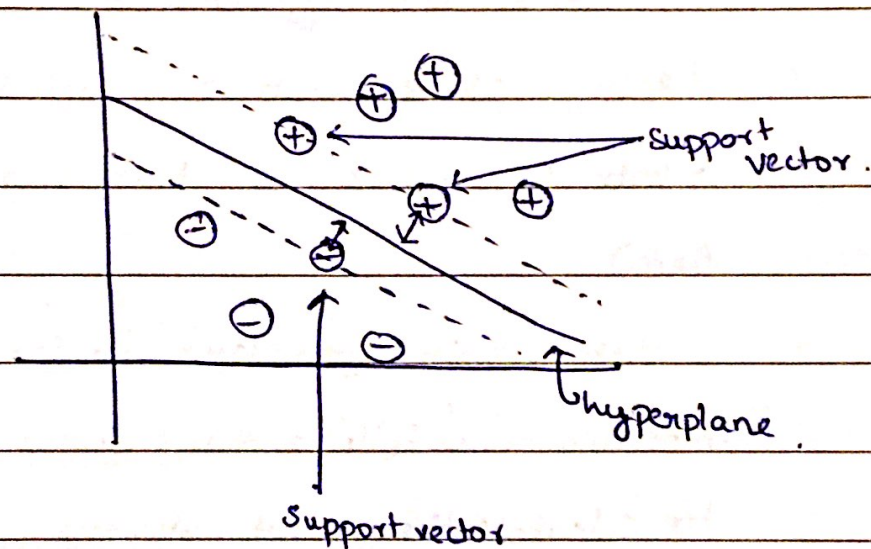


# Support Vector Machines

- Let us start with the basic intuition of SVM. Let us say we have a 2-D space (can be  $n$ -D, but for simplification let us assume a 2-D space)



The objective of SVM is to find a hyperplane <sup>of dimensions  $(n-1)$</sup>  which separates the two classes such that the hyperplane is at a maximum distance from the points which define the boundary of the classes (a.k.a. support vectors)

- Some basic info on SVMs:
- Supervised learning algo
  - Unlike Logistic Regression this can also work on non-linearly separable data using kernels.



→ The mathematics of it:-

The hyperplane can be represented by the equation

$$\vec{w} \cdot \vec{x} + b = 0$$

where  $\vec{w} \in$  coefficients  $\vec{x} \in$  features,  $b \in$  bias

The hyperplane equation is such that it is equidistant to both the support vector planes (and is therefore in between them)

With just the hyperplane  $w \cdot x + b = 0$ , we have two unknowns  $\rightarrow w$  &  $b$  and we don't have enough constraints to calculate them, but with the support vector plane equations defined as

$$w \cdot x + b = 1, \quad w \cdot x + b = -1$$

where if  $w \cdot x + b \leq -1 \quad y = -1$

&  $w \cdot x + b \geq 1 \quad y = 1$  we can find  $w$  &  $b$ .

We can now combine the equations as

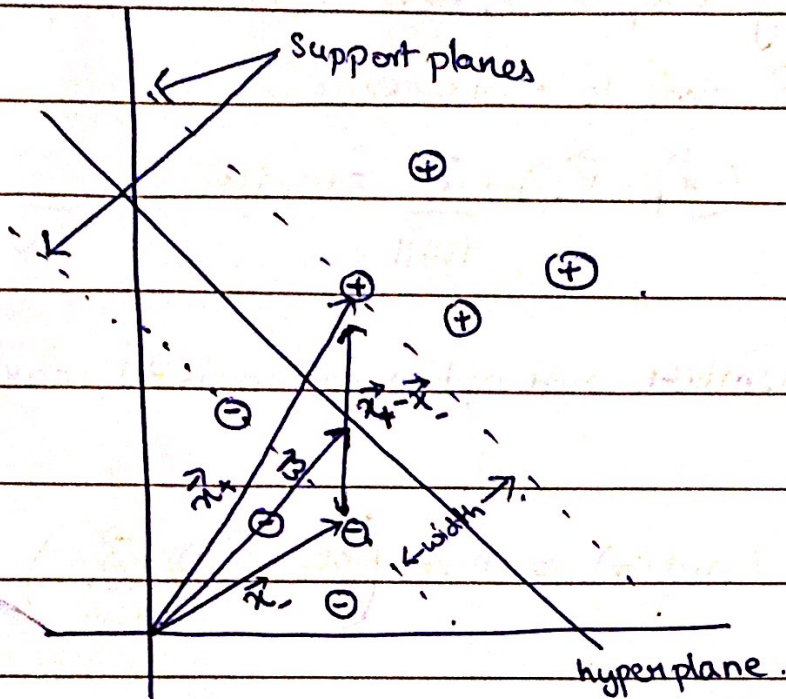
$$y * (\vec{w} \cdot \vec{x} + b) \geq 1$$

