stop_go_bi tband. c

```
1// Stop Go C Example (Bitbanding)
2// Jason Losh
4//-----
5// Hardware Target
8// Target Platform: EK-TM4C123GXL Evaluation Board
             TM4C123GH6PM
9// Target uC:
10// System Clock:
                  40 MHz
12// Hardware configuration:
13// Red LED:
14// PF1 drives an NPN transistor that powers the red LED
15// Green LED:
16// PF3 drives an NPN transistor that powers the green LED
17// Pushbutton:
     SW1 pulls pin PF4 low (internal pull-up is used)
19
20//-----
21// Device includes, defines, and assembler directives
22//-----
23
24#include <stdint.h>
25#include <stdbool.h>
26#include "tm4c123gh6pm.h"
                   (*((volatile\ uint32_t\ *)(0x42000000\ +\ (0x400253FC-0x40000000)*32\ +\ 1*4)))
28#define RED_LED
                  (*((volatile uint32_t *)(0x42000000 + (0x400253FC-0x40000000)*32 + 3*4)))
29#define GREEN_LED
30#define PUSH_BUTTON (*((volatile uint32_t *)(0x42000000 + (0x400253FC-0x40000000)*32 + 4*4)))
31
32//-----
33// Subroutines
34//-----
36// Blocking function that returns only when SW1 is pressed
37 void waitPbPress()
38 {
39
     while(PUSH_BUTTON);
40 }
41
42// Initialize Hardware
43 void initHw()
44 {
45
     // Configure HW to work with 16 MHz XTAL, PLL enabled, system clock of 40 MHz
46
     SYSCTL_RCC_R = SYSCTL_RCC_XTAL_16MHZ | SYSCTL_RCC_OSCSRC_MAIN | SYSCTL_RCC_USESYSDIV | (4
 << SYSCTL_RCC_SYSDIV_S);
47
48
     // Set GPIO ports to use AP (not needed since default configuration -- for clarity)
49
     SYSCTL\_GPIOHBCTL\_R = 0;
50
51
     // Enable GPIO port F peripherals
52
     SYSCTL_RCGC2_R = SYSCTL_RCGC2_GPIOF;
53
54
     // Configure LED and pushbutton pins
     GPIO_PORTF_DIR_R = 0x0A; // bits 1 and 3 are outputs, other pins are inputs
55
```

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```
GPIO_PORTF_DR2R_R = 0xOA; // set drive strength to 2mA (not needed since default
56
 configuration -- for clarity)
     \overrightarrow{GPI}O_PORTF_DEN_R = 0x1A; // enable LEDs and pushbuttons
57
     GPIO_PORTF_PUR_R = 0x10; // enable internal pull-up for push button
58
59}
60
61//-----
62// Main
63//-----
65 int main(void)
66 {
     // Initialize hardware
67
     initHw();
68
69
70
     // Turn on red LED, turn off green LED
71
     RED_LED = 1;
72
     GREEN\_LED = 0;
73
74
     // Wait for PB press
75
     wai tPbPress();
76
77
     // Turn off red LED, turn on green LED
78
     RED_LED = 0;
79
     GREEN\_LED = 1;
80
     // Endless loop
81
82
     while(1);
83}
84
```