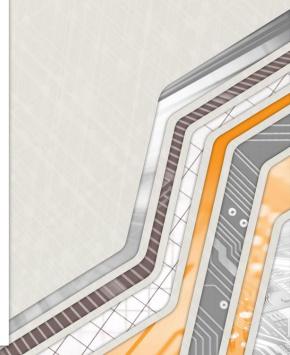
# Improving the Performance of GMRES with Mixed Precision

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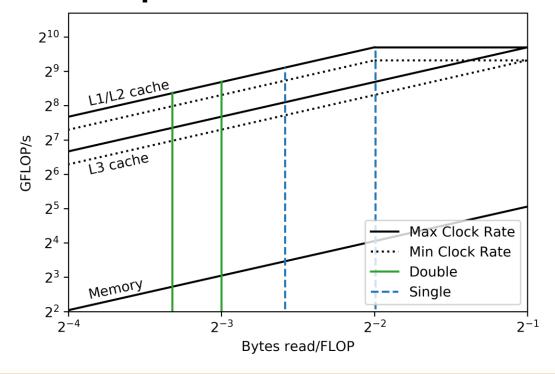






#### **GMRES**

- General purpose, sparse linear solver
- Memory bound performance





#### **GMRES Algorithm**

```
\mathsf{GMRES}_{res}(A, x_0, b, M^{-1})
     for i = 0, 1, 2, ...
              r_i \leftarrow b - Ax_i
              w \leftarrow M^{-1}r_i
              \beta \leftarrow ||w||_2
               V_{:0} \leftarrow w/\beta
              s \leftarrow [\beta, 0, 0, ..., 0]^T
              for j = 0, 1, 2, ..., k
                       w \leftarrow M^{-1}AV_{:,i}
                       for l = 0, 1, ..., j
                                H_{l,j} \leftarrow w \cdot V_{:,l}
                                 w \leftarrow w - H_{l,i}V_{:,l}
                        H_{j+1,j} \leftarrow ||w||_2
                       Let G_j s.t. 0 = (G_j H)_{j+1,j}
                       H_{:,j} \leftarrow G_0 G_1 \dots G_{j-1} H_{:,i}
                        H \leftarrow G_i H
                        s \leftarrow G_i s
                        If s_i small enough, then break.
               u_i \leftarrow VH^{-1}s
               x_{i+1} \leftarrow x_i + u_i
```

Computing Ax = b.  $A^{-1} \approx M^{-1}$ Restarts

Iteration count



# **Computation Requirement**

- Each iteration, *j*, requires:
  - $4jn + 4nnz + \Theta(n)$  FLOP
- Restart with k iterations requires:
  - $2k^2n + 4k nnz + \Theta(kn + nnz)$  FLOP
  - $8kn + 32n + 8k^2 + \Theta(k)$  bytes



#### **GMRES Algorithm**

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Iteration count



#### **GMRES Algorithm**

Double:

Single:

Double:

 $\mathsf{GMRES}_{res}(A, x_0, b, M^{-1})$ for i = 0, 1, 2, ... $r_i \leftarrow b - Ax_i$  $w \leftarrow M^{-1}r_i$  $\beta \leftarrow ||w||_2$  $V_{:.0} \leftarrow w/\beta$  $s \leftarrow [\beta, 0, 0, ..., 0]^T$ for j = 0, 1, 2, ..., k $w \leftarrow M^{-1}AV_{:,i}$ for l = 0, 1, ..., j $H_{l,j} \leftarrow w \cdot V_{:,l}$  $w \leftarrow w - H_{l,j}V_{:,l}$  $H_{j+1,j} \leftarrow ||w||_2$ Let  $G_j$  s.t.  $0 = (G_j H)_{j+1,j}$  $H_{:,j} \leftarrow G_0 G_1 \dots G_{j-1} H_{:,j}$  $H \leftarrow G_i H$  $s \leftarrow G_i s$ If  $s_i$  small enough, then break.  $u_i \leftarrow VH^{-1}s$  $x_{i+1} \leftarrow x_i + u_i$ 