$$\Rightarrow y_i (\vec{w} \cdot \vec{x}_i + b) - 1 = 0 \quad \leftarrow \text{for all samples which lie on the support vector planes, i.e. the support vectors}$$

(\*)



Let us take the graph again



Let us try to understand a few more things about it.

- 1)  $\vec{w}$ , which were our coefficients can be thought of as a vector perpendicular to the hyperplane. Therefore  $\vec{w} \cdot \vec{x}$  is the projection of  $\vec{x}$  on  $\vec{w}$ . Now if this

projection + bias is  $\geq \frac{1}{2}$  that means ~~projection~~ that it is a  $y_i = 1$

classification. Similarly if projection + bias  $\leq -1$  means that it is a  $y_i = -1$  classification. Therefore our intuition with  $\vec{w}$  as a perpendicular vector to hyperplane is justified.

Anyway coming back:-

Lets take one point on the  $\oplus$  support plane as  $\vec{x}_+$

Lets take on point on the  $\ominus$  " " " as  $\vec{x}_-$

between.

$\therefore$  we can say that the width of the support planes can be the perpendicular projection of  $\vec{x}_+ - \vec{x}_-$  on the hyperplane. looking at the graph.



The question is how do we find the perpendicular projection of  $(\vec{x}_+ - \vec{x}_-)$ . Here we have our perpendicular vector  $\vec{w}$  come to our rescue.

$$\therefore \frac{(\vec{x}_+ - \vec{x}_-) \cdot \vec{w}}{\|\vec{w}\|} = \text{width} \quad \frac{\vec{w}}{\|\vec{w}\|} = \hat{w} \in \text{unit vector}$$

Now remember our optimization is to maximise this width

$$\therefore \max(\text{width}) = \max \left( \frac{(\vec{x}_+ - \vec{x}_-) \cdot \vec{w}}{\|\vec{w}\|} \right)$$

now remember our eq<sup>n</sup> where we said for all ~~para~~ support vectors

$$y_i (\vec{w} \cdot \vec{x}_i + b) - 1 = 0$$

$$\therefore \text{for } x_+ \Rightarrow y_i = 1 \Rightarrow \vec{w} \cdot \vec{x}_+ + b - 1 = 0$$

$$\therefore \vec{w} \cdot \vec{x}_+ = 1 - b$$

$$\text{for } x_- \Rightarrow y_i = -1 \Rightarrow -(\vec{w} \cdot \vec{x}_- + b) - 1 = 0$$

$$\therefore \vec{w} \cdot \vec{x}_- = -(1 + b)$$

$$\therefore \frac{(\vec{x}_+ - \vec{x}_-) \cdot \vec{w}}{\|\vec{w}\|} = \frac{\vec{x}_+ \cdot \vec{w} - \vec{x}_- \cdot \vec{w}}{\|\vec{w}\|} = \frac{1 - b + 1 + b}{\|\vec{w}\|}$$

$$= \frac{2}{\|\vec{w}\|}$$

$$\therefore \max(\text{width}) = \max \left( \frac{(\vec{x}_+ - \vec{x}_-) \cdot \vec{w}}{\|\vec{w}\|} \right) = \max \left( \frac{2}{\|\vec{w}\|} \right)$$

$$= \min(\|\vec{w}\|)$$

$$= \min \left( \frac{1}{2} \|\vec{w}\|^2 \right)$$

↑ for mathematical purposes.

