

Data Mining Project Report
on
“HUMAN ACTIVITY RECOGNITION USING RECURRENT
NEURAL NETWORK(LONG SHORT TERM MEMORY
NETWORKS)”

Submitted to
IIT BHU Varanasi

BY

Neha Kumari	18074012
Kumar Shivam Ranjan	18075031
Madhav Bansal	18075036

UNDER THE GUIDANCE OF
Dr. Bhaskar Biswas



DEPARTMENT OF COMPUTER ENGINEERING
IIT BHU Varanasi

IIT BHU(Varanasi)
Department of Computer Science Engineering
LOCATION IN Banaras,UP – 221005



CERTIFICATE

This is certify that the project entitled
**“Human Activity Recognition using recurrent neural
network(Long short term memory networks)”**

submitted by

Neha Kumari	18074012
Madhav Bansal	18075036
Kumar Shivam Ranjan	18075031

is a record of bonafide work carried out by them, in the partial fulfilment of the requirement for the award of Degree of Bachelor of Engineering (Computer Engineering) at IIT BHU Varanasi,Banaras. This work is done during year 2020-2021, under our guidance.

Date: 11/ 2/ 2020

(Dr. Bhaskar Biswas)
Project Guide

(Phd Scholar Shivansh Mishra)
Project Coordinator

Acknowledgements

We are profoundly grateful to **Dr. Bhaskar Biswas Sir** for his expert guidance and continuous encouragement throughout to see that this project rights its target since its commencement to its completion.

We would like to express deepest appreciation towards Project Coordinator **Phd Scholar Mr. Shivansh Mishra**, whose invaluable guidance supported us in completing this project.

At last we must express our sincere heartfelt gratitude to all the staff members of Computer Engineering Department who helped me directly or indirectly during this course of work.

Kumar Shivam Ranjan

Neha Kumari

Madhav Bansal

ABSTRACT

Human Activity Recognition, is the problem of predicting what kind of activity a person is performing based on a signals detected by smartphone sensors on their waist.

Two types of sensors present in smartphones are:

- 1) Accelerometer
- 2) Gyroscope

Accelerometer measures acceleration and **Gyroscope** measures angular velocity

Contents

1	About the Dataset	2
1.1	UCI HAR Dataset	2
1.1.1	Quick Overview of the Dataset	2
1.1.2	How the data was prepared?	2
2	Business Problem	3
2.1	Problem Statement	3
3	Additional Information	4
3.1	Dataset	4
3.1.1	Few more points to take into consideration	4
4	Model to solve Human Activity Recognition problem	5
4.1	Deep Learning approach	5
5	Model Architecture	6
5.1	LSTM network design	6
5.2	Working of LSTM	7
5.3	Step by Step walk through of LSTM	8
6	Plan of Action	9
6.0.1	Data Point Distribution	9
7	Machine Learning Model	10
7.1	Logistic Regression	10
8	Implementation	11
9	Screenshots of Project	13
9.1	Project Code	13

10 Conclusion	23
References	23

Chapter 1

About the Dataset

1.1 UCI HAR Dataset

1.1.1 Quick Overview of the Dataset

- 1) Data is downloaded from following source: **[Link to Dataset.](#)**
2. Feature names are present in UCI HAR dataset/features.txt
3. **Train Data**
 - a) UCI HAR dataset/train/X train.txt
 - b) UCI HAR dataset/train/subject train.txt
 - c) UCI HAR dataset/train/y train.txt
4. **Test Data**
 - a) UCI HAR dataset/test/X test.txt
 - b) UCI HAR dataset/test/subject test.txt
 - c) UCI HAR dataset/test/y test.txt

1.1.2 How the data was prepared?

30 volunteers referred to as subjects performed the experiment for data collection wearing smartphones sensors on their waist.

The two smartphone sensors captured the 3 axial linear acceleration as well as the 3 axial angular velocity of the subject

Chapter 2

Business Problem

2.1 Problem Statement

Predict one of the following six activities that a Smartphone user is performing at that 2.56 Seconds time window by using either 561 feature data or raw features of 128 reading.

1. Walking
2. Walking Upstairs
3. Walking Downstairs
4. Sitting
5. Standing
6. Laying

Chapter 3

Additional Information

3.1 Dataset

3.1.1 Few more points to take into consideration

1. 561 feature vector were engineered from each time window of 2.56 second with both time and frequency domain variables
2. Features are normalized and bounded within $[-1,1]$
3. The gyroscopic data is measured in radian/sec The units used for the accelerations are 'g' (9.8 m/s^2)
4. Both Body acceleration and acceleration due to gravity have three pair-wise mutually orthogonal components.
5. Gyroscope readings are the measure of angular velocities .
6. Fourier Transforms are made on the above time series data to obtain frequency domain readings.
7. Now, on all the base signal or raw readings, various engineered features like mean, standard deviation, max, skewness, kurtosis, etc are calculated for each window.

