

Problem 1584: Min Cost to Connect All Points

Problem Information

Difficulty: Medium

Acceptance Rate: 0.00%

Paid Only: No

Problem Description

You are given an array

points

representing integer coordinates of some points on a 2D-plane, where

$\text{points}[i] = [x$

i

, y

i

]

.

The cost of connecting two points

$[x$

i

, y

i

]

and

[x

j

, y

]

] is the

manhattan distance

between them:

|x

i

- x

j

| + |y

i

- y

j

|

, where

$|val|$

denotes the absolute value of

val

.

Return

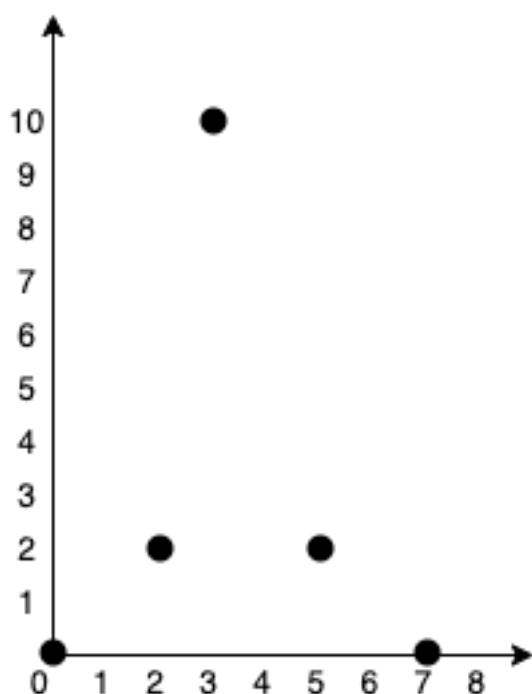
the minimum cost to make all points connected.

All points are connected if there is

exactly one

simple path between any two points.

Example 1:



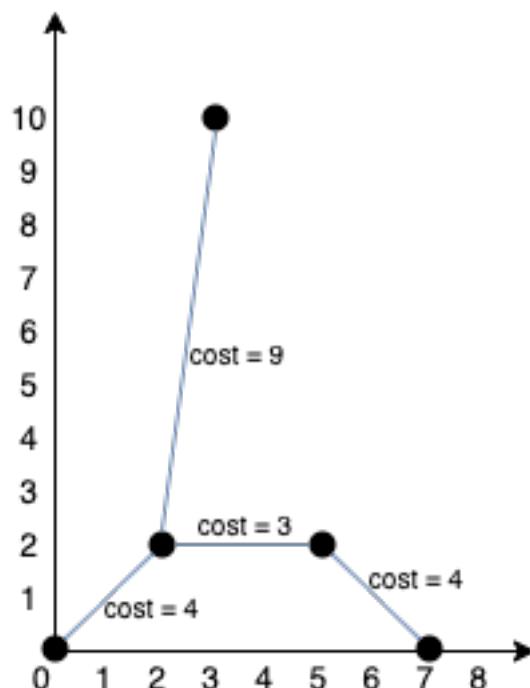
Input:

```
points = [[0,0],[2,2],[3,10],[5,2],[7,0]]
```

Output:

20

Explanation:



We can connect the points as shown above to get the minimum cost of 20. Notice that there is a unique path between every pair of points.

Example 2:

Input:

```
points = [[3,12],[-2,5],[-4,1]]
```

Output:

18

Constraints:

$1 \leq \text{points.length} \leq 1000$

-10

6

$\leq x$

i

, y

i

≤ 10

6

All pairs

(x

i

, y

i

)

are distinct.

