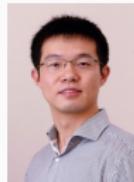
Prof. John Chuang



Prof. Sylvia Ratnasamy



Prof. Björn Hartmann



Prof. Xin Jin



Prof. John Kubiatowicz

Acknowledgment



Prof. Edward Lee



Prof. John Wawrynek



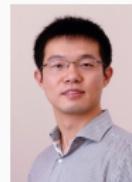
Prof. John Chuang



Prof. Sylvia Ratnasamy



Prof. Björn Hartmann



Prof. Xin Jin



Prof. John Kubiatowicz



Dr. Ilge Akkaya



Dr. Hokeun Kim



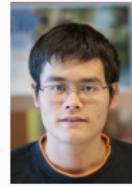
Dr. David Mellis



Dr. Chris Shaver



Antonio Iannopollo



Kaifei Chen



The entire EAL research group (with many visiting scholars)

Acknowledgement

Edward Lee, John
Wawrynek, Syliva Ratnasamy, John
Chuang, Björn Hartmann, John Kubiatowicz, Xiaofan
Fred Jiang, Lin Zhang, David Mellis, Xin Jin, Mary Stewart,
Christopher Brooks, Eunsuk Kang, Ilge Akkaya, Hokeun Kim,
Marten Lohstroh, Matt Weber, Antonio Iannopollo, Mehrdad
Niknami, Chris Shaver (Yvan Vivid), Michael Zimmer, Chris-
tos Stergiou, Dai Bui, Ben Lickly, Eleftherios Matsikoudis,
Joseph Ng, Chadlia Jerad Ep Ben Haj Hmida, Moez Ben
Haj Hmida, Maryam Bagheri, Victor Nouvellet, Ankush
Desai, Nitesh Mor, Yu-Hsiang Sean Chen, Claire Tuna,
Achal Dave, Jack Kolb, Eric Allman, Roy Wang,
Bill N. Schilit, Jin Liang, Chao Mei, Kaifei
Chen, Qifan Pu, Xiang Gao, Peihan Miao,
Zhuo Chen, Yuting Wei, Chaoran
Guo, Qian Zhong, Tianshi
Wang, Meng Wei,
Limin Chen



1N73LL1G3NC3

15 7H3

4B1L17Y

70 4D4P7 70

CH4NG3

1N73LL1G3NC3

15 7H3

4B1L17Y

70 4D4P7 70

CH4NG3



Image Source: 0stees.com

Google Network Infrastructure

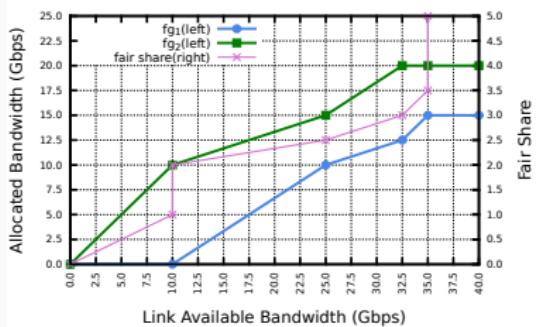


Figure 4: Bandwidth Sharing on a Bottleneck Link.

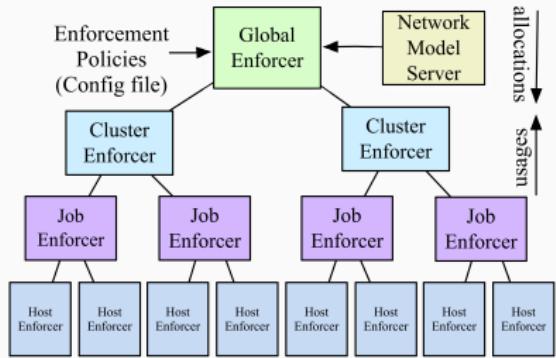


Figure 5: BwE Architecture.

BwE: Flexible, Hierarchical Bandwidth Allocation for WAN Distributed Computing [Kumar et al., 2015]

Google Network Infrastructure

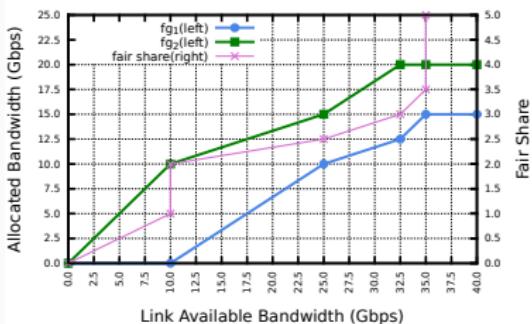


Figure 4: Bandwidth Sharing on a Bottleneck Link.