Chapter 4

Model to solve Human Activity Recognition problem

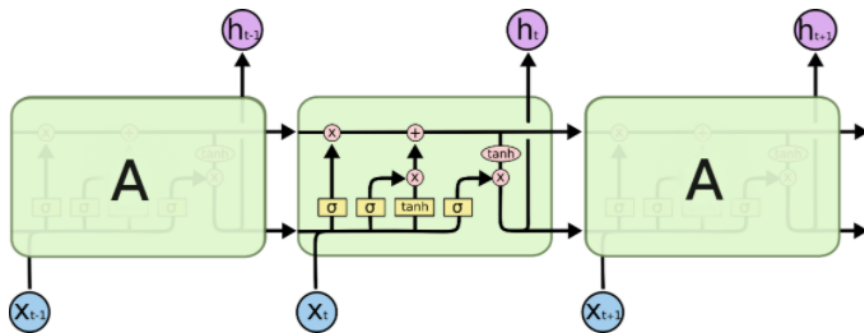
4.1 Deep Learning approach

1. Data obtained from Accelerometer and gyroscope was divided into 2 categories i.e Body acceleration and total acceleration. Body acceleration is the difference between total acceleration and acceleration due to gravity.
2. We can use Long short term memory networks model to identify 6 basic human activity like sitting, standing, walking upstairs and downstairs, laying and walking.
3. LSTM model is an advanced form of recurrent neural network which removes two drawbacks of RNN (vanishing gradient and exploding gradient). It helps us to look at past information to perform the current task or to give output of the current input.
4. LSTM works very well on time-series data as it is very efficient in remembering values over arbitrary intervals.

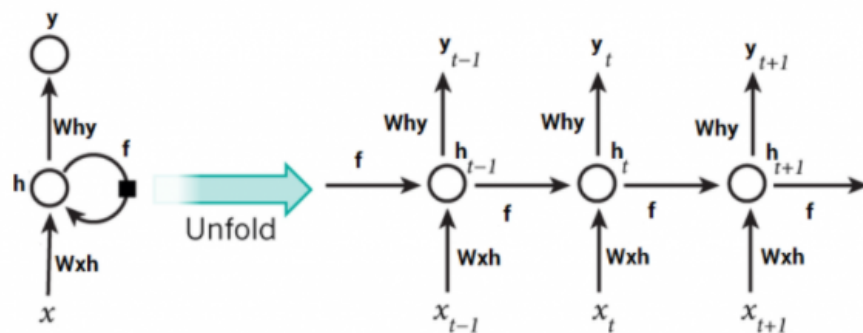
Chapter 5

Model Architecture

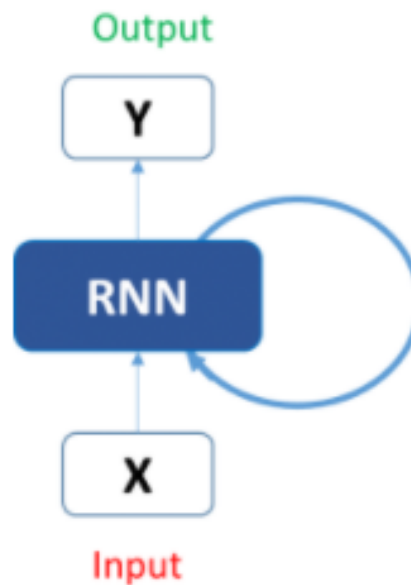
5.1 LSTM network design



The repeating module in an LSTM contains four interacting layers.



Unfolded LSTM network



Typical RNN

5.2 Working of LSTM

The most important feature of an LSTM neuron is the cell state which is analogous to a horizontal wire that runs through every neuron that helps flow the information from one neuron to another

At every neuron, some new information is added and some information is deleted through gates

- 1) Forget Gate
- 2) Input Gate
- 3) Output Gate

Gates are composed of various activation functions like sigmoid, tanh etc. The output of the sigmoid activation function is always either 0 or 1. 0 indicates no information should be let through. 1 denotes let the complete information go through without any loss.

5.3 Step by Step walk through of LSTM

1) Let the current cell state be $C(t)$ and previous cell state by $C(t-1)$.

First of all, we decide what information is irrelevant to store in current neural network. We discard those information using sigmoid activation function in **forget gate layer**. By removing unnecessary information, we update the current cell state $C(t)$. we take $h(t-1)$ and $x(t)$ as input where $h(t-1)$ is output of the previous neuron and $x(t)$ is the current input vector. We feed these two into forget gate layer.

2) Next step is to add some information to the cell state. This is done by the **input gate**. This gate uses two activation functions.

a) **Sigmoid** activation function

b) **Tanh** (hyperbolic tangent Activation Function) activation function

3) The last layer is the **output layer** which decides what will be the output of the current neuron. It uses the current cell state value to predict what will be the output of the current neuron.

Chapter 6

Plan of Action

1. We will use machine learning algorithm on 561 sized human expert engineered features.
2. As we know that LSTM works better on time series data or data that is sequential or contains sequence of information where order is very important, so we decided that we will apply LSTM of Recurrent neural networks on 128 sized raw readings that we obtained from accelerometer and gyroscope signals

6.0.1 Data Point Distribution

1. 30 subjects data is randomly split to 70 % (21) train and 30 % (9) test data
2. Each data point corresponds to one of the 6 activities

Chapter 7

Machine Learning Model

7.1 Logistic Regression

1. In Deep learning Model , we used raw features of 128 readings to predict the activity. The Dataset used there was basically a 3D matrix of (7352x128x9).
2. The Same Dataset cannot be used to train the machine learning model as RNNs are designed to work with time series data not machine learning.
3. This is why 561 features were engineered from raw 128 accelerometer and gyroscope signal readings so that we can use them in our machine learning model.
4. We will apply Logistic Regression Machine Learning models on these 561 sized human engineered features and unlike machine learning model, we will use 128 sized raw readings that we obtained from accelerometer and gyroscope signals in LSTM to predict the output

Chapter 8

Implementation

Output Labels

- a. WALKING (1)
- b. WALKING UPSTAIRS (2)
- c. WALKING DOWNSTAIRS (3)
- d. SITTING (4)
- e. STANDING (5)
- f. LYING (6)

We need to predict the output as one of the 6 labels the user is performing using either handcoded engineered 561 features or raw features of 128 readings.