Code Snippets

C++:

```
class Solution {  
public:  
    int minCostConnectPoints(vector<vector<int>>& points) {  
  
    }  
};
```

Java:

```
class Solution {  
public int minCostConnectPoints(int[][] points) {  
  
}  
}
```

Python3:

```
class Solution:  
    def minCostConnectPoints(self, points: List[List[int]]) -> int:
```

Python:

```
class Solution(object):  
    def minCostConnectPoints(self, points):  
        """  
        :type points: List[List[int]]  
        :rtype: int  
        """
```

JavaScript:

```
/**  
 * @param {number[][]} points  
 * @return {number}  
 */  
var minCostConnectPoints = function(points) {  
  
};
```

TypeScript:

```
function minCostConnectPoints(points: number[][]): number {
```

```
};
```

C#:

```
public class Solution {  
    public int MinCostConnectPoints(int[][] points) {  
        }  
    }
```

C:

```
int minCostConnectPoints(int** points, int pointsSize, int* pointsColSize) {  
}
```

Go:

```
func minCostConnectPoints(points [][]int) int {  
}
```

Kotlin:

```
class Solution {  
    fun minCostConnectPoints(points: Array<IntArray>): Int {  
        }  
    }
```

Swift:

```
class Solution {  
    func minCostConnectPoints(_ points: [[Int]]) -> Int {  
        }  
    }
```

Rust:

```
impl Solution {  
    pub fn min_cost_connect_points(points: Vec<Vec<i32>>) -> i32 {
```

```
}
```

```
}
```

Ruby:

```
# @param {Integer[][]} points
# @return {Integer}
def min_cost_connect_points(points)

end
```

PHP:

```
class Solution {

    /**
     * @param Integer[][] $points
     * @return Integer
     */
    function minCostConnectPoints($points) {

    }
}
```

Dart:

```
class Solution {
    int minCostConnectPoints(List<List<int>> points) {
    }
}
```

Scala:

```
object Solution {
    def minCostConnectPoints(points: Array[Array[Int]]): Int = {
    }
}
```

Elixir:

```

defmodule Solution do
@spec min_cost_connect_points(points :: [[integer]]) :: integer
def min_cost_connect_points(points) do

end
end

```

Erlang:

```

-spec min_cost_connect_points(Points :: [[integer()]]) -> integer().
min_cost_connect_points(Points) ->
    .

```

Racket:

```

(define/contract (min-cost-connect-points points)
  (-> (listof (listof exact-integer?)) exact-integer?))

```

Solutions

C++ Solution:

```

/*
 * Problem: Min Cost to Connect All Points
 * Difficulty: Medium
 * Tags: array, tree, graph
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(h) for recursion stack where h is height
 */

class Solution {
public:
    int minCostConnectPoints(vector<vector<int>>& points) {
        }
    };

```

Java Solution:

```

/**
 * Problem: Min Cost to Connect All Points
 * Difficulty: Medium
 * Tags: array, tree, graph
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(h) for recursion stack where h is height
 */

class Solution {
    public int minCostConnectPoints(int[][] points) {
        }

    }
}

```

Python3 Solution:

```

"""
Problem: Min Cost to Connect All Points
Difficulty: Medium
Tags: array, tree, graph

Approach: Use two pointers or sliding window technique
Time Complexity: O(n) or O(n log n)
Space Complexity: O(h) for recursion stack where h is height
"""

class Solution:
    def minCostConnectPoints(self, points: List[List[int]]) -> int:
        # TODO: Implement optimized solution
        pass

```

Python Solution:

```

class Solution(object):
    def minCostConnectPoints(self, points):
        """
:type points: List[List[int]]
:rtype: int
"""

```

JavaScript Solution:

```
/**  
 * Problem: Min Cost to Connect All Points  
 * Difficulty: Medium  
 * Tags: array, tree, graph  
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 */  
  
/**  
 * @param {number[][]} points  
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var minCostConnectPoints = function(points) {  
  
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TypeScript Solution:

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function minCostConnectPoints(points: number[][]): number {  
  
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C# Solution:

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public class Solution {
    public int MinCostConnectPoints(int[][] points) {
        }
    }
}

```

C Solution:

```

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 * Problem: Min Cost to Connect All Points
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*/
int minCostConnectPoints(int** points, int pointsSize, int* pointsColSize) {
}

```

Go Solution:

```

// Problem: Min Cost to Connect All Points
// Difficulty: Medium
// Tags: array, tree, graph
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func minCostConnectPoints(points [][]int) int {
}

```

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Ruby Solution:

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PHP Solution:

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