

SAMD21J18A -

QFN64										SoK Zero Dawn Rev1.5b (SAMD21J, August 2019)		EXSOKSKELETAL MITT	
	PIN	PORT	INT	INT	PINMODE	NAMING	FUNCTION1	PWM		Schem. Name.	USED TO		
LEFT	1	PA00		0	x	x	XIN32	x					
	2	PA01		1	x	x	XOUT32	x					
	3	PA02	2	2	29 / 60	A4 / (DAC)		DAC	MT1_POT	Motor 1 Potentiometer			
	4	PA03	3	3	44 / 59	SOK (A19)	AREF	x	SOK	Automatic Detection Board			
	5	PB04	4	4	30	A5		x	MT2_POT	Motor 2 Potentiometer			
	6	PB05	5	5	31	A6		x	MT3_POT	Motor 3 Potentiometer			
	7	GNDANA											
	8	VDDANA											
	9	PB06	6	6	33	A8		x	MT5_POT	Motor 5 Potentiometer			
	10	PB07	7	7	34	A9		x	MT6_POT	Motor 6 Potentiometer			
	11	PB08	8	8	45 / 42	I2C_SDA / A17	SERCOM_+4.0	PWM4_CH0	SDA	Communication I2C			
	12	PB09	9	9	46 / 43	I2C_SCL / A18	SERCOM_+4.1	PWM4_CH1	SCL	Communication I2C			
	13	PA04	4	4	35 / 0	A10 / D0 / (Serial1) TX	SERCOM_+0.0	PWM0_CH0	PWM_MT1B_SERVO1	PWM Motor 1 & Servo 1			
	14	PA05	5	5	36 / 1	A11 / D1 / (Serial1) RX	SERCOM_+0.1	PWM0_CH1	PWM_MT1A	PWM Motor 1			
	15	PA06	6	6	37 / 2	A12 / D2	SERCOM_+0.2	PWM1_CH0	PWM_MT2A_SERVO2	PWM Motor 2 & Servo 2			
DOWN	16	PA07	7	7	38 / 3	A13 / D3	SERCOM_+0.3/I2S_SD0	PWM1_CH1	PWM_MT2B	PWM Motor 2			
	17	PA08		NMI	41 / 6	A16 / D6	I2S_SD1	PWM1_CH2	PWM_MT4A_SERVO4	PWM Motor 4 & Servo 4			
	18	PA09	9	9	32	A7	I2S_MCK0	PWM1_CH3	MT4_POT	Motor 4 Potentiometer			
	19	PA10	10	10	39 / 4	A14 / D4	I2S_SCK0	PWM0_CH2	PWM_MT3B_SERVO3	PWM Motor 3 & Servo 3			
	20	PA11	11	11	40 / 5	A15 / D5	I2S_FS0	PWM0_CH3	PWM_MT3A	PWM Motor 3			
	21	VDDIO											
	22	GND											
	23	PB10	10	10	7	D7	I2S_MCK1	PWM0_CH4	PWM_MT4B	PWM Motor 4			
	24	PB11	11	11	8	D8	I2S_SCK1	PWM0_CH5	PWM_MT5B_SERVO5	PWM Motor 5 & Servo 5			
	25	PB12	12	12	9	D9	I2S_FS1	PWM0_CH6	PWM_MT5A	PWM Motor 5			
	26	PB13	13	13	10	D10		PWM0_CH7	PWM_MT6A_SERVO6	PWM Motor 6 & Servo 6			
	27	PB14	14	14	11	D11		PWM5_CH0	PWM_MT6B	PWM Motor 6			
	28	PB15	15	15	12	D12		PWM5_CH1	FINGER_INT5	Finger 5 Interrupt (15)			
	29	PA12	12	12	54	SPI_MISO1	SERCOM2.0+4.0	P2.0					
	30	PA13	13	13	53	SPI_SCK1	SERCOM2.1+4.1	x					
RIGHT	31	PA14	14	14	13	D13	SERCOM2.2+4.2	PWM3_CH0	FINGER_INT6	Finger 6 Interrupt (14)			
	32	PA15	15	15	52	SPI_MOSI1	SERCOM2.3+4.3	P3.1					
	33	GND											
	34	VDDIO											
	35	PA16	0	0	14	LED_BUILTIN	SERCOM1.0+3.0	PWM2_CH0					
	36	PA17	1	1	50	SPI_SCK	SERCOM1.1+3.1	PWM2_CH1	FINGER_INT1	Finger 1 Interrupt (1)			
	37	PA18	2	2	23	nc		x					
	38	PA19	3	3	20	I2S_SD0		P3.1*					
	39	PB16	0	0	24	INT_APDS		x					
	40	PB17	1	1	19	BLE_STATE		x					
	41	PA20	4	4	21	I2S_SCK0		x					
	42	PA21	5	5	22	I2S_FS0		x					
	43	PA22	6	6	47	I2C_SDA1	SERCOM3.0+5.0	x					
	44	PA23	7	7	48	I2C_SCL1	SERCOM3.1+5.1	x					
	45	PA24	12	12	55	USB_D- (Serial)	SerialUSB	x					
	46	PA25	13	13	56	USB_D+ (Serial)	SerialUSB	x					
UP	47	GND											
	48	VDDIO											
	49	PB22	6	6	57	SAM_TX_BLE_RX	SERCOM_+5.2	x					
	50	PB23	7	7	58	SAM_RX_BLE_TX	SERCOM_+5.3	x					
	51	PA27	15	15	15	BLE_RESET	x	x					
	52	nRESET											
	53	PA28	8	8	16	BLE_ENABLE	x	x					
	54	GND											
	55	VDDCORE											
	56	VDDIN											
	57	PA30	10	10	51	SPI_MISO / SWCLK	SERCOM_+1.2	TCC1_CH0*	FINGER_INT2	Finger 3 Interrupt (10)			
	58	PA31	11	11	49	SPI_MOSI / SWDIO	SERCOM_+1.3	TCC1_CH1*	FINGER_INT1	Finger 2 Interrupt (11)			
	59	PB30	14	14	18	BLE_MSTR_SLV	SERCOM_+5.0	x					
	60	PB31	15	15	17	BLE_CONFIG	SERCOM_+5.1	x					
	61	PB00	0	0	25	A0	x	PWM7_CH0	BATTERY_MONITOR	Battery Monitor			
	62	PB01	1	1	26	A1	x	PWM7_CH1	FINGER_IRESET	Fingers !Reset			
	63	PB02	2	2	27	A2	x	PWM6_CH0	FINGER_INT4	Finger 4 Interrupt (2)			
	64	PB03	3	3	28	A3	x	PWM6_CH1	FINGER_INT7	Finger 7 Interrupt (3)			

