

Problem 272: Closest Binary Search Tree Value II

Problem Information

Difficulty: **Hard**

Acceptance Rate: 0.00%

Paid Only: No

Problem Description

Given the

root

of a binary search tree, a

target

value, and an integer

k

, return

the

k

values in the BST that are closest to the

target

. You may return the answer in

any order

.

You are

guaranteed

to have only one unique set of

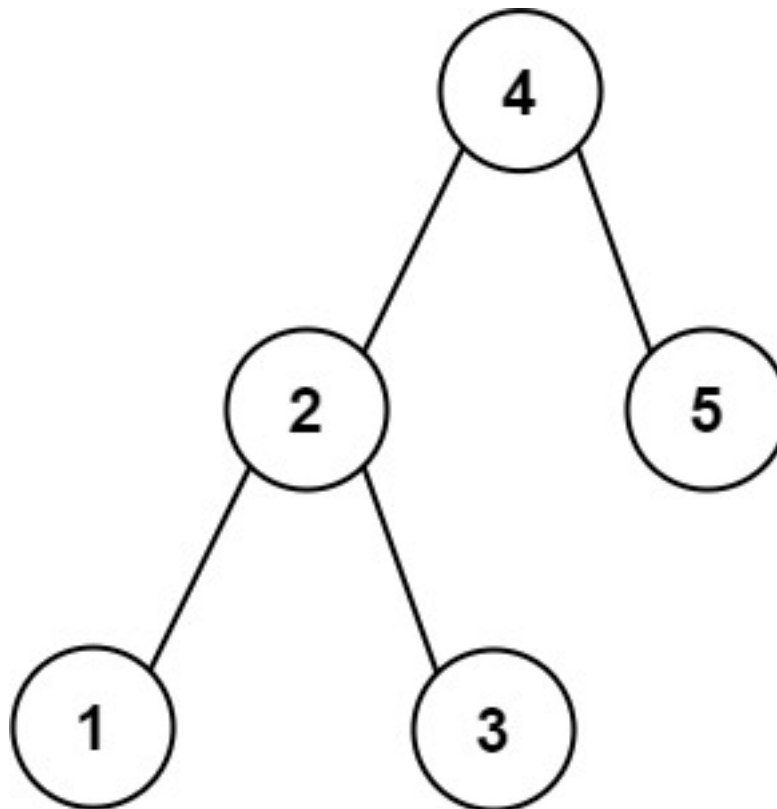
k

values in the BST that are closest to the

target

.

Example 1:



Input:

root = [4,2,5,1,3], target = 3.714286, k = 2

Output:

[4,3]

Example 2:

Input:

root = [1], target = 0.000000, k = 1

Output:

[1]

Constraints:

The number of nodes in the tree is

n

.

$1 \leq k \leq n \leq 10$

4

.

$0 \leq \text{Node.val} \leq 10$

9

-10

9

$\leq \text{target} \leq 10$

9

Follow up:

Assume that the BST is balanced. Could you solve it in less than

$O(n)$

runtime (where

n = total nodes

)?

Code Snippets

C++:

```
/**
 * Definition for a binary tree node.
 * struct TreeNode {
 *     int val;
 *     TreeNode *left;
 *     TreeNode *right;
 *     TreeNode() : val(0), left(nullptr), right(nullptr) {}
 *     TreeNode(int x) : val(x), left(nullptr), right(nullptr) {}
 *     TreeNode(int x, TreeNode *left, TreeNode *right) : val(x), left(left),
 *     right(right) {}
 * };
 */
class Solution {
public:
    vector<int> closestKValues(TreeNode* root, double target, int k) {

    }
};
```

Java:

```

/**
 * Definition for a binary tree node.
 * public class TreeNode {
 *     int val;
 *     TreeNode left;
 *     TreeNode right;
 *     TreeNode() {}
 *     TreeNode(int val) { this.val = val; }
 *     TreeNode(int val, TreeNode left, TreeNode right) {
 *         this.val = val;
 *         this.left = left;
 *         this.right = right;
 *     }
 * }
 */
class Solution {
    public List<Integer> closestKValues(TreeNode root, double target, int k) {

    }

}

```

Python3:

```

# Definition for a binary tree node.
# class TreeNode:
#     def __init__(self, val=0, left=None, right=None):
#         self.val = val
#         self.left = left
#         self.right = right
class Solution:
    def closestKValues(self, root: Optional[TreeNode], target: float, k: int) -> List[int]:

