

analog.c

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1 // Analog LCD Example
2 // Jason Losh
3
4 //-----
5 // Hardware Target
6 //-----
7
8 // Target Platform: EK-TM4C123GXL with LCD/Temperature Sensor
9 // Target uC:      TM4C123GH6PM
10 // System Clock:   40 MHz
11
12 // Hardware configuration:
13 // Red Backlight LED:
14 //   PB5 drives an NPN transistor that powers the red LED
15 // Green Backlight LED:
16 //   PE5 drives an NPN transistor that powers the green LED
17 // Blue Backlight LED:
18 //   PE4 drives an NPN transistor that powers the blue LED
19 // LM60 Temperature Sensor:
20 //   AN0/PE3 is driven by the sensor (Vout = 424mV + 6.25mV / degC with +/-2degC uncalibrated
   error)
21 // ST7565R Graphics LCD Display Interface:
22 //   MOSI (SSI2Tx) on PB7
23 //   MISO (SSI2Rx) is not used by the LCD display but the pin is used for GPIO for A0
24 //   SCLK (SSI2Clk) on PB4
25 //   A0 connected to PB6
26 //   ~CS connected to PB1
27
28 //-----
29 // Device includes, defines, and assembler directives
30 //-----
31
32 #include <stdint.h>
33 #include <stdio.h>
34 #include <stdbool.h>
35 #include <string.h>
36 #include "tm4c123gh6pm.h"
37 #include "graphics_lcd.h"
38 #include "wait.h"
39 #define RED_BL_LED    (*((volatile uint32_t *) (0x42000000 + (0x400053FC-0x40000000)*32 + 5*4)))
40 #define GREEN_BL_LED  (*((volatile uint32_t *) (0x42000000 + (0x400243FC-0x40000000)*32 + 5*4)))
41 #define BLUE_BL_LED   (*((volatile uint32_t *) (0x42000000 + (0x400243FC-0x40000000)*32 + 4*4)))
42
43 //-----
44 // Global variables
45 //-----
46
47 //-----
48 // Subroutines
49 //-----
50
51 // Initialize Hardware
52 void initHw()
53 {
54     // Configure HW to work with 16 MHz XTAL, PLL enabled, system clock of 40 MHz
55     SYSCTL_RCC_R = SYSCTL_RCC_XTAL_16MHZ | SYSCTL_RCC_OSCSRC_MAIN | SYSCTL_RCC_USESYSDIV | (4
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56 << SYSCTL_RCC_SYSDIV_S);
57 // Set GPIO ports to use APB (not needed since default configuration -- for clarity)
58 // Note UART on port A must use APB
59 SYSCTL_GPIOHBCTL_R = 0;
60
61 // Enable GPIO port B and E peripherals
62 SYSCTL_RCGC2_R = SYSCTL_RCGC2_GPIOB | SYSCTL_RCGC2_GPIOE;
63
64 // Configure three backlight LEDs
65 GPIO_PORTB_DIR_R |= 0x20; // make bit5 an output
66 GPIO_PORTB_DR2R_R |= 0x20; // set drive strength to 2mA
67 GPIO_PORTB_DEN_R |= 0x20; // enable bit5 for digital
68 GPIO_PORTB_DIR_R |= 0x30; // make bits 4 and 5 outputs
69 GPIO_PORTB_DR2R_R |= 0x30; // set drive strength to 2mA
70 GPIO_PORTB_DEN_R |= 0x30; // enable bits 4 and 5 for digital
71
72 // Configure A0 and ~CS for graphics LCD
73 GPIO_PORTB_DIR_R |= 0x42; // make bits 1 and 6 outputs
74 GPIO_PORTB_DR2R_R |= 0x42; // set drive strength to 2mA
75 GPIO_PORTB_DEN_R |= 0x42; // enable bits 1 and 6 for digital
76
77 // Configure SSI2 pins for SPI configuration
78 SYSCTL_RCGCSSI_R |= SYSCTL_RCGCSSI_R2; // turn-on SSI2 clocking
79 GPIO_PORTB_DIR_R |= 0x90; // make bits 4 and 7 outputs
80 GPIO_PORTB_DR2R_R |= 0x90; // set drive strength to 2mA
81 GPIO_PORTB_AFSEL_R |= 0x90; // select alternative functions for MOSI,
    SCLK pins
82 GPIO_PORTB_PCTL_R = GPIO_PCTL_PB7_SSI2TX | GPIO_PCTL_PB4_SSI2CLK; // map alt fns to SSI2
83 GPIO_PORTB_DEN_R |= 0x90; // enable digital operation on TX, CLK
    pins
84
85 // Configure the SSI2 as a SPI master, mode 3, 8bit operation, 1 MHz bit rate
86 SSI2_CR1_R &= ~SSI_CR1_SSE; // turn off SSI2 to allow
    re-configuration
87 SSI2_CR1_R = 0; // select master mode
88 SSI2_CC_R = 0; // select system clock as the clock
    source
89 SSI2_CPSR_R = 40; // set bit rate to 1 MHz (if SR=0 in CRO)
90 SSI2_CRO_R = SSI_CRO_SPH | SSI_CRO_SPO | SSI_CRO_FRF_MOTO | SSI_CRO_DSS_8; // set SR=0,
    mode 3 (SPH=1, SPO=1), 8-bit
91 SSI2_CR1_R |= SSI_CR1_SSE; // turn on SSI2
92
93 // Configure ANO as an analog input
94 SYSCTL_RCGCADC_R |= 1; // turn on ADC module 0 clocking
95 GPIO_PORTB_AFSEL_R |= 0x08; // select alternative functions for ANO
    (PE3)
96 GPIO_PORTB_DEN_R &= ~0x08; // turn off digital operation on pin PE3
97 GPIO_PORTB_AMSEL_R |= 0x08; // turn on analog operation on pin PE3
98 ADC0_CC_R = ADC_CC_CS_SYSPLL; // select PLL as the time base (not
    needed, since default value)
99 ADC0_ACTSS_R &= ~ADC_ACTSS_ASEN3; // disable sample sequencer 3 (SS3) for
    programming
100 ADC0_EMUX_R = ADC_EMUX_EM3_PROCESSOR; // select SS3 bit in ADCPSSI as trigger
101 ADC0_SSMUX3_R = 0; // set first sample to ANO
102 ADC0_SSCTL3_R = ADC_SSCTL3_ENDO; // mark first sample as the end

