

RESTARTING THE NON-SYMMETRIC LANCZOS ALGORITHM VIA THE IMPLICITLY SHIFTED LR ALGORITHM*

P. S. NEGI[†] AND C. ARRATIA[‡]

Abstract. The implicitly shifted QR iteration is used as a restart procedure for the Arnoldi method for the calculation of a few dominant eigenvalues of a large matrix. We show that the underlying idea of implicit polynomial filtering can be utilized in much the same manner via the implicitly shifted LR iteration to create a restart procedure for the non-symmetric Lanczos algorithm for eigenvalue computations.

Key words. LR algorithm, non-symmetric Lanczos, implicit restart

MSC codes. 68Q25, 68R10, 68U05

1. Introduction. The Arnoldi iteration [1] is a popular Krylov space method for calculating a few eigenvalues of a large matrix. The method relies on the generation of a sequence of Krylov vectors which determine the subspace within which approximations of the eigenvalue-eigenvector pairs are obtained. Depending on the accuracy and number of eigenpair approximations needed, the Krylov space size can become exceedingly large so that the quality of the results may be limited by the available memory. Sorensen [13] introduced an elegant procedure for restarting the Arnoldi factorization based on polynomial filters, which are applied through the implicitly shifted QR iterations on the reduced Hessenberg matrix obtained through the Arnoldi method. In particular, the use of exact shifts was shown to be successful in the convergence process of the eigenspace[13] of the specified eigenvalues. The method has subsequently found widespread application through the ARPACK library [7]. The use of QR iterations ensures that the reduced matrix preserves its Hessenberg structure through the transforms that make up the restart process. If the underlying matrix is symmetric, the Arnoldi iteration reduces to the Lanczos algorithm and, the Hessenberg matrix reduces to a symmetric tridiagonal matrix. The QR iteration preserves the symmetric tridiagonal structure as well and, as pointed out by Sorensen [13], the implicit restart process applies equally well for the Lanczos method for symmetric matrices.

The Lanczos algorithm introduced in [6] is in fact the predecessor of the Arnoldi method and, can be used for non-symmetric matrices as well. In such cases it is referred to as the non-symmetric or the bi-Lanczos. In this case one builds two Krylov subspaces referred to as the right and the left Krylov subspaces. The idea behind the two methods is similar, which is to obtain a projection of the original large matrix on to an appropriate reduced subspace such that, the eigenvalues may be approximated via the eigenvalues of the reduced operator. The difference being that in the Arnoldi method one obtains an orthogonal projection on to a subspace while, in the Lanczos method one obtains an oblique projection. One would therefore like to extend the idea of implicit restarts to the non-symmetric Lanczos algorithm as well. However, the reduced matrix that one obtains in such a case is a non-symmetric

*Submitted to the editors DATE.

Funding: This work was funded by the Nordita under contract no. FRI-454.

[†]Nordita, Stockholm University, KTH Royal Institute of Technology, Stockholm, Sweden (prabal.negi@su.se).

[‡]Nordita, Stockholm University, KTH Royal Institute of Technology, Stockholm, Sweden (cristo-bal.arratia@su.se).

tridiagonal matrix, with the tridiagonal structure being the result of the recurrence relations of the Lanczos algorithm [12]. Since the QR iterations do not preserve the banded structure of non-symmetric matrices, a straightforward application of the restart procedure put forward by Sorensen will lead to a loss of this tridiagonal structure (the Hessenberg structure will still be preserved). This loss of structure can be circumvented if one looks to the predecessor of the QR algorithm namely, the LR algorithm proposed by Rutishauser [10, 11, 9], which has the attractive property of preserving the band structure of a matrix. This property was already pointed out by Rutishauser in [10] where the banded matrices were referred to as striped matrices. As we will show in the next section, the shifted LR transform is the appropriate analogue of the restart procedure in the case of non-symmetric Lanczos iteration. The process would necessarily require refining both the right as well as the left Krylov spaces simultaneously.

The rest of the paper is organized as follows. In section 2 we start with the introduction of the non-symmetric Lanczos iteration and then develop the restart procedure. In section 3 we apply the restart process to the Grcar matrix, and make some concluding remarks in section 4.