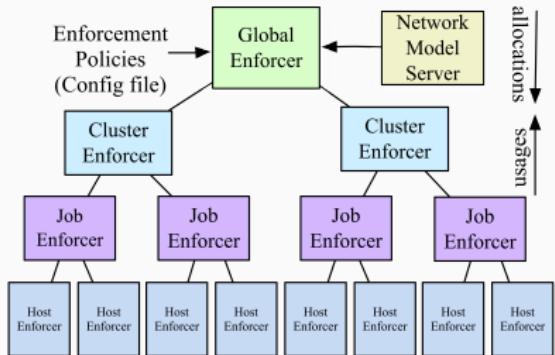


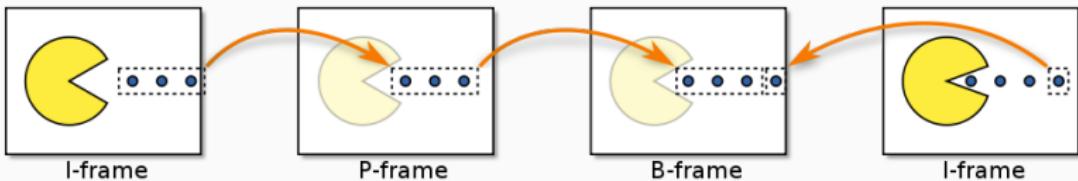
Figure 5: BwE Architecture.

BwE: Flexible, Hierarchical Bandwidth Allocation for WAN Distributed Computing [Kumar et al., 2015]

Move from Lagrangian to Eulerian (ask Edward if you don't know what these words refer to).

Backup Slides.

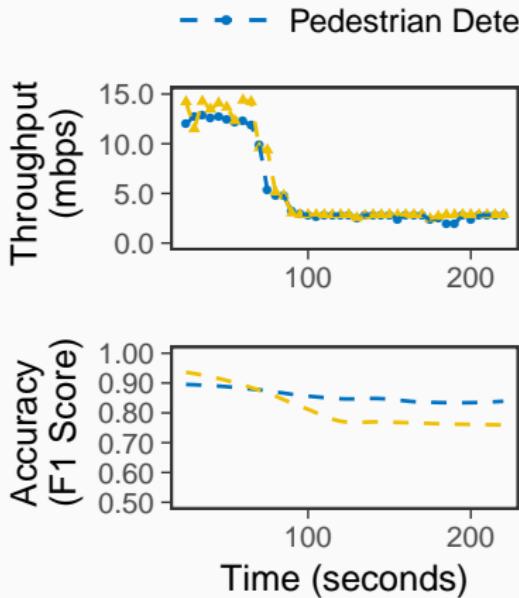
Video Encoding Frames



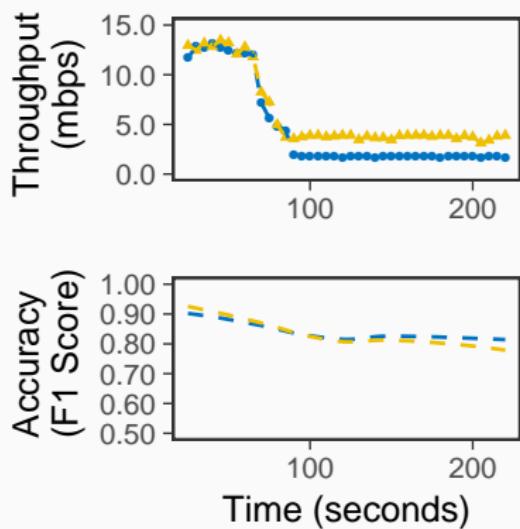
PC: https://en.wikipedia.org/wiki/Video_compression_picture_types

- **I-frames** are the least compressible but don't require other video frames to decode. I-frames are further compressed with quantization.
- **P-frames** can use data from previous frames to decompress and are more compressible than I-frames.
- **B-frames** can use both previous and forward frames for data reference to get the highest amount of data compression (not an option in live streaming).

