# Neehar Peri

Ph.D in Robotics, Carnegie Mellon University

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Aug 2021 - Present

3D Perception In-The-Wild	114g 2021 1 1050110
M.S in Robotics, Carnegie Mellon University  Long-Tailed 3D Detection via Multi-Modal Fusion	$\mathrm{Aug}\ 2023$
B.S. in Computer Engineering, University of Maryland - College Park $QUEST\ Honors\ Program$	May 2021
Conference Publications	
• Towards Learning to Complete Anything in LiDAR A Tacmaz, C Saltori, N Peri, T Meinhardt, RD Lutio, L Leal-Taixe, A Osep	Under Review
<ul> <li>Why is Sparse View Reconstruction Hard?</li> <li>Z Wang, J Tan, T Khurana*, N Peri*, D Ramanan</li> </ul>	Under Review
<ul> <li>Planning with Adaptive World Models for Autonomous Driving</li> <li>AB Vasudevan, N Peri, J Schneider, D Ramanan</li> </ul>	ICRA 2025
• Neural Eulerian Scene Flow Fields  K Vedder, N Peri, I Khatri, S Li, E Eaton, M Kocamaz, Y Wang, Z Yu, D Ramanan, J Pehserl	ICLR 2025
<ul> <li>Revisiting Few-Shot Object Detection with Vision-Language Models</li> <li>A Madan*, N Peri*, S Kong*, D Ramanan*</li> </ul>	NeurIPS 2024
• Shelf-Supervised Cross-Modal Pre-Training for 3D Object Detection M Khurana*, N Peri*, J Hays, D Ramanan	CoRL 2024
• I Can't Believe It's Not Scene Flow!  I Khatri*, K Vedder*, N Peri, D Ramanan, J Hays	ECCV 2024
• Better Call SAL: Towards Segmenting Anything in LiDAR A Osep*, T Meinhardt*, F Ferroni, N Peri, D Ramanan, L Leal-Taixe	ECCV 2024
• ZeroFlow: Scaling Scene Flow via Distillation  K Vedder, N Peri, N Chodosh, I Khatri, E Eaton, D Jayaraman, Y Liu, D Ramanan, J Hays	ICLR 2024
<ul> <li>◆ Towards Long-Tailed 3D Detection</li> <li>N Peri, A Dave, D Ramanan*, S Kong*</li> </ul>	CoRL 2022
• A Brief Survey of Person Recognition at a Distance C Nalty*, N Peri*, J Gleason*, CD Castillo, S Hu, T Bourlai, R Chellappa	ASILOMAR 2022
• Forecasting from LiDAR via Future Object Detection  N Peri, J Luieten, M Li, A Osep, L Leal-Taixe, D Ramanan	CVPR 2022
Assessment of a Novel Virtual Environment for Examining Human Cognitive-Motor  Performance during Execution of Action Sequences  AA Shaver*, N Peri*, R Mezebish, G Matthew, A Berson, C Gaskins, GP Davis, GE  Katz, I Samuel, JA Reggia, J Purtilo, RJ Gentili	HCII 2022
• A Synthesis-Based Approach for Thermal-to-Visible Face Verification <b>N Peri</b> , J Gleason, CD Castillo, T Bourlai, VM Patel, R Chellappa	FG 2021
• PreferenceNet: Encoding Human Preferences in Auction Design with Deep Learning N Peri*, MJ Curry*, S Dooley, JP Dickerson	NeurIPS 2021
• The Devil is in the Details: Self-Supervised Attention for Vehicle Re-ID P Khorramshahi*, N Peri*, JC Chen, R Chellappa	ECCV 2020
• A Dual Path Model with Adaptive Attention for Vehicle Re-ID  P Khorramshahi, A Kumar, N Peri, SS Rambhatla, JC Chen, R Chellappa	ICCV $2019^{\dagger\dagger}$

# WORKSHOP PUBLICATIONS

$^{\star}$ AAPM 2024 $^{\dagger}$
ICCV $2023^{\dagger}$
CHI 2023
ECCV 2020
CVPR 2020
CVPR 2019

# JOURNAL PUBLICATIONS

Long-Tailed 3D Detection via Multi-Modal Late Fusion
 Y Ma\*, N Peri\*, S Wei, A Dave, W Hua, Y Li, D Ramanan, S Kong

Under Review

Accelerating Image Recognition Using High Performance Computing
 J Adams, JM Barton, R Chellappa, J Gabberty, J Gleason, S Hu, J Johnson, F Moor Clingenpeel, B Oshiro, N Peri, D Richie, V To

ITEA 2023

**TBIOM 2023** 

Data and Algorithms for End-to-End Thermal Spectrum Face Verification
 T Bourlai, J Rose, S Mokalla, A Zabin, L Hornak, CB Nalty, N Peri, J Gleason, CD Castillo,
 VM Patel, R Chellappa

