Neehar Peri

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EDUCATION

Ph.D in Robotics, Carnegie Mellon University

August 2021 - Present

B.S. in Computer Engineering, University of Maryland - College Park QUEST Honors Program

August 2017 - May 2021

Journal Publications

• MILAB-VTF(B): A Large-Scale, Multi-Distance, Unconstrained Visible and Thermal Face Dataset T Bourlai, J Rose, S Mokalla, A Zabin, L Hornak, CB Nalty, N Peri, J Gleason,

Under Review

Conference Publications

CD Castillo, VM Patel, R Chellappa

• Long-Tail 3D Detection with Semantic Hierarchies **N Peri**, A Dave, S Kong, D Ramanan

Under Review

• Forecasting from LiDAR via Future Object Detection

CVPR 2022

N Peri, J Luieten, M Li, A Osep, L Leal-Taixe, D Ramanan

Assessment of a Novel Virtual Environment for Examining Human Cognitive-Motor Performance during Execution of Action Sequences

HCII 2022

AA Shaver*, N Peri*, R Mezebish, G Matthew, A Berson, C Gaskins, GP Davis, GE Katz, IBH Samuel, JA Reggia, J Purtilo, RJ Gentili

FG 2021[†]

• A Synthesis-Based Approach for Thermal-to-Visible Face Verification **N Peri**, J Gleason, CD Castillo, T Bourlai, VM Patel, R Chellappa

NeurIPS 2021

• PreferenceNet: Encoding Human Preferences in Auction Design with Deep Learning N Peri*, MJ Curry*, S Dooley, JP Dickerson

• The Devil is in the Details: Self-Supervised Attention for Vehicle Re-ID

ECCV 2020

P Khorramshahi*, N Peri*, JC Chen, R Chellappa • A Dual Path Model with Adaptive Attention for Vehicle Re-ID

ICCV 2019^{††}

P Khorramshahi, A Kumar, N Peri, SS Rambhatla, JC Chen, R Chellappa

Workshop Publications

• Deep k-NN Defense against Clean-label Data Poisoning Attacks N Peri*, N Gupta*, WR Huang*, L Fowl, C Zhu, S Feizi, T Goldstein, JP Dickerson

ECCVW 2020

• Towards Real-Time Systems for Vehicle Re-ID, Multi-Camera Tracking, and Anomaly Detection N Peri*, P Khorramshahi*, SS Rambhatla*, V Shenoy, S Rawat, JC Chen, R Chellappa

CVPRW 2020[†]

• Attention Driven Vehicle Re-ID and Unsupervised Anomaly Detection for Traffic Understanding

CVPRW 2019^{\dagger}

PATENTS

• Streaming 3D Detection and Forecasting from LiDAR Point Clouds N Peri. D Ramanan

Under Review

Academic Experience

Carnegie Mellon University, Pittsburgh, PA, Robotics Institute

Apr 2020 - Present

- Leading research on 3D object detection, tracking, and forecasting for autonomous driving applications
- Advisor: Deva Ramanan

University of Maryland, College Park, MD, UMIACS

May 2018 - May 2021

- Conducted research in unsupervised traffic anomaly detection and discriminative representation learning for vehicle re-id
- Led research in defending against clean-label adversarial poisoning attacks
- Established novel method for encoding human preferences in revenue maximizing auction design
- Advisors: Rama Chellappa & John P. Dickerson

P Khorramshahi, N Peri, A Kumar, A Shah, R Chellappa

^{*}Equal Contribution

[†]Selected for Spotlight Presentation

^{††}Selected for Oral Presentation

Argo AI, Pittsburgh, PA, Research Intern

May 2021 - Aug 2022

- Developed end-to-end 3D object detection and forecasting pipeline from LiDAR point clouds
- Implemented novel metrics that jointly evaluate detection and forecasting accuracy

MUKH Technologies, College Park, MD, Research Intern

Aug 2020 - Apr 2022

- \bullet Led research on improving thermal-to-visible face synthesis for zero-shot identification
- Built robust face verification pipelines for multi-spectral data streams

Bank of America, Charlotte, NC, Conversational Commerce Technology Intern

Jun 2019 - Aug 2019

- Developed novel deep learning pipeline to validate quality of utterance-intent pairs in chatbot conversations using PyTorch, AllenNLP, and NLTK
- Deployed RESTful Active Learning API to introduce targeted learning feedback loop and improve intent classification model performance

Teaching Experience

16-720B, Carnegie Mellon University, Robotics Institute, Head Teaching Assistant

Jan 2022 - Dec 2022

- Managed team of teaching assistants to effectively coordinate course responsibilities
- Updated course projects, held office hours, answered student questions and graded course projects
- Presented guest lectures on Training Convolutional Neural Networks and Transformers for Vision

ENEE 244, University of Maryland, ECE Department, Undergraduate Teaching Fellow Jan 2019 – May 2019

- ullet Led Introduction to Digital Logic recitation for a discussion section of 15 students
- Received highest marks on metrics of preparedness, respect for students, and teaching effectiveness from all students

INVITED TALKS

 Metrics and Methods for Detection and Forecasting in Autonomous Vehicles National Autonomous Vehicle Conference Apr 2022

Research Mentorship

Name	Institution	Year(s)	Details Mentor for project on synthetic data generation for thermal-to-visible face synthesis and verification
Christopher Nalty	UMD	2021-2022	
Aastha Senjalia, Andrew Vetter, Benjamin Namovicz, Cheyenne Mont- gomery, Ferzam Mohammad, Matthew Weinberg, Nicholas Revill	UMD	2021	Project champion for CMSC435 software engineering capstone to build a unified rendering platform for autonomous vehicle data. Project won People's Choice Award.

SERVICE

Conference Reviewer: NeurIPS 2021, CVPR 2022, CoRL 2022

Journal Reviewer: IJCV 2021

Mentorship: CMU AI Mentoring Program (2021-2022), QUEST Mentoring Program (2022), AI for Social Good (2022)

Consulting: Cherehani Africa (2019), Northrop Grumman Corporation (2020)

AWARDS

Name	Institution	Distinction	Year
Maryland Undergraduate Researcher of the Year	UMD	University	2021
Sujan Guha Memorial Best Senior Thesis Award	UMD	Department	2021
CRA Outstanding Undergraduate Researcher (Honorable Mention)	UMD	National	2021
NSF Graduate Research Fellowship (Honorable Mention)	UMD	National	2021