

Physical Principles for Scalable Neural Recording

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“ To understand in depth what is going on in a brain, we need tools that can fit inside or between neurons and transmit reports of neural events to receivers outside. We need observing instruments that are local, nondestructive and noninvasive, with rapid response, high band-width and high spatial resolution. . . There is no law of physics that declares such an observational tool to be impossible. ”

Freeman Dyson, *Imagined Worlds*, 1997

Abstract

Simultaneously measuring the activities of all neurons in a mammalian brain at millisecond resolution is a challenge that goes beyond the limits of existing techniques in neuroscience. Entirely new approaches may be required, motivating an analysis of the fundamental physical constraints on the problem. Here, we outline the physical principles governing brain activity mapping using optical, electrical, magnetic resonance, and molecular modalities of neural recording. Focusing on the mouse brain, we analyze the scalability of each method, concentrating on the limitations imposed by spatiotemporal resolution, energy dissipation, and volume displacement. Based on this analysis, all existing approaches require orders of magnitude improvement in key parameters. Electrical recording is limited by the low multiplexing capacity of electrodes and their lack of intrinsic spatial resolution, optical methods are constrained by the scattering of visible light in brain tissue, magnetic resonance is hindered by the diffusion and relaxation timescales of the spin species, and the implementation of molecular recording is complicated by the stochastic kinetics of enzymes. Understanding the physical limits of brain activity mapping may provide insight into opportunities for novel solutions. For example, unconventional methods for delivering electrodes may enable unprecedented numbers of recording sites, embedded optical devices could allow optical detectors to be placed within a few scattering lengths of the measured neurons, and new classes of molecularly engineered sensors might obviate cumbersome hardware architectures. We also study the physics of powering and communicating with microscale devices embedded in brain tissue and find that, while radio-frequency electromagnetic data transmission suffers from a severe power-bandwidth tradeoff, communication via infrared light or via ultrasound may allow high data rates due to the possibility of spatial multiplexing. The use of an embedded local recording and wireless data transmission strategy would only be viable, however, given major improvements to the power efficiency of microelectronic neural recording devices.

1 INTRODUCTION

Progress in neuroscience depends on recording the electrical activities of neurons within functioning brains. The classical technique of electrical recording with wired electrodes has made remarkable progress: the number of simultaneously recorded neurons has doubled every seven years since the 1950s, currently allowing electrical observation of hundreds of neurons at millisecond timescales [45].

Recording techniques have recently diversified beyond their roots in electrical recording. For example, activity-dependent optical signals from neurons endowed with fluorescent indicators can be measured by photodetectors, and radio-frequency emissions from excited nuclear spins allow the construction of magnetic resonance images modulated by activity-dependent contrast mechanisms. Other methods have been proposed, including the direct recording of neural activities into information-bearing biopolymers [6, 33, 43].

Each modality of neural recording has characteristic advantages and disadvantages. Multi-electrode arrays enable the recording of ~ 250 neurons at sub-millisecond temporal resolutions. Optical microscopy can currently record $\sim 100\,000$ neurons at a 1.25 s timescale in behaving Zebrafish [1] (via light-sheet microscopy), or hundreds to thousands of neurons at a ~ 100 ms timescale in behaving mice [17] (via two-photon microscopy). Magnetic resonance imaging (MRI) allows non-invasive whole brain recordings at a 1 s timescale in humans, but is far from single neuron spatial resolution. Molecular recording devices have been proposed for scalable physiological signal recording but have not yet been demonstrated in neurons [6, 33, 43]. Figure 1 illustrates the recording modalities studied here. While further development of these methods promises to be a crucial driver for future neuroscience research, their fundamental scaling limits are not immediately obvious.

Figure 1. Four generalized neural recording modalities are studied here.

Our analysis is predicated on assumptions that enable us to estimate scaling limits. These include assumptions about basic properties of the brain, which are treated in section 2 (Basic Constraints), as well as those pertaining to the required measurement resolution and the limits to which a neural recording method may perturb brain tissue, which are treated in section 3 (Challenges for Brain Activity Mapping). Together, these considerations form the basis for our estimates of the prospects for scaling of neural recording technologies. We analyze four modalities of brain activity mapping — electrical, optical, magnetic resonance and molecular — in light of these assumptions, and conclude with discussion on opportunities for new developments.

Importantly, our assumptions, analyses and the conclusions thereof are intended as *first approximations and are subject to debate*. We anticipate that as much can be learned from where our logic breaks down as from where it succeeds, and from methods to work around the limits imposed by our assumptions.

2 BASIC CONSTRAINTS

Mouse brain The mouse brain contains $\sim 7.5 \times 10^7$ neurons in a volume of $\sim 420 \text{ mm}^3$ [59] and weighs about 0.5 g. For comparison, the human brain has roughly 8×10^{10} neurons [62] in a volume of 1200 cm^3 [101]. The human brain consumes $\sim 15 \text{ W}$ of power (performing the equivalent of roughly 10^{17} floating point computational operations on that meager power budget) [57]. Because power consumption scales approximately linearly with the number of neurons [40], the mouse brain is expected to utilize $\sim 15 \text{ mW}$ (for comparison, the metabolic rate of the $\sim 20\text{--}30 \text{ g}$ mouse is $\sim 200\text{--}600 \text{ mW}$ depending on its degree of physical activity [13]).

Neural activities Action potentials (spikes) last $\sim 2 \text{ ms}$. The average rate of neuronal spiking is $\sim 5 \text{ Hz}$ [57], but some neurons spike at 500 Hz or even faster [51]. The activities of nearby neurons can be highly correlated.

Absorption and scattering of radiation All existing methods of neural recording utilize electromagnetic waves, from the ultra-low frequencies of wired electrical recordings ($\sim 1 \text{ kHz}$) to the radio-frequencies of wireless electronics and fMRI (MHz–GHz) to visible light in optical approaches ($\sim 500 \text{ THz}$). Electromagnetic waves are attenuated in brain tissue by absorption and scattering. As an approximation to the electromagnetic absorption of brain tissue, we treat the absorption by water, the brain’s main constituent (68–80 % by mass in humans [108, 133]). At visible and IR wavelengths, there is far worse scattering than absorption: absorption lengths range from $\sim 1.5 \text{ mm}$ (blue light) to about $\sim 1 \text{ cm}$ (infrared light), while scattering lengths are in the hundreds of microns. The combined effect of absorption and scattering is measured by the attenuation length, the distance over which the signal strength is reduced by $1/e$ along a path. Figure 2 shows the absorption length of water [121], and the attenuation length in a Mie scattering simulation (from [7]) intended to approximate the scattering properties of cortical tissue. This provides an initial indication of which wavelengths can be used to measure deep-brain signals.

Figure 2. The penetration depth (attenuation length) of electromagnetic radiation in water as a function of wavelength (data from [76]). Radiation is penetrant only in the visible-to-infrared spectrum and in the long-wave RF. Black dashed line: the approximate diameter of the mouse brain. Inset: tissue scattering simulation based on Mie scattering theory and water absorption. Absorption length of water [121] (blue), simulated scattering length of cortical tissue in a simple Mie scattering model (red) and the attenuation length calculated based on these models (green) of infrared light (inset reproduced from [121], with permission).