```

Python:

```

# Definition for a binary tree node.
# class TreeNode(object):
#     def __init__(self, val=0, left=None, right=None):
#         self.val = val
#         self.left = left
#         self.right = right
class Solution(object):
    def closestKValues(self, root, target, k):

```

```

"""
:type root: Optional[TreeNode]
:type target: float
:type k: int
:rtype: List[int]
"""

```

JavaScript:

```

/**
 * Definition for a binary tree node.
 * function TreeNode(val, left, right) {
 *   this.val = (val===undefined ? 0 : val)
 *   this.left = (left===undefined ? null : left)
 *   this.right = (right===undefined ? null : right)
 * }
 */
/**
 * @param {TreeNode} root
 * @param {number} target
 * @param {number} k
 * @return {number[]}
 */
var closestKValues = function(root, target, k) {

};

```

TypeScript:

```

/**
 * Definition for a binary tree node.
 * class TreeNode {
 *   val: number
 *   left: TreeNode | null
 *   right: TreeNode | null
 *   constructor(val?: number, left?: TreeNode | null, right?: TreeNode | null)
 *   {
 *     this.val = (val===undefined ? 0 : val)
 *     this.left = (left===undefined ? null : left)
 *     this.right = (right===undefined ? null : right)
 *   }
 * }
 */

```

```

*/

function closestKValues(root: TreeNode | null, target: number, k: number):
number[] {

};

```

C#:

```

/**
 * Definition for a binary tree node.
 * public class TreeNode {
 *     public int val;
 *     public TreeNode left;
 *     public TreeNode right;
 *     public TreeNode(int val=0, TreeNode left=null, TreeNode right=null) {
 *         this.val = val;
 *         this.left = left;
 *         this.right = right;
 *     }
 * }
 */
public class Solution {
    public IList<int> ClosestKValues(TreeNode root, double target, int k) {

    }
}

```

C:

```

/**
 * Definition for a binary tree node.
 * struct TreeNode {
 *     int val;
 *     struct TreeNode *left;
 *     struct TreeNode *right;
 * };
 */
/**
 * Note: The returned array must be malloced, assume caller calls free().
 */
int* closestKValues(struct TreeNode* root, double target, int k, int*

```

```
returnSize) {

}
```

Go:

```
/**
 * Definition for a binary tree node.
 * type TreeNode struct {
 *     Val int
 *     Left *TreeNode
 *     Right *TreeNode
 * }
 */
func closestKValues(root *TreeNode, target float64, k int) []int {

}
```

Kotlin:

```
/**
 * Example:
 * var ti = TreeNode(5)
 * var v = ti.`val`
 * Definition for a binary tree node.
 * class TreeNode(var `val`: Int) {
 *     var left: TreeNode? = null
 *     var right: TreeNode? = null
 * }
 */
class Solution {
    fun closestKValues(root: TreeNode?, target: Double, k: Int): List<Int> {

    }
}
```

Swift:

```
/**
 * Definition for a binary tree node.
 * public class TreeNode {
 *     public var val: Int
 *     public var left: TreeNode?
```



```

* public var right: TreeNode?
* public init() { self.val = 0; self.left = nil; self.right = nil; }
* public init(_ val: Int) { self.val = val; self.left = nil; self.right =
nil; }
* public init(_ val: Int, _ left: TreeNode?, _ right: TreeNode?) {
* self.val = val
* self.left = left
* self.right = right
* }
* }
*/
class Solution {
func closestKValues(_ root: TreeNode?, _ target: Double, _ k: Int) -> [Int] {

}

}

```

Rust:

```

// Definition for a binary tree node.
// #[derive(Debug, PartialEq, Eq)]
// pub struct TreeNode {
//     pub val: i32,
//     pub left: Option<Rc<RefCell<TreeNode>>>,
//     pub right: Option<Rc<RefCell<TreeNode>>>,
// }
//
// impl TreeNode {
//     #[inline]
//     pub fn new(val: i32) -> Self {
//         TreeNode {
//             val,
//             left: None,
//             right: None
//         }
//     }
// }
// }
// }

use std::rc::Rc;
use std::cell::RefCell;

impl Solution {
    pub fn closest_k_values(root: Option<Rc<RefCell<TreeNode>>>, target: f64, k:
i32) -> Vec<i32> {

```

```
}  
}
```

Ruby:

```
# Definition for a binary tree node.  
# class TreeNode  
# attr_accessor :val, :left, :right  
# def initialize(val = 0, left = nil, right = nil)  
# @val = val  
# @left = left  
# @right = right  
# end  
# end  
# @param {TreeNode} root  
# @param {Float} target  
# @param {Integer} k  
# @return {Integer[]}  
def closest_k_values(root, target, k)  
  
end
```

