

EDUCATION

June 2024 (expected)	Ph.D. in Electrical and Computer Engineering, <i>University of California, Santa Barbara</i> , GPA: 4.0/4.0
June 2020	M.S. in Electrical and Computer Engineering, <i>University of California, Santa Barbara</i> , GPA: 4.0/4.0 <i>Major: Controls, Minor: Signal Processing</i>
May 2018	B.S. in Electrical Engineering and Computer Sciences, <i>University of California, Berkeley</i> , GPA: 3.4/4.0

HONORS AND AWARDS

2023	Best Seminar Speaker at Graduate Simulation Seminar Series (GS ³)
2023	Society for Neuroscience Trainee Professional Development Award
2023	Research Talk Prize at Festival of Touch, Marseille, France
2023 - 2024	UC Santa Barbara Graduate Opportunity Fellow
2022 - 2024	Link Foundation Modeling, Simulation, and Training Program Fellow
2023 - 2024	Society of Women Engineers (SWE) Scholar
2023	Women in Science and Engineering (WiSE) BD Biosciences Research Accelerator Award
2021 - 2023	P.E.O. Foundation Scholarship Recipient
2019 - 2021	UC Santa Barbara Outstanding ECE Teaching Assistant Award
2021	Federal Employee Education & Assistance (FEEA) Scholarship Recipient
2021 - 2022	Intel Society of Women Engineers (SWE) Scholar
2014 - 2018	UC Berkeley Regents and Chancellors Scholar

RESEARCH EXPERIENCE

2020 - Present	UC Santa Barbara: RE Touch Lab, <i>Graduate Student Researcher</i> (Advisor: Dr. Yon Visell) <ul style="list-style-type: none"> Developing novel computational neural simulations driven by vibrometry measurements of touch-elicited skin oscillations to understand the effect of hand biomechanics on tactile neuron populations. Engineering wearable tactile sensing systems for facilitating tactile communication and interaction in the digital domain with applications in accessibility for the deafblind community.
2019	Teledyne FLIR, <i>Research and Development Intern</i> (Advisor: Stephanie Lin) <ul style="list-style-type: none"> Developed image and video signal processing algorithms, performed comprehensive evaluations of various denoising techniques, and assessed signal processing challenges in thermal camera systems. Delivered two company-wide presentations on the development of a new signal processing algorithm and was recognized by the global FLIR intern spotlight feature.
2018 - 2020	UC Santa Barbara: Mostofi Lab, <i>Graduate Researcher</i> (Advisor: Dr. Yasamin Mostofi) <ul style="list-style-type: none"> Applied belief propagation algorithms and sparse signal processing techniques to evaluate line-of-sight and Rytov wave models for reconstructing unknown areas with WiFi power measurements.
2017 - 2018	UC San Francisco Department of Surgery: Wang Lab, <i>Undergraduate Researcher</i> (Advisor: Dr. Rong Wang) <ul style="list-style-type: none"> Studied the effects of genetic modifications and potential treatments on brain arteriovenous malformations (BAVMs) in mice through two-photon, brightfield, and fluorescence microscopy.
2017	MIT Lincoln Laboratory: Communication Systems Division, <i>Research Intern</i> (Advisor: Dr. Brian Proulx) <ul style="list-style-type: none"> Improved a C++ simulation for MIMO communication systems by implementing routing, queue delay, and automatic re-transmission functionalities and analyzed performance via MATLAB visualization.
2016	Naval Postgraduate School: Space Systems Academic Group, <i>Research Intern</i> (Advisor: James Horning) <ul style="list-style-type: none"> Led a multi-disciplinary team in an autonomous high-altitude balloon research project. Developed an autonomous Raspberry Pi system using Python to perform tasks such as parachute deployment and balloon release, and remotely execute commands via radio communication.

PUBLICATIONS

N. Tummala*, G. Reardon*, S. Fani, D. Goetz, M. Bianchi, and Y. Visell, "SkinSource: A Data-Driven Toolbox for Predicting Touch-Elicited Vibrations in the Upper Limb". Manuscript submitted for publication. (*equal contribution)

N. Tummala, G. Reardon, B. Dandu, Y. Shao, H. Saal, and Y. Visell, "Biomechanical filtering modulates and diversifies whole-hand tactile encoding". Manuscript in preparation.

N. Tummala, G. Reardon, B. Dandu, Y. Shao, H. Saal, and Y. Visell, “Biomechanical filtering diversifies tactile encoding in whole-hand Pacinian corpuscle neuron populations” [abstract]. Accepted at *Neuroscience 2023*.

N. Tummala, Y. Shao, and Y. Visell, “Spatiotemporal Organization of Touch Information in Tactile Neuron Population Responses,” *2023 IEEE World Haptics Conference (WHC)*, Delft, Netherlands, 2023.