Evaluation: Resource Allocation for Multiple Applications

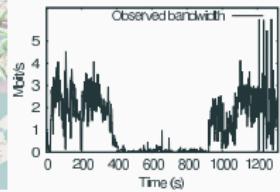


(a) Resource Fairness

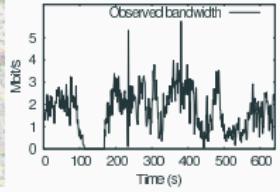


(b) Utility Fairness

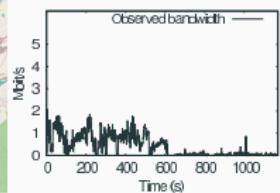
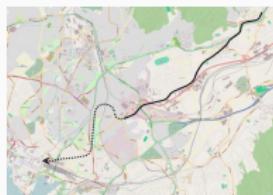
Bandwidth Fluctuations (Cellular)



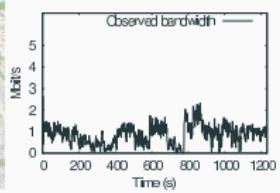
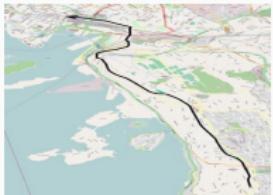
(a) Ferry



(c) Bus



(b) Metro (dotted line in tunnel)



(d) Tram

Riiser, Haakon, et al. "A comparison of quality scheduling in commercial adaptive HTTP streaming solutions on a 3G network." Proceedings of the 4th Workshop on Mobile Video. ACM, 2012.

Bandwidth Fluctuations (WiFi)

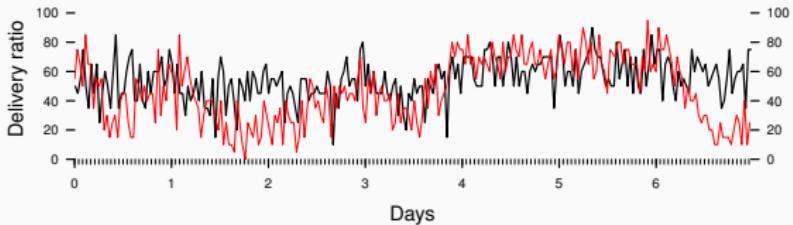


Figure 4: Delivery ratio variation over a week for two randomly chosen 2.4 GHz links.

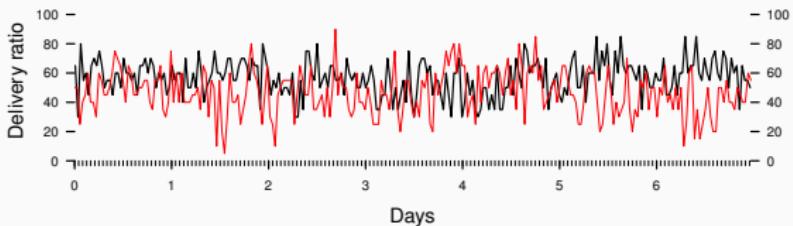


Figure 5: Delivery ratio variation over a week for two randomly chosen 5 GHz links.

Biswas et al, Cisco Meraki, Large-scale Measurements of Wireless Network Behavior, SIGCOMM'15. Two randomly chosen links.

Continue with the main slides.

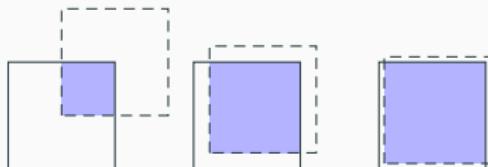
Augmented Reality

- Training and testing data characteristics
 - 1920x1080 resolution with 30 FPS
 - training: 707 frames (23.5 seconds), testing: 1384 frames (46 seconds)
- Object Recognition
 - Darknet: Open Source Neural Networks in C
 - Developed by Joseph Redmon, "Do whatever you want with it" license
 - It supports CPU/GPU
 - In this work, I am using a pre-trained model with Coco dataset
- Other systems such as TensorFlow, Caffe would also work

IOU and F1

Positive if intersection over union (IOU) larger than 0.5.

$$\text{IOU} = \frac{\text{Area of Intersection}}{\text{Area of Union}}$$



(a) $\text{IOU}=0.14$ (b) $\text{IOU}=0.57$ (c) $\text{IOU}=0.82$

F1 is the harmonic mean of precision and recall:

