

```
In [1]: import numpy as np
import pandas as pd
import matplotlib
import matplotlib.pyplot as plt
from sklearn import linear_model
```

### 1,(a) $y = \beta_0 + \beta_1x_1 + \beta_2x_2$

```
In [13]: X = np.array([[0,1,0,1],[0,0,1,1]]).T
y = np.array([2,4,4,5])
```

```
In [17]: nsamp = len(y)
ones = np.ones((nsamp,1))
A = np.hstack((ones,X))
out = np.linalg.lstsq(A,y)
beta = out[0]
beta
```

```
/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:4: FutureWarning: `rcond` parameter will change to the default of machine precision times ``max(M, N)`` where M and N are the input matrix dimensions.
To use the future default and silence this warning we advise to pass `rcond=None`, to keep using the old, explicitly pass `rcond=-1`.
    after removing the cwd from sys.path.
```

```
Out[17]: array([2.25, 1.5 , 1.5 ])
```

### 1. (b) $\beta_0 = 2.25$ $\beta_1 = 1.5$ $\beta_2 = 1.5$

```
In [15]: # Create linear regression object
regr = linear_model.LinearRegression()
regr.fit(X,y)
y_pred = regr.predict(X)
RSS = np.sum((y_pred-y)**2)
Rsq = 1-RSS/len(y)/(np.std(y)**2)
Rsq
```

```
Out[15]: 0.9473684210526316
```

### 1,(c) $R^2$ is 0.9474

2. (a) target variable  $y$  is the age at which the clients died.
- (b) let blood pressure as  $X_1$ , heart rate as  $X_2$ , BMI as  $X_3$ .  
 The model is:
- $$y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_3$$
- (c) Use one-hot encoding to encode the gender  
 Use non-redundant one-hot encoding. Let gender as  $X_4$ , ~~is~~ when the client is female  $X_4=1$ , when the client is male  $X_4=0$   
 the model is:

$$y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_3 + \beta_4 X_4$$

Reason: one-hot coding allows a different intercept for each category. The redundant one-hot coding can avoid the problem of making  $A^T A$  non-invertible.

3. (a)  $y_k \approx \sum_{l=1}^L a_l \cos(\omega_l k) + b_l \sin(\omega_l k)$

$$\underline{y} \propto \underline{AB}$$

$$\underline{y} = [y_0, y_1, \dots, y_N]$$

$$\underline{\beta} = [\beta_0, \beta_1, \dots, \beta_{2L}] = [\beta_0 a_1, a_2, \dots, a_L, b_1, b_2, \dots, b_L]$$

$$\underline{A} = [I \quad \underline{x}]$$
 ~~$\underline{x} = [\cos(\omega_1 \cdot 0), \cos(\omega_2 \cdot 0), \dots, \cos(\omega_L \cdot 0), \sin(\omega_1 \cdot 0), \dots, \sin(\omega_2 \cdot 0), \dots, \sin(\omega_L \cdot 0)]$~~ 

$$\underline{x} = [\cos(\omega_1 \cdot 1), \cos(\omega_2 \cdot 1), \dots, \cos(\omega_L \cdot 1), \sin(\omega_1 \cdot 1), \dots, \sin(\omega_2 \cdot 1), \dots, \sin(\omega_L \cdot 1)]$$

$$\vdots \qquad \vdots \qquad \vdots$$

3.1(a)  
continue:

$$\underline{X} = \begin{bmatrix} \cos(\omega_1 \cdot 0) & \cos(\omega_2 \cdot 0) & \cdots & \cos(\omega_L \cdot 0) & \sin(\omega_1 \cdot 0) & \cdots & \sin(\omega_L \cdot 0) \\ \cos(\omega_1 \cdot 1) & \cos(\omega_2 \cdot 1) & \cdots & \cos(\omega_L \cdot 1) & \sin(\omega_1 \cdot 1) & \cdots & \sin(\omega_L \cdot 1) \\ \vdots & \vdots & & \vdots & \vdots & & \vdots \\ \cos(\omega_1 \cdot (N-1)) & \cos(\omega_2 \cdot (N-1)) & \cdots & \cos(\omega_L \cdot (N-1)) & \sin(\omega_1 \cdot (N-1)) & \cdots & \sin(\omega_L \cdot (N-1)) \end{bmatrix}$$

$\underline{X}$  is  $2L \times N$  matrix

so  $A = \begin{bmatrix} 1 \\ \vdots \\ 1 \\ \vdots \\ 1 \end{bmatrix}$

$A$  is  $(2L+1) \times N$  matrix

(b) No if  $\omega_2$  is unknown, this would not be a linear regression problem

because  $\cos \omega_2 \cdot \sin \omega_2$  is not linear  
the relationship between  $y$  and

4.

(a)  $\underline{\beta} = [1 \ a_1 \ a_2 \ \dots \ a_M \ b_1 \ b_2 \ \dots \ b_N]$   
 $M+N+2$  unknown parameters

(b)  $\underline{y} \approx \underline{A}\underline{\beta}$

$$\underline{y} = [y_0 \ y_1 \ y_2 \ \dots \ y_{T-1}]$$

$$\underline{A} = \begin{bmatrix} 1 & 0 & 0 & 0 & \dots & u_0 & 0 & 0 & \dots & 0 \\ 1 & y_0 & 0 & 0 & \dots & u_1 & u_0 & 0 & \dots & 0 \\ 1 & y_1 & y_0 & 0 & \dots & u_2 & u_1 & u_0 & \dots & 0 \\ 1 & y_2 & y_1 & y_0 & \dots & u_3 & u_2 & u_1 & u_0 & 0 \\ \vdots & \vdots & \vdots & \vdots & & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & y_{T-2} & y_{T-3} & y_{T-4} & \dots & y_{T-1} & u_{T-1} & u_{T-2} & \dots & u_{T-N} \end{bmatrix}$$