

1) $\|\text{proj}_{u,v}(v)\| = ?$

Since v is orthogonal to the vector $u \times v$, the result must also equal to 0.

2) $\|u-v\| = \sqrt{3} \rightarrow \|u-v\|^2 = 3 \rightarrow \|u - 2uv \cos\theta + v\|^2 = 3$

$$u^2 + v^2 - 2u \cdot v \cdot \cos\theta = 3$$

$$1+1 - 2 \cdot \cos\theta = 3$$

$$\cos\theta = -\frac{1}{2}$$

$$\sin\theta = \frac{\sqrt{3}}{2}$$

$$\|u \times v\| = uv \sin\theta = \frac{\sqrt{3}}{2}$$

3) Cauchy-Schwarz $\Rightarrow \|u \cdot v\| \leq \|u\| \cdot \|v\|$

Assume that $u = (1, \frac{1}{2}, \frac{1}{3}, \dots, \frac{1}{n})$ and $v = (\frac{1}{e^2}, \frac{1}{e^4}, \frac{1}{e^6}, \dots, \frac{1}{e^n})$

$$\|u\| = \sqrt{1 + \frac{1}{2^2} + \frac{1}{3^2} + \dots + \frac{1}{n^2}}$$

$$= \sqrt{\sum_{n=1}^{\infty} \frac{1}{n^2}} = \sum_{n=1}^{\infty} \frac{1}{n} = \sqrt{\frac{\pi^2}{6}}$$

$$\|v\| = \sqrt{\frac{1}{e^2} + \frac{1}{e^4} + \frac{1}{e^6} + \dots + \frac{1}{e^{2n}}}$$

$$= \sqrt{\sum_{n=1}^{\infty} \left(\frac{1}{e^2}\right)^n} = \sqrt{\frac{e^2}{1-e^2}} = \sum_{n=1}^{\infty} e^{-n}$$

$$\sum_{n=1}^{\infty} \frac{e^{-n}}{n} = \sqrt{\frac{\pi^2}{6}} \cdot \sqrt{\frac{e^2}{1-e^2}} = \frac{\pi \cdot e}{\sqrt{6 \cdot (1-e^2)}}$$

4) $c_1(1, 1, 2, 1) + c_2(1, -2, -2, 0) + c_3(0, 1, 1, -2) = (3, -1, 1, 4)$

$$c_1 + c_2 = 3$$

$$c_1 - 2c_2 + c_3 = -1$$

$$2c_1 - 2c_2 + c_3 = 1$$

$$c_1 - 2c_3 = 4$$

* It can be represented with

these coefficients (4)

5)

$$\begin{bmatrix} 1 & -1 & 1 & w_1 \\ 2 & -1 & -3 & w_2 \\ 0 & -3 & -1 & w_3 \end{bmatrix} \xrightarrow{(R_2 + 2R_1)} \begin{bmatrix} -1 & -1 & 1 & w_1 \\ 0 & -3 & -1 & w_2 + 2w_1 \\ 0 & -3 & -1 & w_3 \end{bmatrix} \xrightarrow{(R_3 - R_2)} \begin{bmatrix} -1 & -1 & 1 & w_1 \\ 0 & -3 & -1 & w_2 + 2w_1 \\ 0 & 0 & 0 & w_3 - w_2 - 2w_1 \end{bmatrix}$$

* The domain is \mathbb{R}^3

The codomain is \mathbb{R}^3

* The standard Matrix is:

$$\begin{bmatrix} -1 & -1 & 1 \\ 2 & -1 & -3 \\ 0 & -3 & -1 \end{bmatrix}$$

* The range is any set of (w_1, w_2, w_3)

satisfying $2w_1 + w_2 = w_3$

6)

$$a) \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & -1 \\ 1 & -1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & -1 \\ 0 & 0 \end{bmatrix}$$

$$b) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -3 \\ 0 \end{bmatrix}$$

$$c) \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$d) \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ -2+2\sqrt{3} \\ -2+3\sqrt{3} \end{bmatrix}$$

e)

$$\begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

$$7) T_1 \circ T_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos - \sin & 0 \\ 0 & \sin & \cos \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & \sin & \cos \end{bmatrix}$$

$$T_1 \circ T_2 \neq T_2 \circ T_1$$

$$T_2 \circ T_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos - \sin & 0 \\ 0 & \sin & \cos \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & -\sin \\ 0 & 0 & \cos \end{bmatrix}$$

