NEEV PARIKH

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EXPERIENCE

Software Engineer
Stripe
Jul 2022 – Present
San Francisco, CA

- Working on the Financial Data team

Research Engineering Intern
Common Sense Machines
May 2021 – Aug 2021
Boston, MA

- Implemented large-scale, auto-regressive Seq2Seq models for working with 3D geometry from images.
- Worked with Deepspeed to explore scaling options for 500M+ param models to feasibly scale existing sequence-based models.
- Implemented a Blender-based Gym environment for RL to optimize textures on a 3D model.
- Implemented a graphics algorithm to find surface patches in a 3D wireframe (Zhang et. al., 2013)
- Dockerized AWS pipeline to create cloud-independent dev/production environment.

Machine Learning Intern
Myelin Foundry
Jun 2019 – Aug 2019
Bangalore, India

- Developed a cutting-edge, deep-learning based pipeline in Pytorch and Tensorflow to augment VFX workflows for a POC product.
- Researched and managed a company-wide, cloud-compute platform, reducing potential monthly costs by 70%.
- Helped transition MLOps to Microsoft Azure.
- Implemented DeepLabv3+ from **ECCV 2018** to develop SOTA pipelines for semantic segmentation tasks.
- Achieved 90% in business-aligned metrics with reasonable inference time.

Research Assistant
Brown University
Jun 2020 – May 2022
Providence, RI

- Worked on original research on unsupervised, representation learning and multi-task reinforcement learning; see publications.

PUBLICATIONS

*equal contribution

- N. Parikh*, Z. Horvitz*, N. Srinvasan*, A. Shah, and G. Konidaris (Oct. 2020). “Graph Embedding Priors for Multi-task Deep Reinforcement Learning”. In: *NeurIPS 2020. KR2ML Workshop*.
- C. Allen, N. Parikh, and G. Konidaris (Dec. 2021). “Learning Markov State Abstractions for Deep Reinforcement Learning”. In: *34th Neural Information Processing Systems Conference 2021*.
- K. Asadi, N. Parikh, R. Parr, G. Konidaris, and M. Littman (Sept. 2020). “Deep Radial-Basis Value Functions for Continuous Control”. In: *35th AAAI Conference on Artificial Intelligence 2021*.
- M. Merlin, N. Parikh, E. Rosen, and G. Konidaris (May 2020). “Locally Observable Markov Decision Process”. In: *International Conference on Robotics and Automation. Workshop on Perception, Action, Learning*.

EDUCATION

M.Sc. in Computer Science
Brown University
Aug 2018 – May 2022 (Concurrent)
GPA: 4.0

Advised by: **Prof. George Konidaris**

B.Sc. in Computer Science
Brown University
Aug 2018 – May 2022 (Concurrent)
GPA: 3.9

Advised by: **Prof. Michael Littman**

Courses

ML with Limited Labeled Data | Robotics | NLP with ML | Graduate Graphics | Reintegrating AI | Prescriptive Analytics | ML Theory Seminar | Intro to RL (IS) | Distributed Systems | Computer Vision | Accelerated Intro CS | Systems | Networks | Multivariable Calc. | Convex Optimization | Probability & Stats | Microeconomics | Blockchains | Algorithms | Linear Algebra

PROJECTS

Onager
Lightweight hyperparameter tuning and experiment management, with interfaces to Slurm and Gridengine clusters
camall3n/onager

Hierarchical Doom
High-throughput, distributed RL project to implement async. PPO-OC (Proximal Policy Optimized - Option Critic) on the VizDoom environment
neevparikh/hierarchical-doom

SKILLS

Pytorch | Python | Machine Learning | Rust | C++ | Slurm | AWS | Azure | Numpy | Golang | C | Tensorflow | Google Cloud | Docker | Git | Haskell