PHP:

```
/**  
 * Definition for a binary tree node.  
 * class TreeNode {  
 * public $val = null;  
 * public $left = null;  
 * public $right = null;  
 * function __construct($val = 0, $left = null, $right = null) {  
 * $this->val = $val;  
 * $this->left = $left;  
 * $this->right = $right;  
 * }  
 * }  
 */  
class Solution {  
  
/**  
 * @param TreeNode $root
```

```

* @param Float $target
* @param Integer $k
* @return Integer[]
*/
function closestKValues($root, $target, $k) {

}
}

```

Dart:

```

/**
 * Definition for a binary tree node.
 * class TreeNode {
 *   int val;
 *   TreeNode? left;
 *   TreeNode? right;
 *   TreeNode([this.val = 0, this.left, this.right]);
 * }
 */
class Solution {
  List<int> closestKValues(TreeNode? root, double target, int k) {

  }
}

```

Scala:

```

/**
 * Definition for a binary tree node.
 * class TreeNode(_value: Int = 0, _left: TreeNode = null, _right: TreeNode =
 * null) {
 *   var value: Int = _value
 *   var left: TreeNode = _left
 *   var right: TreeNode = _right
 * }
 */
object Solution {
  def closestKValues(root: TreeNode, target: Double, k: Int): List[Int] = {

  }
}

```

Elixir:

```
# Definition for a binary tree node.
#
# defmodule TreeNode do
#   @type t :: %__MODULE__{
#     val: integer,
#     left: TreeNode.t() | nil,
#     right: TreeNode.t() | nil
#   }
#   defstruct val: 0, left: nil, right: nil
# end

defmodule Solution do
  @spec closest_k_values(root :: TreeNode.t() | nil, target :: float, k :: integer) :: [integer]
  def closest_k_values(root, target, k) do

end

end
```

Erlang:

```
%% Definition for a binary tree node.
%%
%% -record(tree_node, {val = 0 :: integer(),
%%   left = null :: 'null' | #tree_node{},
%%   right = null :: 'null' | #tree_node{}}).

-spec closest_k_values(Root :: #tree_node{} | null, Target :: float(), K :: integer()) -> [integer()].
closest_k_values(Root, Target, K) ->
.
```

Racket:

```
; Definition for a binary tree node.
#|

; val : integer?
; left : (or/c tree-node? #f)
; right : (or/c tree-node? #f)
(struct tree-node
```

```

(val left right) #:mutable #:transparent)

; constructor
(define (make-tree-node [val 0])
  (tree-node val #f #f))

|#

(define/contract (closest-k-values root target k)
  (-> (or/c tree-node? #f) flonum? exact-integer? (listof exact-integer?))
  )

```

Solutions

C++ Solution:

```

/*
 * Problem: Closest Binary Search Tree Value II
 * Difficulty: Hard
 * Tags: array, tree, search, stack, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(h) for recursion stack where h is height
 */

/**
 * Definition for a binary tree node.
 * struct TreeNode {
 *     int val;
 *     TreeNode *left;
 *     TreeNode *right;
 *     TreeNode() : val(0), left(nullptr), right(nullptr) {}
 *     TreeNode(int x) : val(x), left(nullptr), right(nullptr) {}
 *     TreeNode(int x, TreeNode *left, TreeNode *right) : val(x), left(left),
 * right(right) {}
 * };
 */
class Solution {
public:

```

```
vector<int> closestKValues(TreeNode* root, double target, int k) {

}

};
```

Java Solution:

```
/**
 * Problem: Closest Binary Search Tree Value II
 * Difficulty: Hard
 * Tags: array, tree, search, stack, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(h) for recursion stack where h is height
 */

/**
 * Definition for a binary tree node.
 * public class TreeNode {
 *     int val;
 *     TreeNode left;
 *     TreeNode right;
 *     TreeNode() {}
 *     TreeNode(int val) { this.val = val; }
 *     TreeNode(int val, TreeNode left, TreeNode right) {
 *         this.val = val;
 *         this.left = left;
 *         this.right = right;
 *     }
 * }
 */

class Solution {
    public List<Integer> closestKValues(TreeNode root, double target, int k) {

    }
}
```

Python3 Solution:

```

"""
Problem: Closest Binary Search Tree Value II
Difficulty: Hard
Tags: array, tree, search, stack, queue, heap

Approach: Use two pointers or sliding window technique
Time Complexity: O(n) or O(n log n)
Space Complexity: O(h) for recursion stack where h is height
"""

# Definition for a binary tree node.
# class TreeNode:
# def __init__(self, val=0, left=None, right=None):
# self.val = val
# self.left = left
# self.right = right
class Solution:
def closestKValues(self, root: Optional[TreeNode], target: float, k: int) ->
List[int]:
# TODO: Implement optimized solution
pass