Built With

- 1. **ipynb-notebook** - Python Text Editor
- 2. **Anaconda** -Data Science platform
- 3. **Python Pip**- for installing python libraries
- 4. **Sklearn** -A Machine learning library for logistic Regression
- 5. **Seaborn** - Python Visualization library
- 6. **Matplotlib** - Python plotting library
- 7. **Numpy, scipy**- number python library
- 8. **Pandas** - data handling library
- 9. **keras and tensorflow** - Used for making deep learning models

Libraries used

```
1
2 import numpy as np          #numpy
3 import pandas as pd         #pandas
4 import matplotlib.pyplot as plt  #matplotlib
5 import seaborn as sns       #seaborn
6 import tensorflow as tf      #tensorflow
7 from keras.models import Sequential  #keras
8 from keras.layers import LSTM        #keras layers
9 from keras.layers.core import Dense, Dropout  #keras layers core
10 from keras.layers.normalization import BatchNormalization  #keras layers
    normalisation
11 from sklearn.model_selection import train_test_split
12 from sklearn.linear_model import LogisticRegression
13 from sklearn import metrics
14 import seaborn as sn
15 import matplotlib.pyplot as plt
```

Chapter 9

Screenshots of Project

9.1 Project Code

Obtaining the train data

```
X_train = pd.read_csv('UCI_HAR_Dataset/train/X_train.txt', delim_whitespace=True, header=None)

X_train['subject'] = pd.read_csv('UCI_HAR_Dataset/train/subject_train.txt', header=None, squeeze=True)

y_train = pd.read_csv('UCI_HAR_Dataset/train/y_train.txt', names=['Activity'], squeeze=True)
y_train_labels = y_train.map({1: 'WALKING', 2: 'WALKING_UPSTAIRS', 3: 'WALKING_DOWNSTAIRS', 4: 'SITTING', 5: 'STANDING', 6: 'LAYING'})

train = X_train
train['Activity'] = y_train
train['ActivityName'] = y_train_labels
train.head()
```

	0	1	2	3	4	5	6	7	8	9	...	554	555	556	557
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.913526	-0.995112	-0.983185	-0.923527	-0.934724	...	-0.112754	0.030400	-0.464761	-0.018446
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.960322	-0.998807	-0.974914	-0.957686	-0.943068	...	0.053477	-0.007435	-0.732626	0.703511
2	0.279653	-0.019467	-0.113462	-0.995380	-0.967187	-0.978944	-0.996520	-0.963668	-0.977469	-0.938692	...	-0.118559	0.177899	0.100699	0.808529
3	0.279174	-0.026201	-0.123283	-0.996091	-0.983403	-0.990675	-0.997099	-0.982750	-0.989302	-0.938692	...	-0.036788	-0.012892	0.640011	-0.485366
4	0.276629	-0.016570	-0.115362	-0.998139	-0.980817	-0.990482	-0.998321	-0.979672	-0.990441	-0.942469	...	0.123320	0.122542	0.693578	-0.615971

5 rows × 564 columns

Obtaining the test data

```
X_test = pd.read_csv('UCI_HAR_Dataset/test/X_test.txt', delim_whitespace=True, header=None)

X_test['subject'] = pd.read_csv('UCI_HAR_Dataset/test/subject_test.txt', header=None, squeeze=True)

y_test = pd.read_csv('UCI_HAR_Dataset/test/y_test.txt', names=['Activity'], squeeze=True)
y_test_labels = y_test.map({1: 'WALKING', 2: 'WALKING_UPSTAIRS', 3: 'WALKING_DOWNSTAIRS', 4: 'SITTING', 5: 'STANDING', 6: 'LAYING'})

test = X_test
test['Activity'] = y_test
test['ActivityName'] = y_test_labels
test.head()
```