Now to solve any maximise/minimise eq<sup>n</sup> with constraints we shall use Lagrange Multiplier.

$$L = (\text{eq}^n \text{ to max/min}) - \sum \alpha_i (\text{constraint})$$

Substituting our terms.

$$L = \frac{1}{2} \|\vec{w}\|^2 - \sum \alpha_i [y_i (\vec{w} \cdot \vec{x}_i + b) - 1]$$

Now we need to equate  $\frac{\partial L}{\partial \vec{w}} = 0$  (to find maxima/minima).

$$\frac{\partial L}{\partial \vec{w}} = \vec{w} - \sum \alpha_i y_i \vec{x}_i = 0 \Rightarrow \boxed{\vec{w} = \sum \alpha_i y_i \vec{x}_i}$$

Similarly  $\frac{\partial L}{\partial b} = -\sum \alpha_i y_i = 0 \Rightarrow \boxed{\sum \alpha_i y_i = 0}$

Now let's plug this into our lagrange equation.



$$L = \frac{1}{2} \left( \sum_i \alpha_i y_i \vec{x}_i \right) \cdot \left( \sum_j \alpha_j y_j \vec{x}_j \right) - \left( \sum_i \alpha_i y_i x_i \right) \left( \sum_j \alpha_j y_j x_j \right) - \sum_i \alpha_i y_i b + \sum_i \alpha_i$$

$$L = -\frac{1}{2} \left( \sum_i \sum_j \alpha_i \alpha_j y_i y_j x_i \cdot x_j \right) - b \sum_i \alpha_i y_i + \sum_i \alpha_i$$

↑  
0 from previous eq<sup>n</sup>

Lagrange eq<sup>n</sup> → 
$$L = \sum_i \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j \vec{x}_i \cdot \vec{x}_j$$
 ← This eq<sup>n</sup> shows that the entire thing just boils down to a dot product ( $\vec{x}_i \cdot \vec{x}_j$ )

Let us also substitute  $\vec{w} = \sum_i \alpha_i y_i \vec{x}_i$  in our hyperplane eq<sup>n</sup>.

$$\vec{w} \cdot \vec{u} + b = 0$$

$$= \sum_i \alpha_i y_i \vec{x}_i \cdot \vec{u} + b = 0$$

← This is our optimization equation.

→ Solving the Lagrange eq<sup>n</sup> in PYTHON:-

$$L = \sum_i \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j \vec{x}_i \cdot \vec{x}_j$$

maximise  $\alpha_i$

given  $\alpha_i \geq 0$

$$\sum_i \alpha_i y_i = 0.$$

for all support  
vectors

This eq<sup>n</sup> can be solved using quadratic programming  
 where eq<sup>n</sup>s of the form can be solved by CVXOPT library's  
 ↓  
 QP solver

$$\min_x \frac{1}{2} x^T P x + q^T x$$

$$\text{subject to } Gx \leq h$$

$$Ax = b$$

The Lagrange eq<sup>n</sup> can be written as

$$-\left( (-1)^T \alpha + \frac{1}{2} x^T \right) \begin{matrix} \text{P} \\ \left[ \begin{array}{cccc} y_1 y_1^T x_1 & y_1 y_2^T x_2 & \dots & y_1 y_N^T x_N \\ y_2 y_1^T x_1 & y_2 y_2^T x_2 & \dots & y_2 y_N^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1^T x_1 & y_N y_2^T x_2 & \dots & y_N y_N^T x_N \end{array} \right] \alpha \end{matrix}$$

subject to

$$\alpha \geq 0$$

$$e^T y^T \alpha = 0$$

$$\Rightarrow (-1) \alpha \leq 0$$

↑  
G

↑  
h

↑  
b

• ②