S. Dinulescu, N. Tummala, G. Reardon, B. Dandu, D. Goetz, S. Topp, and Y. Visell, “A Smart Bracelet Supporting Tactile Communication and Interaction,” *IEEE Haptics Symposium 2022*, Santa Barbara, CA, 2022. **(Runner-up for Best Technical Paper)**

RESEARCH TALKS

Sep. 2023	“Measurement-Driven Neural Simulations for Understanding the Sense of Touch,” <i>2023 Graduate Student Simulation Seminar (GS³)</i> (Best Seminar Speaker)
Jul. 2023	“Spatiotemporal Organization of Touch Information in Tactile Neuron Population Responses,” <i>IEEE World Haptics</i>
Jul. 2023	“Biomechanical Filtering Diversifies Whole-Hand Tactile Encoding,” <i>2023 Festival of Touch</i> (Prize Winner)
Apr. 2022	“Smart Bracelet Supporting Tactile Communication and Interaction,” <i>MRL Science Teacher Workshop</i>
Feb. 2022	“Understanding Our Sense of Touch,” <i>Center for Controls, Dynamical-Systems, and Computation (CCDC) Seminar</i>
Jan. 2022	“Understanding Our Sense of Touch,” <i>Electrical & Computer Engineering Graduate Student Lightning Talks</i>
Jan. 2022	“Understanding Our Sense of Touch,” <i>P.E.O. Foundation Chapter QA Meeting</i>
Jul. 2020	“Simulating Responses of Touch Receptors in the Hand,” <i>2020 Graduate Student Simulation Seminar (GS³)</i>

TEACHING AND SERVICE

2023 - Present	Undergraduate Mentor, <i>Society of Women Engineers</i> , UC Santa Barbara
2023	Student Volunteer, <i>IEEE World Haptics Conference 2023</i> , Delft, Netherlands
2022	Research Mentor, <i>RE Touch Lab</i> , UC Santa Barbara
2021	Research Mentor, <i>UC Leadership Excellence Through Advanced Degrees (UC LEADS)</i> , UC Santa Barbara
2021	Undergraduate Mentor, <i>Women in Science and Engineering (WiSE)</i> , UC Santa Barbara
2021	Computer Science Instructor, <i>SWEE++ (Society of Women Engineers)</i> , UC Santa Barbara
2018 - 2020	Teaching Assistant, <i>Feedback Control Systems: Theory and Design</i> , UC Santa Barbara
2019- 2020	Teaching Assistant, <i>Digital Control</i> , UC Santa Barbara
2019 - 2021	Teaching Assistant, <i>Signal Analysis and Processing</i> , UC Santa Barbara
2019	Research Mentor, <i>LEGtrek Undergraduate Electrical and Computer Engineering Capstone Project</i> , UC Santa Barbara

PROJECTS

Winter 2020	Soft Biomimetic Finger for Robotic Tactile Perception (<i>Advisor</i> : Dr. Elliot Hawkes) <ul style="list-style-type: none"> Developed a soft biomimetic finger prototype composed of silicone and gelatin, integrating an array of accelerometers to capture vibrations across the finger. Evaluated sensing capabilities via texture scanning experiments and mechanical modeling of the finger.
Winter 2019	Low-Cost Robotic Teleoperation System with Haptic Feedback (<i>Advisor</i> : Dr. Yon Visell) <ul style="list-style-type: none"> Developed an inexpensive, customizable, and reproducible teleoperation system with haptic feedback using a Novint Falcon haptic device to control a Lynxmotion AL5D robotic arm equipped with collision detection sensors, allowing the user to feel obstacles in a remote environment.
Spring 2018	Don't Drop the Scalpel – dontdrothescalpel.wordpress.com (<i>Advisor</i> : Dr. Ruzena Bajcsy) <ul style="list-style-type: none"> Implemented slip detection during grasping, adjusted grip force dynamically to minimize object deformation, and classified object rigidity using a Reflex Takkile hand on a Baxter robot for applications in surgical robotics.
Fall 2017	Doctor Sawyer – doctorsawyer.wordpress.com (<i>Advisor</i> : Dr. Ruzena Bajcsy) <ul style="list-style-type: none"> Programmed a 7-DOF Sawyer robot arm and microcontroller to perform medical diagnostic tasks: pulse detection, temperature measurement, and elementary tumor detection using force sensing.
Spring 2017	El Animal: Racing Car Robot (<i>Advisor</i> : Dr. Ron Fearing) <ul style="list-style-type: none"> Developed control algorithms for line-following and steering, and designed PCBs for motor control, Bluetooth communication, debugging functionality, sensor integration, and power management.

SKILLS

General	Computational Neuroscience, Haptics, Signal Processing, Controls, Data Analysis, Software Engineering
Technical	<i>Advanced</i> : Python, MATLAB, Linux, LaTeX, Git. <i>Intermediate</i> : C/C++, Microcontrollers, Java, ROS, Fortran