

Problem 818: Race Car

Problem Information

Difficulty: **Hard**

Acceptance Rate: 0.00%

Paid Only: No

Problem Description

Your car starts at position

0

and speed

+1

on an infinite number line. Your car can go into negative positions. Your car drives automatically according to a sequence of instructions

'A'

(accelerate) and

'R'

(reverse):

When you get an instruction

'A'

, your car does the following:

position += speed

speed *= 2

When you get an instruction

'R'

, your car does the following:

If your speed is positive then

speed = -1

otherwise

speed = 1

Your position stays the same.

For example, after commands

"AAR"

, your car goes to positions

0 --> 1 --> 3 --> 3

, and your speed goes to

1 --> 2 --> 4 --> -1

.

Given a target position

target

, return

the length of the shortest sequence of instructions to get there

.

Example 1:

Input:

target = 3

Output:

2

Explanation:

The shortest instruction sequence is "AA". Your position goes from 0 --> 1 --> 3.

Example 2:

Input:

target = 6

Output:

5

Explanation:

The shortest instruction sequence is "AAARA". Your position goes from 0 --> 1 --> 3 --> 7 --> 7 --> 6.

Constraints:

$1 \leq \text{target} \leq 10$

4

Code Snippets

C++:

```
class Solution {  
public:  
    int racecar(int target) {  
  
    }  
};
```

Java:

```
class Solution {  
    public int racecar(int target) {  
  
    }  
}
```

Python3:

```
class Solution:  
    def racecar(self, target: int) -> int:
```

Python:

```
class Solution(object):  
    def racecar(self, target):  
        """  
        :type target: int  
        :rtype: int  
        """
```

JavaScript:

```
/**  
 * @param {number} target  
 * @return {number}  
 */  
var racecar = function(target) {  
  
};
```

TypeScript:

```
function racecar(target: number): number {  
  
};
```

C#:

```
public class Solution {  
    public int Racecar(int target) {  
  
    }  
}
```

C:

```
int racecar(int target) {  
  
}
```

Go:

```
func racecar(target int) int {  
  
}
```

Kotlin:

```
class Solution {  
    fun racecar(target: Int): Int {  
  
    }  
}
```

Swift:

```
class Solution {  
    func racecar(_ target: Int) -> Int {  
  
    }  
}
```

Rust:

```
impl Solution {  
  pub fn racecar(target: i32) -> i32 {  
  
  }  
}
```

Ruby:

```
# @param {Integer} target  
# @return {Integer}  
def racecar(target)  
  
end
```

PHP:

```
class Solution {  
  
  /**  
   * @param Integer $target  
   * @return Integer  
   */  
  function racecar($target) {  
  
  }  
}
```

Dart:

```
class Solution {  
  int racecar(int target) {  
  
  }  
}
```

Scala:

```
object Solution {  
  def racecar(target: Int): Int = {  
  
  }  
}
```

```
}
```

Elixir:

```
defmodule Solution do
  @spec racecar(target :: integer) :: integer
  def racecar(target) do

  end
end
```

Erlang:

```
-spec racecar(Target :: integer()) -> integer().
racecar(Target) ->
.
```

Racket:

```
(define/contract (racecar target)
  (-> exact-integer? exact-integer?)
)
```

Solutions

C++ Solution:

```
/*
 * Problem: Race Car
 * Difficulty: Hard
 * Tags: dp
 *
 * Approach: Dynamic programming with memoization or tabulation
 * Time Complexity: O(n * m) where n and m are problem dimensions
 * Space Complexity: O(n) or O(n * m) for DP table
 */

class Solution {
public:
    int racecar(int target) {
```

```
}  
};
```

Java Solution:

```
/**  
 * Problem: Race Car  
 * Difficulty: Hard  
 * Tags: dp  
 *  
 * Approach: Dynamic programming with memoization or tabulation  
 * Time Complexity:  $O(n * m)$  where  $n$  and  $m$  are problem dimensions  
 * Space Complexity:  $O(n)$  or  $O(n * m)$  for DP table  
 */  
  
class Solution {  
    public int racecar(int target) {  
  
    }  
}
```

Python3 Solution:

```
"""  
Problem: Race Car  
Difficulty: Hard  
Tags: dp  
  
Approach: Dynamic programming with memoization or tabulation  
Time Complexity:  $O(n * m)$  where  $n$  and  $m$  are problem dimensions  
Space Complexity:  $O(n)$  or  $O(n * m)$  for DP table  
"""  
  
class Solution:  
    def racecar(self, target: int) -> int:  
        # TODO: Implement optimized solution  
        pass
```

Python Solution:


```

class Solution(object):
def racecar(self, target):
    """
    :type target: int
    :rtype: int
    """

```

JavaScript Solution:

```

/**
 * Problem: Race Car
 * Difficulty: Hard
 * Tags: dp
 *
 * Approach: Dynamic programming with memoization or tabulation
 * Time Complexity: O(n * m) where n and m are problem dimensions
 * Space Complexity: O(n) or O(n * m) for DP table
 */

/**
 * @param {number} target
 * @return {number}
 */
var racecar = function(target) {

};

```

TypeScript Solution:

```

/**
 * Problem: Race Car
 * Difficulty: Hard
 * Tags: dp
 *
 * Approach: Dynamic programming with memoization or tabulation
 * Time Complexity: O(n * m) where n and m are problem dimensions
 * Space Complexity: O(n) or O(n * m) for DP table
 */

function racecar(target: number): number {

};

```

C# Solution:

```
/*
 * Problem: Race Car
 * Difficulty: Hard
 * Tags: dp
 *
 * Approach: Dynamic programming with memoization or tabulation
 * Time Complexity: O(n * m) where n and m are problem dimensions
 * Space Complexity: O(n) or O(n * m) for DP table
 */

public class Solution {
    public int Racecar(int target) {

    }
}
```

C Solution:

```
/*
 * Problem: Race Car
 * Difficulty: Hard
 * Tags: dp
 *
 * Approach: Dynamic programming with memoization or tabulation
 * Time Complexity: O(n * m) where n and m are problem dimensions
 * Space Complexity: O(n) or O(n * m) for DP table
 */

int racecar(int target) {

}
```

Go Solution:

```
// Problem: Race Car
// Difficulty: Hard
// Tags: dp
//
// Approach: Dynamic programming with memoization or tabulation
// Time Complexity: O(n * m) where n and m are problem dimensions
```

```
// Space Complexity: O(n) or O(n * m) for DP table

func racecar(target int) int {

}
```

Kotlin Solution:

```
class Solution {
    fun racecar(target: Int): Int {

    }
}
```

Swift Solution:

```
class Solution {
    func racecar(_ target: Int) -> Int {

    }
}
```

Rust Solution:

```
// Problem: Race Car
// Difficulty: Hard
// Tags: dp
//
// Approach: Dynamic programming with memoization or tabulation
// Time Complexity: O(n * m) where n and m are problem dimensions
// Space Complexity: O(n) or O(n * m) for DP table

impl Solution {
    pub fn racecar(target: i32) -> i32 {

    }
}
```

Ruby Solution:

```
# @param {Integer} target
# @return {Integer}
def racecar(target)

end
```

PHP Solution:

```
class Solution {

    /**
     * @param Integer $target
     * @return Integer
     */
    function racecar($target) {

    }

}
```

Dart Solution:

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end
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