	P	N
Y	True Positive	False Positive
N	True Positive	False Positive

$$\text{Precision} = \frac{\text{true positive}}{\text{all positive}}$$

$$\text{Recall} = \frac{\text{true positive}}{\text{all detection}}$$

$$F1 = \frac{2}{\frac{1}{\text{Recall}} + \frac{1}{\text{Precision}}}$$

references i

-  Abdi, H. (2007).
The Kendall Rank Correlation Coefficient.
Encyclopedia of Measurement and Statistics. Sage, Thousand Oaks, CA, pages 508–510.
-  Alipourfard, O., Liu, H. H., Chen, J., Venkataraman, S., Yu, M., and Zhang, M. (2017).
CherryPick: Adaptively Unearthing the Best Cloud Configurations for Big Data Analytics.
In *14th USENIX Symposium on Networked Systems Design and Implementation (NSDI 17)*, pages 469–482, Boston, MA. USENIX Association.
-  Amerasinghe, K. (2009).
H. 264 for the rest of us.
-  Andersen, M. P. and Culler, D. E. (2016).
Btrdb: Optimizing storage system design for timeseries processing.
In *FAST*, pages 39–52.
-  Binois, M. and Picheny, V. (2018).
GParEto: An R Package for Gaussian-Process Based Multi-Objective Optimization and Analysis.
-  Biswas, S., Bicket, J., Wong, E., Musaloiu-e, R., Bhartia, A., and Aguayo, D. (2015).
Large-scale measurements of wireless network behavior.
In *ACM SIGCOMM Computer Communication Review*, volume 45, pages 153–165. ACM.

references ii

-  Bonomi, F., Milito, R., Zhu, J., and Addepalli, S. (2012).
Fog Computing and Its Role in the Internet of Things.
In *Proceedings of the first edition of the MCC workshop on Mobile cloud computing*, pages 13–16. ACM.
-  DERA (2003–2016).
EDGAR Log File Data Set.
<https://www.sec.gov/data/edgar-log-file-data-set>.
Accessed: 2017-01-25.
-  Hernández-Lobato, D., Hernandez-Lobato, J., Shah, A., and Adams, R. (2016).
Predictive Entropy Search for Multi-Objective Bayesian Optimization.
In Balcan, M. F. and Weinberger, K. Q., editors, *Proceedings of The 33rd International Conference on Machine Learning*, volume 48 of *Proceedings of Machine Learning Research*, pages 1492–1501, New York, New York, USA. PMLR.
-  Kumar, A., Jain, S., Naik, U., Raghuraman, A., Kasinadhuni, N., Zermeno, E. C., Gunn, C. S., Ai, J., Carlin, B., Amarandei-Stavila, M., et al. (2015).
Bwe: Flexible, hierarchical bandwidth allocation for wan distributed computing.
In *ACM SIGCOMM Computer Communication Review*, volume 45, pages 1–14. ACM.
-  Milan, A., Leal-Taixé, L., Reid, I., Roth, S., and Schindler, K. (2016).
MOT16: A Benchmark for Multi-Object Tracking.
arXiv preprint arXiv:1603.00831.

references iii

-  Pantos, R. and May, W. (2016).
HTTP Live Streaming.
-  Rabkin, A., Arye, M., Sen, S., Pai, V. S., and Freedman, M. J. (2014).
Aggregation and Degradation in JetStream: Streaming Analytics in the Wide Area.
In *Proceedings of the 11th USENIX Conference on Networked Systems Design and Implementation*, NSDI'14, pages 275–288, Berkeley, CA, USA. USENIX Association.
-  Rijsbergen, C. J. V. (1979).
Information Retrieval.
Butterworth-Heinemann, Newton, MA, USA, 2nd edition.
-  Satyanarayanan, M., Bahl, P., Caceres, R., and Davies, N. (2009).
The Case for VM-based Cloudlets in Mobile Computing.
IEEE Pervasive Computing, 8(4):14–23.
-  Shahriari, B., Swersky, K., Wang, Z., Adams, R. P., and De Freitas, N. (2016).
Taking the human out of the loop: A review of bayesian optimization.
Proceedings of the IEEE, 104(1):148–175.
-  Solnik, B., Golovin, D., Kochanski, G., Karro, J. E., Moitra, S., and Sculley, D. (2017).
Bayesian Optimization for a Better Dessert.

-  Viola, P. and Jones, M. (2001).
Rapid Object Detection Using a Boosted Cascade of Simple Features.
In *Proceedings of the 2001 IEEE Computer Society Conference on Computer Vision and Pattern Recognition. CVPR 2001*, volume 1, pages I-511–I-518 vol.1.
-  Wang, B., Zhang, X., Wang, G., Zheng, H., and Zhao, B. Y. (2016).
Anatomy of a Personalized Livestreaming System.
In *Proceedings of the 2016 ACM on Internet Measurement Conference*, pages 485–498. ACM.
-  Zhang, B., Mor, N., Kolb, J., Chan, D. S., Lutz, K., Allman, E., Wawrzynek, J., Lee, E. A., and Kubiatowicz, J. (2015).
The Cloud is Not Enough: Saving IoT from the Cloud.
In *7th USENIX Workshop on Hot Topics in Cloud Computing (HotCloud 15)*. USENIX Association.