# Neehar Peri

EDUCATION

neeharperi.com

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## Ph.D in Robotics, Carnegie Mellon University

3D Perception In-The-Wild

M.S in Robotics, Carnegie Mellon University

Long-Tailed 3D Detection via Multi-Modal Fusion

B.S. in Computer Engineering, University of Maryland - College Park

QUEST Honors Program

#### Conference Publications

• Scene Flow as a Partial Differential Equation K Vedder, N Peri, I Khatri, S Li, E Eaton, Y Yang, Z Yu, D Ramanan, J Pehserl

• Planning with Adaptive World Models for Autonomous Driving

AB Vasudevan, **N Peri**, J Schneider, D Ramanan • Revisiting Few-Shot Object Detection with Vision-Language Models

A Madan\*, N Peri\*, S Kong, D Ramanan

• Shelf-Supervised Cross-Modal Pre-Training for 3D Object Detection M Khurana\*, N Peri\*, J Hays, D Ramanan

• I Can't Beleive It's Not Scene Flow! I Khatri\*, K Vedder\*, **N Peri**, D Ramanan, J Hays

• Better Call SAL: Towards Segmenting Anything in LiDAR

A Osep\*, T Meinhardt\*, F Ferroni, N Peri, D Ramanan, L Leal-Taixe

• ZeroFlow: Scaling Scene Flow via Distillation

K Vedder, N Peri, N Chodosh, I Khatri, E Eaton, D Jayaraman, Y Liu, D Ramanan, J Hays

• Towards Long-Tailed 3D Detection

N Peri, A Dave, D Ramanan\*, S Kong\*

• A Brief Survey of Person Recognition at a Distance

C Nalty\*, N Peri\*, J Gleason\*, CD Castillo, S Hu, T Bourlai, R Chellappa

• Forecasting from LiDAR via Future Object Detection

N Peri. J Luieten, M Li. A Osev, L Leal-Taixe, D Ramanan

Assessment of a Novel Virtual Environment for Examining Human Cognitive-Motor

Performance during Execution of Action Sequences

AA Shaver\*, N Peri\*, R Mezebish, G Matthew, A Berson, C Gaskins, GP Davis, GE

Katz, I Samuel, JA Reggia, J Purtilo, RJ Gentili

• A Synthesis-Based Approach for Thermal-to-Visible Face Verification

N Peri, J Gleason, CD Castillo, T Bourlai, VM Patel, R Chellappa

• PreferenceNet: Encoding Human Preferences in Auction Design with Deep Learning

N Peri\*, MJ Curry\*, S Dooley, JP Dickerson

• The Devil is in the Details: Self-Supervised Attention for Vehicle Re-ID

P Khorramshahi\*, N Peri\*, JC Chen, R Chellappa

• A Dual Path Model with Adaptive Attention for Vehicle Re-ID

P Khorramshahi, A Kumar, N Peri, SS Rambhatla, JC Chen, R Chellappa

## Workshop Publications

• Semi-Supervised Federated Multi-Organ Segmentation with Partial Labels R Pemmaraju\*, N Peri\*

• An Empirical Analysis of Range for 3D Object Detection N Peri, M Li, B Wilson, YX Wang, J Hays, D Ramanan

• ReBound: An Open-Source 3D Bounding Box Annotation Tool for Active Learning W Chen\*, A Edgley\*, R Hota\*, J Liu\*, E Schwartz\*, A Yizar\*, N Peri\*, J Purtilo\*

 $\bullet$  Deep k-NN Defense Against Clean-label Data Poisoning Attacks

N Peri\*, N Gupta\*, WR Huang\*, L Fowl, C Zhu, S Feizi, T Goldstein, JP Dickerson

• Towards Real-Time Systems for Vehicle Re-ID, Multi-Camera Tracking, and Anomaly Detection N Peri\*, P Khorramshahi\*, SS Rambhatla\*, V Shenoy, S Rawat, JC Chen, R Chellappa

• Attention Driven Vehicle Re-ID and Unsupervised Anomaly Detection for Traffic Understanding P Khorramshahi, N Peri, A Kumar, A Shah, R Chellappa

