# Neehar Peri

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EDUC	CATION
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Ph.D in Robotics, Carnegie Mellon University Aug 2021 - Present 3D Perception In-The-Wild M.S in Robotics, Carnegie Mellon University Aug 2023 Long-Tailed 3D Detection via Multi-Modal Fusion B.S. in Computer Engineering, University of Maryland - College Park May 2021 QUEST Honors Program Conference Publications • Why is Sparse View Reconstruction Hard? Under Review Z Wang, J Tan, T Khurana\*, N Peri\*, D Ramanan • Neural Eulerian Scene Flow Fields Under Review K Vedder, N Peri, I Khatri, S Li, E Eaton, M Kocamaz, Y Wang, Z Yu, D Ramanan, J Pehserl • Planning with Adaptive World Models for Autonomous Driving Under Review AB Vasudevan, **N Peri**, J Schneider, D Ramanan NeurIPS D&B 2024 • Revisiting Few-Shot Object Detection with Vision-Language Models A  $Madan^*$ ,  $N Peri^*$ ,  $S Kong^*$ ,  $D Ramanan^*$ • Shelf-Supervised Cross-Modal Pre-Training for 3D Object Detection CoRL 2024 M Khurana\*, **N Peri\***, J Hays, D Ramanan • I Can't Believe It's Not Scene Flow! **ECCV 2024** I Khatri\*, K Vedder\*, **N Peri**, D Ramanan, J Hays • Better Call SAL: Towards Segmenting Anything in LiDAR ECCV 2024 A Osep\*, T Meinhardt\*, F Ferroni, N Peri, D Ramanan, L Leal-Taixe • ZeroFlow: Scaling Scene Flow via Distillation ICLR 2024 K Vedder, N Peri, N Chodosh, I Khatri, E Eaton, D Jayaraman, Y Liu, D Ramanan, J Hays • Towards Long-Tailed 3D Detection CoRL 2022 N Peri, A Dave, D Ramanan\*, S Kong\* • A Brief Survey of Person Recognition at a Distance ASILOMAR 2022 C Nalty\*, N Peri\*, J Gleason\*, CD Castillo, S Hu, T Bourlai, R Chellappa • Forecasting from LiDAR via Future Object Detection CVPR 2022 N Peri, J Luieten, M Li, A Osep, L Leal-Taixe, D Ramanan Assessment of a Novel Virtual Environment for Examining Human Cognitive-Motor HCII 2022 Performance during Execution of Action Sequences AA Shaver\*, N Peri\*, R Mezebish, G Matthew, A Berson, C Gaskins, GP Davis, GE Katz, I Samuel, JA Reggia, J Purtilo, RJ Gentili • A Synthesis-Based Approach for Thermal-to-Visible Face Verification FG 2021 N Peri, J Gleason, CD Castillo, T Bourlai, VM Patel, R Chellappa • PreferenceNet: Encoding Human Preferences in Auction Design with Deep Learning NeurIPS 2021 N Peri\*, MJ Curry\*, S Dooley, JP Dickerson • The Devil is in the Details: Self-Supervised Attention for Vehicle Re-ID ECCV 2020 P Khorramshahi\*, N Peri\*, JC Chen, R Chellappa • A Dual Path Model with Adaptive Attention for Vehicle Re-ID ICCV 2019†† P Khorramshahi, A Kumar, N Peri, SS Rambhatla, JC Chen, R Chellappa Workshop Publications • Semi-Supervised Federated Multi-Organ Segmentation with Partial Labels AAPM 2024<sup>††</sup> R Pemmaraju\*, N Peri\* ICCV  $2023^{\dagger\dagger}$ • An Empirical Analysis of Range for 3D Object Detection N Peri, M Li, B Wilson, YX Wang, J Hays, D Ramanan • ReBound: An Open-Source 3D Bounding Box Annotation Tool for Active Learning CHI 2023<sup>†</sup> W Chen\*, A Edgley\*, R Hota\*, J Liu\*, E Schwartz\*, A Yizar\*, N Peri\*, J Purtilo\* • Deep k-NN Defense Against Clean-label Data Poisoning Attacks ECCV 2020<sup>†</sup> N Peri\*, N Gupta\*, WR Huang\*, L Fowl, C Zhu, S Feizi, T Goldstein, JP Dickerson

• Towards Real-Time Systems for Vehicle Re-ID, Multi-Camera Tracking, and Anomaly Detection N  $Peri^*$ , P  $Khorramshahi^*$ , SS  $Rambhatla^*$ , V Shenoy, S Rawat, JC Chen, R Chellappa

CVPR  $2020^{\dagger}$ 

• Attention Driven Vehicle Re-ID and Unsupervised Anomaly Detection for Traffic Understanding P Khorramshahi, N Peri, A Kumar, A Shah, R Chellappa

