

Problem 802: Find Eventual Safe States

Problem Information

Difficulty: **Medium**

Acceptance Rate: 0.00%

Paid Only: No

Problem Description

There is a directed graph of

n

nodes with each node labeled from

0

to

$n - 1$

. The graph is represented by a

0-indexed

2D integer array

graph

where

graph[i]

is an integer array of nodes adjacent to node

i

, meaning there is an edge from node

i

to each node in

graph[i]

.

A node is a

terminal node

if there are no outgoing edges. A node is a

safe node

if every possible path starting from that node leads to a

terminal node

(or another safe node).

Return

an array containing all the

safe nodes

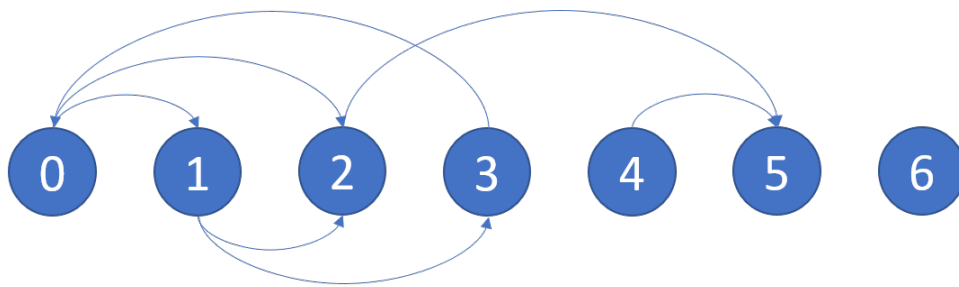
of the graph

. The answer should be sorted in

ascending

order.

Example 1:



Input:

graph = [[1,2],[2,3],[5],[0],[5],[],[[]]]

Output:

[2,4,5,6]

Explanation:

The given graph is shown above. Nodes 5 and 6 are terminal nodes as there are no outgoing edges from either of them. Every path starting at nodes 2, 4, 5, and 6 all lead to either node 5 or 6.

Example 2:

Input:

graph = [[1,2,3,4],[1,2],[3,4],[0,4],[[]]]

Output:

[4]

Explanation:

Only node 4 is a terminal node, and every path starting at node 4 leads to node 4.

Constraints:

$n == \text{graph.length}$

$1 \leq n \leq 10$

4

$0 \leq \text{graph}[i].\text{length} \leq n$

$0 \leq \text{graph}[i][j] \leq n - 1$

`graph[i]`

is sorted in a strictly increasing order.

The graph may contain self-loops.

The number of edges in the graph will be in the range

$[1, 4 * 10$

4

]

.

Code Snippets

C++:

```
class Solution {
public:
    vector<int> eventualSafeNodes(vector<vector<int>>& graph) {

    }
};
```

Java:

```

class Solution {
public List<Integer> eventualSafeNodes(int[][] graph) {

}

}

```

Python3:

```

class Solution:
def eventualSafeNodes(self, graph: List[List[int]]) -> List[int]:

```

Python:

```

class Solution(object):
def eventualSafeNodes(self, graph):
"""
:type graph: List[List[int]]
:rtype: List[int]
"""

```

JavaScript:

```

/**
 * @param {number[][]} graph
 * @return {number[]}
 */
var eventualSafeNodes = function(graph) {

};

```

TypeScript:

```

function eventualSafeNodes(graph: number[][]): number[] {

};

```

C#:

```

public class Solution {
public IList<int> EventualSafeNodes(int[][] graph) {

}

}

```

C:

```
/**
 * Note: The returned array must be malloced, assume caller calls free().
 */
int* eventualSafeNodes(int** graph, int graphSize, int* graphColSize, int*
returnSize) {

}
```

Go:

```
func eventualSafeNodes(graph [][]int) []int {

}
```

Kotlin:

```
class Solution {
    fun eventualSafeNodes(graph: Array<IntArray>): List<Int> {

    }
}
```

Swift:

```
class Solution {
    func eventualSafeNodes(_ graph: [[Int]]) -> [Int] {

    }
}
```

Rust:

```
impl Solution {
    pub fn eventual_safe_nodes(graph: Vec<Vec<i32>>) -> Vec<i32> {

    }
}
```

Ruby:

```

# @param {Integer[][]} graph
# @return {Integer[]}
def eventual_safe_nodes(graph)

end