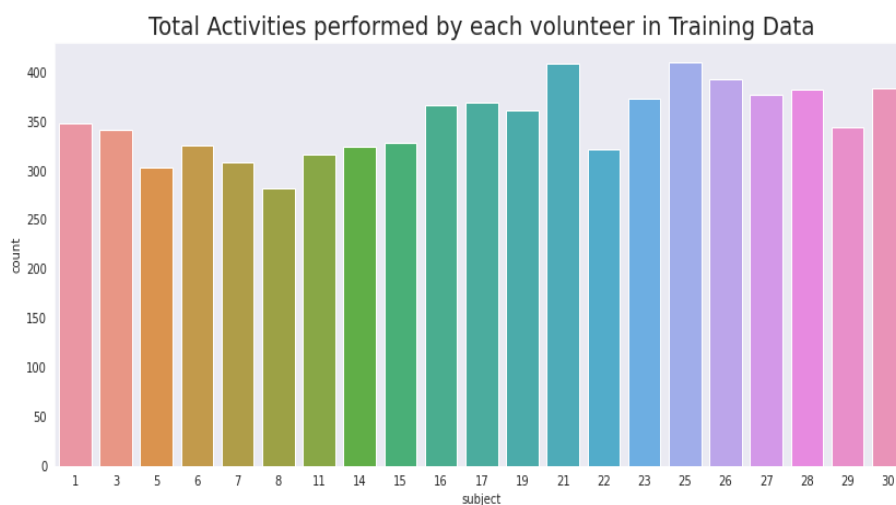
	0	1	2	3	4	5	6	7	8	9	...	554	555	556	557
0	0.257178	-0.023285	-0.014654	-0.938404	-0.920091	-0.667683	-0.952501	-0.925249	-0.674302	-0.894088	...	0.006462	0.162920	-0.825886	0.271151
1	0.286027	-0.013163	-0.119083	-0.975415	-0.967458	-0.944958	-0.986799	-0.968401	-0.945823	-0.894088	...	-0.083495	0.017500	-0.434375	0.920593
2	0.275485	-0.026050	-0.118152	-0.993819	-0.969926	-0.962748	-0.994403	-0.970735	-0.963483	-0.939260	...	-0.034956	0.202302	0.064103	0.145068
3	0.270298	-0.032614	-0.117520	-0.994743	-0.973268	-0.967091	-0.995274	-0.974471	-0.968897	-0.938610	...	-0.017067	0.154438	0.340134	0.296407
4	0.274833	-0.027848	-0.129527	-0.993852	-0.967445	-0.978295	-0.994111	-0.965953	-0.977346	-0.938610	...	-0.002223	-0.040046	0.736715	-0.118545

5 rows x 564 columns

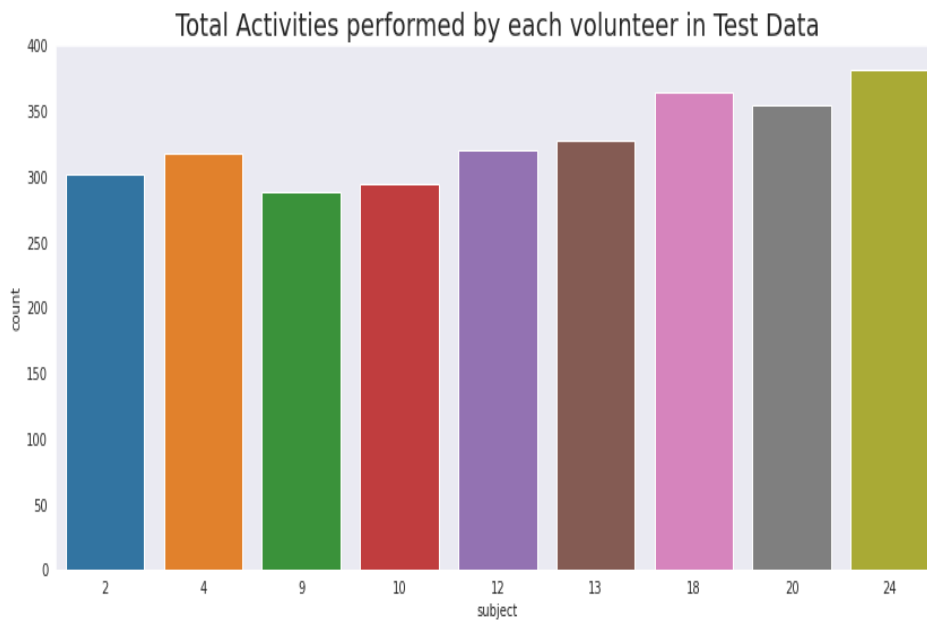
1. Visualising the Dataset

```
sns.set_style('dark')
plt.rcParams['lines.linewidth'] = 1
plt.rcParams['font.family'] = 'DejaVu Sans'
```

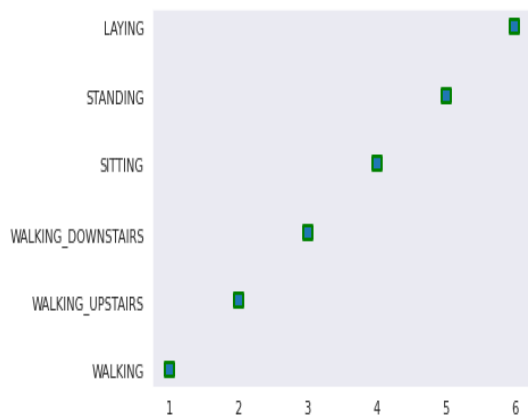
```
plt.figure(figsize=(14,6))
plt.title("Total Activities performed by each volunteer in Training Data",fontsize=20)
sns.countplot(x=train.subject)
plt.show()
```

