Online Reinforcement Learning for Autoformalization

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Abstract

We study online reinforcement learning for *autoformalization*: translating informal mathematical conjectures into formal statements in Lean 4. Autoformalization lacks a natural dense reward; using type-check success alone produces syntactically valid but semantically vacuous outputs and is vulnerable to reward hacking. We propose composite reward formulations that combine syntactic signals (Lean typecheck) with semantic measures: (i) exact-match style metrics based on BEq / BEq+ when ground-truth formalizations exist, and (ii) a continuous embedding-based similarity reward that requires no paired data. Training uses Group Relative Policy Optimization with a KL-divergence penalty to avoid distributional collapse, and we release a multi-project Lean-4 REPL API and training code. On RLMEval (including a manually curated, context-aware Con-NF set of 71 samples), our best RL model (batch size 768, "TripleEmbed" scaling) substantially raises typecheck rates (TC1 from 17.29% \to 26.01%, TC50 from 76.41% \to 85.46%) while producing modest gains in BEq / BEq+. We analyse reward tradeoffs, show the importance of the KL penalty, and discuss extensions to proof autoformalization and learned critics as future work.

1 Introduction

Online Reinforcement Learning has proven successful for mathematical reasoning in natural languages [Shao et al., DeepSeek-AI et al.] and more recently for Automated Theorem Proving (ATP) [Wang et al., 2025, Ren et al., 2025] with Large Language Models (LLMs).

Unlike ATP, autoformalization, translating informal into formal language, has no obvious underlying reward function. Using type-check accuracy as the only reward might lead to models producing syntactically valid yet meaningless output. Instead, semantic alignment can be explored with metrics such as BEq [Liu et al.] and BEq+ [Poiroux et al., 2025].

We develop reward functions that use both syntactic and semantic accuracy, and test online reinforcement learning for autoformalization of natural language conjectures. We publicly release our training code, including a new Lean REPL [LeanProver-Community, 2025] API that can handle multiple different Lean 4 [Moura and Ullrich, 2021] projects simultaneously.

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2 Method

We use Group Relative Policy Optimization, which was introduced by Shao et al. and has seen success in informal languages [DeepSeek-AI et al.] and formal languages [Ren et al., 2025]. We generate 48 formal outputs per informal conjecture, and compute advantage estimates \hat{A}_i within each such group i.

This advantage estimate is then used for Proximal Policy Optimization with gradient clipping [Schulman et al., Zhang et al.], resulting in the objective function

$$\frac{1}{G} \sum_{i=1}^{G} \frac{1}{|o_i|} \sum_{t=1}^{|o_i|} \min \left\{ r(\theta, t) \hat{A}_i, \operatorname{clip} \left(r(\theta, t), 1 - \epsilon, 1 + \epsilon \right) \hat{A}_i \right\} \\
- \beta D_{KL} \left[\pi_{\theta}, \pi_{\theta_{\text{old}}} \right]$$

where π is our policy, o_i one of the G completions to the input prompt q, D_{KL} the Kullback-Leibler divergence for o_i , and r the probability ratio given by

$$r(\theta, t) := \frac{\pi_{\theta}(o_{i,t}|q \cdot o_{i, < t})}{\pi_{\theta_{\text{old}}}(o_{i,t}|q \cdot o_{i, < t})}$$

with \cdot as string concatenation and $\theta_{\rm old}$ as the weights of the supervised base model.

A naive reward for an LLM completion would be type-check information such as assigning a binary reward of 0 or 1 depending on whether the type-check succeeded, resulting in a model that generates valid Lean syntax for any given informal statement. But this can be achieved trivially by always predicting the same short sequence with reward 1, for example .

To mitigate this, one can incorporate a Kullback-Leibler-divergence penalty [Schulman et al., Shao et al.]. However, a large coefficient for the divergence penalty limits the ability to improve performance, as the model's existing weaknesses can only partially be resolved without shifting the distribution [Schulman et al., Kaufmann et al.]. Instead of solely penalizing distributions, we adapt the reward to also convey semantic meaning by adding a second reward term. We consider two formulations.

- 1. *BEq*: With existing ground-truth data, metrics such as BEq+ [Poiroux et al., 2025] can be used to compare prediction and ground-truth. A new binary result can be introduced, assigning 1 whenever two statements are equal in BEq+, and 0 otherwise. But if ground-truth data is available, supervised finetuning is also possible, and it is unclear whether reinforcement learning outperforms training with language modeling loss.
- 2. *Embed*: Without ground-truth data, a proxy for semantic correctness could be the similarity between formal and informal conjecture embeddings assigned by an embedding model. This can provide a continuous reward function that gradually increases from 0 to 1, without sudden loss spikes whenever a reward of 1 is reached, which is common with sparse rewards [Kaufmann et al.]. We find divergence penalties to still be relevant to prevent reward hacking for the embedding model used, which is the retriever by Liu et al..

2.1 Technical details

All experiments were seeded with seed 42.

We rely on vLLM for generations [Kwon et al., 2023], and use DeepSpeed Zero stage 3 for training, using a single node with 4 A100 80 GiB GPUs and bfloat16. We use five warmup steps and a constant learning rate of 10^{-6} . We use a modified version of the trl [von Werra et al., 2025] library for training, and a weight decay of 0.1. Training runs for 3 epochs, which is 198 GRPO-steps.

The supervised finetuning for the Kimina model [Wang et al., 2025] uses a batch size of 8, a learning rate of 0.000007, and runs for 4 epochs, trained on a single node with bfloat16 and DeepSpeed Zero stage 3.

