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ECE 271A Homework 1

1. The goal of this problem is to segment the "'cheetah" image (shown below in the left) into its two components, cheetah (foreground) and grass (background).

(a) Using the training data in **TrainingSamplesDCT 8.mat**, what are reasonable estimates for the prior probabilities?

Solution.

We can assume that the probability of being cheetah for some x_i is higher than that of being grass, that is $P_{X|Y}(x_i | cheetah) > P_{X|Y}(x_i | grass)$, and vice versa.

(b) Using the training data in TrainingSamplesDCT 8.mat, compute and plot the index histograms $P_{X|Y}(x | cheetah)$ and $P_{X|Y}(x | grass)$.

Solution.

The following are my codes.

If we look at the histogram of training sample data sets (see Table 1), we can tell that the likelihood of being **grass** is higher than being **cheetah** for x_i for i = 2, 3, ..., 6; whereas the likelihood of being **cheetah** is higher than being **grass** for x_i for $x \ge 7$.

Matlab Code

```
1 % we first deal with the training data sets
2 load ("TrainingSamplesDCT_8.mat"); % load the training data
     sets
<sup>3</sup> M_cheetah = CreateHisto(TrainsampleDCT_FG); % the training
     data set of cheetah
4 M_grass = CreateHisto(TrainsampleDCT_BG); % the training data
     set of grass
[m_cheetah, ~] = size (TrainsampleDCT_FG); % the size of the
     training data set of cheetah
[m_grass, ~] = size (TrainsampleDCT_BG); % the size of the
     training data set of cheetah
7 P_cheetah = m_cheetah / (m_cheetah + m_grass); % the
     probability of cheetah
* P_grass = m_grass / (m_cheetah + m_grass); % the probability
     of grass
9 H_cheetah = histogram (M_cheetah, "Normalization", "probability
            % create a histogram of cheetah
     ");
10 hold on
posMax = 25; % there is no data after x = 25
Y_{\text{cheetah}} = zeros(1, posMax); % store in a vector
Y_{\text{cheetah}}(1, 2 : \text{end}) = H_{\text{cheetah}} \cdot \text{Values}(1, 1 : \text{posMax} - 1);
P_X-cheetah = Y-cheetah * P-cheetah; % P(x, cheetah)
H_grass = histogram (M_grass, "Normalization", "probability");
        % create a histogram of grass
title ("Probability of Cheetah vs. Probability of Grass");
Y_{grass} = zeros(1, posMax); \% store in a vector
Y_{grass}(1, 2 : 18) = H_{grass}.Values(1, 1 : end);
P_X_{grass} = Y_{grass} * P_{grass}; \% P(x, grass)
```

ProbabilityOfCheetahVsProbabilityOfGrass.jpg

Table 1: A histogram of the probability of cheetah vs. the probability of grass

(c) For each block in the image cheetah.bmp, compute the feature X (index of the DCT coefficient with 2nd greatest energy). Compute the state variable Y using the minimum probability of error rule based on the probabilities obtained in a) and b). Store the state in an array A. Using the commands **imagesc** and **colormap(gray(255))** create a picture of that array.

Solution. The following are my code.

And my result is shown at Figure 1.

My code yield an error rate of 18.01%.