3 CHALLENGES FOR BRAIN ACTIVITY MAPPING

Any activity mapping technology must extract the required information without disrupting normal neuronal activity. This gives rise to three primary challenges:

3.1 SPATIOTEMPORAL RESOLUTION

A sampling rate of 1 kHz is necessary to capture the fastest trains of action potentials at single-spike resolution. A minimal data rate of 7.5×10^{10} bits processed per second is required to record 1 bit per mouse neuron at 1 kHz.

In electrical recording, higher sampling rates (e.g. 10–40 kHz) are often necessary to distinguish neurons based on spike shapes when each electrode monitors multiple neurons. One bit per neuron sampling at 1 kHz would likely not be sufficient to reliably distinguish spikes above noise: transmitting ~ 10 bit samples at ~ 10 kHz (full waveform) or ~ 10 –20 bit time-stamps upon spike detection would be more realistic. On the other hand, it may be possible to locally compress measurements of a spike train before transmission. In the fly, the entropy of spike trains has been measured to be up to ~ 180 bit/s, and the information about a stimulus encoded by a spike train (mutual information) was as high as ~ 90 bit/s [115]. This would suggest that in the worst case, a compression factor of $5 \times$ – $10 \times$ should be possible, relative to a 1000 bit/s raw binary sampling. As a naïve estimate of the entropy as a function of firing rate, one can write the entropy H in bit/s, assuming 1 ms long spikes and 1000 Hz sampling rate, as

$$H \approx \left(-P_{\text{spike}} \cdot \log_2(P_{\text{spike}}) - (1 - P_{\text{spike}}) \cdot \log_2(1 - P_{\text{spike}}) \right) \cdot 1000 \text{ bit/s}$$

where P_{spike} is the probability of spiking during the sampling interval. For the average firing rate of 5 Hz, $P_{\text{spike}} = 0.005$ and $H = 45$ bit/s, corresponding to a compression factor of $\sim 20 \times$. However, at 500 Hz, $P_{\text{spike}} = 0.5$ with $H \approx 1000$ bit/s, i.e., no compressibility. Therefore, compression could conceivably reduce the data transmission burden of activity mapping by 1–2 orders of magnitude, depending on the neurons and activity regimes under consideration. Based on the above considerations, we assume 1 bit/neuron/ms or 100 Gbit/s for the entire mouse brain, as a “minimal whole brain data rate” in what follows. In many cases, this constitutes a lower bound on what will be feasible in practice.

3.2 ENERGY DISSIPATION

Brain tissue can sustain local temperature increases (ΔT) of $\sim 2^\circ\text{C}$ without severe damage [62]. Assuming that the brain is receiving a constant power influx $P_{\text{delivered}}$ and that the local thermal transport properties of mouse brains are similar to those of humans [101], we can approximate the temperature change in deep-brain tissue as a function of the applied power [7]:

$$\frac{dT}{dt} = (P_{\text{delivered}} + P_{\text{metabolic}} - \rho_{\text{blood}} C_{\text{blood}} f_{\text{blood}} \Delta T) / C_{\text{tissue}}$$

where $P_{\text{metabolic}} = 0.0116 \text{ W/g}$ is the power per unit mass of basal metabolism, $C_{\text{tissue}} \approx 3.7 \text{ J/(K g)} \approx 0.88 \cdot C_{\text{water}}$ is the specific heat capacity of brain tissue, $\rho_{\text{blood}} = 1.05 \text{ g/cm}^3$ is the density of blood, $C_{\text{blood}} = 3.9 \text{ J/(K g)}$ is the specific heat capacity of blood, $f_{\text{blood}} = 9.3 \times 10^{-9} \text{ m}^3/(\text{g s})$ is the volume flow rate of blood, and ΔT is the temperature difference between the brain tissue and the blood (at temperature 37°C). A steady-state temperature increase ($dT/dt = 0$) of 2°C corresponds to a power dissipation of $\sim 40 \text{ mW}$ per 500 mg mouse brain. Therefore, a recording technique should not dissipate more than $\sim 40 \text{ mW}$ of power in a mouse brain at steady state.

Higher power levels may be introduced transiently. According to the above equation, if a neural recorder dissipates $\sim 40 \text{ mW}$ per 500 mg mouse brain, then the brain approaches the steady-state temperature in 2–3 min, so shorter experiments may be feasible. Increasing convective heat loss from the brain by increasing blood flow (e.g. via increased heart rate) or cooling the brain, the blood, or the whole animal, could increase the allowable power dissipation. Note that radiative loss of heat from the brain was ignored here since infrared light emitted by deep-brain tissue is quickly re-absorbed by nearby tissue. We have also assumed that conductive heat loss is negligible compared to the heat extracted by blood flow.

In addition to the whole-brain steady-state power, there are limits on the acceptable power density. For radio-frequency electromagnetic radiation, the specific absorption rate (SAR) limit on the power density exposed to tissue (calibrated for $\sim 1^\circ\text{C}$ temperature change) is $\sim 10 \text{ mW/cm}^2$, while for ultrasound (which couples less strongly to dissipative loss mechanisms in tissue) the SAR limits are up to $72 \times$ higher. The power density limit for visible and near-IR light exposures are also in the ~ 10 – 100 mW/cm^2 range for

~ 1 ms long exposures, decreasing as the exposure time lengthens (based on the IEC 60825 formulas [73]). High local power dissipation (transient or steady-state) can also modify the electrical properties of excitable membranes, altering neuronal activity patterns. For example, heating of cell membranes and surrounding solution by millisecond optical pulses leads to changes in membrane electrical capacitance mediated by the ionic double layer [28]. Slower temperature changes (scale of seconds) resulting from RF radiation lead to accelerated ion channel and transporter kinetics [11]. Both of these effects are appreciable when the temperature changes are on the order of $1\text{--}10^\circ\text{C}$.

3.3 SENSITIVITY TO VOLUME DISPLACEMENT

To prevent damage to the brain, we assume that a recording technique should not introduce a brain volume change of $> 1\%$. The appropriate damage threshold is not yet established, however, so this constitutes a first guess.

The nature of the volume displacement is important — sheets of instrumentation that sever long-range connectivity, for example, would disrupt normal brain function regardless of the degree of volume displacement. Conversely, higher volume displacement might be possible if introduced during the early development of the brain, so that the brain can adapt.

4 EVALUATION OF MODALITIES

We next evaluate neural recording technologies with respect to the above challenges, using the mouse brain as a model system. Table 1 lists the modalities studied, the assumptions made, the analysis strategies applied, and the conclusions derived.

4.1 ELECTRICAL RECORDING

In the oldest strategy for neural recording, an electrode is used to measure the local voltage at a recording site, which conveys information about the spiking activity of one or more nearby neurons. The number of recording sites may be smaller than the number of neurons recorded since each recording site may detect signals from multiple neurons. Typical electrical recording techniques keep active devices such as amplifiers outside the skull and therefore do not pose a heat dissipation challenge.

4.1.1 SPATIOTEMPORAL RESOLUTION

One way to estimate the minimal number of electrodes required to record from the entire mouse brain is to extrapolate the state of the art in spike sorting. In an optimistic scenario, ~ 10 neurons per electrode may be distinguishable using current spike-sorting algorithms [28, 44, 115], although the theoretical upper bound is unknown. Indeed, most current techniques (e.g. hand-positioned tetrodes) optimize for signal separability, not for total number of recorded neurons. This scenario would necessitate $N = 7.5 \times 10^6$ electrodes to record from all mouse neurons. This could correspond to recording sites spaced on the vertices of a $\sim 200 \times 200 \times 200$ site cubic lattice with $\sim 40\text{ }\mu\text{m}$ edge length.