CVPR  $2019^{\dagger}$ 

## JOURNAL PUBLICATIONS

• Long-Tailed 3D Detection via Multi-Modal Late Fusion Y Ma\*, N Peri\*, S Wei, A Dave, W Hua, Y Li, D Ramanan, S Kong

Under Review

• Accelerating Image Recognition Using High Performance Computing

ITEA 2023

J Adams, JM Barton, R Chellappa, J Gabberty, J Gleason, S Hu, J Johnson, F Moor-Clingenpeel, B Oshiro, **N Peri**, D Richie, V To

Data and Algorithms for End-to-End Thermal Spectrum Face Verification
 T Bourlai, J Rose, S Mokalla, A Zabin, L Hornak, CB Nalty, N Peri, J Gleason, CD Castillo,
 VM Patel, R Chellappa

**TBIOM 2023** 

#### PATENTS

• Few-Shot Object Detection with Vision-Language Models
A Madan, N Peri, S Kong, D Ramanan, CK Mummadi, FC Condessa

Under Review

• Learning Driving Behavior Control Parameters Using Machine Learning Models AB Vasudevan, N Peri, D Ramanan, CK Mummadi, FC Condessa

18/882,013

End-to-End Systems and Methods for Streaming 3D Detection And Forecasting from LiDAR Point Clouds 17/692,973
 N Peri, D Ramanan

#### Work Experience

## Carnegie Mellon University, Pittsburgh, PA, Research Assistant

Apr 2020 - Present

- Leading research on 3D object detection, multi-object tracking, motion forecasting, and multi-agent planning for embodied perception
- Advisor: Deva Ramanan

## **NVIDIA**, Pittsburgh, PA, Research Scientist Intern

Jan 2024 - Dec 2024

- Led research on persistent 3D object detection in-the-wild
- Built GNN-based tracker that outperforms production system by 5% HOTA and achieves a 10x speedup

## MUKH Technologies, College Park, MD, Research Scientist

 $Aug \ 2020 - May \ 2023$ 

- $\bullet$  Led research on improving thermal-to-visible face synthesis for zero-shot identification
- Built robust face verification pipelines for multi-spectral data streams

#### Argo AI, Pittsburgh, PA, Research Scientist Intern

May 2021 - Oct 2022

- Developed end-to-end 3D object detection and forecasting pipeline from LiDAR point clouds
- Implemented novel metrics that jointly evaluate detection and forecasting accuracy

#### University of Maryland, College Park, MD, Research Assistant

May 2018 - May 2021

- Conducted research in unsupervised traffic anomaly detection and discriminative representation learning for vehicle re-id
- Led research in defending against clean-label adversarial poisoning attacks
- Established novel method for encoding human preferences in revenue maximizing auction design
- Advisors: Rama Chellappa & John P. Dickerson

#### Bank of America, Charlotte, NC, Conversational Commerce Technology Intern

Jun 2019 - Aug 2019

- Developed novel deep learning pipeline to validate quality of utterance-intent pairs in chatbot conversations using PyTorch, AllenNLP, and NLTK
- Deployed RESTful Active Learning API to introduce targeted learning feedback loop and improve intent classification model performance

<sup>\*</sup>Equal Contribution

<sup>\*</sup>Equal Supervision

<sup>†</sup>Selected for Spotlight Presentation

<sup>††</sup>Selected for Oral Presentation

TEACHING EXPERIENCE 16-720, Carnegie Mellon University, Robotics Institute, Head Teaching Assistant Spring 2022, Fall 2022 • Managed team of teaching assistants to effectively coordinate course responsibilities • Graded course projects and held office hours **ENEE 244**, University of Maryland, ECE Department, Undergraduate Teaching Fellow Spring 2019 • Led Introduction to Digital Logic recitation for a discussion section of 15 students INVITED TALKS Oct 2024 • Long-Tailed 3D Detection via 2D Late Fusion Invited Talk: ECCV 2024, Workshop on Vision-Centric Autonomous Driving • Shelf-Supervised Cross-Modal Pre-Training for 3D Object Detection Oct 2024 Invited Talk: ECCV 2024, Autonomous Vehicles meet Multimodal Foundation Models Workshop • Argoverse 2 End-to-End Forecasting Challenge Jun 2024 Invited Talk: CVPR 2024, Workshop on Autonomous Driving • Foundational Few-Shot Object Detection Challenge Jun 2024 Invited Talk: CVPR 2024, Workshop on Visual Perception via Learning in an Open World

• Better Call SAL: Towards Learning to Segment Anything in LiDAR Invited Talk: Stack AV