2. Non-symmetric Lanczos. Lanczos first introduced his algorithm in [6] as a method for tridiagonalizing a matrix, but also realized that the method could be used iteratively to find eigenvalues. For an arbitrary matrix A , the method generates a pair of Krylov subspaces $\{v_1, \dots, v_j\}$ and $\{w_1, \dots, w_j\}$, through repeated action of A and A^H respectively. We refer to these as the right and left Krylov spaces respectively and they satisfy the biorthogonality relation $w_i^H v_j = \delta_{ij}$. The two subspaces are generated through a three term recurrence relation which, for a Krylov space of size m , can be written in matrix form as

$$(2.1a) \quad AV_m - V_m T_m = \tilde{v}_{m+1} e_m^T,$$

$$(2.1b) \quad A^H W_m - W_m T_m^H = \tilde{w}_{m+1} e_m^T,$$

$$(2.1c) \quad W_m^H V_m = I_m,$$

where, I_m represents the Identity matrix of size m , T_m is a tri-diagonal matrix of size m with T_m^H its Hermitian conjugate, and e_m is the standard unit vector. \tilde{v}_{m+1} and \tilde{w}_{m+1} represent the residual vectors at the m^{th} step. If either \tilde{v}_{m+1} or \tilde{w}_{m+1} vanishes it represents the convergence of the right or the left Krylov subspaces to an invariant subspace of dimension m . A more serious breakdown occurs if $\tilde{w}_{m+1}^H \tilde{v}_{m+1} = 0$ with both $\tilde{v}_{m+1} \neq 0$ and $\tilde{w}_{m+1} \neq 0$, in which case a look-ahead strategy may be employed. We do not address the issues with breakdown here since it is not specifically related to the restart procedure. We refer the reader to [8] for the look-ahead Lanczos and to [5] for a comprehensive overview on Lanczos type solvers and the related issues of breakdown.

As Sorensen points out for the Arnoldi method [13], if one is interested in an invariant subspace of dimension m , the starting vector of the Krylov subspace must not contain components of the generator of a cyclic subspace of dimension greater than m . This applies equally for the right and left Krylov subspaces generated through the Lanczos recurrence relations. Hence a non-vanishing \tilde{v}_{m+1} (respectively \tilde{w}_{m+1}) implies that v_1 (respectively w_1) contains components of an invariant subspace of dimension greater than m . The idea behind restarts then is to discard the components of the starting vector v_1 (and w_1) along the unwanted dimensions, such that each restart process moves the Krylov space(s) closer to being invariant. For the Arnoldi

method Sorensen [13] proposed to achieve this via polynomial filtering, *i.e.* replacing

$$(2.2a) \quad v_1 \leftarrow \psi(A)v_1,$$

$$(2.2b) \quad \psi(\lambda) = (1/\tau)\prod_{j=1}^p(\lambda - \mu_j).$$

Obviously $\psi(\lambda)$ is the filtering polynomial, τ is a normalization constant and each μ_j specifies a node of the polynomial. The polynomial acts on v_1 to filter out the part of the spectrum of A that is close to each μ_j . If a particular μ_j corresponds to an exact eigenvalue of A , then components of the corresponding eigenvector are completely filtered out from v_1 (at least in exact arithmetic). The node μ_j is referred to as a shift since the application of the polynomial filtering relies on the shifted QR algorithm, where μ_j is used as the shift. As shown below for the case of a single shift, an analogous procedure can be followed using a shifted LR algorithm which achieves the same effect of applying a polynomial filter to the starting vector v_1 . Starting with the Lanczos relation for the right subspace (2.1a), and adding and subtracting μV_m we obtain

$$(2.3a) \quad (A - \mu I)V_m - V_m(T_m - \mu I) = \tilde{v}_{m+1}e_m^T$$

$$(2.3b) \quad (A - \mu I)V_m - V_m(L_1 R_1) = \tilde{v}_{m+1}e_m^T$$

$$(2.3c) \quad (A - \mu I)V_m L_1 - V_m(L_1 R_1)L_1 = \tilde{v}_{m+1}e_m^T L_1$$

$$(2.3d) \quad A(V_m L_1) - (V_m L_1)(R_1 L_1 + \mu I) = \tilde{v}_{m+1}e_m^T L_1$$

