



ESF projekt Západočeské univerzity v Plzni reg. č. CZ.02.2.69/0.0/0.0/16 015/0002287

USVP 2 (Work in progress)

In [1]:

```
# priprava pro Jupyter notebook
%pylab inline
```

Populating the interactive namespace from numpy and matplotlib

Averaging over multiple images.



Figure 1 Example of averaging over multiple images. Inputs (left and middle image) and result (right image)

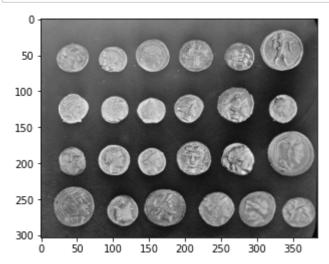
In [2]:

```
import numpy as np
import skimage
import skimage.data
import matplotlib.pyplot as plt
```

In [3]:

```
# Load image coins from skimage.data
img = skimage.data.coins()

# Matplotlib show image like matrix (numpy ndimage)
plt.imshow(img, cmap="gray") # colormap grayscale
plt.show() # nothing showed without this line
```



Average filter

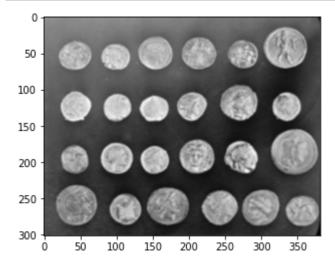
In [4]:

```
def avg filter(img, size):
        Function avg filter
        Function applies average filter with defined size on the input image.
        The function doesn't work with the img borders.
        Thus, the new image is smaller than the input (new_img_size_x == img_siz
e x - floor(size/2), same for y)
        @param img input image
        Oparam size size of the avg filter. size == 3 + 2*k , k = 0,1,2,...
   if (size % 2) == 0:
        return None
   if (size == 1):
        return None
   h = (size // 2)
   output = np.zeros([img.shape[0]-(2*h), img.shape[1]-(2*h)])
   mask = np.ones([size,size]) * (1/(size*size))
   for y in range(h, img.shape[0] - h):
        for x in range(h, img.shape[1] - h):
            output[y - h, x - h] = np.sum(img[y-h:y+h+1,x-h:x+h+1] * mask)
   return output
```

Example for filter size 3

In [5]:

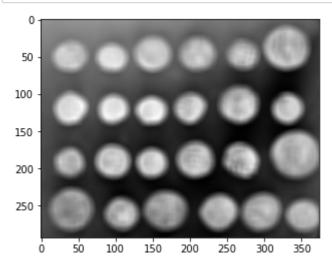
```
output = avg_filter(img, 3)
plt.imshow(output, cmap="gray") # colormap grayscale
plt.show() # nothing showed without this line
```



Example for filter size 11

In [6]:

```
output = avg_filter(img, 11)
plt.imshow(output, cmap="gray") # colormap grayscale
plt.show()
```



Median filter

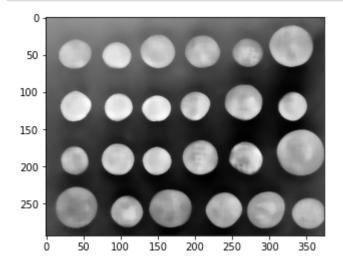
In [7]:

```
def median filter(img, size):
        Median filter
        The function applies median filter of defined size on the input image.
        Filter iteratively grabs parts of the image and search for the median va
lue.
        @param img input image
        Oparam size size of the filter
    h = (size // 2)
    output = np.zeros([img.shape[0]-(2*h), img.shape[1]-(2*h)])
    for y in range(h, img.shape[0] - h):
        for x in range(h, img.shape[1] - h):
            img part = sorted(img[y-h:y+h+1,x-h:x+h+1].ravel())
            if (len(img part) % 2) == 1:
                output[y - h, x - h] = img part[(len(img part) // 2)]
            else:
                output[y - h, x - h] = (img_part[(len(img_part) // 2) - 1] + img_
part[(len(img part) // 2)]) // 2
    return output
```

Example for filter size 11

In [8]:

```
output = median_filter(img, 11)
plt.imshow(output, cmap="gray") # colormap grayscale
plt.show()
```



Edge detection

In [9]:

```
def edge_detect(img, mask):
        Function edge detect
        Function applies mask in order to detect edges in the image.
        @param img input image
        Qparam mask input mask of size == 3 + 2*k , k = 0,1,2,...
    if (mask.shape[0] != mask.shape[1]):
        return None
    if (mask.shape[0] % 2) == 0:
        return None
    if (mask.shape[0] == 1):
        return None
    h = (mask.shape[0] // 2)
    output = np.zeros([img.shape[0]-(2*h), img.shape[1]-(2*h)])
    for y in range(h, img.shape[0] - h):
        for x in range(h, img.shape[1] - h):
            output[y - h, x -h] = np.sum(img[y-h:y+h+1,x-h:x+h+1] * mask)
    return output
```

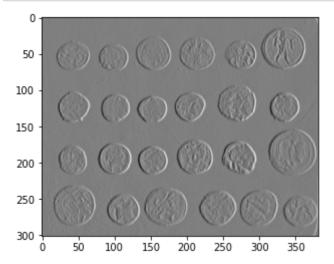
Examples

In [10]:

```
# Mask generation
mask = np.ones([3,3])
mask[:,1] = 0
mask[:,2] = -1

output = edge_detect(img, mask)

plt.imshow(output, cmap="gray") # colormap grayscale
plt.show()
```



In [11]:

```
mask = mask.T

output = edge_detect(img, mask)

plt.imshow(output, cmap="gray") # colormap grayscale
plt.show()
```