A more optimistic estimate, neglecting difficulties with spike sorting, derives from the maximum distance between an extracellular electrical recorder and a neuron from which it records spikes. In a first approximation, this is determined by two factors: the decay of the signal with distance from the spiking neuron and the background noise level at the recording site. In a crude approximation to signal detection theory, for one electrode to reliably detect the signal from a neuron, the size of the signal must be larger than the electrode's noise level.

The peak signals of spikes from neurons immediately adjacent to an electrode are in the $0.1\text{--}1.0\text{ mV}$ range and scales roughly as e^{-r/r_0} , where r is the distance from the cell surface and the $1/e$ falloff distance r_0 has been experimentally measured at $\sim 28\text{ }\mu\text{m}$ in both salamander retina [95] and cat cortex [117], and computed at $\sim 18\text{ }\mu\text{m}$ in a biophysically realistic simulation [75]. However, this decay is strongly influenced by its detailed geometry and the properties of the extracellular space, making analytical calculation of the decay rate difficult.

Several sources of background noise enter the recordings. Johnson noise, which arises from thermal fluctuations in the electrode, is

$$V_{\text{johnson}} = (4k_{\text{B}}T\text{ZBW})^{1/2}$$

which for physiological temperature, electrodes of impedance $Z = 0.5\text{ M}\Omega$, and 10 kHz bandwidth is $\sim 9\text{ }\mu\text{V}$. The recordings are also affected by interference from other neurons, which has been reported to exceed the Johnson noise, and is non-stationary due to changes in the cells' firing properties [111]. The noise and interference from these sources realistically produces $> 10\text{--}20\text{ }\mu\text{V}$ of voltage

Table 1. Summary of modalities, models, assumptions and conclusions

Modality	Analysis Strategy	Assumptions	Conclusions
<i>Extracellular electrical recording</i>	Compute minimal number recorders based on max distance from recorder to recorded neuron	Decay profile of extracellular voltage Approximate noise levels at recording site	Maximum recording distance $r_{\max} \approx 100\text{--}200\mu\text{m}$ from electrode to neuron measured $\sim 100\,000$ recording sites are required per mouse brain at current noise levels However, $\sim 10^7$ electrodes are required in practice to enable sorting of noisy, temporally overlapping spikes using current algorithms
<i>Implanted electrical recorders</i>	Compute power dissipation of electronic devices that digitally sample neuronal activity	Physical limit: $k_B T \ln(2)$ /bit processed, practical limit $\sim 10k_B T$ /bit Current CMOS digital circuits: $> 10^5 k_B T$ /bit	Requires at least 2–3 orders of magnitude increase in the power efficiency of electronics relative to current devices to scale to whole-brain simultaneous recordings Minimalist architectures should be developed to reduce local data processing overhead
<i>Wireless data transmission</i>	Compute tradeoff between power efficiency and channel bandwidth using information theory	Transmitter must supply enough power to overcome noise and path loss	Data transmission at optical or near-optical frequencies is necessary to achieve sufficient data rates using electromagnetic radiation. Radio-frequency (RF) electromagnetic transmission of whole-brain data would draw excessive power due to bandwidth constraints. Bandwidth cannot effectively be split over multiple independent RF channels.
<i>Optical imaging</i>	Relate the scattering and absorption lengths of optical wavelengths in brain tissue to signal-to-noise ratios for optical imaging	Approximate values of scattering and absorption lengths as a function of wavelength	Light scattering imposes severe limits on optical techniques, but strategies exist which could negate the effects of scattering, such as implantable optics, infrared fluorescence or bioluminescence, and online inversion of the scattering matrix
<i>Multi-photon optics</i>	Compute minimum total excitation light power to excite multi-photon transitions from indicators within each neuron in every imaging frame	Approximate values of multi-photon cross-sections Pulse durations similar to those currently used in multi-photon imaging	Multi-photon pulsed-laser excitation of a whole mouse brain will over-heat the brain except in very short experiments
<i>Beam scanning microscopies</i>	Calculate device and indicator parameters necessary for fast beam re-positioning and signal detection	Fast optical phase modulators could re-position beams at GHz switching rates Fluorescence lifetimes in the 0.1–1.0 ns range	Beam re-positioning time limits the speed of current systems but we are far from the physical limits of scan speed Fluorescence lifetimes of activity indicators may limit temporal resolution
<i>Magnetic resonance imaging</i>	Calculate spatial and temporal resolution of MRI based on spin relaxation times and spin diffusion	Proton MRI using tissue water Approximate values of T1 and T2 relaxation times and self-diffusion times for tissue water	To a first approximation, proton MRI is limited by the T1 relaxation time of water to ~ 100 ms temporal resolution and by the self-diffusion of water to spatial resolutions of $\sim 40\mu\text{m}$. T1 pre-mapping could allow T2 contrast on a ~ 10 ms timescale.
<i>Ultrasound</i>	Calculate spatial resolution, signal strength and bandwidth limits on ultrasound imaging	Speed of sound in brain Attenuation rate of ultrasound in brain	Attenuation of ultrasound by brain tissue and bone may be prohibitive at the ~ 100 MHz frequencies needed for single-cell resolution ultrasound imaging Ultrasound may be a viable medium for multiplexed data transmission from embedded devices
<i>Molecular recording</i>	Compute metabolic load and DNA volume for synthesis of large nucleic acid polymers Evaluate temporal resolution in simulated experiments	Polymerase biochemical parameter ranges Metabolic requirements of genome replication	Molecular recording devices fall within physical limits but their development poses major challenges in synthetic biology

fluctuations [5]. Typical current recording setups thus have signal to interference-plus-noise ratios (SINRs) of < 100 , where the SINR is defined as the ratio of the peak voltage from immediately adjacent neurons to the voltage fluctuation floor of the electrode.

Importantly, this calculation underestimates the required number of electrodes in practice, because sorting spikes from all neurons within the $6 \times 10^6 \mu\text{m}^3$ cube corresponding to a single electrode is likely to be unrealistic for several reasons. First, signals from the weakest cells are far weaker than those from the strongest cells and the signals from some cells decay much faster than others [117]. Second, because of neuronal synchronization, the local noise produced by nearby neurons may sometimes be large. Finally, with many neurons per electrode or at high firing rates, spikes from detectable neurons will often temporally overlap, making spike sorting difficult. This would be exacerbated by correlated firing patterns of nearby neurons.

4.1.2 VOLUME DISPLACEMENT

We require $< 1\%$ total volume displacement from N recorders. Wires from each electrode must make it to the surface of the brain, which implies an average length $\ell \approx 4\text{ mm}$ for the mouse brain (depending on assumptions about the wiring geometry).