$$(2.3e) \quad AV'_m - V'_m T'_m = \tilde{v}_{m+1}e_m^T L_1.$$

Here we have set $V'_m = V_m L_1$ and $T'_m = (R_1 L_1 + \mu I)$. The matrices L_1, R_1 are the lower and upper triangular matrices obtained from the LU decomposition of $(T_m - \mu I)$. The matrix L_1 can be required to be unit triangular (all entries on the main diagonal are ones), in which case the LU decomposition is unique. Furthermore, L_1 for a tridiagonal matrix only consists of one sub-diagonal (in addition to the main diagonal). One can easily recognize that the new reduced matrix T'_m is a result of one step of the shifted LR iteration. Hence T'_m retains the tridiagonal structure of the T_m [10, 9]. The relationship between starting vectors of the two spaces V_m and V'_m can be obtained by multiplying (2.3b) by e_1 , *i.e.*

$$(A - \mu I)V_m e_1 - (V'_m)R_1 e_1 = \tilde{v}_{m+1}e_m^T e_1$$

$$\implies (A - \mu I)v_1 = v'_1 \rho_{11},$$

where $\rho_{11} = e_1^T R_1 e_1$. This clearly shows the filtering operation done on the original vector v_1 to generate the new vector v'_1 .

Since the Lanczos method creates a biorthogonal basis, one must simultaneously transform the left basis W_m to maintain the biorthogonality property. It is easy to see that the necessary transform to maintain biorthogonality is $W'_m = W_m L_1^{-H}$, since,

$$W'^H V'_m = (W_m L_1^{-H})^H (V_m L_1) = L_1^{-1} (W_m^H V_m) L_1 = I$$

Substituting the relation obtained from the LU decomposition $T_m^H = (R_1^H L_1^H + \bar{\mu} I)$ in to equation (2.1b) we can obtain the modified Lanczos relation for the left Krylov space as

$$(2.4) \quad A^H W_m - W_m (R_1^H L_1^H + \bar{\mu} I) = \tilde{w}_{m+1}e_m^T$$

$$(2.5) \quad A^H (W_m L_1^{-H}) - W_m (L_1^{-H} L_1) (R_1^H L_1^H + \bar{\mu} I) L_1^{-H} = \tilde{w}_{m+1}e_m^T L_1^{-H}$$

$$(2.6) \quad A^H (W_m L_1^{-H}) - (W_m L_1^{-H}) (L_1^H R_1^H + \bar{\mu} I) = \tilde{w}_{m+1}e_m^T L_1^{-H}$$

$$(2.7) \quad A^H W'_m - W'_m (T'_m)^H = \tilde{w}_{m+1}e_m^T L_1^{-H}.$$

Conveniently the structure of the Lanczos iteration for the left Krylov space is also preserved. Noting that L_1^{-H} is upper triangular, one can again expose the relationship between the generating vectors of the two left Krylov spaces as

$$\begin{aligned} W'e_1 &= (W_m L_1^{-H})e_1 \\ \implies w'_1 &= w_1(e_1^T L_1^{-H} e_1). \end{aligned}$$

Clearly w'_1 is simply a scalar multiple of the old vector w_1 and no filtering of the generating vector has occurred. In order to ensure that we filter the left Krylov space as well, we perform one step of the shifted LR iteration with the conjugated shift $\bar{\mu}$ on the reduced matrix $(T'_m)^H$ obtained in equation (2.7).