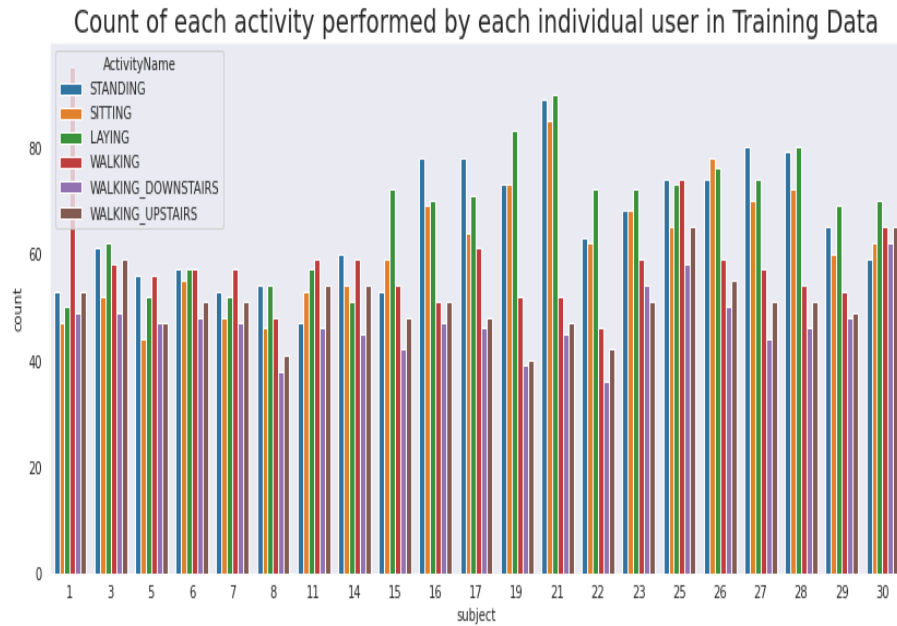


```
plt.figure(figsize=(14,6))
plt.title("Total Activities performed by each volunteer in Test Data",fontsize=20)
sns.countplot(x=test.subject)
plt.show()
```

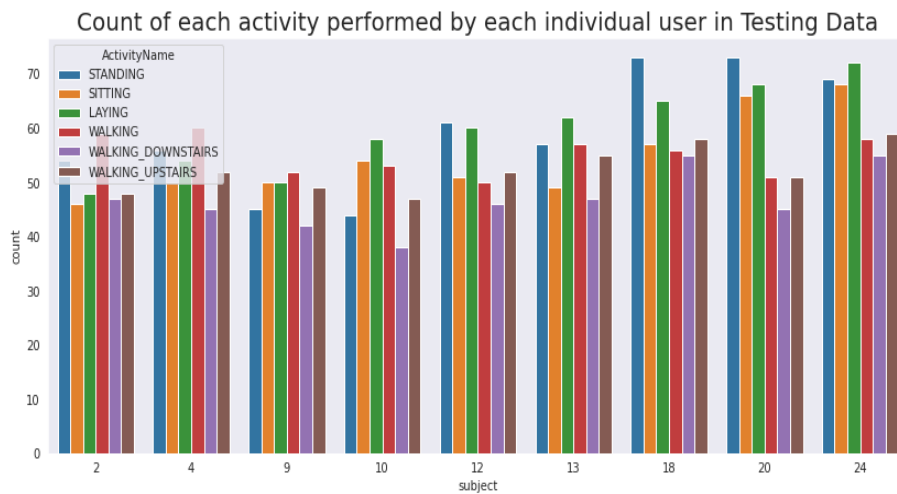


```
y_train_labels = {1: 'WALKING', 2: 'WALKING_UPSTAIRS', 3: 'WALKING_DOWNSTAIRS', 4: 'SITTING', 5: 'STANDING', 6: 'LAYING'}
lists=sorted(y_train_labels.items())
x, y = zip(*lists)
plt.scatter(x, y,linewidths = 2,marker = "s",edgecolor = "green", s = 50)
plt.show()
```

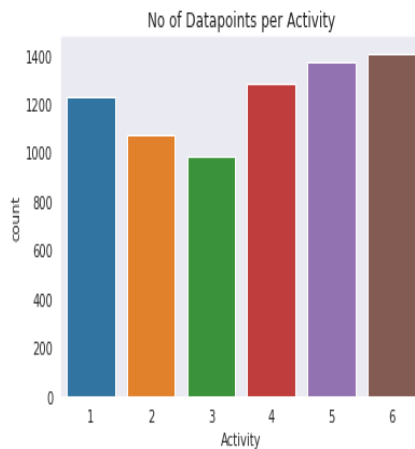




```
plt.figure(figsize=(14,6))
plt.title('Count of each activity performed by each individual user in Testing Data', fontsize=20)
sns.countplot(x='subject',hue='ActivityName', data = test)
plt.show()
```



```
plt.title('No of Datapoints per Activity')
sns.countplot(x=train.Activity)
plt.xticks(rotation=0)
plt.show()
```



LSTM model for HAR

```
np.random.seed(42)
import tensorflow as tf
tf.random.set_seed(42)
```

```
# Configuring a session
session_conf = tf.compat.v1.ConfigProto(
    intra_op_parallelism_threads=1,
    inter_op_parallelism_threads=1
)
```

```
# Import Keras
from tensorflow.compat.v1.keras import backend as K
sess = tf.compat.v1.Session(graph=tf.compat.v1.get_default_graph(), config=session_conf)
K.set_session(sess)
```

```
# Importing Libraries
from keras.models import Sequential
from keras.layers import LSTM
from keras.layers.core import Dense, Dropout
from keras.layers.normalization import BatchNormalization
```

```
DATADIR = 'UCI_HAR_Dataset'
```

```
ACTIVITIES = {
    0: 'WALKING',
    1: 'WALKING_UPSTAIRS',
    2: 'WALKING_DOWNSTAIRS',
    3: 'SITTING',
    4: 'STANDING',
    5: 'LAYING',
}

def confusion_matrix(Y_true, Y_pred):
    Y_true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_true, axis=1)])
    Y_pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_pred, axis=1)])

    return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
```

```

SIGNALS = [
    "body_acc_x",
    "body_acc_y",
    "body_acc_z",
    "body_gyro_x",
    "body_gyro_y",
    "body_gyro_z",
    "total_acc_x",
    "total_acc_y",
    "total_acc_z"
]

def _read_csv(filename):
    return pd.read_csv(filename, delim_whitespace=True, header=None)

def generate_x_data(subset):
    signals_data = []

    for signal in SIGNALS:
        filename = f'UCI_HAR_Dataset/{subset}/Inertial Signals/{signal}_{subset}.txt'
        signals_data.append(_read_csv(filename).values)
    return np.transpose(signals_data, (1, 2, 0))

def _count_classes(y):
    return len(set([tuple(category) for category in y]))

def generate_y_data(subset):
    filename = f'UCI_HAR_Dataset/{subset}/y_{subset}.txt'
    y = _read_csv(filename)[0]

    return pd.get_dummies(y).values

def load_data():
    X_train, X_test = generate_x_data('train'), generate_x_data('test')
    y_train, y_test = generate_y_data('train'), generate_y_data('test')

    return X_train, X_test, y_train, y_test