As a rough approximation we consider each recorder to require a volume displacement associated with a single cylindrical wire, with length ℓ and radius r . Thus r must satisfy

$$\pi r^2 \ell N_{\text{min,rd}} < 0.01 V_{\text{brain}}$$

Using $N_{\text{min,rd}} = 110,000$ or $21,000$ recording sites and $\ell \approx 4\text{ mm}$ requires wires of radius $r_{\text{max}} \approx 8.0\text{ }\mu\text{m}$, or $3.4\text{ }\mu\text{m}$, respectively. While these dimensions are readily achievable using lithographic micro-fabrication, there would be a challenge to produce *isolated* wires of such dimensions at scale. Still, the volume constraints are unlikely to limit whole-mouse-brain electrical recording even in the most pessimistic scenario.

Figure 3 illustrates the above considerations as a function of the electrode SNR.

Figure 3. The voltage signal to interference-plus-noise ratio (SINR) at the recording site sets an approximate upper bound on the distance r_{max} between the recording site and the farthest neuron it can sense (blue). Assuming at least one electrode per cube of edge length $\sqrt{2}r_{\text{max}}$ in the mouse brain in turn limits the number of neurons per recording site (gold), the total number of recording sites (red) and the diameter of wiring consistent with $< 1\%$ total brain volume displacement (turquoise). SINR values for current recording setups are typically $< 10^2$. In practice, the number of neurons per electrode distinguishable by spike-sorting algorithms is only ~ 10 , so these curves greatly under-estimate the number of electrodes which would be required based on current spike-sorting approaches.

4.1.3 IMPLANTING ELECTRODES IN THE BRAIN

There are several technology options for introducing many electrodes into a brain. For example, flexible nanowire electrodes could be threaded through the capillary network [92]. Capillaries are present in the brain at a density of $2500\text{--}3000\text{ mm}^3$ [126], which equates to one capillary per $73\text{ }\mu\text{m}$, with each neuron lying within $\sim 200\text{ }\mu\text{m}$ of a capillary [70]. Neural tissues could be grown around pre-fabricated electrode arrays [22], or silicon probes arrays with many nano-fabricated recording sites per probe [38] could be inserted into the brain.

Mechanical forces during insertion and retraction of silicon and tungsten microelectrodes from brain tissue have been measured in rat cortex at $\sim 1\text{ mN}$ for electrodes of $\sim 25\text{ }\mu\text{m}$ radius [100]. These forces are comparable to the Euler bucking force F of a 2 mm long cylindrical tungsten rod of $5\text{ }\mu\text{m}$ radius

$$F = \frac{\pi^2 EI}{(KL)^2} \approx 1\text{ mN}$$

where $E = 411\text{ GPa}$ is the elastic modulus of tungsten, $I = (\pi/2)(5\text{ }\mu\text{m})^4$ is the area moment of inertia of the cylindrical wire cross-section, $L \approx 2\text{ mm}$ is the length of the wire, and K is the column effective length factor which depends on the boundary conditions and is set to $K = 1$ here for simplicity. This suggests that it may be possible to push structures of $< 10\text{ }\mu\text{m}$ diameter into brain tissue (see [125] for related calculations).

4.1.4 CONCLUSIONS AND FUTURE DIRECTIONS

The main challenge for electrical recordings is the large number of required recording sites. Ongoing innovations which could enable viable all-electrical recording methods include the development of highly multiplexed probes, thinner wires, smaller electrode impedances, amplifiers with lower input-referred noise levels, novel methods to implant large numbers of electrodes, multilayer lithography for routing electrical traces, spike sorting algorithms capable of handling temporally overlapping, non-independent spikes and adaptively modeling the noise, and hybrid systems integrating electrical recording with implantable optics or other methods. Furthermore, highly miniaturized embedded electronics (see the below section) could allow shorter wires, reducing volume displacement.

A caveat, however, pertains to the ability to relate the measured electrical signals to specific cells within a circuit. As the set of neurons recorded by each electrode grows to encompass a large volume around the electrode, it will become more difficult to attribute the recorded spikes to particular neurons. Furthermore, given the complex geometries of neuronal processes, it is not obvious how to determine the spatial position or layout of a neuron from its electrical signature on a nearby electrode. A given electrode will be positioned near the axons or dendrites of some neurons, and near the cell bodies of other neurons, complicating data interpretation. Until these issues can be resolved, readouts with intrinsic spatial resolving power may be more appropriate than pure electrical recording for the goal of whole-brain activity mapping (as opposed to sparsely sampling neural activities at high temporal resolutions).

4.2 OPTICAL RECORDING

Optical techniques measure activity-dependent light emissions from neurons, which typically are generated by fluorescent indicator proteins (although activity-dependent bioluminescent emissions are an emerging possibility). Note that typical optical techniques place the optical hardware outside of the brain and do not pose challenges due to volume displacement.

4.2.1 SPATIOTEMPORAL RESOLUTION

Recording all neurons requires separation of the signal from each neuron from background noise originating from other points in the brain. Epi-fluorescence microscopy focuses the detector on one plane in the specimen, while all neurons in a 3D volume are illuminated. Out-of-focus neurons then add background noise. Light sheet imaging illuminates only those neurons that are near the focal plane, reducing the amount of noise from out-of-focus neurons, and has been successfully used in transparent zebrafish brains [1]. In both traditional imaging and light sheet imaging, the focal plane is scanned through the sample to achieve signal separation and 3D coverage. Multi-photon and confocal techniques restrict the detected photons to those originating from a region of interest. In multi-photon techniques, nonlinear optical effects result in fluorescence being excited only near the focal point of the excitation laser. The detector can then integrate over all multiple-scattering paths of photons emitted from the focal volume to measure its total fluorescence. In confocal techniques only photons from the point of interest are measured due to geometric constraints (e.g., pinholes). Multi-photon and confocal techniques scan the focal spot in order to isolate the signals from different neurons. Optical techniques therefore achieve spatial resolution by multiplexing spatially (e.g., epi-fluorescence imaging) or temporally (e.g., beam scanning), and often by a combination of the two.

Single-photon, visible-light techniques, including epi-fluorescence, light sheet and confocal techniques only allow imaging to a depth defined by the scattering lengths of the relevant photons. Importantly, scattering not only causes signal attenuation, but also causes noise and impairs signal separation (e.g., by expanding width of the point spread function due to photon diffusion). The scattering length of visible light in brain tissue is $> 200 \mu\text{m}$ [7] while some wavelengths of infrared light have attenuation lengths of $\sim 500 \mu\text{m}$ (see Figure 2). Infrared light may thus pass through $\sim 1\text{--}2 \text{ mm}$ of tissue without prohibitively strong scattering [7, 66], while depths of $> 500 \mu\text{m}$ cannot easily be reached for dyes with absorption and emission peaks in the visible range. Activity dependent dyes operating in the infrared [12, 39] could thus be decisive for improvements in imaging depth.

Multi-photon techniques allow deeper penetration. Two or more infrared photons can be combined to excite a fluorophore with an excitation peak in the visible range, leading to the emission of a visible photon. Because only one neuron is illuminated at a time, all of the light emissions captured by the detector originate from the illuminated neuron, regardless of the extent of scattering of the outgoing light. Therefore, the emission pathway is limited less by scattering than by absorption and a single detector may collect a large number of scattered emission photons to obtain a sufficiently large integrated signal. Exploiting these ideas allows imaging at $> 1 \text{ mm}$ depth [7, 66] and allows multi-photon techniques to largely sidestep the signal separation challenge inasmuch as the excitation spot is sufficiently well-focused.