$$\begin{aligned} (2.8a) \quad & (A - \mu I)^H W'_m - W'_m (T'_m - \mu I)^H = \tilde{w}_{m+1} e_m^T L_1^{-H}, \\ (2.8b) \quad & (A - \mu I)^H W'_m - W'_m (L_2 R_2) = \tilde{w}_{m+1} e_m^T L_1^{-H}, \\ (2.8c) \quad & (A - \mu I)^H W'_m L_2 - W'_m (L_2 R_2) L_2 = \tilde{w}_{m+1} e_m^T L_1^{-H} L_2, \\ (2.8d) \quad & A(W'_m L_2) - (W'_m L_2)(R_2 L_2 + \bar{\mu} I) = \tilde{w}_{m+1} e_m^T L_1^{-H} L_2, \\ (2.8e) \quad & A W''_m - W''_m (T''_m)^H = \tilde{w}_{m+1} e_m^T L_1^{-H} L_2. \end{aligned}$$

One may again obtain the relation between the starting vectors of the two spaces as

$$(2.9) \quad (A^H - \bar{\mu} I)w'_1 = w''_1(e_1^T R_2 e_1),$$

which clearly shows the filtering operation performed on the starting vector of the left Krylov space. Obviously the appropriate transform for the right subspace to maintain orthogonality is $V''_m = V'_m L_2^{-H} = V_m L_1 L_2^{-H}$. Again, note that the upper triangular L_2^{-H} implies that the new v''_1 is simply the scalar multiple of v'_1 and no additional filtering occurs for v_1 in this step. One can write the corresponding modified Lanczos relation as

$$(2.10) \quad A V''_m - V''_m T''_m = \tilde{v}_{m+1} e_m^T L_1 L_2^{-H}.$$

The above process can be repeated for p unwanted shifts. We denote by $L_1^p = L_{11} L_{12} \dots L_{1p}$ as the product of the lower triangular matrices generated due to p shifted-LR steps for the right Krylov space V_m , and by $L_2^p = L_{21} L_{22} \dots L_{2p}$ as the product of the lower triangular matrices due to the p shifted-LR iterations for the left Krylov space. Then for a Krylov space size of $m = k + p$ we have two modified Lanczos relations

$$(2.11a) \quad A V''_{k+p} - V''_{k+p} T''_{k+p} = \tilde{v}_{k+p+1} e_{k+p}^T L_1^p (L_2^p)^{-H},$$

$$(2.11b) \quad A^H W''_{k+p} - W''_{k+p} (T''_{k+p})^H = \tilde{w}_{k+p+1} e_{k+p}^T (L_1^p)^{-H} L_2^p.$$

We may take a closer look at the structure of the residual matrices on the right hand side of equation (2.11a). L_1^p is a product of p matrices that are lower triangular with just one subdiagonal. L_1^p then is lower triangular with p non-zero subdiagonals. $(L_2^p)^{-H}$ is upper triangular and the product $L_1^p (L_2^p)^{-H}$ therefore has p non-zero subdiagonals. Left multiplication by e_{k+p}^T therefore has the form

$$e_{k+p}^T L_1^p (L_2^p)^{-H} = \underbrace{(0, 0, \dots, \theta_{k+p})}_k, \underbrace{b_1^T}_p$$

where, $\theta_{k+p} = e_{k+p}^T (L_1^p (L_2^p)^{-H}) e_k$. Therefore the matrix on the right hand side of (2.11a) has zeros in the first $k - 1$ columns and the k^{th} column is simply $\theta_{k+p} \tilde{v}_{k+p+1}$.

The remaining columns are non-zero in general. A very similar structure is obtained for the residual matrix in the right hand side of equation (2.11b) with zeros in the first $k - 1$ columns and the k^{th} column being equal to $\phi_{k+p}\tilde{w}_{k+p+1}$, with $\phi_{k+p} = e_{k+p}^T((L_1^p)^{-H}L_2^p)e_k$

