

Phase/Tasks	Fall Semester					Winter Break		Spring Semester						
	October		November		December		January		February		March		April	
Phase 1: Model Selection														
Literature Review														
Model Selected														
Phase 2: Model Calibration														
Formulate dynamical terms														
Run actuation tests on robot														
Calibrate model based on results														
Phase 3: Controller Implementation														
Formulate controller														
Implement controller in simulation														
Hardware implementation														
												Buffer Space		