8)

$$a) \begin{bmatrix} 1 & 1 & -1 \\ 2 & -3 & -1 \\ 5 & 6 & -4 \end{bmatrix} \xrightarrow{(R_2 - 2R_1)} \begin{bmatrix} 1 & 1 & -1 \\ 0 & -5 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{(R_2 + 5R_3)} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{(R_2, R_3 \text{ swap})} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{(R_1 - R_2)} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \text{independent one-to-one}$$

(R₂ - 2R₁) (R₂ + 5R₃) (R₂, R₃ swap) (R₁ - R₂)

(R₃ - 5R₁) (then R₂ - $\frac{1}{6}$ R₁) (then R₂ - R₃) (R₁ + R₃)

$$b) \begin{bmatrix} 1 & -3 & -1 \\ 1 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} \xrightarrow{(R_2 - R_1)} \begin{bmatrix} 1 & -3 & -1 \\ 0 & 4 & 0 \\ 0 & 3 & 0 \end{bmatrix} \xrightarrow{(R_3 - R_1)} \begin{bmatrix} 1 & -3 & -1 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{No pivot every column, row of zeros, determinant 0, } \infty \text{ solutions, Many-to-one, Has no inverse.}$$

(R₂ - R₁) (R₃ - $\frac{3}{4}$ R₂)

Inverse of a

$$\begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 2 & -3 & -1 & 0 & 1 & 0 \\ 5 & 6 & -4 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{(R_2 - 2R_1)} \begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 0 & -5 & -1 & -2 & 1 & 0 \\ 0 & 1 & 1 & -5 & 0 & 1 \end{bmatrix} \xrightarrow{(R_2 + 5R_3)} \begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 0 & 5 & 1 & -2 & 1 & 0 \\ 0 & 1 & 1 & -5 & 0 & 1 \end{bmatrix} \xrightarrow{(R_1 - R_2)} \begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 0 & 1 & -5 & 0 & 1 & 0 \\ 0 & 1 & 1 & -5 & 0 & 1 \end{bmatrix} \xrightarrow{(R_3 - R_1)} \begin{bmatrix} 1 & 1 & -1 & 1 & 0 & 0 \\ 0 & 1 & -5 & 0 & 1 & 0 \\ 0 & 0 & 6 & -2 & 1 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -2 & 6 & 0 & -1 \\ 0 & 1 & 1 & -5 & 0 & 1 \\ 0 & 0 & 1 & -9 & \frac{1}{2} & \frac{5}{6} \end{bmatrix} \xrightarrow{(R_2 - R_1)} \begin{bmatrix} 1 & 0 & 0 & -3 & \frac{1}{3} & \frac{2}{3} \\ 0 & 1 & 0 & -3 & -1 & 1/6 \\ 0 & 0 & 1 & -9 & \frac{1}{2} & \frac{5}{6} \end{bmatrix}$$

inverse transformation of a is

$$\begin{bmatrix} -3 & \frac{1}{3} & \frac{2}{3} \\ \frac{1}{2} & -\frac{1}{6} & \frac{1}{6} \\ \frac{-9}{2} & \frac{1}{6} & \frac{5}{6} \end{bmatrix}$$

The range is a subset of the codomain which is \mathbb{R}^3 .

9) $T(x_1, x_2) + T(a, b) \stackrel{?}{=} T(x_1+a, x_2+b)$

$$(2x_1+2a+x_2+b, 2-x_1-a) \neq (2x_1+2a+x_2+b, 1-x_1-a)$$

*The transformation is not linear.

10) $\begin{array}{l} L \\ - \end{array} x + \begin{array}{l} t \\ - \end{array} = y \quad A \cdot \begin{bmatrix} x \\ 1 \end{bmatrix} = \begin{bmatrix} y \\ 1 \end{bmatrix}$

$$\begin{bmatrix} L & t \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} = \begin{bmatrix} Lx + t \\ 1 \end{bmatrix} = \begin{bmatrix} y \\ 1 \end{bmatrix}$$

11) $\begin{bmatrix} 1/2 & 0 & \frac{\sqrt{3}}{2} \\ 0 & 1 & 0 \\ \frac{\sqrt{3}}{2} & 0 & 1/2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1/2 & 0 & \frac{\sqrt{3}}{2} \\ 0 & 0 & 0 \\ \frac{\sqrt{3}}{2} & 0 & 1/2 \end{bmatrix} \rightsquigarrow \text{The standard matrix}$

12) T_1 = many-to-one, dependent, has row of 0's, non-invertible.