Partitioning the matrices such that

$$\begin{aligned} V''_{k+p} &= (V''_k, V''_p), & T''_{k+p} &= \begin{pmatrix} T''_k & \delta_{k+1}e_1e_1^T \\ \beta_{k+1}e_1e_k^T & T''_p \end{pmatrix}, \\ W''_{k+p} &= (W''_k, W''_p), & (T''_{k+p})^H &= \begin{pmatrix} (T''_k)^H & \bar{\beta}_{k+1}e_1e_1^T \\ \bar{\delta}_{k+1}e_1e_k^T & (T''_p)^H \end{pmatrix}, \end{aligned}$$

with the length of the e_i vectors understood to be such that the resulting matrices are consistent. We can write the modified Lanczos relations of (2.11a) and (2.11b) as

$$\begin{aligned} A(V''_k, V''_p) &= (V''_k, V''_p) \begin{pmatrix} T''_k & \delta_{k+1}e_1e_1^T \\ \beta_{k+1}e_1e_k^T & T''_p \end{pmatrix} + (\theta_{k+p}\tilde{v}_{k+p+1}e_k^T, M_v), \\ A^H(W''_k, W''_p) &= (W''_k, W''_p) \begin{pmatrix} (T''_k)^H & \bar{\beta}_{k+1}e_1e_1^T \\ \bar{\delta}_{k+1}e_1e_k^T & (T''_p)^H \end{pmatrix} + (\phi_{k+p}\tilde{w}_{k+p+1}e_k^T, M_w), \end{aligned}$$

Finally, equating the individual columns on both sides and discarding columns $k + 1, \dots, k + p$ we are left with the new Krylov spaces of order k and the Lanczos relations

$$(2.13a) \quad AV''_k - V''_kT''_k = \tilde{v}_{k+1}e_k^T,$$

$$(2.13b) \quad A^HW''_k - W''_k(T''_k)^H = \tilde{w}_{k+1}e_k^T,$$

$$(2.13c) \quad (W''_k)^H V_k = I.$$

The new residual vectors are defined as

$$(2.14a) \quad \tilde{v}_{k+1}'' = \beta_{k+1}V''_p e_1 + \theta_{k+p}\tilde{v}_{k+p+1},$$

$$(2.14b) \quad \tilde{w}_{k+1}'' = \bar{\delta}_{k+1}W''_p e_1 + \phi_{k+p}\tilde{w}_{k+p+1},$$

which may be normalized appropriately such that the inner product of the new Krylov vectors is unity. The Lanczos process may now be carried out again to generate the next p vectors of the right and left Krylov spaces and the cycle may be repeated till an adequately converged subspace has been obtained. In the case that exact shifts (eigenvalues of T_m) are used for the restart procedure β_{k+1} and δ_{k+1} are both zero in exact arithmetic.

As a final note, we mention that Della-Dora [3] introduced a class of algorithms of the GR type of which, LR and QR are special cases. Watkins then introduced generic bulge-chasing algorithms for the entire GR class of methods[14]. The shifted LR algorithm used in the restart procedure outlined above can therefore be carried out in an implicit manner through the bulge-chase sequence of Watkins [14]. For real matrices, the operations can be confined in the real space by using the double-shift strategy introduced by Francis [4]. The entire restart process is put together in algorithm 2.1.

