



# Computer vision methods timeline

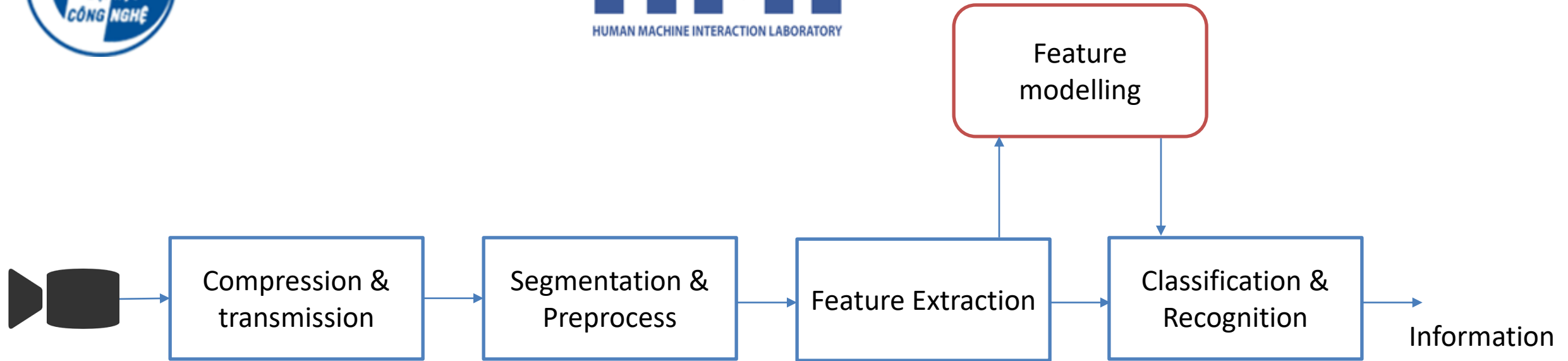
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# Computer vision methods timeline

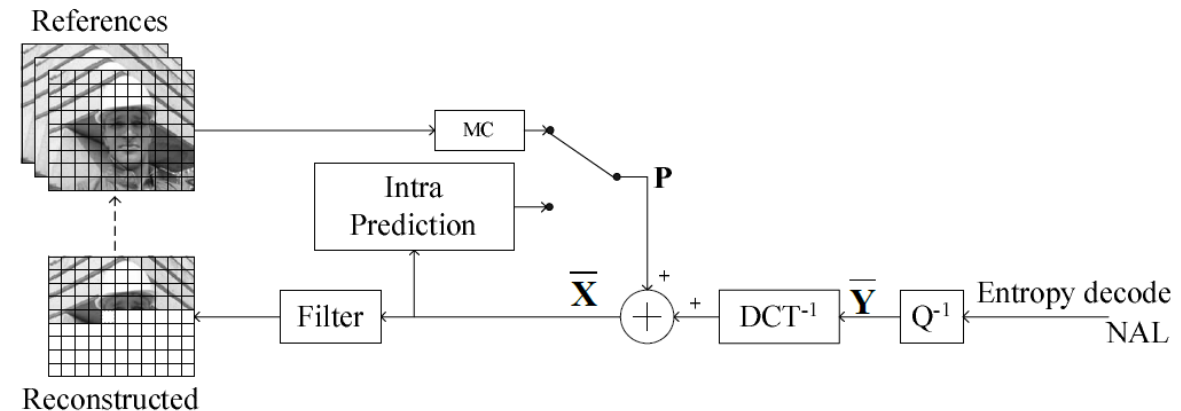
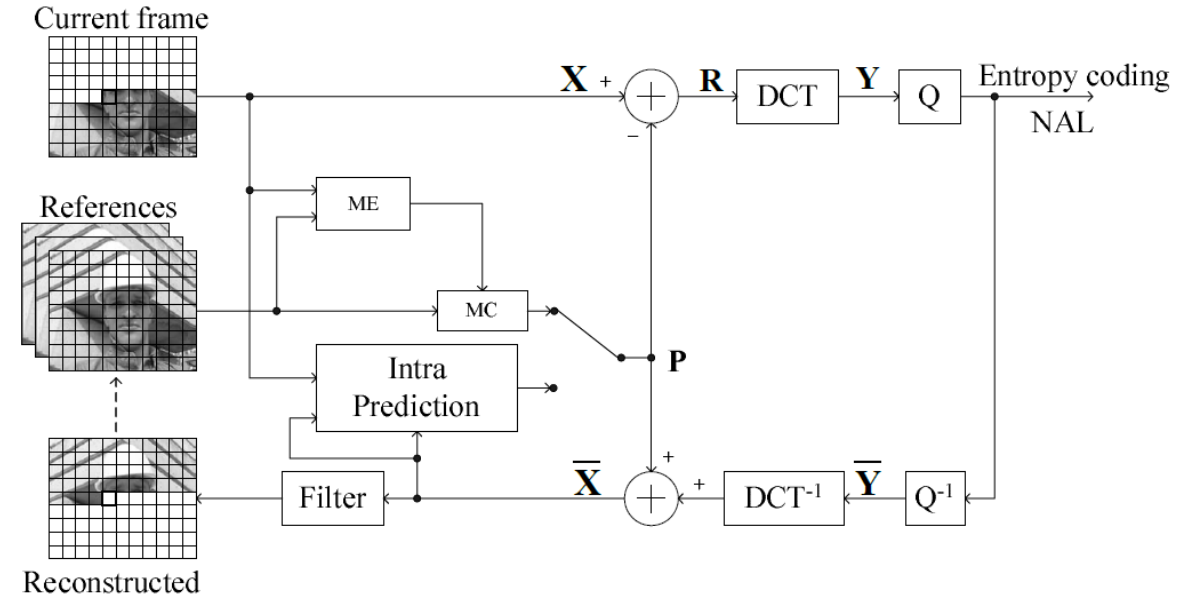
- Before 1995: Template matching
  - Match patches to find the correspondence between images.
- 1995 – 2000: Local feature descriptor
  - Scale Invariant Feature Transform (SIFT)
- 2000 – 2005: Machine learning for feature descriptors
  - Modern image dataset
  - Bins, Grids, and Visual Words
- 2005 – 2010: Object template
  - Histogram of Oriented Gradients (HOG)
  - Deformable Parts-based Model (DPM)
- 2010 – now: Big data, Convolutional network, Deep learning