### PATENTS

• Few-Shot Object Detection with Vision-Language Models
A Madan, N Peri, S Kong, D Ramanan, CK Mummadi, FC Condessa

Under Review

• Learning Driving Behavior Control Parameters Using Machine Learning Models

AB Vasudevan, N Peri, D Ramanan, CK Mummadi, FC Condessa

End-to-End Systems and Methods for Streaming 3D Detection And Forecasting from LiDAR Point Clouds 17/692,973
 N Peri, D Ramanan

### Work Experience

## Carnegie Mellon University, Pittsburgh, PA, Research Assistant

Apr 2020 - Present

- Leading research on 3D object detection, multi-object tracking, motion forecasting, and multi-agent planning for embodied perception
- Advisor: Deva Ramanan

# Boston Dynamics AI Institute, Boston, MA, Research Scientist Intern

June 2025 - Present

• Leading research on data collection for bi-manual manipulation

# **NVIDIA**, Pittsburgh, PA, Research Scientist Intern

Jan 2024 - Dec 2024

- Led research on persistent 3D object detection in-the-wild
- Built GNN-based tracker that outperforms production system by 5% HOTA and achieves a 10x speedup

# MUKH Technologies, College Park, MD, Research Scientist Intern

Aug 2020 - May 2023

- Led research on improving thermal-to-visible face synthesis for zero-shot identification
- Built robust face verification pipelines for multi-spectral data streams

### Argo AI, Pittsburgh, PA, Research Scientist Intern

May 2021 - Oct 2022

- Developed end-to-end 3D object detection and forecasting pipeline from LiDAR point clouds
- Implemented novel metrics that jointly evaluate detection and forecasting accuracy

<sup>\*</sup>Equal Contribution

<sup>\*</sup>Equal Supervision

<sup>&</sup>lt;sup>†</sup>Selected for Spotlight Presentation

<sup>††</sup>Selected for Oral Presentation

# University of Maryland, College Park, MD, Research Assistant

May 2018 - May 2021

- Conducted research in unsupervised traffic anomaly detection and discriminative representation learning for vehicle re-id
- Led research in defending against clean-label adversarial poisoning attacks
- Established novel method for encoding human preferences in revenue maximizing auction design
- Advisors: Rama Chellappa & John P. Dickerson

# Bank of America, Charlotte, NC, Conversational Commerce Technology Intern

 $Jun\ 2019 - Aug\ 2019$ 

- Developed novel deep learning pipeline to validate quality of utterance-intent pairs in chatbot conversations using PyTorch, AllenNLP, and NLTK
- Deployed RESTful Active Learning API to introduce targeted learning feedback loop and improve intent classification model performance

## TEACHING EXPERIENCE

### 16-720, Carnegie Mellon University, Robotics Institute, Head Teaching Assistant

Spring 2022, Fall 2022

- Managed team of teaching assistants to effectively coordinate course responsibilities
- Graded course projects and held office hours

# ENEE 244, University of Maryland, ECE Department, Undergraduate Teaching Fellow

Spring 2019

• Led Introduction to Digital Logic recitation for a discussion section of 15 students

## INVITED TALKS

• Argoverse 2 Open-World Scenario Mining Challenge Invited Talk: CVPR 2025, Workshop on Autonomous Driving	Jun 2025
• Foundational Few-Shot Object Detection Challenge Invited Talk: CVPR 2025, Workshop on Visual Perception via Learning in an Open World	Jun 2025
• 3D Object Detection for Autonomous Vehicles Guest Lecture: 16-825, Learning for 3D Vision	Apr 2025
• Towards Foundational 3D Perception Invited Talk: Carnegie Mellon University (FLAME Seminar)	Mar 2025
• Image Processing from a Frequency Perspective Guest Lecture: 16-720, Computer Vision	Feb 2025
• Long-Tailed 3D Detection via 2D Late Fusion Invited Talk: ECCV 2024, Workshop on Vision-Centric Autonomous Driving	Oct 2024
• Shelf-Supervised Cross-Modal Pre-Training for 3D Object Detection Invited Talk: ECCV 2024, Autonomous Vehicles meet Multimodal Foundation Models Workshop	Oct 2024
• Argoverse 2 End-to-End Forecasting Challenge Invited Talk: CVPR 2024, Workshop on Autonomous Driving	Jun 2024
• Foundational Few-Shot Object Detection Challenge Invited Talk: CVPR 2024, Workshop on Visual Perception via Learning in an Open World	Jun 2024
• 3D Object Detection for Autonomous Vehicles Guest Lecture: 16-720, Computer Vision	Apr 2024
• Better Call SAL: Towards Learning to Segment Anything in LiDAR  Invited Talk: Stack AV	Apr 2024
• 3D Object Detection for Autonomous Vehicles Guest Lecture: 16-825, Learning for 3D Vision	Apr 2024
• Long-Tailed 3D Object Detection via Multi-Modal Fusion Invited Talk: Carnegie Mellon University (R-PAD Lab)	Jan 2024
• An Empirical Analysis of Range for 3D Object Detection Invited Talk: ICCV 2023, Robustness and Reliability of Autonomous Vehicles in the Open-World	Oct 2023
• Argoverse 2 End-to-End Forecasting Challenge Invited Talk: CVPR 2023, Workshop on Autonomous Driving	Jun 2023
• 3D Object Detection for Autonomous Vehicles Guest Lecture: 16-825, Learning for 3D Vision	Mar 2023
• Image Processing and Convolutions Guest Lecture: 16-720, Computer Vision	Sep 2022