T_2 = one-to-one, independent, invertible.

Assume

$$T_1 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T_2 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$T_1 \circ T_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$T_2 \circ T_1 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

determinant = 0

determinant = 0

not invertible

13) Vector space $\rightarrow a, b, a+b, ka \in V$

a)

$$a = (x_1, y_1, z_1) \quad b = (x_2, y_2, z_2) \quad a+b = (x_1+x_2, y_1+y_2, z_1+z_2)$$

$$k+z=2y \rightarrow x_1+z=2y_1, x_2+z=2y_2, x_1+x_2+z_1+z_2=2y_1+2y_2$$

$$kx_1 + kz_1 = 2ky_1$$

$$kx_2 + kz_2 = 2ky_2$$

Vector Space



$$b) x_1^2 + y_1^2 + z_1^2 = 0 \Rightarrow x_1^2 + y_1^2 + z_1^2 = 0, x_2^2 + y_2^2 + z_2^2 = 0$$

$$(x_1+x_2)^2 + (y_1+y_2)^2 + (z_1+z_2)^2 = x_1^2 + 2x_1x_2 + x_2^2 + y_1^2 + 2y_1y_2 + y_2^2 + z_1^2 + 2z_1z_2 + z_2^2$$

* As in real space all the values can only be 0. It is a vector space.

$$c) x - y = 1 \Rightarrow x_1 - y_1 = 1, x_2 - y_2 = 1 \rightarrow x_1 + x_2 - y_1 - y_2 = 2$$

Not Vector Space

$$d) x + y < 1 \Rightarrow x_1 + y_1 < 1, x_2 + y_2 < 1 \rightarrow x_1 + y_1 + x_2 + y_2 < 2$$

Not Vector Space

14)

$$a - \begin{bmatrix} a & b \\ a+b & 0 \end{bmatrix} + \begin{bmatrix} d & e \\ d+e & 0 \end{bmatrix} = \begin{bmatrix} a+d & b+e \\ a+b+d+e & 0 \end{bmatrix}, K \cdot \begin{bmatrix} a & b \\ a+b & 0 \end{bmatrix} = \begin{bmatrix} ka & kb \\ k(a+b) & 0 \end{bmatrix} \Rightarrow \text{Subspace}$$

$$b - \begin{bmatrix} a & b \\ ab & 0 \end{bmatrix} + \begin{bmatrix} d & e \\ de & 0 \end{bmatrix} = \begin{bmatrix} a+d & b+e \\ ab+de & 0 \end{bmatrix} \rightarrow \text{Not Subspace}$$

$$c - \begin{bmatrix} a & b \\ ab & 1 \end{bmatrix} + \begin{bmatrix} d & e \\ de & 1 \end{bmatrix} = \begin{bmatrix} a+d & b+e \\ ab+de & 2 \end{bmatrix} \rightarrow \text{Not Subspace}$$

15) Subspace axioms require functions to ensure $k \cdot w \in W$. If $k=0$, then the result becomes equal to zero which is not a subspace.

16) Because of the requirements of subspace axioms, $k \cdot w \in W$ must be true. So if $k=0$, the result is equal to 0 matrix and not invertible. Hence, they can not form a subspace.

Let's assume $V = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $W = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $V+W = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$v \in W, w \in W$ but $v+w \notin W$ so they don't form a subspace.