Aug 2023

Aug 2021 - Present

May 2021

Under Review

Under Review

NeurIPS D&B 2024

CoRL 2024

**ECCV 2024** 

ECCV 2024

ICLR 2024

CoRL 2022

ASILOMAR 2022

CVPR 2022

HCII 2022

FG 2021

NeurIPS 2021

ECCV 2020

ICCV  $2019^{\dagger\dagger}$ 

AAPM  $2024^{\dagger\dagger}$ 

ICCV  $2023^{\dagger\dagger}$ 

CHI 2023<sup>†</sup>

ECCV 2020<sup>†</sup>

CVPR  $2020^{\dagger}$ 

CVPR 2019<sup>†</sup>

## JOURNAL PUBLICATIONS

• Long-Tailed 3D Detection via Multi-Modal Late Fusion Y Ma\*, N Peri\*, S Wei, A Dave, W Hua, Y Li, D Ramanan, S Kong

Under Review

• Accelerating Image Recognition Using High Performance Computing

ITEA 2023

J Adams, JM Barton, R Chellappa, J Gabberty, J Gleason, S Hu, J Johnson, F Moor-Clingenpeel, B Oshiro, **N Peri**, D Richie, V To

Data and Algorithms for End-to-End Thermal Spectrum Face Verification
 T Bourlai, J Rose, S Mokalla, A Zabin, L Hornak, CB Nalty, N Peri, J Gleason, CD Castillo,
 VM Patel, R Chellappa

TBIOM 2023

### PATENTS

• Learning Driving Behavior Control Parameters Using Machine Learning Models AB Vasudevan, N Peri, D Ramanan, CK Mummadi, FC Condessa

18/882,013

End-to-End Systems and Methods for Streaming 3D Detection And Forecasting from LiDAR Point Clouds 17/692,973
 N Peri, D Ramanan

#### ACADEMIC EXPERIENCE

## Carnegie Mellon University, Pittsburgh, PA, Robotics Institute

Apr 2020 - Present

- Leading research on 3D object detection, multi-object tracking, motion forecasting, and multi-agent planning for embodied perception
- Advisor: Deva Ramanan

#### University of Maryland, College Park, MD, UMIACS

May 2018 - May 2021

- Conducted research in unsupervised traffic anomaly detection and discriminative representation learning for vehicle re-id
- Led research in defending against clean-label adversarial poisoning attacks
- Established novel method for encoding human preferences in revenue maximizing auction design
- Advisors: Rama Chellappa & John P. Dickerson

#### Industry Experience

## **NVIDIA**, Pittsburgh, PA, Research Scientist Intern

January 2024 - Current

- Leading research on persistent 3D object detection in-the-wild
- Built GNN-based tracker that outperforms production system by 5% HOTA and achieves a 10x speedup

#### MUKH Technologies, College Park, MD, Research Scientist

Aug 2020 - May 2023

- Led research on improving thermal-to-visible face synthesis for zero-shot identification
- Built robust face verification pipelines for multi-spectral data streams

## Argo AI, Pittsburgh, PA, Research Scientist Intern

May 2021 - Oct 2022

- Developed end-to-end 3D object detection and forecasting pipeline from LiDAR point clouds
- Implemented novel metrics that jointly evaluate detection and forecasting accuracy

## Bank of America, Charlotte, NC, Conversational Commerce Technology Intern

 $Jun\ 2019 - Aug\ 2019$ 

- Developed novel deep learning pipeline to validate quality of utterance-intent pairs in chatbot conversations using PyTorch, AllenNLP, and NLTK
- Deployed RESTful Active Learning API to introduce targeted learning feedback loop and improve intent classification model performance

#### TEACHING EXPERIENCE

16-720, Carnegie Mellon University, Robotics Institute, Head Teaching Assistant

Spring 2022, Fall 2022

- Managed team of teaching assistants to effectively coordinate course responsibilities
- Graded course projects and held office hours

ENEE 244, University of Maryland, ECE Department, Undergraduate Teaching Fellow

Spring 2019

• Led Introduction to Digital Logic recitation for a discussion section of 15 students

