

Problem 973: K Closest Points to Origin

Problem Information

Difficulty: Medium

Acceptance Rate: 0.00%

Paid Only: No

Problem Description

Given an array of

points

where

$\text{points}[i] = [x$

i

, y

i

]

represents a point on the

X-Y

plane and an integer

k

, return the

k

closest points to the origin

(0, 0)

.

The distance between two points on the

X-Y

plane is the Euclidean distance (i.e.,

$\sqrt{(x$

1

$- x$

2

)

2

$+ (y$

1

$- y$

2

)

2

).

You may return the answer in

any order

. The answer is

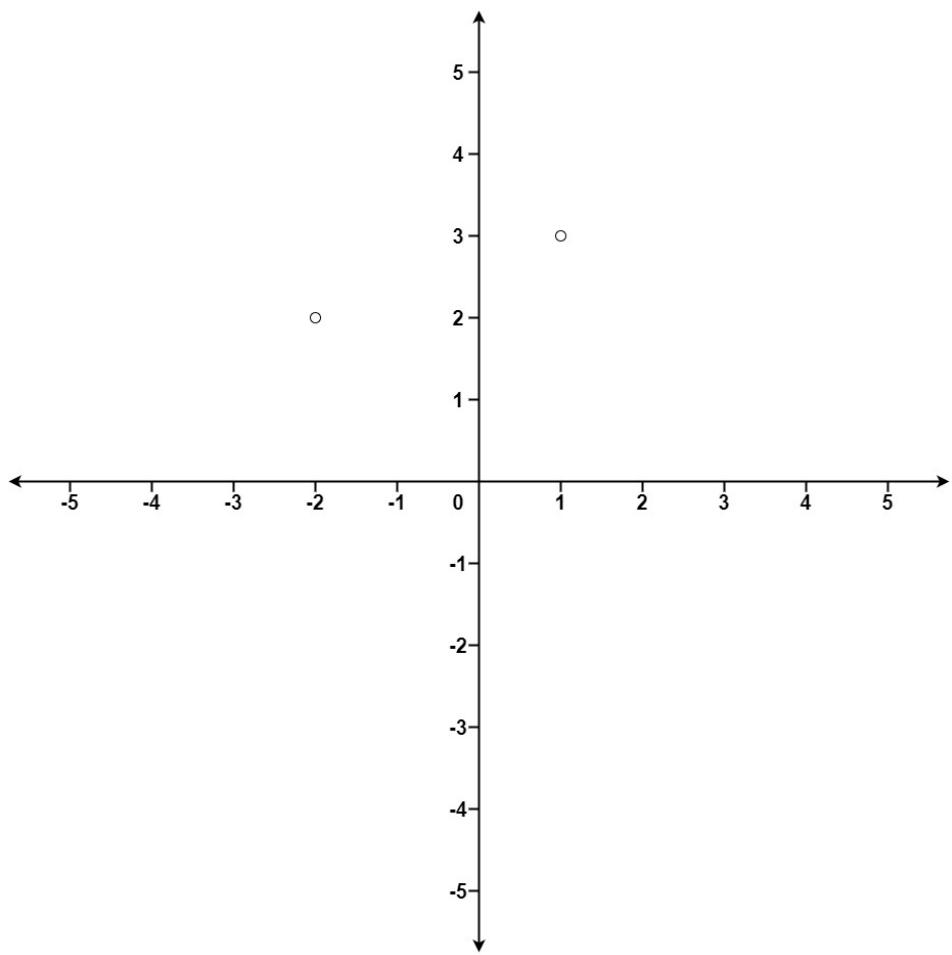
guaranteed

to be

unique

(except for the order that it is in).

Example 1:



Input:

points = [[1,3],[-2,2]], k = 1

Output:

[-2,2]

Explanation:

The distance between (1, 3) and the origin is $\sqrt{10}$. The distance between (-2, 2) and the origin is $\sqrt{8}$. Since $\sqrt{8} < \sqrt{10}$, (-2, 2) is closer to the origin. We only want the closest k = 1 points from the origin, so the answer is just [-2,2].

Example 2:

Input:

points = [[3,3],[5,-1],[-2,4]], k = 2

Output:

[3,3],[-2,4]

Explanation:

The answer [[-2,4],[3,3]] would also be accepted.