•	How do Autonomous Vehicles See the World?	Aug 2022
	Invited Talk: Carnegie Mellon University (RoboLaunch)	
•	Transformers for Vision	$\mathrm{Apr}\ 2022$
	Guest Lecture: 16-720, Computer Vision	
•	Training Convolutional Neural Networks	$\mathrm{Apr}\ 2022$
	Guest Lecture: 16-720, Computer Vision	
•	Metrics and Methods for Detection and Forecasting in Autonomous Vehicles	Apr 2022
	Invited Talk: National Autonomous Vehicle Conference	

# SERVICE

Conference Reviewer: NeurIPS  $20\{21,22,23,24\}$ , CVPR  $20\{22,23,24,25\}$ , AAAI  $20\{23,24\}$ , ICCV 2023, ICLR 2024, ECCV 2024, ICRA 2025

Journal Reviewer: IJCV 2021, TPAMI 2023

Mentorship: CMU AI Mentoring Program (20{21, 22}), QUEST Mentoring Program (2022), CMU AI for Social Good

Summit (2022)

Organizer: Visual Perception and Learning in an Open World (CVPR 20{22, 23, 24, 25}), Computer Vision Reading Group (20{23, 24, 25})

Masters Thesis Committee Member: Bharath Raj, Anish Madan

 $\textbf{Other:} \ \ \text{TRINITY Cluster Management 20} \\ \{22,23,24\}, \ \text{AUTOBOT Cluster Management 20} \\ \{22,23,24\}, \ \text{Robotics Institute Management 20} \\ \{22,23,24\}, \ \text{Roboti$ 

Summer Scholars Admission Committee (2024)

## MENTORSHIP

Name Cainan Davidson	Institution CMU	<b>Year(s)</b> 2024 –	Project Benchmarking open-world 3D perception for autonomous vehicles
Guang-Lin Wei, Eric Chang, Padmini Gopinath, Ian Gordon, Amanuel Seifu, Daniel Syomichev	UMD	2024	CMSC435 software engineering capstone to build an active-learning framework for medical image analysis
Zihan Wang	CMU	2024 -	Sparse-view dynamic reconstruction in-the-wild
Nina Johe, Aryan Kakadia, Muzzamil Khan, Morgan Ko, Josh Leeman, Max Son, Sashwat Venkatesh	UMD	2024	CMSC435 software engineering capstone to build an end-to-end platform for medical image analysis
Mehar Khurana	IIITD	2023 - 2024	Shelf-supervised 3D object detection with vision-language models
Anish Madan	$\mathrm{CMU}$	2022 - 2024	Few-shot multi-modal 2D detection with vision-language models
Andrew Shen	$\mathrm{CMU}$	2022 - 2023	Benchmarking modular 3D perception stack for autonomous vehicles
Xindi Wu	$\mathrm{CMU}$	2022	Self-supervised multi-modal representation learning for point clouds
Aminah Yizar, Andrew Edgley, Ezra Schwartz, Joshua Liu, Raunak Hota, Royce He, Wesley Chen	UMD	2022	CMSC435 software engineering capstone to build an active learning framework to allow human-in-the-loop 3D object annotation
Christopher Nalty	MUKH	2021 - 2022	Synthetic data augmentation for thermal-to-visible face verification
Aastha Senjalia, Andrew Vetter, Benjamin Namovicz, Cheyenne Mont- gomery, Ferzam Mohammad, Matthew Weinberg, Nicholas Revill	UMD	2021	CMSC435 software engineering capstone to build a visualization platform for autonomous vehicle data. Project won People's Choice Award.

### AWARDS

Name	Institution	Distinction	$\mathbf{Y}\mathbf{e}\mathbf{a}\mathbf{r}$
NSF Graduate Research Fellowship	CMU	National	2023

Maryland Undergraduate Researcher of the Year	UMD	University	2021
Sujan Guha Memorial Best Senior Thesis Award	UMD	Department	2021
CRA Outstanding Undergraduate Researcher (Honorable Mention)	UMD	National	2021
Yurie & Jeong H. Kim Scholarship	UMD	Department	$20\{18,19,20\}$