Algorithm 2.1 Restarted nonsymmetric Lanczos

Input: $V_{k+p}, \tilde{v}_{k+p+1}, W_{k+p}, \tilde{w}_{k+p+1}, T_{k+p}$
Input: $\mu_1, \mu_2, \dots, \mu_p$ ▷ Unwanted shifts
Output: $V_k, v_{k+1}, W_k, w_{k+1}, T_k$
Require: $AV_{k+p} - V_{k+p}T_{k+p} = \tilde{v}_{k+p+1}e_{k+p}^T$ ▷ Right Lanczos relation
Require: $A^H W_{k+p} - W_{k+p}T_{k+p}^H = \tilde{w}_{k+p+1}e_{k+p}^T$ ▷ Left Lanczos relation
Require: $W_{k+p}^H V_{k+p} = I$; $W_{k+p}^H \tilde{v}_{k+p+1} = 0$; $V_{k+p}^H \tilde{w}_{k+p+1} = 0$; ▷ Bi-orthogonality
1: **procedure** REFINE RIGHT SUBSPACE
2: $L_r \leftarrow I_{k+p}$
3: **for** $j \leftarrow 1$ to p **do**
4: $T_{k+p} \leftarrow L^{-1}T_{k+p}L$ ▷ Implicitly shifted LR with shift μ_j
5: $L_r \leftarrow LL_r$
6: **end for**
7: **end procedure**
8: **procedure** REFINE LEFT SUBSPACE
9: $L_l \leftarrow I_{k+p}$
10: **for** $j \leftarrow 1$ to p **do**
11: $T_{k+p}^H \leftarrow L^{-1}T_{k+p}^H L$ ▷ Implicitly shifted LR with shift $\bar{\mu}_j$
12: $L_l \leftarrow LL_l$
13: **end for**
14: **end procedure**
15: **procedure** UPDATE
16: $\beta \leftarrow e_{k+1}^T T_{k+p} e_k$; $\delta \leftarrow e_k^T T_{k+p} e_{k+1}$
17: $\theta = e_{k+p}^T (L_r (L_l)^{-H}) e_k$; $\phi = e_{k+p}^T (L_r^{-H} L_l) e_k$
18: $\tilde{v}_{k+1} \leftarrow \beta V_{k+p} e_{k+1} + \theta \tilde{v}_{k+p+1}$ ▷ New right residual
19: $\tilde{w}_{k+1} \leftarrow \delta W_{k+p} e_{k+1} + \phi \tilde{w}_{k+p+1}$ ▷ New left residual
20: $V_k \leftarrow V_{k+p} (L_r L_l^{-H}) \begin{pmatrix} I_k \\ 0_p \end{pmatrix}$ ▷ New right Krylov space
21: $W_k \leftarrow W_{k+p} (L_r^{-H} L_l) \begin{pmatrix} I_k \\ 0_p \end{pmatrix}$ ▷ New left Krylov space
22: $T_k \leftarrow \begin{pmatrix} I_k & 0_p \end{pmatrix} T_{k+p} \begin{pmatrix} I_k \\ 0_p \end{pmatrix}$ ▷ New tridiagonal matrix
23: **end procedure**
24: **return** $V_k, \tilde{v}_{k+1}, W_k, \tilde{w}_{k+1}, T_k$

3. Computational Results. We present the results of computational tests performed in the Gcar matrix which is highly non-normal and has presented problems with convergence in previous studies. In his implicit restart work Sorensen [13] indeed points out that the restarted Arnoldi has trouble converging to the left-most part of the spectrum and even though the algorithm claimed convergence, what was obtained was in fact part of the pseudospectrum.

We present the results of the restarted Lanczos method applied to the 50×50 Gcar matrix for $k = 10$ and $p = 10$. Figure 1 shows the spectrum obtained after performing eleven restarts of the Lanczos algorithm. The restarts were performed such that the k eigenvalues with the largest imaginary part were retained for the reduced operator and the remaining were used as shifts to be discarded from the subspace. The same part of the spectrum was sought by Sorensen in [13]. In this particular case we obtained $\tilde{w}_{m+1}^T \tilde{v}_{m+1} \sim O(10^{-11})$ even though the individual residuals were both of

order $10^{-3} - 10^{-4}$. At this particular moment, one would need to employ a look-ahead step of the Lanczos however, we have shown the spectrum of the reduced matrix at this point. One may think of the spectrum to have converged to $O(10^{-4})$. As seen from the figure, the spectrum of the reduced operator matches quite well with the original spectrum of the Grcar matrix. In figure 2, we show the convergence history of the individual eigenvalues with each restart step as the Lanczos algorithm progresses. Clearly the restart process is working well to shift the Krylov spaces towards the wanted region of the spectrum. The error in the eigenvalues is of $O(10^{-7})$ even though the perturbation to the reduced matrix is of order 10^{-4} . This is contrast to the results obtained in [13] which reported large perturbations to the eigenvalues even when the Arnoldi method reported convergence. We suspect this is due to the fact that the non-symmetric Lanczos approximates both the right and left eigenspaces simultaneously and leads to a lower error in the truncated matrix. We expect this to be particularly useful in hydrodynamic problems where highly non-normal matrices are a routine occurrence and where problems with convergence of the spectrum have often been reported (see [2] for example, **cite Trefethen and Toeplitz matrices**).