Computing Ax = b.  $A^{-1} \approx M^{-1}$ Restarts

Iteration count



#### **GMRES Simplified Algorithm**

GMRES<sub>res</sub>
$$(A, x_0, b, M^{-1})$$
  
for  $i = 0, 1, 2, ...$ 

Double:

$$r_i \leftarrow b - Ax_i$$

Single:

$$u_i \leftarrow \mathsf{GMRES}_{no\ res}(A, \overline{0}, r_i, M^{-1})$$

Double:

$$x_{i+1} \leftarrow x_i + u_i$$



### **Effect on Memory Allocation**

- Double:  $8kn + 12nnz + 32n + 8k^2$  bytes
- Mixed:  $4kn + 12nnz + 28n + 4k^2$  bytes
  - Including GMRES internals,  $M^{-1} = ILU(0)$
  - Excluding A, x, b
  - At most k inner iterations before restarting



### **Effect on Convergence: Setup**

- •ILU(0) preconditioner  $(M^{-1})$
- CSR matrix format
- Custom, mixed precision kernels
  - Kokkos for storage and parallelism
- A 20-core Haswell node
  - 2x Intel® Xeon® E5-2650 v3 processors

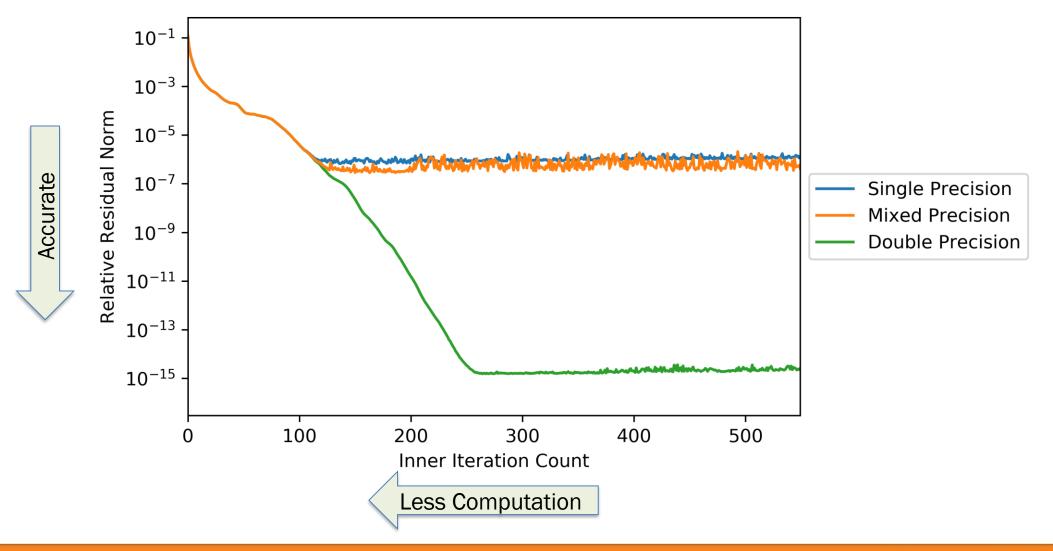


# Effect on Convergence: Setup

- airfoil\_2d from SuiteSparse collection
  - n = 14,214
  - nnz = 259,688
  - $\kappa_2 = 1.8 \cdot 10^6$
- Plots show residual if GMRES terminated after that iteration