17)

$$a) \begin{bmatrix} 1 & 0 & -2 & 2 \\ 2 & 1 & 4 & -4 \\ 1 & -1 & 3 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & -2 & 2 & 0 \\ 2 & 1 & 4 & -4 & 0 \\ 1 & -1 & 3 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 8 & -8 & 0 \\ 0 & -1 & 5 & -2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 8 & -8 & 0 \\ 0 & 0 & 13 & -10 & 0 \end{bmatrix}$$

$(R_2 - 2R_1)$ $(R_3 + R_2)$
 $(R_3 - R_1)$

$$\left[\begin{array}{ccccc} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 0 & -\frac{24}{13} & 0 \\ 0 & 0 & 1 & \frac{-10}{13} & 0 \end{array} \right] \xrightarrow{\text{(R}_3 + R_1\text{)}} \left[\begin{array}{ccccc} 1 & 0 & 0 & \frac{6}{13} & 0 \\ 0 & 1 & 0 & \frac{24}{13} & 0 \\ 0 & 0 & 1 & \frac{-10}{13} & 0 \end{array} \right] \Rightarrow \begin{aligned} x_1 &= -\frac{6}{13}x_4 \\ x_2 &= \frac{24}{13}x_3 \\ x_3 &= \frac{10}{13}x_4 \end{aligned}$$

$(R_3 + R_1)$ $(R_1 + 2R_3)$

(then $R_2 - 8R_3$)

$$b) \begin{bmatrix} 1 & 0 & -2 & 2 & 0 \\ 2 & 1 & 4 & -4 & 0 \end{bmatrix} \xrightarrow{\text{Row operations}} \begin{bmatrix} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 8 & -8 & 0 \end{bmatrix} \quad \begin{aligned} x_1 &= 2x_3 + 2x_4 \\ x_2 &= 8x_4 - 8x_3 \end{aligned}$$

$R_2 \rightarrow R_2 - 2R_1$

$$\text{C) } \left[\begin{array}{ccccc|c} 1 & 0 & -2 & 2 & 0 \\ 2 & 1 & 4 & -4 & 0 \\ 0 & 1 & 6 & -6 & 0 \end{array} \right] \xrightarrow{\text{(R}_2 - 2\text{R}_1\text{)}} \left[\begin{array}{ccccc|c} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 8 & -8 & 0 \\ 0 & 1 & 6 & -6 & 0 \end{array} \right] \xrightarrow{\text{(R}_3 - \text{R}_2\text{)}} \left[\begin{array}{ccccc|c} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 8 & -8 & 0 \\ 0 & 0 & -2 & 2 & 0 \end{array} \right] \xrightarrow{\text{(R}_3 + \frac{1}{2}\text{R}_1\text{)}} \left[\begin{array}{ccccc|c} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{array} \right] \xrightarrow{\text{(R}_1 + 2\text{R}_3\text{)}} \left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{array} \right]$$

$(R_2 - 2R_1)$ $(R_3 - R_2)$ $(R_3 + \frac{1}{2}R_1)$ $(R_1 + 2R_3)$
 $(R_2 - 8R_3)$

$$d) \begin{bmatrix} 1 & 0 & -2 \\ 2 & 0 & -4 \\ 0 & 1 & 6 \\ -1 & 0 & 8 \end{bmatrix} \xrightarrow{\text{(R}_2 - 2\text{R}_1)} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 0 & 0 \\ 0 & 1 & 6 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\text{(R}_2 \text{ swapped R}_3)} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$x_1 = 0$
 $x_2 = 0$
 $x_3 = 0$

$(R_2 - 2R_1)$ $(R_2 \text{ swapped } R_3)$
 $(R_4 + R_1)$ $(R_3 \text{ swapped } R_4)$
 $(R_1 - \frac{1}{6})$ $(R_2 - 6R_4)$

$$18) \quad a) \quad \left[\begin{array}{ccc|c} 4 & -2 & 0 & x \\ 3 & 0 & 3 & y \\ 2 & -1 & 0 & z \\ 1 & 0 & 1 & w \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 4 & -2 & 0 & x \\ 3 & 0 & 3 & y \\ 0 & 0 & 0 & z - \frac{x}{2} \\ 0 & 0 & 0 & w - y/3 \end{array} \right]$$