At this point we make a note of caution that for large Grcar matrices our attempts have been somewhat less successful and the convergence sometimes fails. We expect this is due to the naive implementations of the implicit LR method that we have done in Julia where, the standard checks for small sub-diagonal elements have not been performed. In our investigations of such cases we indeed do find small sub diagonal elements which lead to loss of precision. Very small sub diagonal elements also lead to rapid loss of biorthogonality of the two subspaces. Similarly we have not paid attention to the issue arising out of the Lanczos algorithm itself, except for employing a double (two-sided) Gram-Schmidt to ensure biorthogonality. We also note that for large number of restarts, the biorthogonality property of the two subspaces is progressively lost, probably due to accruing floating point errors. Hence we expect some method of reorthogonalization would be required to ensure stability for very long calculations which, has not been done in the current work. Finally we note that the (implicit) LR decomposition is not unique. Uniqueness is ensured for unit main diagonal of the lower triangular matrix however, this does not pay any heed to conditioning of the transforming matrices. A better strategy of building the matrices could be pursued which has better conditioning while at the same time preserves the tridiagonal structure. These issues would require careful implementation of all the individual components and we do not address those in the current work.

4. Conclusion. We present an algorithm to restart the non-symmetric Lanczos method which is based on the idea of polynomial filtering via the implicit QR method proposed by Sorensen [13] for restarting the Arnoldi iteration. It is shown that the (implicitly) shifted LR method is the appropriate analogue for restarting the non-symmetric Lanczos algorithm which preserves the tridiagonal structure of the reduced matrix. It is shown that the polynomial filtering process needs to be carried out for both the right and the left Krylov spaces and the appropriate transforms for maintaining biorthogonality of the two spaces are highlighted. Computational results are shown for a Grcar matrix which is known to be highly non-normal and the spectrum is found to converge adequately even when the residual error is relatively large.

As a final note, we point out that the Lanczos method is a low order reduction via oblique projections that inspired the Arnoldi method, which is an orthogonal reduction to a low order subspace. In the same spirit the (shifted) QR iterations are the unitary equivalent of their predecessor, the (shifted) LR iteration. Just as the