There are at least four options for overcoming the scattering of visible light to enable signal-separation from deep-brain neurons:

1. Infrared light can excite multi-photon fluorescence in an excitation-scanning architecture.
2. Fluorophores with both excitation and emission wavelengths in the infrared could be developed.
3. Emerging techniques based on beam shaping allow transmission of focused light through random scattering media by inverting the scattering matrix [18]. Because the scattering properties change over time, this must be done quickly, possibly faster than the imaging frame rate, necessitating high-speed wavefront modulation. This can currently be achieved with digital micro-mirror devices (DMDs), but not with phase-only spatial light modulators (SLMs) [2].
4. Light sources and/or detectors could be positioned close to the measured neurons, necessitating the use of embedded optical devices. This could be done using optical fiber [9] and/or waveguide [34, 61] technologies, which are developing rapidly. For example, single-mode fiber cables used in telecommunications can support > 1 TB/s data rates with low light loss over hundreds of kilometers.

While implanted optics might seem to require a number of implanted photodetectors, fibers or waveguide ports comparable to the number of neurons, new developments suggest ways of imaging with far fewer elements. For example, compressive sensing or ghost imaging techniques based on random mask projections [14, 29, 46, 87] might allow a smaller number of photodetectors to be used. In an illustrative case, an imaging system may be constructed simply from a single photodetector and a transmissive LCD screen presenting a series of random binary mask patterns [8], where the number of required mask patterns is much smaller than the number of image pixels due to a compressive reconstruction. Furthermore, it is possible to directly image through gradient index of refraction (GRIN) lenses [25] or optical fibers [9, 54, 90].

Hybrid techniques combining optics with other modalities may also provide new ways to overcome scattering. For example, ultrasound encoding [30], which frequency-tags light emissions emerging from a known location via a mechanical Doppler shift of the emitter [113], is powerful in that it provides a generic mechanism to sidestep problems of elastic optical scattering, but it requires distinguishing MHz frequency modulations in THz light waves (part per million frequency discrimination) and tags only a small fraction of the emitted photons.

Speed of beam scanning Multi-photon and confocal approaches rely on the serial scanning of an excitation beam across the sample. The speed of scanning microscopes is limited by beam re-positioning times ($\sim 0.1 \mu\text{s}$ for spinning disk [9, 54, 90], $\sim 3 \mu\text{s}$ for piezo-controlled linear scan mirrors, $\sim 10 \mu\text{s}$ for acousto-optic deflectors [81], ~ 8 kHz line scans for resonant galvanometer mirrors), and the fluorescence lifetimes of activity indicators (~ 1 ns). Note that $0.1 \mu\text{s}$ repositioning time for current spinning-disk confocal techniques would require 10 seconds per frame for whole mouse brain imaging with a single scanned beam: $(10^{-7} \text{ s/site}) (10^8 \text{ site/brain}) = 10 \text{ s/brain}$. There is therefore a need for a 10^4 fold improvement in beam re-positioning time and/or beam parallelization in order to achieve 1 kHz imaging frame rates for whole mouse brains. The $10 \mu\text{s}$ repositioning time for acousto-optic deflectors is set by the speed of sound in the deflector crystal, while scanning mirrors and spinning disks are limited by inertia. In principle, however, optical phase modulators could switch at GHz rates [2] and arrays of such phase modulators could arbitrarily re-shape coherent optical wavefronts to re-position beamlets. Moreover, parallelization of beamlets and detectors could allow further speedups. The speed of beam scanning is thus far from its physical limits. Fluorescence lifetimes in the 0.1–1 ns range [112] may ultimately limit the frame rates of scanning microscopies to 10–100 Hz for whole mouse brain imaging.

Diffraction Due to diffraction, a lens (or other limiting optical aperture) of a certain size is necessary to achieve a given angular resolution, and it might be hypothesized that this would be limiting factor for optical methods. However, this is not the case. To illustrate, at a depth of 10 mm we must be able to distinguish two neurons which are $10 \mu\text{m}$ apart. In the small angle approximation, we have $\theta \approx (10 \mu\text{m})/(10 \text{ mm}) \approx \lambda/D$. Therefore, using light of wavelength $\lambda \approx 1 \mu\text{m}$ requires a lens aperture D of only 1 mm. As such, it seems that diffraction is not a significant limiting factor for cellular resolution imaging, at least outside the context of microscale apertures that might find use in embedded optics approaches.

4.2.2 ENERGY DISSIPATION

Light that does not leave the brain is ultimately dissipated as heat. The total light power requirements for optical measurement of neuronal activity using fluorescent indicators depend on factors including fluorophore quantum efficiency, absorption cross-section, activity-dependent change in fluorescence, background fluorescence, labeling density, activation kinetics, detector noise, scattering and absorption lengths, and others. Unfortunately, many of these variables are unknown or highly dependent on particular experimental parameters.

A detailed analysis of photon count requirements for spike detection (in the context of calcium imaging) can be found in [15], which derived a relationship between the number of background photon counts (N_{bg}) and the required number of signal photon counts for

high fidelity spike detection given photon shot noise, scaling roughly as $N_{\text{signal}} > 3\sqrt{2N_{\text{bg}}}$, even at low absolute photon count rates. While this analysis governs the number of detected photons, the number of emitted photons will be higher due to losses. In one example using two-photon excitation, 5 % of the emitted photons were captured by the photodetector [109].

Current technology Multi-photon excitation poses a particularly severe power problem due to the high light intensities required to excite nonlinear optical processes. In typical multi-photon experiments on mice, ~ 50 mW of time-averaged laser power is used with a dwell time of $\sim 3 \mu\text{s}$ [82]. This would allow imaging ~ 300 neurons at millisecond resolution with a single scanned excitation beam. Current multi-photon imaging experiments are therefore at or near the permissible energy dissipation limit and improvements cannot come at the cost of greatly increased light power delivery.

Theoretical calculations Multi-photon experiments rely on short laser pulses with high peak light intensities at a focused excitation spot to excite nonlinear transitions [109]. This imposes an experimentally relevant physical limit: at least one excitation pulse of sufficient intensity per neuron per frame is required in order to excite multi-photon fluorescence during each frame. Assuming 1 kHz frame rate and 0.1 nJ pulses, delivering only one pulse per neuron per frame would dissipate roughly $(10^8) (1 \text{ kHz}) (0.1 \text{ nJ}) = 10 \text{ W}$ in the mouse brain, which is clearly prohibitive. As previously noted, this is a lower bound because, in general, more than one excitation pulse per neuron per frame will be required to excite detectable fluorescence (e.g., one reference reported 12 pulses per spot [109]). For three-photon excitation, the situation will be even worse as higher peak light intensities are required to excite three-photon fluorescence.