Constraints:

$1 \leq k \leq \text{points.length} \leq 10$

4

-10

4

$\leq x$

i

, y

i

<= 10

4

Code Snippets

C++:

```
class Solution {  
public:  
vector<vector<int>> kClosest(vector<vector<int>>& points, int k) {  
}  
};
```

Java:

```
class Solution {  
public int[][] kClosest(int[][] points, int k) {  
}  
}
```

Python3:

```
class Solution:  
def kClosest(self, points: List[List[int]], k: int) -> List[List[int]]:
```

Python:

```
class Solution(object):  
def kClosest(self, points, k):  
"""  
:type points: List[List[int]]  
:type k: int  
:rtype: List[List[int]]
```

```
"""
```

JavaScript:

```
/**  
 * @param {number[][]} points  
 * @param {number} k  
 * @return {number[][]}  
 */  
var kClosest = function(points, k) {  
  
};
```

TypeScript:

```
function kClosest(points: number[][], k: number): number[][] {  
  
};
```

C#:

```
public class Solution {  
    public int[][] KClosest(int[][] points, int k) {  
  
    }  
}
```

C:

```
/**  
 * Return an array of arrays of size *returnSize.  
 * The sizes of the arrays are returned as *returnColumnSizes array.  
 * Note: Both returned array and *columnSizes array must be malloced, assume  
 caller calls free().  
 */  
int** kClosest(int** points, int pointsSize, int* pointsColSize, int k, int*  
returnSize, int** returnColumnSizes) {  
  
}
```

Go:

```
func kClosest(points [][]int, k int) [][]int {  
    }  
}
```

Kotlin:

```
class Solution {  
    fun kClosest(points: Array<IntArray>, k: Int): Array<IntArray> {  
        }  
    }
```

Swift:

```
class Solution {  
    func kClosest(_ points: [[Int]], _ k: Int) -> [[Int]] {  
        }  
    }
```

Rust:

```
impl Solution {  
    pub fn k_closest(points: Vec<Vec<i32>>, k: i32) -> Vec<Vec<i32>> {  
        }  
    }
```

Ruby:

```
# @param {Integer[][]} points  
# @param {Integer} k  
# @return {Integer[][]}  
def k_closest(points, k)  
  
end
```

PHP:

```
class Solution {  
  
    /**  
     * @param Integer[][] $points
```

```
* @param Integer $k
* @return Integer[][][]
*/
function kClosest($points, $k) {

}
}
```

Dart:

```
class Solution {
List<List<int>> kClosest(List<List<int>> points, int k) {

}
```

Scala:

```
object Solution {
def kClosest(points: Array[Array[Int]], k: Int): Array[Array[Int]] = {

}
```

Elixir:

```
defmodule Solution do
@spec k_closest(points :: [[integer]], k :: integer) :: [[integer]]
def k_closest(points, k) do

end
end
```

Erlang:

```
-spec k_closest(Points :: [[integer()]], K :: integer()) -> [[integer()]].
k_closest(Points, K) ->
.
```

Racket:

```
(define/contract (k-closest points k)
(-> (listof (listof exact-integer?)) exact-integer? (listof (listof
exact-integer?)))
)
```

Solutions

C++ Solution:

```
/*
 * Problem: K Closest Points to Origin
 * Difficulty: Medium
 * Tags: array, math, sort, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(1) to O(n) depending on approach
 */

class Solution {
public:
vector<vector<int>> kClosest(vector<vector<int>>& points, int k) {

}
};
```

Java Solution:

```
/**
 * Problem: K Closest Points to Origin
 * Difficulty: Medium
 * Tags: array, math, sort, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(1) to O(n) depending on approach
 */

class Solution {
public int[][] kClosest(int[][] points, int k) {
```

```
}
```

```
}
```

Python3 Solution:

```
"""
Problem: K Closest Points to Origin
Difficulty: Medium
Tags: array, math, sort, queue, heap

Approach: Use two pointers or sliding window technique
Time Complexity: O(n) or O(n log n)
Space Complexity: O(1) to O(n) depending on approach
"""

class Solution:

    def kClosest(self, points: List[List[int]], k: int) -> List[List[int]]:
        # TODO: Implement optimized solution
        pass
```

