

## EDUCATION

**CALTECH** | 2015 – 2019  
Pasadena, CA | G.P.A. 4.0  
B.S. Mechanical Engineering

- Depth in Robotics

### COURSEWORK

- Capstone Design Contest
- Robotics, Autonomy, Mechatronics
- Mechanics, Thermal Science, Fluid Dynamics
- Experiments & Modeling in Mechanical Engineering, Microfabrication Lab
- Biology Lab, Nanorobotics, Computation & Neural Systems, Decision Making
- Core Math, Physics, Chemistry, and CS

## SKILLS

### PROGRAMMING

- Python, Java, C, C++
- Mathematica, Matlab, Octave, R
- HTML, CSS

### ROBOTICS

- Raspberry Pi, Arduino, Code Composer Studio
- ROS
- OpenCV

### ENGINEERING

- Solidworks
- ANSYS (CFD, FEA)
- Excel (VB)

### CREATIVE

- Photoshop
- InDesign
- Final Cut Pro
- Microsoft Office

## WORK EXPERIENCE

**CALTECH** | Electronic skin development with Daraio & Ames Labs  
Student Researcher | September 2018 –

- Developing flexible force sensing array for bipedal robot

**VERB SURGICAL** | Google and J&J robotic surgery partnership  
Mechanical Engineering Intern | June – September 2018

- Robotics experience in sensors and controls
- Fixture and light pipe design

**KRAENION** | Startup developing applied computer vision solutions  
Robotics Intern | December 2017

- Prepared forklift prototype to demo stereo vision technology

**NIMA LABS** | Portable food allergen sensor startup  
Mechanical Engineering Intern | June – September 2016, 2017

- 2016: Tested multi-channel version of consumer device and isolated key variables affecting chemistry development and camera readings
- 2017: Redesigned multi-channel device from scratch. Created manufacturing and assembly drawings and worked with vendors

### STANFORD UNIVERSITY

Computational Genomics Intern | June – August 2014

- Created a tool in R to select RNA guides for CRISPR/Cas9 library

## PROJECTS

More projects and details at [nehasunil.com](http://nehasunil.com)

- RC Car with Computer Vision, Ackerman Steering, Independent Suspension & Nerf Ball Shooter
- D\* Lite Path Planner for ROS Navigation Stack
- Vehicle Teleoperation with Haptic Feedback
- Tank with Robotic Arm
- Autonomous Warehouse Product Locator
- Ultrasonic Signal-Seeking Pontoon Boat

## ACHIEVEMENTS

- Tau Beta Pi Engineering Honor Society Member
- Certified Yoga Instructor
- 2<sup>nd</sup> Degree Black Belt in Taekwondo
- Successful Aging Mini-Fellowship: Stanford School of Medicine
- America Library of Poetry Publication
- Scholastic Art & Writing Award (Photography)
- National Scholastic Press Association Journalism Honor Roll