Could the single-pulse energy be reduced while maintaining efficient two-photon excitation? The number of two-photon (2P) transitions excited per fluorophore per pulse is $n_a = F^2 C / t$, where F is the number of photons per pulse per area, in units of photon/cm², C is the two-photon cross-section in units of cm⁴/s/photon, and t is the pulse duration in s. This can be expanded as

$$n_a = \left(\frac{4E (\text{NA})^2}{hc\lambda} \right)^2 \frac{C}{t}$$

where NA is the numerical aperture of the focusing optics, and λ is the stimulation wavelength. For a typical 2P experiment with 100 fs, 0.1 nJ pulses, assuming typical 2P cross section [85] of 10^{-49} cm⁴/s/photon, $\lambda = 900$ nm and NA = 1.0, $n_a \approx \frac{1}{20}$. While multiple pulses per neuron per frame are thus required to excite each fluorophore in every frame, a single pulse per neuron per frame will likely excite at least one fluorophore when there are > 20 fluorophores per excitation spot. If the single-pulse energy is reduced much further at fixed pulse duration, however, the excitation efficiency will become unacceptably low. To improve this situation, shorter pulses could be used to achieve the same excitation rate with lower pulse energy, or indicators with improved 2P or 3P cross-sections could be developed.

4.2.3 BIOLUMINESCENCE

To work around the requirement for large amounts of excitation light, bioluminescent rather than fluorescent activity indicators could be used. Consider a hypothetical activity-dependent bioluminescent indicator emitting at ~ 1700 nm (IR), in order to evade light scattering. As a crude estimate, assuming that 100 photons must be collected by the detector per neuron per 1 ms frame, and 1 % light collection efficiency by the detector relative to the emitted photons, $\sim 100 \mu\text{W}$ of emitted bioluminescent photons emissions are required for the entire mouse brain. This would be feasible from the perspective of heat dissipation. By contrast, in a 1-photon fluorescent scenario, if 100 excitation photons must be delivered into the brain to generate a single fluorescent emission photon, the power requirement becomes 10 mW, which is on the threshold of the steady-state heat dissipation limit. Therefore, bioluminescent indicators could potentially circumvent problems of heat dissipation associated with whole-brain optical imaging even in the 1-photon case.

Bioluminescence may, however, incur unacceptable metabolic costs in the regime of millisecond resolution whole mouse brain imaging. The widely used bioluminescent protein firefly luciferase is ~ 80 % efficient in converting ATP hydrolysis coupled with luciferin oxidation into photon production, yielding ~ 0.8 photons per ATP-luciferin pair consumed [136], and has ~ 90 % energetic efficiency in converting free energy to light production. Heat dissipation associated with the luciferase biochemistry itself is therefore not a significant overhead relative to the $100 \mu\text{W}$ of emitted photons calculated above. In the same scenario, however, the brain would consume $\sim 6 \times 10^8$ additional ATP molecules per minute per neuron in order to power the bioluminescence, which is within the limits of cellular aerobic respiration rates (~ 1 fmol O₂ per minute per cell [67], with ~ 30 ATP per 6 O₂, hence 3×10^9 molecules ATP synthesized per minute from ADP via glucose oxidation), but not by a large margin. Note that transient increases in metabolic rate are possible: energy dissipation more than doubles in the mouse during high physical activity [13]. Therefore, whole-brain activity-dependent bioluminescence, at speeds high enough to achieve millisecond frame rates, may be metabolically taxing for the cell but is nevertheless plausible as a light generation strategy.

4.2.4 CONCLUSIONS AND FUTURE DIRECTIONS

Scattering of visible light in the brain creates a problem of signal-separation from deep-brain neurons. Multi-photon techniques, which scan an infrared excitation beam, can work around this scattering problem. However, current multi-photon techniques applied at whole brain scale would dissipate too much power to avoid thermal damage to brain tissue. Systems (such as plasmonic nano-antennas [35]) that could locally excite multi-photon fluorescence without the need for high-energy laser pulses could conceivably ameliorate this issue. Furthermore, scanning microscopies require orders of magnitude improvement in speed or parallelization to apply to whole brains. This speed improvement may ultimately be limited by fluorescence lifetimes of the indicators. New methods besides multi-photon techniques could also work around the scattering of visible light in the brain. For example, fluorophores or bio-luminescent proteins could be developed which operate at infrared wavelengths. A compelling example from nature is the black dragonfish, which generates far red light (~ 705 nm) via a multi-step bioluminescent process (using this light to see in deep ocean waters) [127, 130]. A large set of activity indicators with distinguishable colors, generated through a combinatorial genetic recombination mechanism such as BrainBow [77], could also improve signal separation (e.g., in conjunction with static post-mortem microscopy to map between cell colors and positions). In addition, implanted optical devices, which place emitters and detectors within a few scattering lengths of the neurons being probed, could potentially obviate the negative effects of scattering and allow visible-wavelength indicators to be used without a need for multi-photon excitation.

4.3 EMBEDDED ACTIVE ELECTRONICS

The preceding sections have assumed that electrical or optical signals from the recorded neurons are shuttled out of the brain before digitization and storage, but it is also conceivable to develop embedded electronic systems that locally digitize and then store or transmit (e.g., wirelessly) measurements of the activities of nearby neurons. This could allow for shorter wires in electrical recording approaches, and for shorter light path lengths in optical recording approaches, as well as for more facile (e.g., non-surgical) delivery mechanisms for the recording hardware.

Integrated circuits have shrunk to a remarkable degree: in about 3 years, following the Moore’s law trajectory, it will likely be possible to fit the equivalent of Intel’s original 4004 micro-processor in a $10\text{ }\mu\text{m} \times 10\text{ }\mu\text{m}$ chip area. Functional wirelessly powered radio-frequency identification (RFID) chips as small as $50\text{ }\mu\text{m}$ in diameter have been developed and tags with chip-integrated antennas function at the $400\text{ }\mu\text{m}$ scale. Integrated neural sensors including analog front ends are also scaling to unprecedented form factors, e.g., a $250\text{ }\mu\text{m} \times 450\text{ }\mu\text{m}$ wireless implant (operating at ~ 1 mm range in air from a wireless power transmitter generating ~ 50 mW of transmitted power) including the antenna (with ~ 1 mm electrode shank to separate signal from ground) drawing only $2.5\text{ }\mu\text{W}$ per recording channel [3]. Note that for a single such embedded recording device, the heat dissipation constraint is set not by the device’s own dissipation ($10\text{ }\mu\text{W}$ for four recording channels) but rather by the RF specific absorption rate limit associated with the 50 mW transmit power. Remarkably, cells such as macrophages ($\sim 13\text{ }\mu\text{m}$ in size) can engulf structures up to at least $20\text{ }\mu\text{m}$ in diameter [122], suggesting possibilities for non-surgical delivery of embedded electronics to the brain.

If a large amount of local storage is used, the real-time transmission bandwidth requirements for neural recording could be significantly reduced if it is only desired to take a “snapshot” of neural activity patterns over a limited period of time. For example, flash memory, which will likely be the densest form of electronic memory storage in the near future, can store 1 Mbit of data in a device $100\text{ }\mu\text{m}$ on a side. Even denser forms of memory storage are under development and could perhaps be used in a one-time-write mode in the context of neural recording long before they become commercially viable for use as rewritable media in the consumer electronics industry.

Here we consider the power dissipation associated with such embedded electronic devices, as well as the constraints on possible methods to power them. In the next section, we describe how physics constrains the achievable data transmission rates from such devices.