<sup>\*</sup>Equal Contribution

<sup>\*</sup>Equal Supervision

<sup>†</sup>Selected for Spotlight Presentation

<sup>††</sup>Selected for Oral Presentation

#### INVITED TALKS

• Long-Tailed 3D Detection via 2D Late Fusion	Oct 2024
Invited Talk: ECCV 2024, Workshop on Vision-Centric Autonomous Driving	
• Shelf-Supervised Cross-Modal Pre-Training for 3D Object Detection  Invited Talk: ECCV 2024, Autonomous Vehicles meet Multimodal Foundation Models Workshop	Oct 2024
• Argoverse 2 End-to-End Forecasting Challenge	Jun 2024
Invited Talk: CVPR 2024, Workshop on Autonomous Driving	
• Foundational Few-Shot Object Detection Challenge Invited Talk: CVPR 2024, Workshop on Visual Perception via Learning in an Open World	Jun 2024
• 3D Object Detection for Autonomous Vehicles	Apr 2024
Guest Lecture: 16-720, Computer Vision	
• Better Call SAL: Towards Learning to Segment Anything in LiDAR Invited Talk: Stack AV	Apr 2024
• 3D Object Detection for Autonomous Vehicles	Apr 2024
Guest Lecture: 16-825, Learning for 3D Vision	
• Long-Tailed 3D Object Detection via Multi-Modal Fusion	Jan 2024
Invited Talk: Carnegie Mellon University (R-PAD Lab)	
• An Empirical Analysis of Range for 3D Object Detection	Oct 2023
Invited Talk: ICCV 2023, Robustness and Reliability of Autonomous Vehicles in the Open-World	
• Argoverse 2 End-to-End Forecasting Challenge	Jun 2023
Invited Talk: CVPR 2023, Workshop on Autonomous Driving	
• 3D Object Detection for Autonomous Vehicles	Mar 2023
Guest Lecture: 16-825, Learning for 3D Vision	
• Image Processing and Convolutions	Sep 2022
Guest Lecture: 16-720, Computer Vision	
• How do Autonomous Vehicles See the World?  Invited Talk: Carnegie Mellon University (RoboLaunch)	Aug 2022
• Transformers for Vision	Apr 2022
Guest Lecture: 16-720, Computer Vision	Apr 2022
• Training Convolutional Neural Networks	Apr 2022
Guest Lecture: 16-720, Computer Vision	r 10-1
• Metrics and Methods for Detection and Forecasting in Autonomous Vehicles	Apr 2022
Invited Talk: National Autonomous Vehicle Conference	-

SERVICE

 $\textbf{Conference Reviewer: NeurIPS 20} \{21,22,23,24\}, \ CVPR \ 20\{22,23,24\}, \ AAAI \ 20\{23,24\}, \ ICCV \ 2023, \ ICLR \ 20\{24,25\}, \ ECCV \ 2024$ 

Journal Reviewer: IJCV 2021, TPAMI 2023

Mentorship: CMU AI Mentoring Program (20{21, 22}), QUEST Mentoring Program (2022), CMU AI for Social Good Summit (2022)

**Organizer:** Visual Perception and Learning in an Open World (CVPR 20{22, 23, 24}), Computer Vision Reading Group (20{23, 24})

Masters Thesis Committee Member: Bharath Raj, Anish Madan

#### MENTORSHIP

Name Guang-Lin Wei, Eric Chang, Padmini Gopinath, Ian Gordon, Amanuel Seifu, Daniel Syomichev	Institution UMD	Year(s) 2024	Project CMSC435 software engineering capstone to build an active-learning framework for medical image analysis
Zihan Wang	CMU	2024 -	Sparse-view dynamic reconstruction in-the-wild
Nina Johe, Aryan Kakadia, Muzzamil Khan, Morgan Ko, Josh Leeman, Max Son, Sashwat Venkatesh	UMD	2024	CMSC435 software engineering capstone to build an end-to-end platform for medical image analysis

Mehar Khurana	IIITD	2023 - 2024	Shelf-supervised 3D object detection with vision-language models	
Anish Madan	CMU	2022 - 2024	Few-shot multi-modal 2D detection with vision-language models	
Andrew Shen	CMU	2022 - 2023	Benchmarking modular 3D perception stack for autonomous vehicles	
Xindi Wu	CMU	2022	Self-supervised multi-modal representation learning for point clouds	
Aminah Yizar, Andrew Edgley, Ezra Schwartz, Joshua Liu, Raunak Hota, Royce He, Wesley Chen	UMD	2022	CMSC435 software engineering capstone to build an active learning framework to allow human-in-the-loop 3D object annotation	
Christopher Nalty	MUKH	2021-2022	Synthetic data augmentation for thermal-to-visible face verification	
Aastha Senjalia, Andrew Vetter, Benjamin Namovicz, Cheyenne Mont- gomery, Ferzam Mohammad, Matthew Weinberg, Nicholas Revill	UMD	2021	CMSC435 software engineering capstone to build a visualization platform for autonomous vehicle data. Project won People's Choice Award.	

## Awards

Name	Institution	Distinction	Year
NSF Graduate Research Fellowship	CMU	National	2023
Maryland Undergraduate Researcher of the Year	UMD	University	2021
Sujan Guha Memorial Best Senior Thesis Award	UMD	Department	2021
CRA Outstanding Undergraduate Researcher (Honorable Mention)	UMD	National	2021
Yurie & Jeong H. Kim Scholarship	UMD	Department	$20\{18,19,20\}$