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103     ADC0_ACTSS_R |= ADC_ACTSS_ASEN3;           // enable SS3 for operation
104 }
105
106 uint16_t readAdc0Ss3()
107 {
108     ADC0_PSSI_R |= ADC_PSSI_SS3;               // set start bit
109     while (ADC0_ACTSS_R & ADC_ACTSS_BUSY);     // wait until SS3 is not busy
110     return ADC0_SSIF03_R;                       // get single result from the FIFO
111 }
112
113 //-----
114 // Main
115 //-----
116
117 int main(void)
118 {
119     // Initialize hardware
120     initHw();
121
122     // Turn-on all LEDs to create white backlight
123     RED_BL_LED = 1;
124     GREEN_BL_LED = 1;
125     BLUE_BL_LED = 1;
126
127     // Initialize graphics LCD
128     initGraphicsLcd();
129
130     // Draw legend
131     setGraphicsLcdTextPosition(0, 0);
132     putsGraphicsLcd("Raw ADC");
133     setGraphicsLcdTextPosition(0, 1);
134     putsGraphicsLcd("Unfiltered (C)");
135     setGraphicsLcdTextPosition(0, 2);
136     putsGraphicsLcd("Filtered (C)");
137
138     // Display raw ADC value and temperatures
139     uint16_t raw;
140     float instantTemp, iirTemp;
141     char str[10];
142     float alpha = 0.99;
143     int firstUpdate = true;
144     while(1)
145     {
146         // Read sensor
147         raw = readAdc0Ss3();
148         // Calculate temperature in degC as follows:
149         // For the 12-bit SAR ADC with Vref+ = 3.3V and Vref- = 0V, outputting a result R:
150         // Resolution is approx 0.81mV / LSb or 0.13 degC / LSb
151         //  $R(Vin) = \text{floor}(Vin/3.3V * 4096) \rightarrow Vin(R) \approx 3.3V * ((R+0.5) / 4096)$ 
152         // (~ and 0.5LSb offset in Vin(R) equation are introduced for mid-tread value of the
153         SAR transfer function)
154         //  $T(Vin) = (Vin - 0.424V) / 0.00625V$ 
155         //  $T(R) \approx ([3.3V * ((R+0.5) / 4096)] - 0.424V) / 0.00625V$ 
156         //  $T(R) \approx (0.12890625 * R) - 67.775546875$  (simplified floating point equation to
157         save cycles)
158         instantTemp = ((raw / 4096.0 * 3.3) - 0.424) / 0.00625;

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157 // First order IIR filter
158 // In the z-domain:
159 //  $H(z) = \sum_{j=0..M} \{b_j * z^{-j}\}$ 
160 // -----
161 //  $\sum_{i=0..N} \{a_i * z^{-i}\}$ 
162 // Setting  $a_0 = 1$ , yields:
163 //  $H(z) = \sum_{j=0..M} \{b_j * z^{-j}\}$ 
164 // -----
165 //  $1 + \sum_{i=1..N} \{a_i * z^{-i}\}$ 
166 // for  $N = 1, M = 0$ :
167 //  $H(z) = b_0 / [1 + a_1 * z^{-1}]$ 
168 // Given IIR difference equation:
169 //  $\sum_{i=0..N} \{a_i * y(n-i)\} = \sum_{j=0..M} \{b_j * x(n-j)\}$ 
170 // Separating  $y(n)$ , rearranging and inverting signs of  $a(1-N)$ , yields
171 //  $a_0 * y(n) = \sum_{i=1..N} \{a_i * y(n-i)\} + \sum_{j=0..M} \{b_j * x(n-j)\}$ 
172 // for  $N = 1, M = 0$ , and  $a_0 = 1$ ,
173 //  $y(n) = b_0 * x(n) + a_1 * y(n-1)$ 
174 // Setting  $b_0 = (1-a_1)$ , yields
175 //  $y(n) = \alpha * y(n-1) + (1-\alpha) * x(n)$ 
176 // Adding an exception for the first sample, yields:
177 //  $y(n) = x(n); n = 0$ 
178 //  $y(n) = \alpha * y(n-1) + (1-\alpha) * x(n); n > 0$ 
179 if (firstUpdate)
180 {
181     iirTemp = instantTemp;
182     firstUpdate = false;
183 }
184 else
185     iirTemp = iirTemp * alpha + instantTemp * (1-alpha);
186
187 // display raw ADC value and temperatures
188 sprintf(str, "%u", raw);
189 setGraphicsLcdTextPosition(100, 0);
190 putsGraphicsLcd(str);
191 sprintf(str, "%3.1f", instantTemp);
192 setGraphicsLcdTextPosition(100, 1);
193 putsGraphicsLcd(str);
194 sprintf(str, "%3.1f", iirTemp);
195 setGraphicsLcdTextPosition(100, 2);
196 putsGraphicsLcd(str);
197 waitMicrosecond(500000);
198 }
199 }
200
201

```