• 3D Object Detection for Autonomous Vehicles Apr 2024

Apr 2024

Apr 2024

Oct 2023

Apr 2022

Apr 2022

Guest Lecture: 16-825, Learning for 3D Vision

• 3D Object Detection for Autonomous Vehicles

Guest Lecture: 16-720, Computer Vision

• Long-Tailed 3D Object Detection via Multi-Modal Fusion Jan 2024 Invited Talk: Carnegie Mellon University (R-PAD Lab)

• An Empirical Analysis of Range for 3D Object Detection Invited Talk: ICCV 2023, Robustness and Reliability of Autonomous Vehicles in the Open-World

• Argoverse 2 End-to-End Forecasting Challenge Jun 2023

Invited Talk: CVPR 2023, Workshop on Autonomous Driving

• 3D Object Detection for Autonomous Vehicles Mar 2023

Guest Lecture: 16-825, Learning for 3D Vision

• Image Processing and Convolutions Sep 2022 Guest Lecture: 16-720, Computer Vision

• How do Autonomous Vehicles See the World?

Aug 2022 Invited Talk: Carnegie Mellon University (RoboLaunch)

• Transformers for Vision

Guest Lecture: 16-720, Computer Vision

• Training Convolutional Neural Networks Guest Lecture: 16-720, Computer Vision

• Metrics and Methods for Detection and Forecasting in Autonomous Vehicles Apr 2022

Invited Talk: National Autonomous Vehicle Conference

SERVICE

Conference Reviewer: NeurIPS 20{21,22,23,24}, CVPR 20{22,23,24,25}, AAAI 20{23,24}, ICCV 2023, ICLR 2024, ECCV 2024, ICRA 2025

Journal Reviewer: IJCV 2021, TPAMI 2023

Mentorship: CMU AI Mentoring Program (20{21, 22}), QUEST Mentoring Program (2022), CMU AI for Social Good Summit (2022)

Organizer: Visual Perception and Learning in an Open World (CVPR 20{22, 23, 24, 25}), Computer Vision Reading Group (20{23, 24, 25})

Masters Thesis Committee Member: Bharath Raj, Anish Madan

Other: TRINITY Cluster Management 20{22,23,24}, AUTOBOT Cluster Management 20{22,23,24}, Robotics Institute Summer Scholars Admission Committee (2024)

## Mentorship

Name Cainan Davidson	Institution CMU	<b>Year(s)</b> 2024 –	Project Benchmarking open-vocabulary 3D perception for autonomous vehicles		
Guang-Lin Wei, Eric Chang, Padmini Gopinath, Ian Gordon, Amanuel Seifu, Daniel Syomichev	UMD	2024	CMSC435 software engineering capstone to build an active-learning framework for medical imaginallysis		
Zihan Wang	CMU	2024 -	Sparse-view dynamic reconstruction in-the-wild		
Nina Johe, Aryan Kakadia, Muzzamil Khan, Morgan Ko, Josh Leeman, Max Son, Sashwat Venkatesh	UMD	2024	CMSC435 software engineering capstone to build an end-to-end platform for medical image analysis		
Mehar Khurana	IIITD	2023 - 2024	Shelf-supervised 3D object detection with vision-language models		
Anish Madan	$\mathrm{CMU}$	2022 - 2024	Few-shot multi-modal 2D detection with vision-language models		
Andrew Shen	$\mathrm{CMU}$	2022 - 2023	Benchmarking modular 3D perception stack for autonomous vehicles		
Xindi Wu	$\mathrm{CMU}$	2022	Self-supervised multi-modal representation learning for point clouds		
Aminah Yizar, Andrew Edgley, Ezra Schwartz, Joshua Liu, Raunak Hota, Royce He, Wesley Chen	UMD	2022	CMSC435 software engineering capstone to build an active learning framework to allow human-in-the-loop 3D object annotation		
Christopher Nalty	MUKH	2021-2022	Synthetic data augmentation for thermal-to-visible face verification		
Aastha Senjalia, Andrew Vetter, Benjamin Namovicz, Cheyenne Mont- gomery, Ferzam Mohammad, Matthew Weinberg, Nicholas Revill	UMD	2021	CMSC435 software engineering capstone to build a visualization platform for autonomous vehicle data. Project won People's Choice Award.		

## Awards

Name NSF Graduate Research Fellowship	Institution CMU	Distinction National	<b>Year</b> 2023
Maryland Undergraduate Researcher of the Year	UMD	University	2021
Sujan Guha Memorial Best Senior Thesis Award	UMD	Department	2021
CRA Outstanding Undergraduate Researcher (Honorable Mention) Yurie & Jeong H. Kim Scholarship	UMD UMD	National Department	$2021 20\{18,19,20\}$