Matlab Code

```
1 clear
2 clc
4 % we first deal with the training data sets
5 load ("TrainingSamplesDCT_8.mat"); % load the training data
     sets
6 M_cheetah = CreateHisto(TrainsampleDCT_FG); % the training
     data set of cheetah
7 M_grass = CreateHisto(TrainsampleDCT_BG); % the training data
     set of grass
s [m_cheetah, ~] = size (TrainsampleDCT_FG); % the size of the
     training data set of cheetah
g [m_grass, ~] = size (TrainsampleDCT_BG); % the size of the
     training data set of cheetah
P_cheetah = m_cheetah / (m_cheetah + m_grass); % the
     probability of cheetah
P_grass = m_grass / (m_cheetah + m_grass); % the probability
     of grass
12 H_cheetah = histogram (M_cheetah, "Normalization", "probability
            % create a histogram of cheetah
13 hold on
_{14} posMax = 25;
                % there is no data after x = 25
Y_cheetah = zeros(1, posMax); % store in a vector
Y_{\text{cheetah}}(1, 2 : \text{end}) = H_{\text{cheetah}} \cdot \text{Values}(1, 1 : \text{posMax} - 1);
P_X-cheetah = Y-cheetah * P-cheetah; % P(x, \text{ cheetah})
H_grass = histogram (M_grass, "Normalization", "probability");
        % create a histogram of grass
  title ("Probability of Cheetah vs. Probability of Grass");
  Y_grass = zeros(1, posMax); % store in a vector
  Y_{grass}(1, 2 : 18) = H_{grass}.Values(1, 1 : end);
  P_X_{grass} = Y_{grass} * P_{grass}; \% P(x, grass)
23
  maskTable = zeros(1, posMax);
  for i = 1 : posMax
27
      if P_X_cheetah(i) > P_X_grass(i)
```

```
maskTable(i) = 1;
29
       else
30
           maskTable(i) = 0;
31
       end
32
  end
34
  img = imread ("cheetah.bmp");
  img = im2double(img);
  [m, n] = size(img); \% row = 255, column = 270
  img_answer = imread("cheetah_mask.bmp");
  img_answer = im2gray(img_answer);
40
  % padding the image
  I = zeros(m + 7, n + 7);
  I(1:m, 1:n) = img;
  % the zigzag map
  ZigZagM = [0]
                        5
                                         27
                                              28;
                   1
                                14
                                     15
           2
                4
                    7
                        13
                             16
                                 26
                                      29
                                           42;
           3
                8
                   12
                             25
                        17
                                 30
                                      41
                                           43;
48
           9
               11
                   18
                        24
                             31
                                 40
                                      44
                                           53;
            10
                     23
                                            54;
                19
                         32
                              39
                                  45
                                       52
50
            20
                22
                     33
                                            60;
                         38
                              46
                                  51
                                       55
51
            21
                34
                     37
                         47
                              50
                                  56
                                       59
                                            61;
52
           35
                36
                    48
                         49
                                  58
                                       62
                                            63];
                              57
53
  ZigZagV = ZigZagM(:);
55
  % use sliding window method to perform dct2
  X = zeros(m, n);
58
  for i = 1 : m
       for j = 1 : n
60
            Block = I(i : i + 7, j : j + 7);
           Block_DCT = dct2(Block, 8, 8);
62
           V = abs(Block_DCT(:));
           V_descend = sort(V, "descend");
64
            val = V_descend(2);
           index = find(V = val);
66
           x = ZigZagV(index);
67
```

```
X(i, j) = x(1);
68
       end
69
   end
70
   H.X = histogram (X, "Normalization", "probability");
   mask = zeros(m, n);
   for i = 1 : m
       for j = 1 : n
            pos = X(i, j);
76
            if 1 <= pos && pos <= 25
                mask(i, j) = maskTable(pos);
            end
       end
80
   end
81
82
   img_mask = mat2gray(mask);
  % compare the result with the answer
   subplot(1, 2, 1), imshow(img_answer), title('Idea Mask');
   subplot(1, 2, 2), imshow(img_mask), title('My Result');
   \% change the answer to 0s and 1s
   for i = 1 : m
       for j = 1 : n
            bit = img_answer(i, j);
92
            if bit = 255
                img_answer(i, j) = 1;
94
            end
       end
96
   end
97
   error = 0;
   for i = 1 : m
100
       for j = 1 : n
101
            a = img_answer(i, j);
           b = img_mask(i, j);
103
            if a = b
                error = error + 1;
105
            end
106
```

```
end
107
   end
   e = error / (m * n)
109
110
  % analysize training data sets function
   function H = CreateHisto(M)
       [m, \tilde{z}] = size(M);
       H = zeros(m, 1);
114
       for i = 1 : m
            v = abs(M(i, :));
116
            v_descend = sort(v, "descend");
117
            val = v_descend(2);
118
            index = find(v = val);
119
           H(i) = index;
       end
121
   end
```

Homework1-Result.jpg

Figure 1: The ideal result compares with mine