$x, y, z, w \in \mathbb{R}^4$

$w = \frac{y}{3}$

$z = \frac{x}{2}$

$(R_3 - \frac{1}{2}R_1)$

$(R_4 - \frac{1}{3}R_2)$

$$b) c_1(4, 3, 2, 1) + c_2(-2, 0, -1, 0) + c_3(0, 3, 0, 1) = 0$$

$$4c_1 = 2c_2 \quad c_2 = 2c_1 \quad * \text{The equation has more than only trivial solution. Also, the matrix form has row of 0's. Thus, dependent.}$$

$$c_1 = -c_3 \quad c_3 = -c_1$$

$$c) c_1(0, 3, 0, 1) + c_2(-2, 0, -1, 0) = (4, 3, 2, 1)$$

$a_2 = -2 \quad a_1 = 1$ * Basis of \mathbb{R}^4 must have 4 vectors so two more vectors must be added which are not in the span.

$$\begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$1.) \mathbf{V} = \begin{vmatrix} f(x) & f_1(x) \\ f'(x) & f_2'(x) \end{vmatrix} \quad V \neq \text{dependent} \quad \begin{vmatrix} \cos(2x) & \cos^2 x - \sin^2 x \\ -2\sin(2x) & -2\sin x \cos x - 2\sin x \cos x \end{vmatrix}$$

$$-(\cos(2x)) \cdot 4\sin x \cdot \cos x + (\cos 2x) 4\sin x \cdot \cos x = 0 \rightarrow \text{dependent}$$

$$20) \begin{bmatrix} 1 & 1 & 1 & 0 & k_1 \\ -2 & 2 & 0 & 0 & k_2 \\ 0 & 4 & -1 & 7 & k_3 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 0 & k_1 \\ -2 & 2 & 0 & 0 & k_2 \\ 0 & 4 & -1 & 7 & k_3 \end{bmatrix} \xrightarrow{\begin{array}{l} R_2 \rightarrow R_2 + \frac{1}{2}R_1 \\ \text{(then } R_2 \leftrightarrow R_1\text{)} \end{array}} \begin{bmatrix} 1 & 1 & 1 & 0 & k_1 \\ 0 & 2 & 1 & 0 & k_1 + k_2/2 \\ 0 & 4 & -1 & 7 & k_3 \end{bmatrix} \xrightarrow{\begin{array}{l} R_3 \rightarrow R_3 - 2R_1 \\ R_3 \rightarrow R_3 - 4R_2 \end{array}} \begin{bmatrix} 1 & 1 & 1 & 0 & k_1 \\ 0 & 1 & \frac{1}{2} & 0 & k_1/2 + k_2/4 \\ 0 & 0 & -3 & 7 & k_3 - k_2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 0 & k_1 \\ 0 & 1 & \frac{1}{2} & 0 & k_1/2 + k_2/4 \\ 0 & 0 & -3 & 7 & k_3 - k_2 - 2k_1 \end{bmatrix}$$

Basis is

$$\begin{bmatrix} 1 & 1 & 1 \\ -2 & 1 & 2 \\ 0 & 4 & -1 \end{bmatrix}$$

with dimension \mathbb{R}^3

$$a_1 \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} + a_2 \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} + a_3 \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$a_1 + a_2 + a_3 = 0$$

$$a_1 = -a_2$$

$$a_1 = a_2 = \frac{7}{6}$$

$$4a_2 - a_3 = 7$$

$$a_3 = -\frac{7}{3}$$

21) Dependent Vectors $\rightarrow c_1v_1 + c_2v_2 + c_3v_3 + c_4v_4 = 0$, has more than only trivial solution.

And if one of the remaining vectors is the combination of other two vectors, then there will be a possibility of the set being independent.

- Basis of \mathbb{R}^4 must consist of 4 vectors, therefore 3 vectors are not enough to be basis hence no basis.

22) \mathbb{R}^5 can be written with 5 independent vectors at most. Thus at most only 1 vector can be added.

23) U, V and W are not on the same plane if they are independent. $\text{proj}_{UV} w$ can be equal to w which makes $\text{proj}_{UV} w, v$ and u independent.

If U, V and W are orthogonal, then $\text{proj}_{UV} w$ becomes 0. Thus $\text{proj}_{UV} w$ and U, V becomes dependent because the sets contains containing zero vector is linearly dependent.

24) Basis of 2×2 matrices consists of 4 vectors. If the set has 5, at least 1 vector is linearly dependent. Hence it can be written as a linear combination of the other vectors.

- Basis of 3×3 matrices consists of 9 vectors. If the set has 5 vectors, then every vector can be independent. Therefore, they can not be written as a combination of the other vectors.