\*Timers repeated: MISO = D2, MOSI = D3

	SoK Zero Dawn (SAMD21J)		EXSOKSKELETAL MITT	
Physical Pin	Port	Arduino Function	Function1	Function2
32	GND	GND	GND	
31	PB09	(I2C) SCL~ / A18	SCL	
30	PB08	(I2C) SDA~ / A17	SDA	
29	PA14	D13~	Finger 6 Interrupt (14)	
28	PB15	D12~	Finger 5 Interrupt (15)	
27	PB14	D11~	Motor 6 PWM B	
26	PB13	D10~	Motor 6 PWM A	Servo6
25	PB12	D9~ / (I2S) FS1	Motor 5 PWM A	
24	PB11	D8~ / (I2S) SCK1	Motor 5 PWM B	Servo5
23	PB10	D7~ / (I2S) MCK1	Motor 4 PWM B	
22	PA08	A16 / D6~ / (I2S) SD1	Motor 4 PWM A	Servo4
21	PA11	A15 / D5~ / (I2S) FS0	Motor 3 PWM A	
20	PA10	A14 / D4~ / (I2S) SCK0	Motor 3 PWM B	Servo3
19	PA07	A13 / D3~ / (I2S) SD0	Motor 2 PWM B	
18	PA06	A12 / D2~	Motor 2 PWM A	Servo2
17	PA05	A11 / D1~ / (Serial1) RX	Motor 1 PWM A	
16	PA04	A10 / D0~ / (Serial1) TX	Motor 1 PWM B	Servo1
15	PB07	A9	Motor 6 Potentiometer	
14	PB06	A8	Motor 5 Potentiometer	
13	PA09	A7~ / (I2S) MCK0	Motor 4 Potentiometer	
12	PB05	A6	Motor 3 Potentiometer	
11	PB04	A5	Motor 2 Potentiometer	
10	PA02	A4~ (DAC)	Motor 1 Potentiometer	
9	PB03	A3~	Finger 7 Interrupt (3)	
8	PB02	A2~	Finger 4 Interrupt (2)	
7	PB01	A1~	Fingers !Reset	
6	PB00	A0~	Monitor Batería	
5	PA03	AREF / SOK (SoK Selector)	SoK Selector	
4	PA30	(SPI) MISO / (SWD) SWCLK	Finger 3 Interrupt (10)	
3	PA31	(SPI) MOSI / (SWD) SWDIO	Finger 2 Interrupt (11)	
2	PA17	(SPI) SCK ~	Finger 1 Interrupt (1)	
1	3.3V	3.3V	3.3V	

Analog	8
PWM	12
Interrupts	7
Digital	1
I2C	2
Total	30

Notes:  
Finger 1 interrupt 1 collides with BLE\_STATE interrupt 1  
Some interrupts could not be activated on variant.cpp file