

College of Engineering

Thesis Prospectus

3-DIMENSIONAL TRAJECTORY GENERATION FOR SOFT ROBOT MANIPULATORS

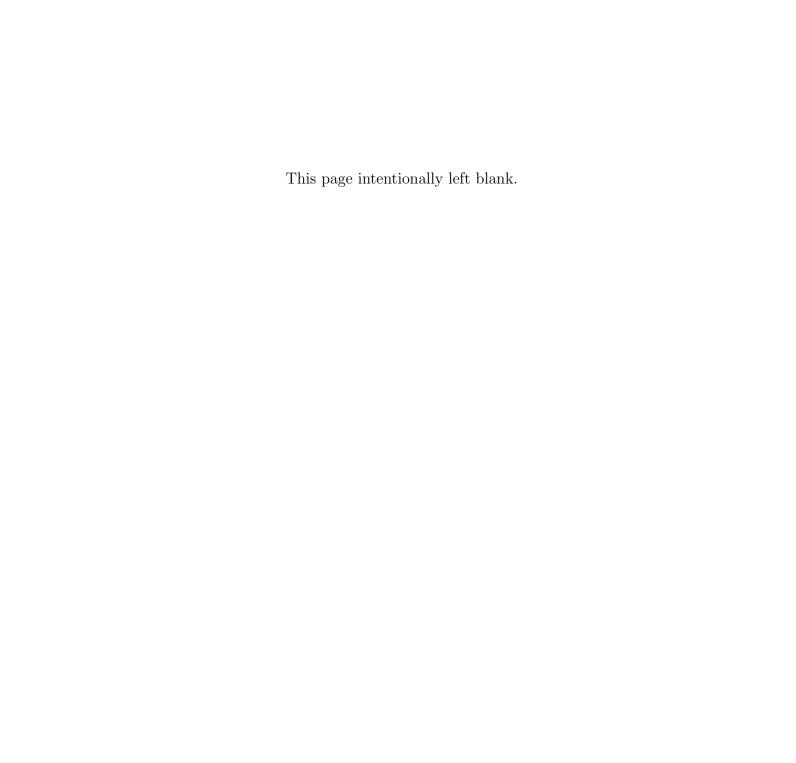
by

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B.Sc., Boston University, 2024

Submitted in partial fulfillment of the requirements for the degree of Master of Science

2025



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1 Abstract

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2 Topic Background

Background

- 3 Prior Work
- 4 Research Approach
- 5 References