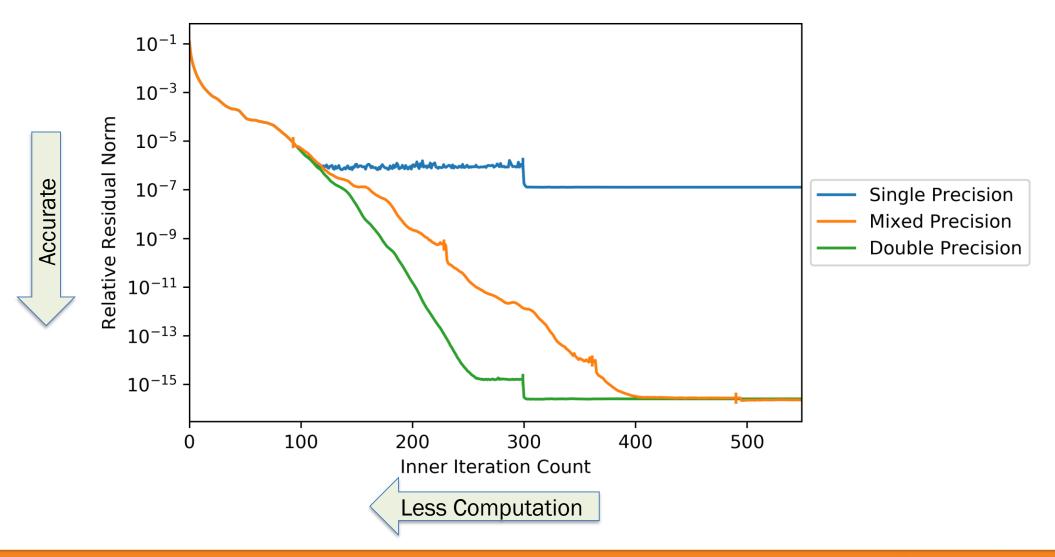


#### **Effect on Convergence: Without Restarts**





# **Effect on Convergence: With Restarts**





#### When to Restart?

- Too few restarts: improvement stalls
- Too many restarts: rate of convergence slows

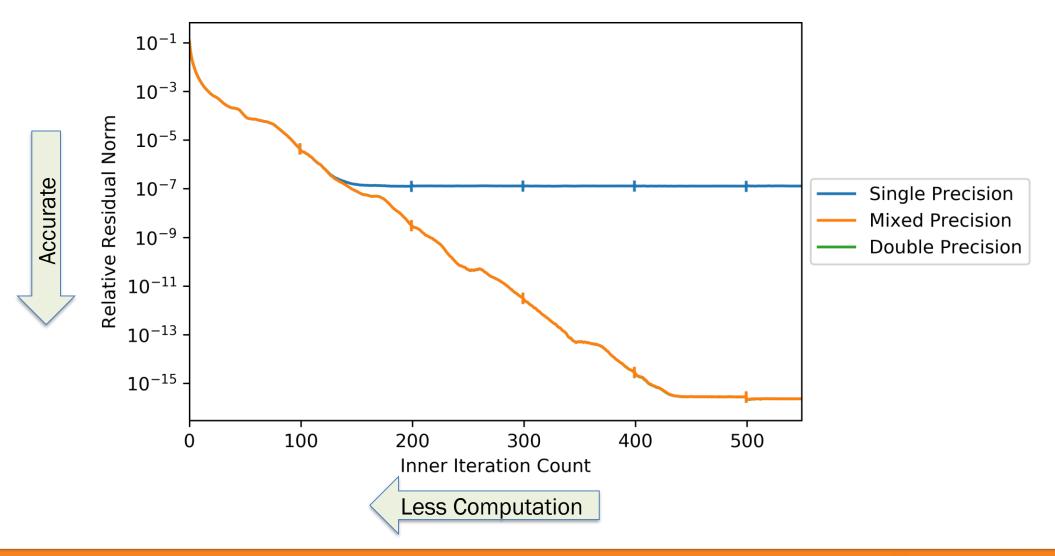


#### **Possible Restart Strategies**

- Fixed iteration count
- Fixed improvement tolerance
- Detecting stalled improvement
  - Change in improvement
  - Versus double precision iteration