4.3.1 POWER REQUIREMENTS FOR RECORDING

Any embedded system needs to process data, in preparation either for local storage or wireless transmission. Physics defines hard limits on the required power consumption associated with data processing (neglecting the possibility of reversible logic architectures [132]), arising from the entropy cost for erasing a bit of information [135]:

$$E_{\text{Landauer}} = \ln(2) k_B T \approx 3 \times 10^{-21} \text{ J/bit} \quad (\text{the Landauer limit})$$

Ambitious yet physically realistic values for beyond-CMOS logic would thus lie in the tens of $k_B T$ per bit processed. Scaling $40 k_B T/\text{bit}$ to record raw voltage waveforms at a minimal 1 kbit/s/neuron (e.g. 1 kHz sampling rate, 1 bit processed per neuron

per sample), the total power consumption for whole mouse brain recording could in principle be as low as ~ 16 nW. Thus, at the physical limits of power efficiency, implanted devices could in principle digitally buffer and locally store a complete record of a mammalian brain's activity. While this leaves $> 10^6$ -fold room for overhead due to increased data processing burden (more required bit flips per second), or energetic inefficiency of the switching device (greater dissipation per bit), realistic devices in the near-term may in fact require this much overhead, if not more. This necessitates a more detailed consideration of limiting factors for today's microelectronic devices.

In the context of electrical recording, the first step that must be performed by an embedded neural recording device is digitization of the voltage waveform. Until mV-scale switching devices are developed (see discussion below), it is necessary to amplify the ~ 10 – 100 μ V spike potential in order to drive digital switching events in downstream gates. During this sub-threshold amplification step, a CMOS (or BJT) device will dissipate static power (associated with a bias current). Importantly, in order to decrease the input-referred voltage noise of this amplification process, it is necessary to increase the bias current and hence the static power dissipation. For a simple differential transistor amplifier, the minimal bias current scales as

$$I_d = \frac{\pi}{2} \frac{4k_B T}{V_{n,\max}^2} \frac{k_B T}{q} \text{BW}$$

where $V_{n,\max}$ is the input-referred voltage noise of the amplifier and q is the electron charge. For an extracellular recording with $\text{BW} = 10$ kHz and $V_{n,\max} = 10$ μ V, this implies a minimal bias current $I_d \approx 60$ nA or a minimal static power of $(I_d V_{dd}) \approx 6 \times 10^{-8}$ W at 1 V operating voltage. Assuming 10 neurons per recording channel, we then have 7.5 million recording channels for a mouse brain, which gives a power dissipation associated with signal amplification of ~ 500 mW, which is prohibitive. Note that realistic analog front ends (which are subject to $1/f$ noise and require multiple gain stages) draw $6 \times$ – $10 \times$ greater bias current, quantified by the noise efficiency factor (NEF) [128], to achieve the same input-referred noise levels.

Local on-chip digital computation also incurs an energy cost. Current CMOS digital circuits consume 5–6 orders of magnitude [42, 47, 48, 50] more energy per switching event (~ 1 fJ/bit including charging of the wires [48]) compared to the Landauer limit (e.g., for a digital CMOS inverter, and ignoring the static power associated with the leakage current). This corresponds to a ~ 1 fF total load capacitance at 1 V operating voltage. For 100 GHz switching rates (10^8 neurons \times 1 kHz) as above, this corresponds to 0.02–0.2 mW. Realistic architectures, however, will incur overhead in the number of switching events required to store, compress and/or transmit neural signals, likely bringing the power consumption into an unacceptable range (e.g., 1000 bits processed per sample would be 200 mW here). To take a concrete example, commercial RFID tags consume ~ 10 μ W [49]. At a chip rate of 256 kbit/s with a Miller encoding of 2, this yields 7.8×10^{-11} J/bit, which is ~ 10 orders of magnitude higher than the Landauer limit. Applying current RFID technology to whole mouse brain recording at 1 kbit/s/neuron would thus draw ~ 8 W of power. Therefore, at least 2–3 orders of magnitude reduction in power consumption will be necessary in order to apply embedded electronics for whole-brain neural recording.

Until recently, the energy efficiency of digital computing has scaled on an exponential improvement curve [42]. This was a consequence of Moore's law and Dennard scaling, where both the capacitance of each transistors as well as its associated interconnect and the operating voltages were reducing with the device dimensions. Unfortunately however, issues related to device variability and the three dimensional structures needed to maintain good transistor performance in terms of on-to-off current ratio have largely stopped the reduction in effective capacitance per device; current devices are stuck at ~ 100 – 200 aF for a minimum sized transistor. Furthermore, the exponential increase in leakage current that comes along with the scaling of the threshold voltage in this scenario also eventually precluded substantial further decreases in voltage at a given performance level. Indeed, for the past several technology generations (since about 2005), CMOS devices have operated at a supply voltage of ~ 1 V. While neural processing does not demand very stringent transistor speeds and so reductions below ~ 1 V are certainly feasible, a fundamental limitation in scaling the supply voltage still remains. Specifically, CMOS has a well-defined minimum-energy per bit and an associated minimum-energy operating voltage that is defined by the tradeoff between static (leakage) and dynamic (switching) energy: as the operating voltage is decreased, the capacitive switching energy decreases, but the ratio of currents in the on and off states, $I_{\text{off}}/I_{\text{on}}$, increases exponentially, increasing the energy associated with leakage (this effect is independent of the threshold voltage in the sub-threshold regime). For practical circuits, the supply voltage that leads to this minimum energy is on the order of 300–500 mV, and thus supply voltage scaling will at most provide $3 \times$ – $10 \times$ improvement in energy over today's designs. Thus, a paradigm shift is needed to reduce power by several orders of magnitude if we are to approach the physical limits. Developing a switching device operating in the mV range, rather than the 1 V range of current transistors, would allow $(1 \text{ V}/1 \text{ mV})^2 = 10^6$ fold reduction in power consumption [50]. Electronic circuits constructed using analog techniques [114], which sometimes rely on bio-inspired computational architectures show promise for reducing energy costs by up to five orders of magnitude [68, 78, 114], depending on the nature of the computation and the required level of precision.

Figure 4 shows the power consumption per bit processed for several technology classes as well as the corresponding total power consumption required for whole brain readout, assuming a minimal whole-brain bit rate of 100 Gbit/s.

Figure 4. Energy cost of elementary operations across a variety of recording and data transmission modalities, expressed in units of the thermal energy (left axis) and as a power assuming 100 GHz switching rate (right axis). The Landauer limit of $k_B T \ln 2$ sets the minimum energy associated with a logically irreversible bit flip. The a practical limit for computation will likely lie in the tens of $k_B T$ per bit, comparable to the free energy release for hydrolysis of a single ATP molecular (or addition of a single nucleotide to DNA or RNA). The energy of a single infrared photon is $\sim 50 k_B T$. Single gates in current CMOS chips dissipate $\sim 1 \times 10^5 - 10^6 k_B T$ per switching event, including the capacitive charging of the wires interconnecting the gates (red curve). The switching energy for the gate, not including the wires, is $\sim 100\times$ lower (blue curve). The power efficiency of CMOS is on an exponential improvement trend due to the continuing miniaturization of components according to Moore's law (data re-digitized from [48]). Current RFID chips compute and communicate at $\sim 1 \times 10^9 - 10^{10} k_B T$ (> 10 pJ) per bit transmitted, while the energy per floating point operation in a 2010 laptop was $\sim 1 \times 10^{12} k_B T$. A single two-photon laser pulse at 0.1 nJ pulse energy corresponds to $\sim 1 \times 10^{10} k_B T$. For comparison, the 40 mW approximate maximal power dissipation of a neural recording, according to section 2 (Basic Constraints) above, with its equivalent per-bit energy of $\sim 1 \times 10^8 k_B T$ assuming the minimal 100 Gbit/s bit rate.