```

PHP:

```

class Solution {

    /**
     * @param Integer[][] $graph
     * @return Integer[]
     */
    function eventualSafeNodes($graph) {

    }

}

```

Dart:

```

class Solution {
  List<int> eventualSafeNodes(List<List<int>> graph) {

  }

}

```

Scala:

```

object Solution {
  def eventualSafeNodes(graph: Array[Array[Int]]): List[Int] = {

  }

}

```

Elixir:

```

defmodule Solution do
  @spec eventual_safe_nodes(graph :: [[integer]]) :: [integer]
  def eventual_safe_nodes(graph) do

  end

end

```

Erlang:

```
-spec eventual_safe_nodes(Graph :: [[integer()]]) -> [integer()].  
eventual_safe_nodes(Graph) ->  
.
```

Racket:

```
(define/contract (eventual-safe-nodes graph)  
  (-> (listof (listof exact-integer?)) (listof exact-integer?))  
  )
```

Solutions

C++ Solution:

```
/*  
 * Problem: Find Eventual Safe States  
 * Difficulty: Medium  
 * Tags: array, graph, sort, search  
 *  
 * Approach: Use two pointers or sliding window technique  
 * Time Complexity: O(n) or O(n log n)  
 * Space Complexity: O(1) to O(n) depending on approach  
 */  
  
class Solution {  
public:  
    vector<int> eventualSafeNodes(vector<vector<int>>& graph) {  
  
    }  
};
```

Java Solution:

```
/**  
 * Problem: Find Eventual Safe States  
 * Difficulty: Medium  
 * Tags: array, graph, sort, search  
 *  
 * Approach: Use two pointers or sliding window technique
```



```

* Time Complexity: O(n) or O(n log n)
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*/

class Solution {
public List<Integer> eventualSafeNodes(int[][] graph) {

}
}

```

Python3 Solution:

```

"""
Problem: Find Eventual Safe States
Difficulty: Medium
Tags: array, graph, sort, search

Approach: Use two pointers or sliding window technique
Time Complexity: O(n) or O(n log n)
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"""

class Solution:
def eventualSafeNodes(self, graph: List[List[int]]) -> List[int]:
# TODO: Implement optimized solution
pass

```

Python Solution:

```

class Solution(object):
def eventualSafeNodes(self, graph):
"""
:type graph: List[List[int]]
:rtype: List[int]
"""

```

JavaScript Solution:

```

/**
* Problem: Find Eventual Safe States
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```

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/**
* @param {number[][]} graph
* @return {number[]}
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var eventualSafeNodes = function(graph) {

};

```

TypeScript Solution:

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* Approach: Use two pointers or sliding window technique
* Time Complexity: O(n) or O(n log n)
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*/

function eventualSafeNodes(graph: number[][]): number[] {

};

```

C# Solution:

```

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*/

```

```

*/

public class Solution {
    public IList<int> EventualSafeNodes(int[][] graph) {

    }
}

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C Solution:

```

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 * Problem: Find Eventual Safe States
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/**
 * Note: The returned array must be malloced, assume caller calls free().
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int* eventualSafeNodes(int** graph, int graphSize, int* graphColSize, int*
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Go Solution:

```

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// Difficulty: Medium
// Tags: array, graph, sort, search
//
// Approach: Use two pointers or sliding window technique
// Time Complexity: O(n) or O(n log n)
// Space Complexity: O(1) to O(n) depending on approach

func eventualSafeNodes(graph [][]int) []int {

}

```

Kotlin Solution:

```
class Solution {  
    fun eventualSafeNodes(graph: Array<IntArray>): List<Int> {  
  
    }  
}
```

Swift Solution:

```
class Solution {  
    func eventualSafeNodes(_ graph: [[Int]]) -> [Int] {  
  
    }  
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// Time Complexity: O(n) or O(n log n)  
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impl Solution {  
    pub fn eventual_safe_nodes(graph: Vec<Vec<i32>>) -> Vec<i32> {  
  
    }  
}
```

Ruby Solution:

```
# @param {Integer[][]} graph  
# @return {Integer[]}  
def eventual_safe_nodes(graph)  
  
end
```

PHP Solution:

```

class Solution {

    /**
     * @param Integer[][] $graph
     * @return Integer[]
     */
    function eventualSafeNodes($graph) {

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Dart Solution:

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class Solution {
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