Python Solution:

```
class Solution(object):

    def kClosest(self, points, k):
        """
:type points: List[List[int]]
:type k: int
:rtype: List[List[int]]
"""


```

JavaScript Solution:

```
/**
 * Problem: K Closest Points to Origin
 * Difficulty: Medium
 * Tags: array, math, sort, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(1) to O(n) depending on approach
 */
```

```

/**
 * @param {number[][]} points
 * @param {number} k
 * @return {number[][]}
 */
var kClosest = function(points, k) {

};

```

TypeScript Solution:

```

/**
 * Problem: K Closest Points to Origin
 * Difficulty: Medium
 * Tags: array, math, sort, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(1) to O(n) depending on approach
 */

function kClosest(points: number[][], k: number): number[][] {
}

```

C# Solution:

```

/*
 * Problem: K Closest Points to Origin
 * Difficulty: Medium
 * Tags: array, math, sort, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(1) to O(n) depending on approach
 */

public class Solution {
    public int[][] KClosest(int[][] points, int k) {

```

```
}
```

```
}
```

C Solution:

```
/*
 * Problem: K Closest Points to Origin
 * Difficulty: Medium
 * Tags: array, math, sort, queue, heap
 *
 * Approach: Use two pointers or sliding window technique
 * Time Complexity: O(n) or O(n log n)
 * Space Complexity: O(1) to O(n) depending on approach
 */

/**
 * Return an array of arrays of size *returnSize.
 * The sizes of the arrays are returned as *returnColumnSizes array.
 * Note: Both returned array and *columnSizes array must be malloced, assume
 caller calls free().
 */
int** kClosest(int** points, int pointsSize, int* pointsColSize, int k, int*
returnSize, int** returnColumnSizes) {

}
```

Go Solution:

```
// Problem: K Closest Points to Origin
// Difficulty: Medium
// Tags: array, math, sort, queue, heap
//
// Approach: Use two pointers or sliding window technique
// Time Complexity: O(n) or O(n log n)
// Space Complexity: O(1) to O(n) depending on approach

func kClosest(points [][]int, k int) [][]int {

}
```

Kotlin Solution:

```
class Solution {  
    fun kClosest(points: Array<IntArray>, k: Int): Array<IntArray> {  
        }  
        }  
}
```

Swift Solution:

```
class Solution {  
    func kClosest(_ points: [[Int]], _ k: Int) -> [[Int]] {  
        }  
        }
```

Rust Solution:

```
// Problem: K Closest Points to Origin  
// Difficulty: Medium  
// Tags: array, math, sort, queue, heap  
//  
// Approach: Use two pointers or sliding window technique  
// Time Complexity: O(n) or O(n log n)  
// Space Complexity: O(1) to O(n) depending on approach  
  
impl Solution {  
    pub fn k_closest(points: Vec<Vec<i32>>, k: i32) -> Vec<Vec<i32>> {  
        }  
        }
```

Ruby Solution:

```
# @param {Integer[][]} points  
# @param {Integer} k  
# @return {Integer[][]}  
def k_closest(points, k)  
  
end
```

PHP Solution:

```

class Solution {

    /**
     * @param Integer[][] $points
     * @param Integer $k
     * @return Integer[][]
     */
    function kClosest($points, $k) {

    }
}

```

Dart Solution:

```

class Solution {
List<List<int>> kClosest(List<List<int>> points, int k) {

}
}

```

Scala Solution:

```

object Solution {
def kClosest(points: Array[Array[Int]], k: Int): Array[Array[Int]] = {

}
}

```

Elixir Solution:

```

defmodule Solution do
@spec k_closest(points :: [[integer]], k :: integer) :: [[integer]]
def k_closest(points, k) do

end
end

```

Erlang Solution:

```

-spec k_closest(Points :: [[integer()]], K :: integer()) -> [[integer()]].
k_closest(Points, K) ->
.

```

Racket Solution:

```
(define/contract (k-closest points k)
  (-> (listof (listof exact-integer?)) exact-integer? (listof (listof
    exact-integer?)))
  )
```