# Neehar Peri

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CVPR  $2020^{\dagger}$ 

#### **EDUCATION** Ph.D in Robotics, Carnegie Mellon University Aug 2021 - Present M.S in Robotics, Carnegie Mellon University Aug 2023 Long-Tailed 3D Detection via Multi-Modal Fusion B.S. in Computer Engineering, University of Maryland - College Park May 2021 QUEST Honors Program Journal Publications • Data and Algorithms for End-to-End Thermal Spectrum Face Verification **TBIOM 2023** T Bourlai, J Rose, S Mokalla, A Zabin, L Hornak, CB Nalty, N Peri, J Gleason, CD Castillo, VM Patel, R Chellappa Conference Publications • Planning with an Ensemble of World Models Under Review AB Vasudevan, N Peri, D Ramanan • Better Call SAL: Towards Segmenting Anything in LiDAR Under Review A Osep, T Meinhardt, F Ferroni, N Peri, D Ramanan, L Leal-Taixe • 3D Video Object Detection Under Review **N Peri**, A Osep, L Leal-Taixe, D Ramanan • Revisiting Few-Shot Object Detection with Vision-Language Models Under Review A Madan, N Peri, S Kong, D Ramanan • Long-Tailed 3D Detection via 2D Late Fusion Under Review Y Ma\*, N Peri\*, S Wei, D, Ramanan, W Hua\*, Y Li \*, S Kong\* • ZeroFlow: Scaling Scene Flow via Distillation ICLR 2024 K Vedder, N Peri, N Chodosh, I Khatri, E Eaton, D Jayaraman, Y Liu, D Ramanan, J Hays • Towards Long-Tailed 3D Detection CoRL 2022 $N \ Peri$ , A Dave, D Ramanan\*, S Kong\* • A Brief Survey of Person Recognition at a Distance ASILOMAR 2022 C Nalty\*, N Peri\*, J Gleason\*, CD Castillo, S Hu, T Bourlai, R Chellappa • Forecasting from LiDAR via Future Object Detection CVPR 2022 N Peri, J Luieten, M Li, A Osep, L Leal-Taixe, D Ramanan Assessment of a Novel Virtual Environment for Examining Human Cognitive-Motor HCII 2022 Performance during Execution of Action Sequences AA Shaver\*, N Peri\*, R Mezebish, G Matthew, A Berson, C Gaskins, GP Davis, GE Katz, I Samuel, JA Reggia, J Purtilo, RJ Gentili • A Synthesis-Based Approach for Thermal-to-Visible Face Verification FG 2021 N Peri, J Gleason, CD Castillo, T Bourlai, VM Patel, R Chellappa • PreferenceNet: Encoding Human Preferences in Auction Design with Deep Learning NeurIPS 2021 N Peri\*, MJ Curry\*, S Dooley, JP Dickerson • The Devil is in the Details: Self-Supervised Attention for Vehicle Re-ID ECCV 2020 P Khorramshahi\*, N Peri\*, JC Chen, R Chellappa ICCV $2019^{\dagger\dagger}$ • A Dual Path Model with Adaptive Attention for Vehicle Re-ID P Khorramshahi, A Kumar, N Peri, SS Rambhatla, JC Chen, R Chellappa Workshop Publications ICCV $2023^{\dagger}$ • An Empirical Analysis of Range for 3D Object Detection N Peri, M Li, B Wilson, YX Wang, J Hays, D Ramanan • ReBound: An Open-Source 3D Bounding Box Annotation Tool for Active Learning CHI 2023<sup>†</sup> W Chen\*, A Edgley\*, R Hota\*, J Liu\*, E Schwartz\*, A Yizar\*, N Peri\*, J Purtilo\* • Deep k-NN Defense Against Clean-label Data Poisoning Attacks ECCV 2020<sup>†</sup>

N Peri\*, N Gupta\*, WR Huang\*, L Fowl, C Zhu, S Feizi, T Goldstein, JP Dickerson

N Peri\*, P Khorramshahi\*, SS Rambhatla\*, V Shenoy, S Rawat, JC Chen, R Chellappa

Towards Real-Time Systems for Vehicle Re-ID, Multi-Camera Tracking, and Anomaly Detection

• Attention Driven Vehicle Re-ID and Unsupervised Anomaly Detection for Traffic Understanding P Khorramshahi, N Peri, A Kumar, A Shah, R Chellappa CVPR  $2019^{\dagger}$ 

#### PATENTS

 End-to-End Systems and Methods for Streaming 3D Detection And Forecasting from LiDAR Point Clouds N Peri, D Ramanan

17/692,973

#### ACADEMIC EXPERIENCE

## Carnegie Mellon University, Pittsburgh, PA, Robotics Institute

Apr 2020 - Present

- Leading research on 3D object detection, multi-object tracking, motion forecasting, and multi-agent planning for embodied perception
- Advisor: Deva Ramanan

## University of Maryland, College Park, MD, UMIACS

May 2018 - May 2021

- Conducted research in unsupervised traffic anomaly detection and discriminative representation learning for vehicle re-id
- Led research in defending against clean-label adversarial poisoning attacks
- Established novel method for encoding human preferences in revenue maximizing auction design
- Advisors: Rama Chellappa & John P. Dickerson