```

```

: timesteps = len(X_train[0])
  input_dim = len(X_train[0][0])
  n_classes = _count_classes(Y_train)

  print(len(X_train))
  print(timesteps)
  print(input_dim)
  print(n_classes)

```

```

7352
128
9
6

```

```

: epochs = 30
  batch_size = 32
  n_hidden = 128
  pv = 0.25

```

```

: model = Sequential()

  model.add(LSTM(n_hidden, input_shape=(timesteps, input_dim)))
  model.add(BatchNormalization())

  model.add(Dropout(pv))

  model.add(Dense(n_classes, activation='sigmoid'))
  model.summary()

```

Model: "sequential"

Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 128)	70656
batch_normalization (Batch Normalization)	(None, 128)	512
dropout (Dropout)	(None, 128)	0
dense (Dense)	(None, 6)	774
Total params: 71,942		
Trainable params: 71,686		
Non-trainable params: 256		

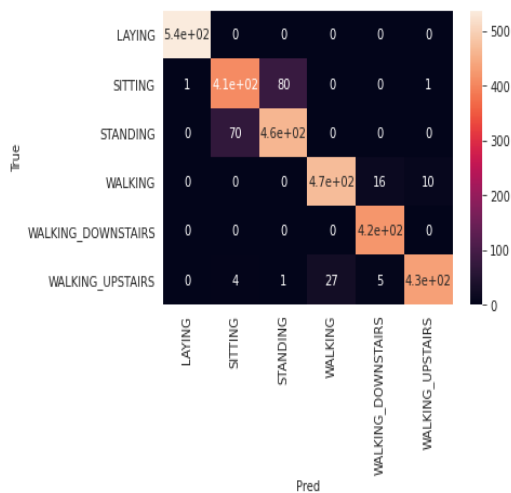
```
model.compile(loss='categorical_crossentropy', optimizer='rmsprop', metrics=['accuracy'])
```

```
model.fit(X_train, Y_train, batch_size=batch_size, validation_data=(X_test, Y_test), epochs=epochs)
```

```
Epoch 1/30
230/230 [=====] - 17s 76ms/step - loss: 0.9775 - accuracy: 0.5635 - val_loss: 0.9544 - val_accuracy: 0.5836
Epoch 2/30
230/230 [=====] - 16s 70ms/step - loss: 0.7032 - accuracy: 0.6602 - val_loss: 0.7071 - val_accuracy: 0.6566
Epoch 3/30
230/230 [=====] - 17s 74ms/step - loss: 0.6357 - accuracy: 0.7076 - val_loss: 0.7523 - val_accuracy: 0.6203
Epoch 4/30
230/230 [=====] - 17s 74ms/step - loss: 0.4320 - accuracy: 0.8298 - val_loss: 0.3244 - val_accuracy: 0.8894
Epoch 5/30
230/230 [=====] - 17s 75ms/step - loss: 0.2150 - accuracy: 0.9214 - val_loss: 0.3481 - val_accuracy: 0.8823
Epoch 6/30
230/230 [=====] - 17s 75ms/step - loss: 0.1855 - accuracy: 0.9320 - val_loss: 0.3101 - val_accuracy: 0.9006
Epoch 7/30
230/230 [=====] - 17s 75ms/step - loss: 0.1877 - accuracy: 0.9328 - val_loss: 0.3312 - val_accuracy: 0.8887
Epoch 8/30
230/230 [=====] - 17s 75ms/step - loss: 0.1598 - accuracy: 0.9377 - val_loss: 0.3471 - val_accuracy: 0.9019
Epoch 9/30
230/230 [=====] - 17s 75ms/step - loss: 0.1444 - accuracy: 0.9377 - val_loss: 0.5204 - val_accuracy: 0.9087
Epoch 10/30
230/230 [=====] - 17s 75ms/step - loss: 0.1532 - accuracy: 0.9421 - val_loss: 0.3719 - val_accuracy: 0.8911
Epoch 11/30
230/230 [=====] - 17s 75ms/step - loss: 0.1623 - accuracy: 0.9429 - val_loss: 0.2438 - val_accuracy: 0.9240
Epoch 12/30
230/230 [=====] - 17s 75ms/step - loss: 0.1344 - accuracy: 0.9436 - val_loss: 0.2704 - val_accuracy: 0.9125
Epoch 13/30
230/230 [=====] - 17s 75ms/step - loss: 0.1401 - accuracy: 0.9437 - val_loss: 0.3632 - val_accuracy: 0.9036
Epoch 14/30
230/230 [=====] - 17s 75ms/step - loss: 0.1305 - accuracy: 0.9437 - val_loss: 0.2415 - val_accuracy: 0.9138
Epoch 15/30
230/230 [=====] - 17s 75ms/step - loss: 0.1403 - accuracy: 0.9438 - val_loss: 0.3694 - val_accuracy: 0.9067
Epoch 16/30
230/230 [=====] - 17s 75ms/step - loss: 0.1271 - accuracy: 0.9475 - val_loss: 0.3459 - val_accuracy: 0.9128
Epoch 17/30
230/230 [=====] - 17s 75ms/step - loss: 0.1247 - accuracy: 0.9464 - val_loss: 0.3513 - val_accuracy: 0.9179
Epoch 18/30
230/230 [=====] - 17s 75ms/step - loss: 0.1455 - accuracy: 0.9479 - val_loss: 0.2809 - val_accuracy: 0.9118
Epoch 19/30
230/230 [=====] - 17s 75ms/step - loss: 0.1230 - accuracy: 0.9467 - val_loss: 0.3377 - val_accuracy: 0.9237
Epoch 20/30
```

```
result=confusion_matrix(Y_test, model.predict(X_test))
sn.heatmap(result, annot=True)
```

```
<AxesSubplot:xlabel='Pred', ylabel='True'>
```



```
score = model.evaluate(X_test, Y_test)
```

```
93/93 [=====] - 2s 18ms/step - loss: 0.3387 - accuracy: 0.9270
```

```
score
```

```
[0.33865147829055786, 0.9270444512367249]
```