All training runs use AdamW [Loshchilov and Hutter] for optimisation, with $\beta_1 = 0.9$, $\beta_2 = 0.999$, and $\epsilon = 0.00000001$.

2.2 Batch size

Larger batch sizes lead to increased performance. We ultimately settled on 768 for computational reasons. For a comparison of batch sizes 384 and 768, see Figure 1.

2.3 KL-divergence penalty

Omitting the KL-divergence penalty lead to drastic performance decreases. Specifically, for all runs, we observed a collapse at around 100 training steps. Figure 2 displays the decrease at step 100, and also shows how the models, once reward has fallen to 0, do not recover.

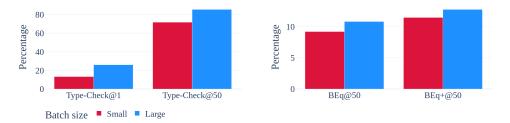


Figure 1: The larger batch size of 768 increases over 384 in every metric on RLMEval [Poiroux et al., 2025]

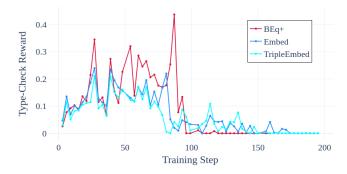


Figure 2: Type-Check reward over time for runs without KL-divergence penalty. For all runs, the reward reaches 0, and the runs never recover from it.

3 Results

As a baseline, we evaluate the Kimina autoformalization model [Wang et al., 2025] on RLMEval [Poiroux et al., 2025]. The model can generate syntactically correct statements, but rarely generates statements that are equal to the ground-truth according to BEq [Liu et al.], see Table 1. Especially, since RLMEval is based on external repositories with custom definitions, formalization requires handling these in the model context.

For a context-aware base-model, we manually curate a dataset of 71 Con-NF samples with definition context as training for context-aware autoformalization. The context-aware model supervised fine-tuned on this dataset significantly improves RLMEval results semantically. For online reinforcement learning, we split RLMEval, using the FLT repository as validation, such that the model is tested on unseen definitions.

We find the KL-divergence penalty to be important to prevent distributional collapse, shown in Figure 3. As the type-check accuracy has low mean and high variance compared to the embedding reward, we also test scaling it by a factor of 3, called *TripleEmbed*, which leads to similar means for both reward components.

While the reward formulation with BEq on ground-truth data significantly outperforms in syntactic and semantic metrics, it is unclear whether it improves over supervised finetuning on the same data.

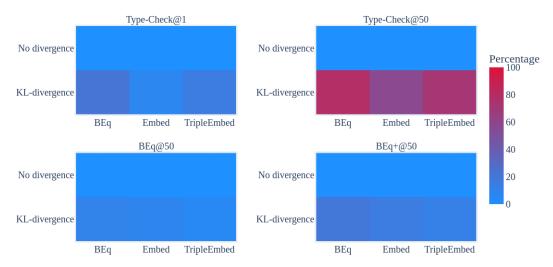


Figure 3: Heatmap of type-check accuracy in pass@1 and pass@50, as well as pass@50 BEq [Liu et al.] and BEq+ [Poiroux et al., 2025] scores for the six configurations on the FLT repository of RLMEval [Poiroux et al., 2025].

The reward function using our embedding model does not rely on ground-truth data. Consequently, we can even report results on all of RLMEval. This is not training on test data, as our method uses ground-truth statements only during evaluation.

Throughout training, we iteratively refine our outputs purely with type-check information and embedding similarity scores, which are also available during inference. Therefore, this approach would even be valid at inference time.

Our overall best model uses a batch size of 768 and the *TripleEmbed* reward. The final results in Table 2 indicate a strong improvement in type-check accuracy, and a slight increase in BEq and BEq+scores across RLMEval.

4 Future works

We aim to extend this work on conjecture autoformalization to online reinforcement learning on proof autoformalization. Two possible methods for this arise. Proof autoformalization can be decomposed into individual steps, such as sketching and ATP in Draft, Sketch, and Prove [Jiang et al., 2023], and a reward can be assigned to each step separately. This might be type-check accuracy of the proof sketch, and a binary reward for successful proofs for ATP. Alternatively, proof autoformalization could be treated as an end-to-end problem, only rewarding 1 once the whole proof has been correctly formalized.

Further, different semantic reward formulations could lead to a more pronounced increase in BEq results. Separate critic models or LLMs as judges are promising avenues that can be explored in the future.

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Table 1: Pass@50 rates for type-check, BEq, and BEq+ for Kimina's autoformalizer and our supervised model [Wang et al., 2025] on the six repositories of RLMEval [Poiroux et al., 2025].

Model	Dataset	Type-Check	BEq	BEq+
6*Kimina	PFR	83.45%	0.00%	0.00%
	Carleson	82.88%	0.00%	0.00%
	FLT	30.36%	0.00%	3.57%
	FLT3	76.19%	2.38%	3.57%
	Prime	90.91%	2.02%	3.03%
	Testing	43.55%	0.00%	0.00%
6*SFT	PFR	71.72%	8.28%	8.97%
	Carleson	66.66%	3.60%	3.60%
	FLT	64.29%	10.71%	19.64%
	FLT3	94.05%	29.76%	33.33%
	Prime	95.96%	13.13%	15.15%
	Testing	68.55%	4.84%	5.65%

Table 2: Our final reinforcement learning model achieves comparable pass@50 BEq and BEq+ scores, and significantly higher type-check (TC) rates on RLMEval [Poiroux et al., 2025].

Model	TC@1	TC@50	BEq	BEq+
SFT	17.29%	76.41%	10.66%	12.60%
RL	26.01 %	85.46 %	10.82%	12.76%

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