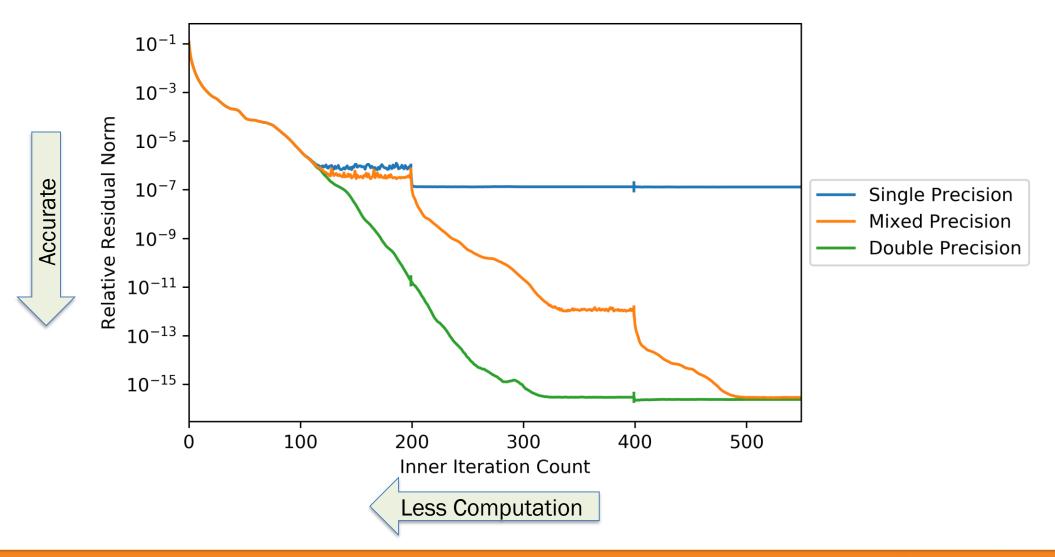


### Restart Strategy: Fixed Iteration (100)



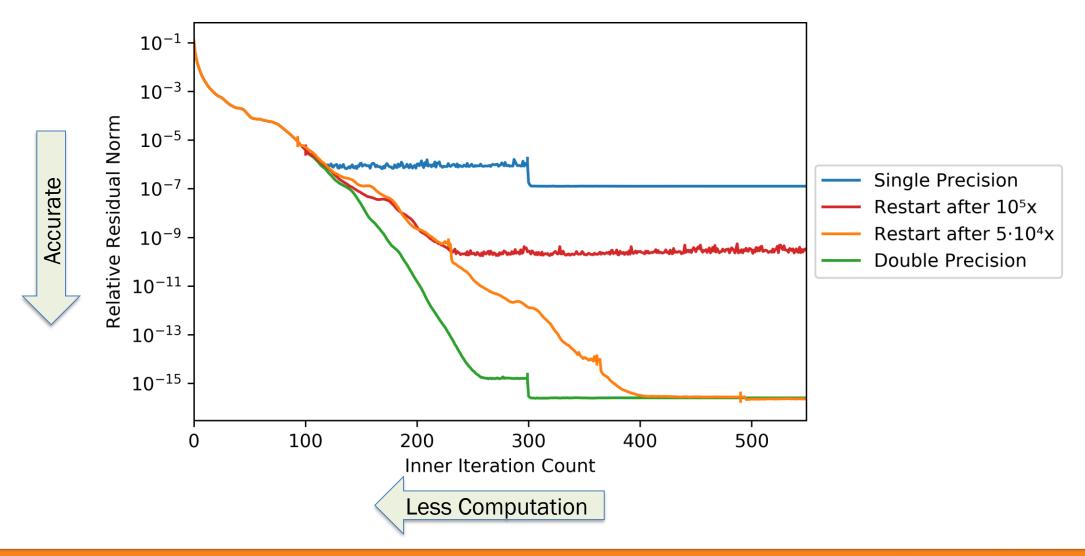


# Restart Strategy: Fixed Iteration (200)





#### Restart Strategy: Fixed Improvement





#### Performance Results: Setup

- ILU(0) preconditioner  $(M^{-1})$
- CSR matrix format
- KokkosKernels
  - Backed by Intel's MKL
  - Except for preconditioner
- A 20-core Haswell node
  - 2x Intel® Xeon® E5-2650 v3 processors



