

# Robust Principal Component Analysis & Collaborative Filtering

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# Motivation

Let

$$M \in \mathbb{R}^{n \times m}$$

be a data matrix where  $n$  is the number of samples and  $m$  is the number of features.

We are interested in the scenario where

$$\left. \begin{array}{ll} i & m \text{ is large} \\ ii & n \approx m \\ iii & \text{noise} \\ iv & \text{outliers/corruption} \\ v & \text{missing entries} \end{array} \right\} \rightarrow \text{Collaborative Filtering (CF)}$$

In CF a fraction of entries in  $M$  are present, whose locations are  $(i, j) \in \Omega$

## PCA (as matrix separation):

$$\begin{aligned} \min_L \quad & ||M - L|| \\ \text{s.t.} \quad & \text{rank}(L) \leq k \end{aligned} \tag{1}$$

where  $||A|| = \max(\sigma_i(A) \forall i)$

$\hat{L}$  would be the data in the  $k$  principal directions with the highest singular values (or variance).

Well-posed when  $M = L_0 + N_0$

- $L_0$  is a low-rank matrix
- $N_0$  is a matrix of noise

Assume

$$M = L_0 + S_0$$

$S_0$  is sparse corruption/outliers

**Robust PCA:**

$$\begin{aligned} \min_{L, S} \quad & \text{rank}(L) + \|S\|_0 \\ \text{s.t.} \quad & M = L + S \end{aligned} \tag{2}$$

where  $\|A\|_0 = \#(i | A_i \neq 0)$

## Through Principal Component Pursuit

$$\begin{aligned} \min_{L, S} \quad & ||L||_* + \lambda ||S||_1 \\ \text{s.t.} \quad & M = L + S \end{aligned} \tag{3}$$

where

- $||A||_* = \sum_i \sigma_i(A)$
- $||A||_1 = \sum_{ij} |A_{ij}|$

$\hat{L} = L_0, \hat{S} = S_0$  when  $\lambda = \frac{1}{\sqrt{n}}$  and

- $L_0$  should not be sparse
- $S_0$  should not be low-rank

## Matrix Completion:

If we assume no outliers in  $M \rightarrow S_0 = \mathbf{0}$  then we can rewrite RPCA as;

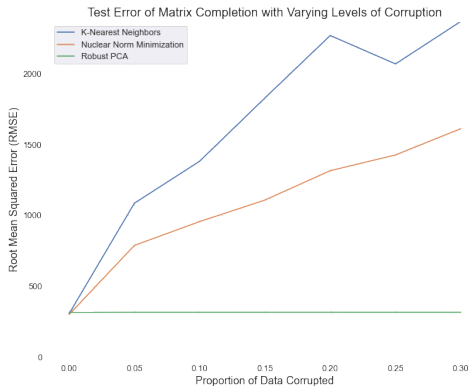
$$\begin{aligned} \min_L \quad & \|L\|_* \\ \text{s.t.} \quad & M_{ij} = L_{ij}, \forall (i,j) \in \Omega \end{aligned} \tag{4}$$

Represents the exact matrix completion problem under similar coherence constraints on  $M$  as RPCA.

## Experiment

- Steam Video Games dataset: take a subset and introduce corruption (random outliers)
- Incorporate varying levels of corruption to the dataset.
- Implement Robust PCA and traditional Matrix Completion techniques on the datasets.

# Matrix Completion Experiment

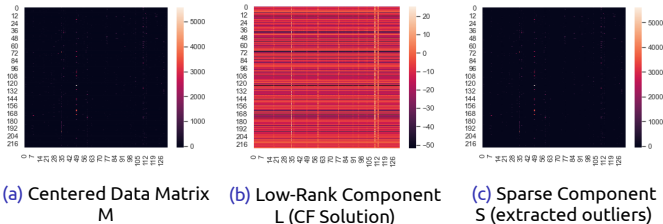


**Figure:** Plot of Root Mean Squared Error (RMSE) on test set for 3 matrix completion techniques with varying levels of corruption. K-Nearest Neighbors and Nuclear Norm Minimization slightly outperform Robust PCA on dataset with no corruption. However, performance of the former 2 techniques significantly deteriorates as corruption is added, while RPCA performs consistently in the presence of outliers.



# Heatmap Visualization

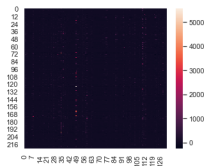
## RPCA No Corruption



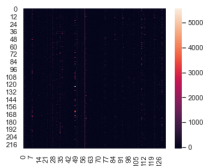
**Figure:** Heatmaps of Robust PCA output with no corruption. Games displayed on x-axis and users on y-axis. Low-rank and sparse components extracted. Recall that RPCA minimizes objective function subject to  $M = L + S$ .

# Heatmap Visualization

## NNM+kNN No Corruption



(a) Low-Rank Output L  
Nuclear Norm  
Minimization

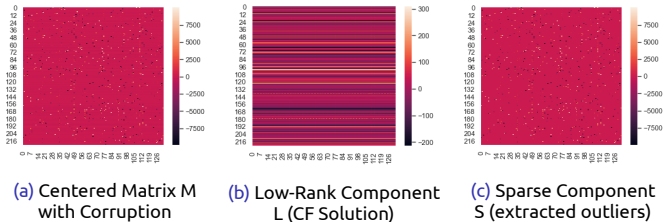


(b) Matrix Completion  
Solution  
K-Nearest Neighbors

**Figure:** Heatmaps of traditional matrix completion techniques with no corruption. Games displayed on x-axis and users on y-axis. For certain games, entries in original matrix filled in with values inferred by the 2 techniques.

# Heatmap Visualization

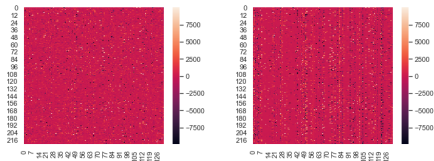
## RPCA Corruption



**Figure:** Heatmaps of Robust PCA output with 10% corruption. Games displayed on x-axis and users on y-axis. A coherent low-rank component is still extracted, and outliers added by corruption are pulled into the sparse component. As in Figure 3,  $M=L+S$ .

# Heatmap Visualization

## NNM+kNN with Corruption



(a) Low-Rank Output L  
Nuclear Norm  
Minimization

(b) Matrix Completion  
Solution  
K-Nearest Neighbors

**Figure:** Heatmaps of traditional matrix completion techniques with 10% corruption. Games displayed on x-axis and users on y-axis. For certain games, entries in original matrix filled in with values inferred by the 2 techniques.

## Closing Remarks

### *Points of Emphasis:*

- Focus was **not** overall performance
- Other RPCA Applications (Video Surveillance)
- Matrix Completion Methods

### *Helpful Resources:*

- [Video + TextBook](#)
- [Prof. Fernandez-Granda's notes](#)