



COLLEGE OF ENGINEERING

Thesis Prospectus

3-DIMENSIONAL TRAJECTORY GENERATION FOR SOFT ROBOT MANIPULATORS

by

Nashr El Auliya
B.Sc., Boston University, 2024

Submitted in partial fulfillment of the requirements for the degree of

Master of Science

2025

This page intentionally left blank.

Contents

1	Abstract	1
2	Topic Background	1
3	Prior Work	1
4	Research Approach	1
5	References	1

1 Abstract

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Ut purus elit, vestibulum ut, placerat ac, adipiscing vitae, felis. Curabitur dictum gravida mauris. Nam arcu libero, nonummy eget, consectetur id, vulputate a, magna. Donec vehicula augue eu neque. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Mauris ut leo. Cras viverra metus rhoncus sem. Nulla et lectus vestibulum urna fringilla ultrices. Phasellus eu tellus sit amet tortor gravida placerat. Integer sapien est, iaculis in, pretium quis, viverra ac, nunc. Praesent eget sem vel leo ultrices bibendum. Aenean faucibus. Morbi dolor nulla, malesuada eu, pulvinar at, mollis ac, nulla. Curabitur auctor semper nulla. Donec varius orci eget risus. Duis nibh mi, congue eu, accumsan eleifend, sagittis quis, diam. Duis eget orci sit amet orci dignissim rutrum.

2 Topic Background

Background

3 Prior Work

4 Research Approach

5 References