```

Python Solution:

```

# Definition for a binary tree node.
# class TreeNode(object):
# def __init__(self, val=0, left=None, right=None):
# self.val = val
# self.left = left
# self.right = right
class Solution(object):
def closestKValues(self, root, target, k):
"""
:type root: Optional[TreeNode]
:type target: float
:type k: int
:rtype: List[int]
"""

```

JavaScript Solution:

```

/**
 * Problem: Closest Binary Search Tree Value II
 * Difficulty: Hard
 * Tags: array, tree, search, stack, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(h) for recursion stack where h is height
 */

/**
 * Definition for a binary tree node.
 * function TreeNode(val, left, right) {
 *   this.val = (val===undefined ? 0 : val)
 *   this.left = (left===undefined ? null : left)
 *   this.right = (right===undefined ? null : right)
 * }
 */

/**
 * @param {TreeNode} root
 * @param {number} target
 * @param {number} k
 * @return {number[]}
 */
var closestKValues = function(root, target, k) {

};

```

TypeScript Solution:

```

/**
 * Problem: Closest Binary Search Tree Value II
 * Difficulty: Hard
 * Tags: array, tree, search, stack, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(h) for recursion stack where h is height
 */

/**
 * Definition for a binary tree node.

```



```

* class TreeNode {
*   val: number
*   left: TreeNode | null
*   right: TreeNode | null
*   constructor(val?: number, left?: TreeNode | null, right?: TreeNode | null)
*   {
*     this.val = (val===undefined ? 0 : val)
*     this.left = (left===undefined ? null : left)
*     this.right = (right===undefined ? null : right)
*   }
* }
*/

function closestKValues(root: TreeNode | null, target: number, k: number):
number[] {

};

```

C# Solution:

```

/*
* Problem: Closest Binary Search Tree Value II
* Difficulty: Hard
* Tags: array, tree, search, stack, queue, heap
*
* Approach: Use two pointers or sliding window technique
* Time Complexity: O(n) or O(n log n)
* Space Complexity: O(h) for recursion stack where h is height
*/

/**
* Definition for a binary tree node.
* public class TreeNode {
*   public int val;
*   public TreeNode left;
*   public TreeNode right;
*   public TreeNode(int val=0, TreeNode left=null, TreeNode right=null) {
*     this.val = val;
*     this.left = left;
*     this.right = right;
*   }
* }

```

```

* }
*/
public class Solution {
public IList<int> ClosestKValues(TreeNode root, double target, int k) {

}

}

```

C Solution:

```

/*
* Problem: Closest Binary Search Tree Value II
* Difficulty: Hard
* Tags: array, tree, search, stack, queue, heap
*
* Approach: Use two pointers or sliding window technique
* Time Complexity: O(n) or O(n log n)
* Space Complexity: O(h) for recursion stack where h is height
*/

/**
* Definition for a binary tree node.
* struct TreeNode {
*   int val;
*   struct TreeNode *left;
*   struct TreeNode *right;
* };
*/

/**
* Note: The returned array must be malloced, assume caller calls free().
*/
int* closestKValues(struct TreeNode* root, double target, int k, int*
returnSize) {

}

```

Go Solution:

```

// Problem: Closest Binary Search Tree Value II
// Difficulty: Hard
// Tags: array, tree, search, stack, queue, heap

```

```
//
// Approach: Use two pointers or sliding window technique
// Time Complexity: O(n) or O(n log n)
// Space Complexity: O(h) for recursion stack where h is height

/**
 * Definition for a binary tree node.
 * type TreeNode struct {
 *     Val int
 *     Left *TreeNode
 *     Right *TreeNode
 * }
 */
func closestKValues(root *TreeNode, target float64, k int) []int {

}
```

Kotlin Solution:

```
/**
 * Example:
 * var ti = TreeNode(5)
 * var v = ti.`val`
 * Definition for a binary tree node.
 * class TreeNode(var `val`: Int) {
 *     var left: TreeNode? = null
 *     var right: TreeNode? = null
 * }
 */
class Solution {
    fun closestKValues(root: TreeNode?, target: Double, k: Int): List<Int> {

    }
}
```