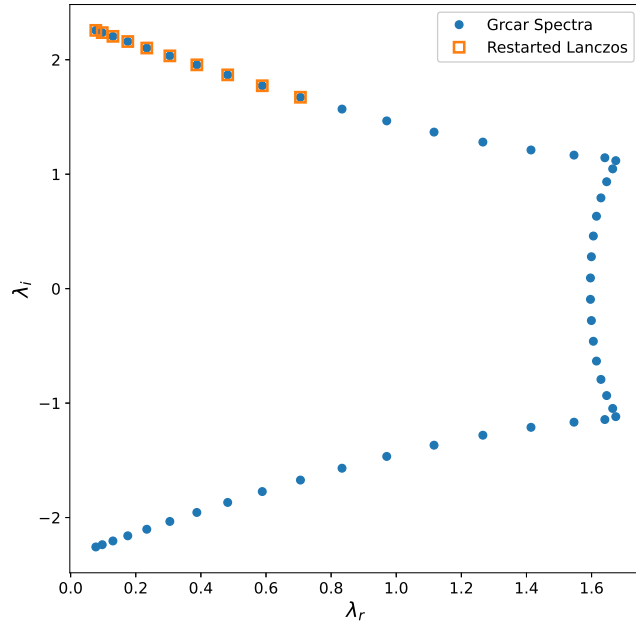


FIG. 1. *Spectrum obtained from the restarted Lanczos after 11 restart steps.*

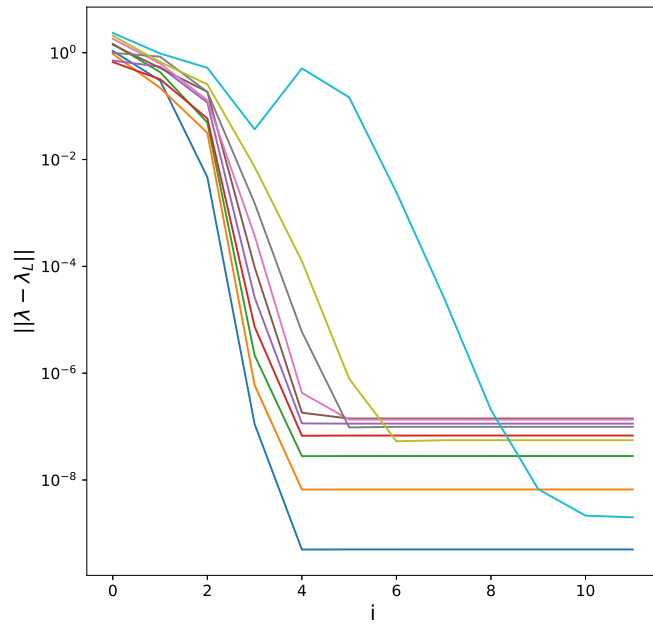


FIG. 2. *Error in the eigenvalues after each restart.*

shifted QR restarts the Arnoldi algorithm, the shifted LR restarts the non-symmetric Lanczos, and we find this particular symmetry aesthetically rather elegant.

Acknowledgments. Mention someone funding here.

REFERENCES

- [1] W. E. ARNOLDI, *The principle of minimized iterations in the solution of the matrix eigenvalue problem*, Quarterly of applied mathematics, 9 (1951), pp. 17–29.
- [2] M. BRYNJELL-RAHKOLA, N. SHAHRIARI, P. SCHLATTER, A. HANIFI, AND D. S. HENNINGSON, *Stability and sensitivity of a cross-flow-dominated falkner–skan–cooke boundary layer with discrete surface roughness*, Journal of Fluid Mechanics, 826 (2017), p. 830–850, <https://doi.org/10.1017/jfm.2017.466>.
- [3] J. DELLA-DORA, *Numerical linear algorithms and group theory*, Linear Algebra and its Applications, 10 (1975), pp. 267–283, [https://doi.org/10.1016/0024-3795\(75\)90074-9](https://doi.org/10.1016/0024-3795(75)90074-9).
- [4] J. G. F. FRANCIS, *The QR Transformation—Part 2*, The Computer Journal, 4 (1962), pp. 332–345, <https://doi.org/10.1093/comjnl/4.4.332>.
- [5] M. H. GUTKNECHT, *Lanczos-type solvers for nonsymmetric linear systems of equations*, Acta numerica, 6 (1997), pp. 271–397.
- [6] C. LANCZOS, *An iteration method for the solution of the eigenvalue problem of linear differential and integral operators*, (1950).
- [7] R. B. LEHOUCQ, D. C. SORENSEN, AND C. YANG, *ARPACK users’ guide: solution of large-scale eigenvalue problems with implicitly restarted Arnoldi methods*, SIAM, 1998.
- [8] B. N. PARLETT, D. R. TAYLOR, AND Z. A. LIU, *A look-ahead lanczos algorithm for unsymmetric matrices*, Mathematics of Computation, 44 (1985), pp. 105–124, <https://doi.org/10.2307/2007796>.
- [9] H. RUTISHAUSER, *Lectures on Numerical Mathematics*, Birkhauser, 1990.
- [10] H. RUTISHAUSER, *Solution of eigenvalue problems with the lr-transformation*, National Bureau of Standards, Applied Mathematics Series, 49 (1958), pp. 47–81.
- [11] H. RUTISHAUSER AND H. SCHWARZ, *Their transformation method for symmetric matrices*, Numerische Mathematik, 5 (1963), pp. 273–289.
- [12] Y. SAAD, *The lanczos biorthogonalization algorithm and other oblique projection methods for solving large unsymmetric systems*, SIAM Journal on Numerical Analysis, 19 (1982), pp. 485–506.
- [13] D. C. SORENSEN, *Implicit application of polynomial filters in a k-step arnoldi method*, Siam journal on matrix analysis and applications, 13 (1992), pp. 357–385.
- [14] D. S. WATKINS AND L. ELSNER, *Chasing algorithms for the eigenvalue problem*, SIAM Journal on Matrix Analysis and Applications, 12 (1991), pp. 374–384, <https://doi.org/10.1137/0612027>.