- With a simple semi tuned stacked LSTM architecture we got 92.7% accuracy and a loss of 0.33

LSTM Model2

stacking 2 LSTM

```
epochs1 = 30
batch_size1 = 32
n_hidden1 = 128
n_hidden2 = 64
pv1 = 0.2
pv2 = 0.5
```

```
model1 = Sequential()

model1.add(LSTM(n_hidden1, return_sequences=True, input_shape=(timesteps, input_dim)))

model1.add(Dropout(pv1))

model1.add(LSTM(n_hidden2))

model1.add(Dropout(pv2))

model1.add(Dense(n_classes, activation='sigmoid'))
model1.summary()
```

Model: "sequential_1"

Layer (type)	Output Shape	Param #
lstm_1 (LSTM)	(None, 128, 128)	70656
dropout_1 (Dropout)	(None, 128, 128)	0
lstm_2 (LSTM)	(None, 64)	49408
dropout_2 (Dropout)	(None, 64)	0

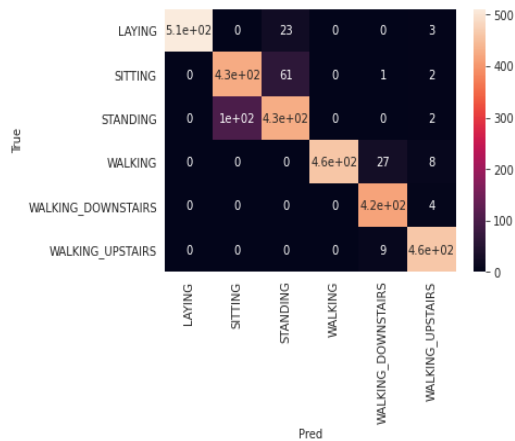
```
model1.compile(loss='categorical_crossentropy', optimizer='rmsprop', metrics=['accuracy'])
```

```
model1.fit(X_train, Y_train, batch_size=batch_size, validation_data=(X_test, Y_test), epochs=epochs1)
```

```
Epoch 1/30
230/230 [=====] - 30s 129ms/step - loss: 1.1419 - accuracy: 0.5018 - val_loss: 0.9634 - val_accuracy: 0.5304
Epoch 2/30
230/230 [=====] - 29s 126ms/step - loss: 0.9308 - accuracy: 0.5928 - val_loss: 0.8050 - val_accuracy: 0.6220
Epoch 3/30
230/230 [=====] - 29s 126ms/step - loss: 0.7290 - accuracy: 0.6783 - val_loss: 0.9499 - val_accuracy: 0.6356
Epoch 4/30
230/230 [=====] - 29s 127ms/step - loss: 0.7000 - accuracy: 0.7114 - val_loss: 0.5584 - val_accuracy: 0.7659
Epoch 5/30
230/230 [=====] - 29s 126ms/step - loss: 0.4265 - accuracy: 0.8513 - val_loss: 0.4920 - val_accuracy: 0.8354
Epoch 6/30
230/230 [=====] - 29s 125ms/step - loss: 0.2448 - accuracy: 0.9191 - val_loss: 0.3404 - val_accuracy: 0.8914
Epoch 7/30
230/230 [=====] - 29s 127ms/step - loss: 0.1919 - accuracy: 0.9354 - val_loss: 1.1314 - val_accuracy: 0.7862
Epoch 8/30
230/230 [=====] - 29s 126ms/step - loss: 0.1676 - accuracy: 0.9410 - val_loss: 0.3229 - val_accuracy: 0.9067
Epoch 9/30
230/230 [=====] - 29s 126ms/step - loss: 0.1585 - accuracy: 0.9437 - val_loss: 0.4327 - val_accuracy: 0.8938
Epoch 10/30
230/230 [=====] - 29s 126ms/step - loss: 0.1697 - accuracy: 0.9455 - val_loss: 0.3099 - val_accuracy: 0.9036
Epoch 11/30
230/230 [=====] - 29s 127ms/step - loss: 0.1355 - accuracy: 0.9495 - val_loss: 0.4072 - val_accuracy: 0.8955
Epoch 12/30
230/230 [=====] - 29s 127ms/step - loss: 0.1358 - accuracy: 0.9484 - val_loss: 0.4100 - val_accuracy: 0.9023
Epoch 13/30
230/230 [=====] - 29s 126ms/step - loss: 0.1504 - accuracy: 0.9483 - val_loss: 0.4309 - val_accuracy: 0.9026
Epoch 14/30
230/230 [=====] - 29s 126ms/step - loss: 0.1349 - accuracy: 0.9484 - val_loss: 0.4948 - val_accuracy: 0.9002
Epoch 15/30
230/230 [=====] - 29s 126ms/step - loss: 0.1277 - accuracy: 0.9539 - val_loss: 0.4652 - val_accuracy: 0.9013
Epoch 16/30
230/230 [=====] - 29s 127ms/step - loss: 0.1405 - accuracy: 0.9504 - val_loss: 0.3800 - val_accuracy: 0.9135
Epoch 17/30
230/230 [=====] - 29s 126ms/step - loss: 0.1190 - accuracy: 0.9512 - val_loss: 0.4618 - val_accuracy: 0.9006
```

```
result=confusion_matrix(Y_test, model1.predict(X_test))
sn.heatmap(result, annot=True)
```

```
<AxesSubplot: xlabel='Pred', ylabel='True'>
```



```
score1 = model1.evaluate(X_test, Y_test)
```

```
93/93 [=====] - 3s 28ms/step - loss: 0.4102 - accuracy: 0.9182
```

```
score1
```

```
[0.41017231345176697, 0.9182218909263611]
```