#### Performance Results: Setup

- Matrices from SuiteSparse collection
- •Solved for preconditioned residual accuracy of  $10^{-10}$
- Each trial run 5 times
  - Speedup of medians
  - Error bars for max and min speedup



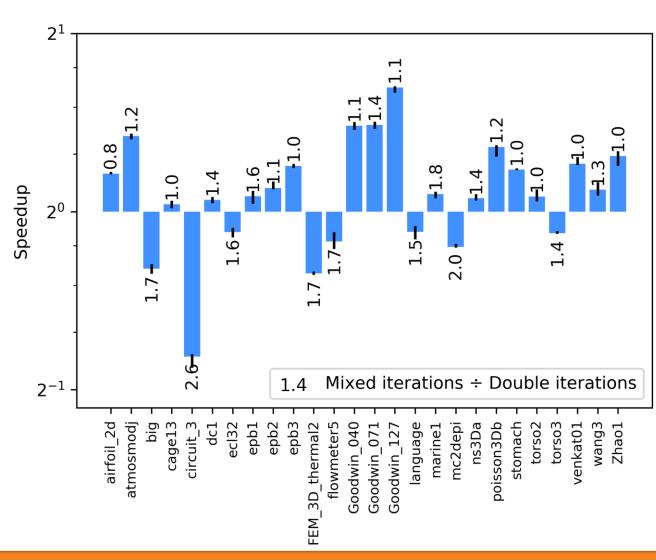
# Performance Results: Optimal Configuration

- Optimal restart length found for double precision
- Optimal restart length and improvement tolerance found for mixed precision
- •Speedup:  $\frac{\text{GMRES}_{\text{Double}} + \text{ILU}_{\text{Double}}}{\text{GMRES}_{\text{Mixed}} + \text{ILU}_{\text{Mixed}}}$



# Improvement

# **Timing Results: Optimal Configuration**





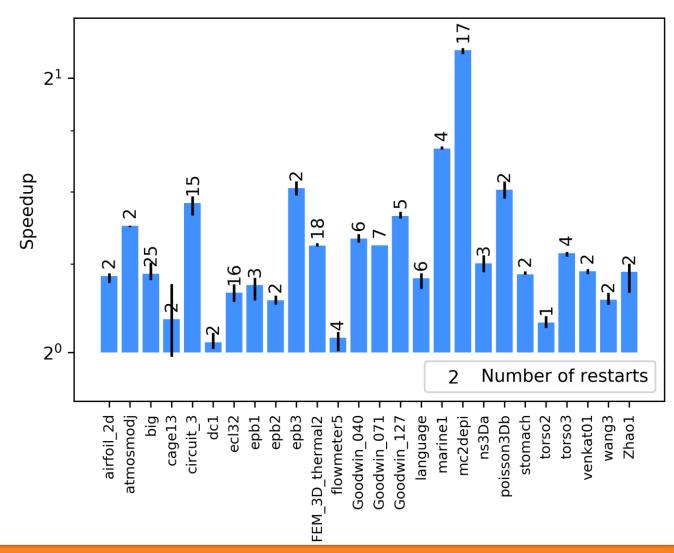
#### Performance Results: Forced Restarts

- k iterations for non-restarting, double precision GMRES to reach  $10^{-10}$
- Double and mixed precision were run, restarting every  $^k/_2$  iterations
- $\textbf{-Speedup:} \frac{\text{GMRES}_{\text{Double}} + \text{ILU}_{\text{Double}}}{\text{GMRES}_{\text{Mixed}} + \text{ILU}_{\text{Mixed}}}$



#### Performance Results: Forced Restarts







#### Conclusions

- With appropriate restarts, mixed precision
  GMRES has
  - double precision accuracy
  - better performance



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