Swift Solution:

```
/**
 * Definition for a binary tree node.
 * public class TreeNode {
 *     public var val: Int
```

```

* public var left: TreeNode?
* public var right: TreeNode?
* public init() { self.val = 0; self.left = nil; self.right = nil; }
* public init(_ val: Int) { self.val = val; self.left = nil; self.right =
nil; }
* public init(_ val: Int, _ left: TreeNode?, _ right: TreeNode?) {
* self.val = val
* self.left = left
* self.right = right
* }
* }
*/
class Solution {
func closestKValues(_ root: TreeNode?, _ target: Double, _ k: Int) -> [Int] {

}
}

```

Rust Solution:

```

// Problem: Closest Binary Search Tree Value II
// Difficulty: Hard
// Tags: array, tree, search, stack, queue, heap
//
// Approach: Use two pointers or sliding window technique
// Time Complexity: O(n) or O(n log n)
// Space Complexity: O(h) for recursion stack where h is height

// Definition for a binary tree node.
// #[derive(Debug, PartialEq, Eq)]
// pub struct TreeNode {
//     pub val: i32,
//     pub left: Option<Rc<RefCell<TreeNode>>>,
//     pub right: Option<Rc<RefCell<TreeNode>>>,
// }
//
// impl TreeNode {
//     #[inline]
//     pub fn new(val: i32) -> Self {
//         TreeNode {
//             val,

```

```

// left: None,
// right: None
// }
// }
// }
use std::rc::Rc;
use std::cell::RefCell;
impl Solution {
pub fn closest_k_values(root: Option<Rc<RefCell<TreeNode>>>, target: f64, k:
i32) -> Vec<i32> {

}
}

```

Ruby Solution:

```

# Definition for a binary tree node.
# class TreeNode
# attr_accessor :val, :left, :right
# def initialize(val = 0, left = nil, right = nil)
# @val = val
# @left = left
# @right = right
# end
# end
# @param {TreeNode} root
# @param {Float} target
# @param {Integer} k
# @return {Integer[]}
def closest_k_values(root, target, k)

end

```

PHP Solution:

```

/**
 * Definition for a binary tree node.
 * class TreeNode {
 * public $val = null;
 * public $left = null;
 * public $right = null;

```

```

* function __construct($val = 0, $left = null, $right = null) {
* $this->val = $val;
* $this->left = $left;
* $this->right = $right;
* }
* }
*/
class Solution {

/**
 * @param TreeNode $root
 * @param Float $target
 * @param Integer $k
 * @return Integer[]
 */
function closestKValues($root, $target, $k) {

}

}

```

Dart Solution:

```

/**
 * Definition for a binary tree node.
 * class TreeNode {
 *   int val;
 *   TreeNode? left;
 *   TreeNode? right;
 *   TreeNode([this.val = 0, this.left, this.right]);
 * }
 */
class Solution {
  List<int> closestKValues(TreeNode? root, double target, int k) {

  }

}

```

Scala Solution:

```

/**
 * Definition for a binary tree node.

```

```

* class TreeNode(_value: Int = 0, _left: TreeNode = null, _right: TreeNode =
null) {
*   var value: Int = _value
*   var left: TreeNode = _left
*   var right: TreeNode = _right
* }
*/
object Solution {
def closestKValues(root: TreeNode, target: Double, k: Int): List[Int] = {

}
}

```

Elixir Solution:

```

# Definition for a binary tree node.
#
# defmodule TreeNode do
#   @type t :: %__MODULE__{
#     val: integer,
#     left: TreeNode.t() | nil,
#     right: TreeNode.t() | nil
#   }
#   defstruct val: 0, left: nil, right: nil
# end

defmodule Solution do
  @spec closest_k_values(root :: TreeNode.t() | nil, target :: float, k ::
integer) :: [integer]
  def closest_k_values(root, target, k) do

  end
end

```

Erlang Solution:

```

%% Definition for a binary tree node.
%%
%% -record(tree_node, {val = 0 :: integer(),
%%   left = null :: 'null' | #tree_node{},
%%   right = null :: 'null' | #tree_node{}}).

```

```

-spec closest_k_values(Root :: #tree_node{} | null, Target :: float(), K ::
integer()) -> [integer()].
closest_k_values(Root, Target, K) ->
.

```

Racket Solution:

```

; Definition for a binary tree node.
#|

; val : integer?
; left : (or/c tree-node? #f)
; right : (or/c tree-node? #f)
(struct tree-node
  (val left right) #:mutable #:transparent)

; constructor
(define (make-tree-node [val 0])
  (tree-node val #f #f))

|#

(define/contract (closest-k-values root target k)
  (-> (or/c tree-node? #f) flonum? exact-integer? (listof exact-integer?))
  )

```