## TYPICAL IMAGE PROCESSING WORKFLOW

# Compression & Transmission

- Reduce the size of video presentation to be sent effectively over error-prone network or to be stored
- Smallest in size, best in quality
- Tolerate with network conditions
- H.264/AVC, H.265/HEVC, VP9, Raspro



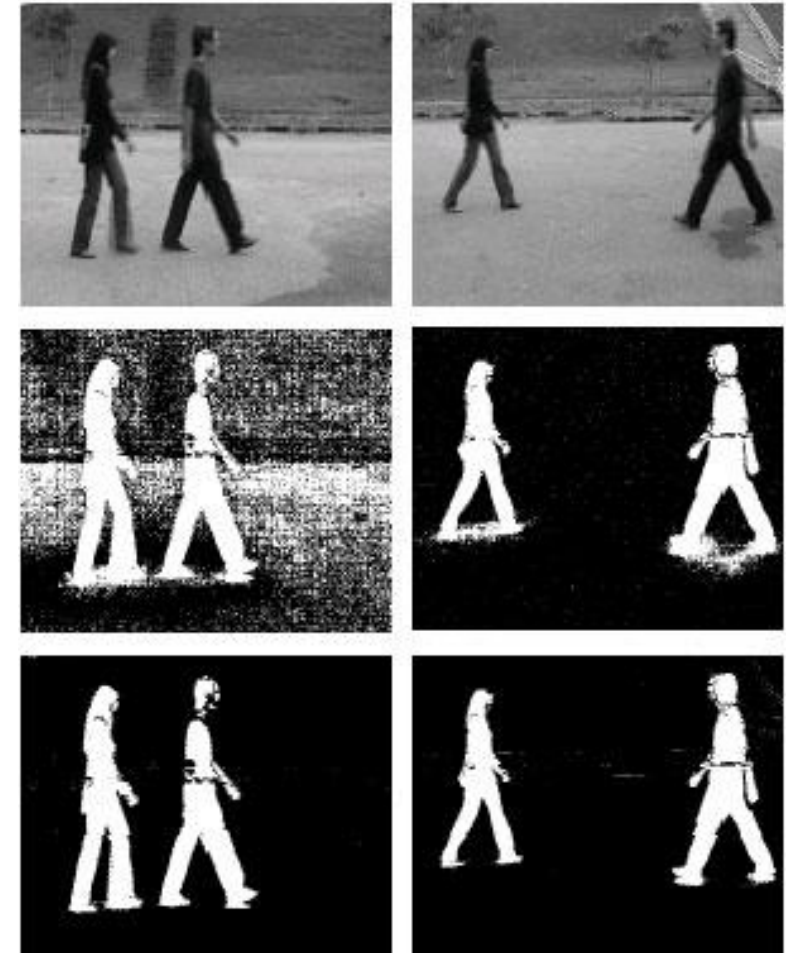
# Segmentation & Preprocess

- Noise removal
- Image enhancement
- Temporal segmentation: scene cut, key frames,...
- Spatial segmentation: grabcut, background subtraction