25)

a) 4 vectors are not enough to be basis for \mathbb{R}^6 since basis of \mathbb{R}^6 has 6 vectors.

b) $\begin{vmatrix} -x & y \\ x & -y \end{vmatrix} \rightarrow \begin{vmatrix} 0 & 0 \\ x-y & \end{vmatrix}$ determinant is 0, dependent \rightarrow can't form basis for \mathbb{R}^2

$$\left[\begin{array}{ccc|c} 1 & 1 & -1 & a_1 \\ 1 & 2 & 0 & a_2 \\ -1 & 2 & 6 & a_3 \end{array} \right] \sim \left[\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 1 & -3 & 0 \end{array} \right]$$

$$\begin{array}{cccccc} \left[\begin{array}{ccc|c} 1 & 1 & -1 & 0 \\ 1 & 2 & 0 & 0 \\ -1 & 2 & 6 & 0 \end{array} \right] & \xrightarrow{(R_2-R_1)} & \left[\begin{array}{ccc|c} 1 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 2 & 6 & 0 \end{array} \right] & \xrightarrow{(R_3+3R_2)} & \left[\begin{array}{ccc|c} 1 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{array} \right] & a_1=0 & \text{Only the trivial} \\ & & \xrightarrow{(R_3-R_1)} & & \xrightarrow{(R_1-R_2)} & a_2=0 & \text{solutions so independent} \\ & & \left[\begin{array}{ccc|c} 1 & 1 & -1 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 1 & -3 & 0 \end{array} \right] & & \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{array} \right] & a_3=0 & \text{can be basis for } \mathbb{R}^3 \end{array}$$

(R_2-R_1) $(R_2 \cdot \frac{1}{4})$ (R_3+3R_2)
 (R_3+R_1) $(R_3 \cdot \frac{1}{4})$ $(R_1+R_2-R_3)$

d) Any set containing 0 vector is dependent. Therefore can't be basis for \mathbb{R}^n .

26)

$$\begin{bmatrix} 2 & 0 & 1 \\ -2 & 1 & 5 \\ 0 & 1 & 4 \end{bmatrix} \cdot \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 0 & 1 & 1 \\ -2 & 1 & 5 & 1 \\ 0 & 1 & 4 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 0 & 1 & 1 \\ 0 & 1 & 6 & 2 \\ 0 & 1 & 4 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1/2 & 1/2 \\ 0 & 1 & 6 & 2 \\ 0 & 0 & 10 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1/2 & 1/2 \\ 0 & 1 & 6 & 2 \\ 0 & 0 & 1 & 3/10 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 3/10 \\ 0 & 1 & 0 & 2/10 \\ 0 & 0 & 1 & 3/10 \end{bmatrix} \Rightarrow k_1 = \frac{3}{20}, k_2 = \frac{1}{5}, k_3 = \frac{3}{10}$$

$$\frac{3}{20}a + \frac{1}{5}b + \frac{3}{10}c = w$$

$(\frac{3}{20}, \frac{1}{5}, \frac{3}{10}) \rightarrow \text{coordinates}$

27)

a) All the given vectors are in 3 dimension which can have an linearly independent set of maximum 3 vectors. 4 vectors can not form a linearly independent set.

$$\begin{bmatrix} 2 & 0 & 1 & 1 \\ -1 & 1 & -1 & 0 \\ -1 & 3 & -2 & 1 \end{bmatrix} \cdot \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 0 & 1 & 1 & x \\ -1 & 1 & -1 & 0 & y \\ -1 & 3 & -2 & 1 & z \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1/2 & 1/2 & x/2 \\ -1 & 1 & -1 & 0 & y \\ 0 & 2 & -1 & 1 & z-y \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1/2 & 1/2 & x/2 \\ 1 & -1 & 1 & 0 & -y \\ 0 & 1 & -1/2 & 1/2 & (z-y)/2 \end{bmatrix}$$

$(R_1 - \frac{1}{2}R_2), (R_3 - R_2), (R_2, -1)$

$$\begin{bmatrix} 1 & 0 & 1/2 & 1/2 & x/2 \\ 0 & -1 & 1/2 & -1/2 & -y \\ 0 & 1 & -1/2 & 1/2 & (z-y)/2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1/2 & 1/2 & x/2 \\ 0 & 1 & -1/2 & 1/2 & y + x/2 \\ 0 & 0 & 0 & (2-y)/2 & -x/2 \end{bmatrix}$$