## Industry Experience

#### **NVIDIA**, Remote, Research Scientist Intern

January 2024 - Current

• Leading research on multi-modal 3D object detection

#### MUKH Technologies, College Park, MD, Research Engineer

Aug 2020 - May 2023

- Led research on improving thermal-to-visible face synthesis for zero-shot identification
- Built robust face verification pipelines for multi-spectral data streams

## Argo AI, Pittsburgh, PA, Research Scientist Intern

May 2021 - Oct 2022

- Developed end-to-end 3D object detection and forecasting pipeline from LiDAR point clouds
- Implemented novel metrics that jointly evaluate detection and forecasting accuracy

#### Bank of America, Charlotte, NC, Conversational Commerce Technology Intern

Jun 2019 - Aug 2019

- Developed novel deep learning pipeline to validate quality of utterance-intent pairs in chatbot conversations using PyTorch, AllenNLP, and NLTK
- Deployed RESTful Active Learning API to introduce targeted learning feedback loop and improve intent classification model performance

#### TEACHING EXPERIENCE

16-720, Carnegie Mellon University, Robotics Institute, Head Teaching Assistant

Spring 2022, Fall 2022

- Managed team of teaching assistants to effectively coordinate course responsibilities
- Updated course projects, held office hours, answered student questions and graded course projects

**ENEE 244**, University of Maryland, ECE Department, *Undergraduate Teaching Fellow* 

Spring 2019

• Led Introduction to Digital Logic recitation for a discussion section of 15 students

<sup>\*</sup>Equal Contribution

<sup>\*</sup>Equal Supervision

<sup>&</sup>lt;sup>†</sup>Selected for Spotlight Presentation

<sup>††</sup>Selected for Oral Presentation

## INVITED TALKS

• Long-Tailed 3D Object Detection via Multi-Modal Fusion Invited Talk: Carnegie Mellon University (R-PAD Lab)	Jan 2024
• Argoverse 2 End-to-End Forecasting Challenge	Jun 2023
Invited Talk: CVPR 2023, Workshop on Autonomous Driving	
• 3D Object Detection for Autonomous Vehicles	Mar 2023
Guest Lecture: 16-825, Learning for 3D Vision	
• Image Processing and Convolutions	Sep 2022
Guest Lecture: 16-720, Computer Vision	-
• How do Autonomous Vehicles See the World?	Aug 2022
Invited Talk: Carnegie Mellon University (RoboLaunch)	
• Transformers for Vision	Apr 2022
Guest Lecture: 16-720, Computer Vision	
• Training Convolutional Neural Networks	Apr 2022
Guest Lecture: 16-720, Computer Vision	-
• Metrics and Methods for Detection and Forecasting in Autonomous Vehicles	Apr 2022
Invited Talk: National Autonomous Vehicle Conference	-

## SERVICE

 $\textbf{Conference Reviewer:} \ \ \text{NeurIPS} \ \ 20\{21,22,23\}, \ \ \text{CVPR} \ \ 20\{22,23,24\}, \ \ \text{AAAI} \ \ 20\{23,24\}, \ \ \text{ICCV} \ \ 2023, \ \ \text{ICLR} \ \ 2024, \ \ \text{ECCV} \ \ 2024$ 

Journal Reviewer: IJCV 2021, TPAMI 2023

Mentorship: CMU AI Mentoring Program (20{21, 22}), QUEST Mentoring Program (2022), CMU AI for Social Good

Summit (2022)

 $(20\{23, 24\})$ 

Other: TRINITY Cluster Management 20{22,23,24}, AUTOBOT Cluster Management 20{22,23,24}

## Mentorship

Name Zihan Wang	Institution CMU	Year(s) 2024 –	Project Benchmarking dynamic reconstruction with RGBD videos		
Mehar Khurana	IIITD	2023 -	Shelf-supervised 3D object detection		
Anish Madan	CMU	2022 –	Few-shot multi-modal 2D detection with vision-language models		
Andrew Shen	CMU	2022 - 2023	Benchmarking modular 3D perception stack for autonomous vehicles		
Xindi Wu	CMU	2022	Self-supervised multi-modal representation learning for point clouds		
Aminah Yizar, Andrew Edgley, Ezra Schwartz, Joshua Liu, Raunak Hota, Royce He, Wesley Chen	UMD	2022	Project champion for CMSC435 software engineering capstone to build an active learning framework to allow human-in-the-loop 3D object annotation		
Christopher Nalty	MUKH	2021-2022	Synthetic data augmentation for thermal-to-visible face verification		
Aastha Senjalia, Andrew Vetter, Benjamin Namovicz, Cheyenne Mont- gomery, Ferzam Mohammad, Matthew Weinberg, Nicholas Revill	UMD	2021	Project champion for CMSC435 software engineering capstone to build a visualization platform for autonomous vehicle data. Project won People's Choice Award.		

# AWARDS

Name	Institution	Distinction	Year
NSF Graduate Research Fellowship	CMU	National	2023
Maryland Undergraduate Researcher of the Year	UMD	University	2021
Sujan Guha Memorial Best Senior Thesis Award	UMD	Department	2021
CRA Outstanding Undergraduate Researcher (Honorable Mention)	UMD	National	2021
Yurie & Jeong H. Kim Scholarship	UMD	Department	$20\{18,19,20\}$