Noise removal

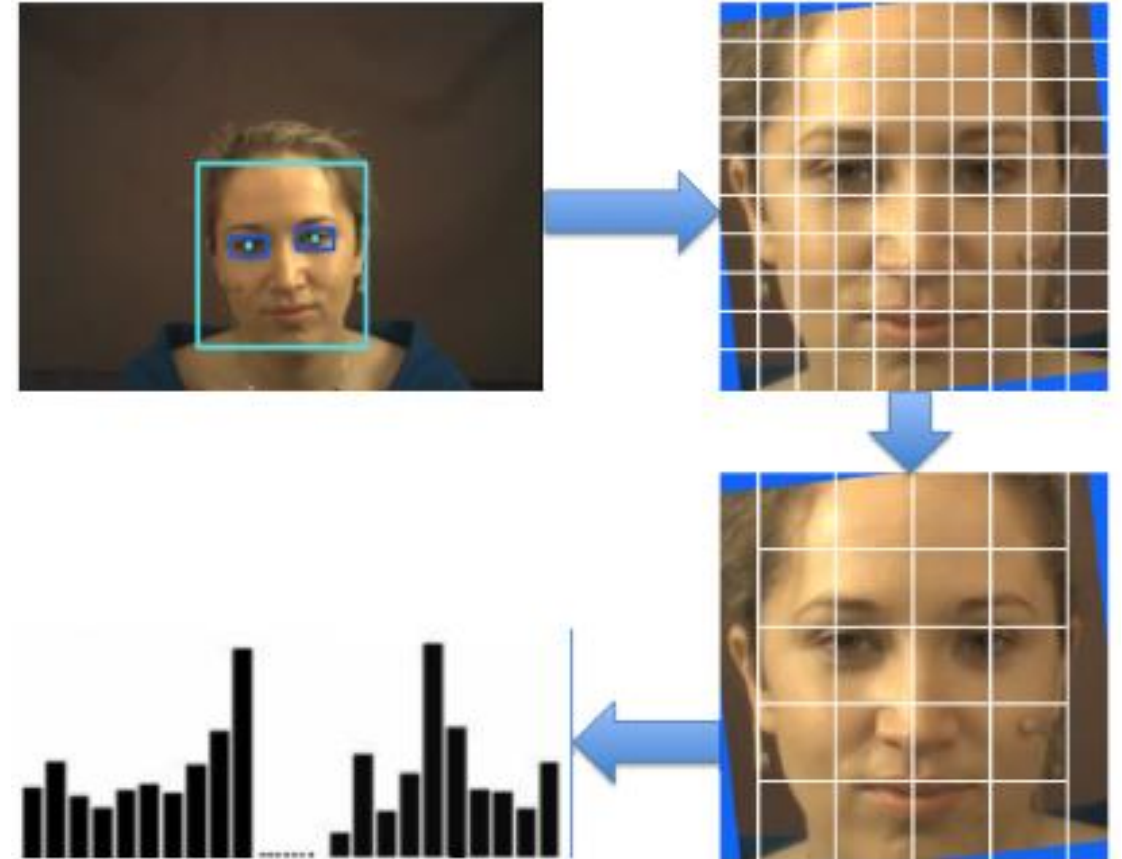


Background subtraction



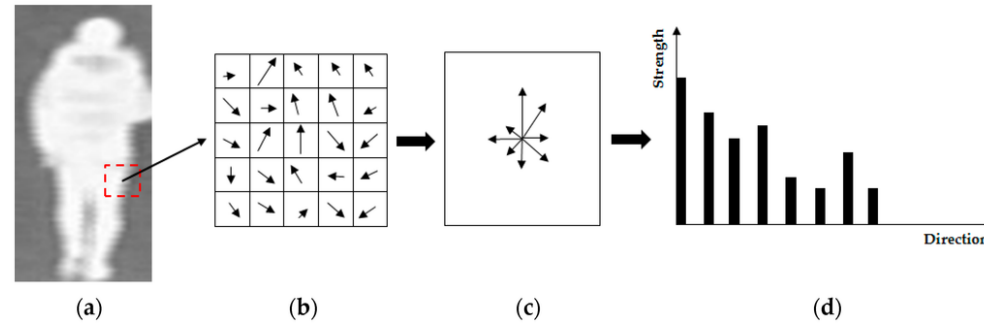
# Feature Extraction

- Target object must be detected and described with small number of dimensions. It should be:
  - Robustness
  - Repeatable
  - Noise tolerable
  - Invariant to illumination, rotation, scaling, and view point.

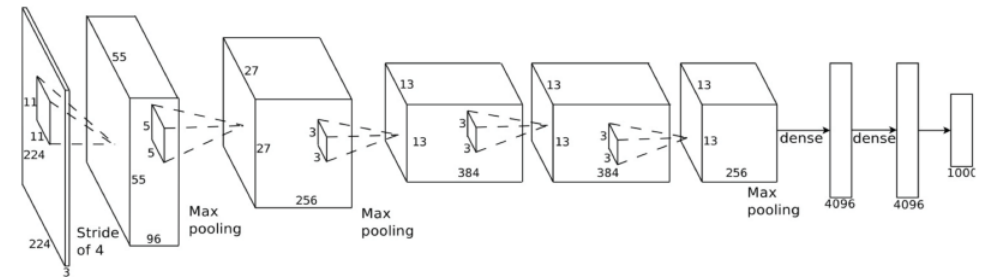


# Image feature examples

- Histogram based: Histogram of oriented gradients (HOG)



- Feature points:
  - Harris corners
  - Sussan corner
- Feature points description:
  - SIFT
  - SURF



**Deep learning**

# Feature modeling/learning

- A training dataset must be collected.
- A model must be used to generalize the input features and map it to desired output (class):
  - Support Vector Machines
  - Neuron networks
  - Logistics
  - Decision tree
  - Ada-boost
  - ...
- After trained, the model can be used to classify the testing data.