$(R_2 - R_1), (R_3 + R_2), (R_2, -1)$

$$z = 3y + x$$

$$x \rightarrow a, y \rightarrow b$$

$$\begin{pmatrix} a \\ b \\ a+3b \end{pmatrix} = a \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \text{ and } \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}$$

c) The space has 2 basis vectors thus the dimension is 2.

$$\rightarrow d) \text{Span} = \begin{pmatrix} a \\ b \\ a+3b \end{pmatrix} \sim a \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix}$$

$$e) a(1,0,1) + b(0,1,3) \stackrel{?}{=} (2,2,0)$$

$$a=2, b=2, a+3b \neq 0$$

↓

*The system is inconsistent so w

is not in the span of $\{v_1, v_2, v_3, v_4\}$

28) $x+y+z=2$, $x \Rightarrow a_1$, $y \Rightarrow a_2$, $z \Rightarrow 2-a_1-a_2$

$a_1 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + a_2 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$ Since the system has a constant, it can't form a basis.

29)

$$\left[\begin{array}{cccc|c} 1 & 1 & -1 & 1 & 0 \\ 2 & -1 & 2 & -1 & 0 \end{array} \right] \xrightarrow{(R_2-2R_1)} \left[\begin{array}{cccc|c} 1 & 1 & -1 & 1 & 0 \\ 0 & -3 & 4 & -3 & 0 \end{array} \right] \xrightarrow{(R_2+1/3R_1)} \left[\begin{array}{cccc|c} 1 & 1 & -1 & 1 & 0 \\ 0 & 1 & -\frac{1}{3} & 1 & 0 \end{array} \right] \xrightarrow{(R_1-R_2)} \left[\begin{array}{ccc|cc} 1 & 0 & 1/3 & 0 & 0 \\ 0 & 1 & -\frac{4}{3} & 1 & 0 \end{array} \right]$$

\downarrow

$x \rightarrow a_1$ $y \rightarrow a_2$
 $-3y \rightarrow a_3$
 $-4x-y \rightarrow a_4$

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{pmatrix} = \begin{pmatrix} x \\ y \\ -3x \\ -4x-y \end{pmatrix} = x \begin{pmatrix} 1 \\ 0 \\ -3 \\ -4 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Dimension is 2.

30) $\begin{pmatrix} 3 \\ 1 \\ -3 \end{pmatrix} - \begin{pmatrix} -1 \\ -\frac{1}{3} \\ 1 \end{pmatrix}$

$$\begin{pmatrix} 3+ \\ 1 \\ -3+ \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -3 \end{pmatrix}$$

Basis is $\begin{pmatrix} 3 \\ 1 \\ -3 \end{pmatrix}$

31)

$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & 3 \\ 0 & -2 & 1 & 2 \\ 1 & 3 & 1 & -1 \end{array} \right] \cdot \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \Rightarrow \left[\begin{array}{ccc|x} 1 & 1 & 0 & 3 & x \\ 0 & -2 & 1 & 2 & y \\ 1 & 3 & 1 & 1 & z \end{array} \right] \xrightarrow{\text{Row operations}} \left[\begin{array}{ccc|x} 1 & 1 & 0 & 3 & x \\ 0 & -2 & 1 & 2 & y \\ 0 & 2 & -1 & -2 & z-x \end{array} \right] \xrightarrow{\text{Row operations}} \left[\begin{array}{ccc|x} 1 & 1 & 0 & 3 & x \\ 0 & -2 & 1 & 2 & y \\ 0 & 0 & 0 & 0 & z+y-x \end{array} \right]$$

$\rightarrow x+y+z=0$

$x \rightarrow a$, $y \rightarrow b$, $-z \rightarrow a-b$

$$\begin{pmatrix} a \\ b \\ a-b \end{pmatrix} = a \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

Span of subspace P^2

* Since the vector number is 2 and not 3, it does not span second order polynomials.

$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ is not in the span of the vectors, so if it is added to the basis, it will span the second order polynomials.