Final Comments

- By Simple two layered LSTM, we got a good accuracy of 91.82%.
- In short, Deep Learning help us to built models even when we don't have domain expert engineered features.
- LSTM model can be further improved by running it for more epochs and more evaluations while tuning hyper-parameter.

Machine learning model(Logistic Regression)

```
print('X_train and y_train : ({},{})'.format(X_train.shape, y_train.shape))
print('X_test and y_test : ({},{})'.format(X_test.shape, y_test.shape))
y_test.sample()
y_test
```

```
X_train and y_train : ((7352, 128, 9),(7352,))
X_test and y_test : ((2947, 128, 9),(2947,))
```

```
0      5
1      5
2      5
3      5
4      5
```

```
..
2942    2
2943    2
2944    2
2945    2
2946    2
```

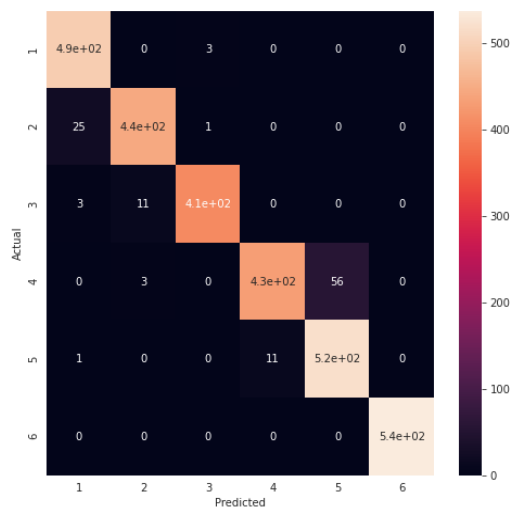
```
Name: Activity, Length: 2947, dtype: int64
```

```
logistic_regression= LogisticRegression(solver='lbfgs',max_iter=100000)
result=logistic_regression.fit(X_train,y_train)
y_pred=logistic_regression.predict(X_test)
```

```
plt.figure(figsize=(8,8))
plt.grid(b=False)
confusion_matrix = pd.crosstab(y_test, y_pred, rownames=['Actual'], colnames=['Predicted'])
sn.heatmap(confusion_matrix, annot=True)
```

```
plt.figure(figsize=(8,8))
plt.grid(b=False)
confusion_matrix = pd.crosstab(y_test, y_pred, rownames=['Actual'], colnames=['Predicted'])
sns.heatmap(confusion_matrix, annot=True)

<AxesSubplot:xlabel='Predicted', ylabel='Actual'>
```



```
print('Accuracy: ',metrics.accuracy_score(y_test, y_pred))
plt.show()
```

Accuracy: 0.9613165931455717

Chapter 10

Conclusion

The final accuracy for the LSTM model comes out to be almost **93%!** And it can peak to values such as **94%**, at some moments during the training, depending on random initialisation of network's weights.

Machine learning algorithm too has an outstanding accuracy of **96%** but it uses the expert engineered 561 features to build its model while LSTM uses the raw features of data signals because it works well on time series data. This is one of the most important advantage of LSTM deep learning algorithm over other machine learning algorithms.

Final Comments:

Model	Accuracy
Machine learning (Logistic Regression)	96.13%
LSTM Model (Recurrent Neural Network)	92.70%

References

- [1] <https://towardsdatascience.com/time-series-classification-for-human-act>.
- [2] <https://machinelearningmastery.com/deep-learning-models-for-human-activ>.
- [3] <https://machinelearningmastery.com/how-to-develop-rnn-models-for-human>.