4.3.2 POWERING EMBEDDED DEVICES

Embedded systems need power, which could be supplied via electromagnetic or acoustic energy transfer, or could be harvested from the local environment in the brain.

There are two key regimes for wireless electromagnetic power transfer: non-linear device rectification and photovoltaics. If the single-photon energy is sufficient to allow electrons to move from the valence to the conduction band — that is, band gap $< h\nu/q$, where q is the electron charge, h is Planck's constant, and ν is the frequency of the photon — a photovoltaic effect can occur. Otherwise, light energy is converted to voltage by an antenna and non-linear device rectification may occur. In this regime (single photon energy much lower than the band gap), power conversion is governed by the total RF power and by the impedances of the antenna and the rectifier, rather than by the individual photon energy. For a monochromatic RF source, there is no thermodynamic or quantum limit to the RF to DC conversion efficiency, other than the resistive losses and threshold voltages for a semiconductor process. For rectification, when the input voltage to the rectifier is much higher than a semiconductor process threshold, conversion efficiencies of 85 % have been achieved [103]. At low input voltages relative to the semiconductor process threshold, efficiencies as high as 25 % and 2 μ W load have been achieved (see [78] for an analysis of low power efficiency). Ultimately, rectification improvements are dependent on the same improvements which will be needed for next-generation low-power computing: mV scale switching devices (promising research directions include tunnel FETs [41], electromechanical relays [24] and other options). Wireless power transfer also imposes range constraints due to the loss in power density with distance. For directional power transfer, placing the receiver at the edge of the transmitter's near field (the Rayleigh distance $D^2/4\lambda$ where D is the transmitter aperture) has advantages in terms of energy capture efficiency [55], whereas for omni-directional antennas it is typically advantageous to place the receiver as close as possible to the transmitter.

Alternatively, if the photon energy is above the silicon band gap ($\lambda < \frac{hc}{qV_{th}} \approx 3 \mu\text{m}$ or less for silicon), the chip is essentially acting as a photovoltaic cell. There is no thermodynamic or quantum limit to the conversion efficiency of light to DC electrical power for monochromatic sources, other than resistive losses and dark currents in the material (86 % in GaAs for example [69]). In the use of infrared light for photovoltaics, the penetration of the photons through tissue is decreased compared to radio frequencies. To supply 10 μ W (typical of current wirelessly-powered RFID chips) photovoltaically to a 10 $\mu\text{m} \times 10 \mu\text{m}$ (cell sized) chip at 34 % photovoltaic efficiency requires a light intensity of $\sim 300 \text{ kW/m}^2$ at the chip. Whole-brain illumination at this intensity would be prohibitive, although it could be supplied at localized spots. Therefore, in order to be compatible with wireless power transfer, the power dissipation of embedded electronics must be decreased by several orders of magnitude.

Piezoelectric harvesting of ultrasound energy by micro-devices is also a possibility. The efficiency of electrical harvesting of mechanical strain energy in piezoelectrics can be above 30 % for materials with high electromechanical coupling coefficients (e.g., PZT) [16, 72]. The losses in the piezoelectric transduction process are well described by models such as the KLM model [98, 134].

An alternative to wireless energy transmission is the local harvesting of biochemical energy carriers. Implanted neural recording devices could conceivably be powered by free glucose, the main energy source used by the brain itself. The theoretical

maximum thermodynamic efficiency for a fuel cell in aqueous solution is equal to that of the hydrogen fuel cell: $\Delta G^0/\Delta H^0 = 83\%$ at 25°C . Furthermore, if glucose is only oxidized to gluconic acid, the Coulombic (electron extraction) efficiency is at most 8.33% [27], which bounds the thermodynamic efficiency. The blood glucose concentration in rats has been measured at $\sim 7.6\text{ mM}$, with an extracellular glucose concentration in the brain of $\sim 2.4\text{ mM}$ [120]. A hypothetical highly miniaturized neural recorder with a device area of $25\text{ }\mu\text{m} \times 25\text{ }\mu\text{m}$ and efficiency of 80% , processing a blood flow rate of $\sim 1\text{ mm/s}$ [131] could extract $(80\%)(7.6\text{ mmol/dm}^3)(25\text{ }\mu\text{m})^2(1\text{ mm/s})(2880\text{ kJ/mol}) \approx 11\text{ }\mu\text{W}$, which is sufficient for low-power device such as RFID chips [89]. Unfortunately, current non-microbial glucose fuel cells obtain only $\sim 180\text{ }\mu\text{W/cm}^2$ peak power and $\sim 3.4\text{ }\mu\text{W/cm}^2$ steady state power [27]. Thus there is a need for 10^4 - and 10^6 -fold improvements in peak and steady state power densities, respectively, for non-microbial glucose fuel cells to power brain-embedded electronics of the complexity of today's RFID chips (or better, the corresponding decrease in power requirements for the chips, as emphasized above).

4.3.3 CONCLUSIONS AND FUTURE DIRECTIONS

The power consumption of today's microelectronic devices is more than 6 orders of magnitude higher than the physical limit for irreversible computing, and 2–3 orders of magnitude higher than would be permissible for use in whole brain millisecond resolution activity mapping, even under favorable assumptions on the required switching rates and neglecting both the much higher powers associated with noise rejection in the analog front end and the CMOS leakage current. Thus, the first priority is to reduce the power consumption associated with embedded electronics. In principle, methods such as photovoltaics using infrared light, RF harvesting via diode rectification, or glucose fuel cells, could supply power to embedded neural recorders, but again, significant improvements in the power efficiency of electronics are necessary to enable this. Other potential energy harvesting strategies include or materials/enzymes harnessing local biological gradients such in voltage, osmolarity, or temperature. An analysis of the energy transduction potential of each of these systems is beyond the scope of this discussion. Fortunately, with many orders of magnitude potential for improvement, we can expect that embedded nano-electronic devices will emerge as an energetically viable neural interfacing option at some point in the future.

4.4 EMBEDDED DEVICES: INFORMATION THEORY

«to be completed»

4.4.1 POWER REQUIREMENTS FOR SINGLE-CHANNEL DATA TRANSMISSION

«to be completed»

4.4.2 SPATIALLY MULTIPLEXED DATA TRANSMISSION

«to be completed»

4.4.3 ULTRASOUND AS A DATA TRANSMISSION MODALITY

«to be completed»

4.4.4 CONCLUSIONS AND FUTURE DIRECTIONS

«to be completed»

4.5 MAGNETIC RESONANCE IMAGING

«to be completed»

4.5.1 SPATIOTEMPORAL RESOLUTION

«to be completed»

4.5.2 ENERGY DISSIPATION

«to be completed»

4.5.3 IMAGING AGENTS

«to be completed»

4.6 MOLECULAR RECORDING

«to be completed»

4.6.1 SPATIOTEMPORAL RESOLUTION

«to be completed»

4.6.2 ENERGY DISSIPATION

«to be completed»

4.6.3 VOLUME DISPLACEMENT

«to be completed»

4.6.4 CONCLUSIONS AND FUTURE DIRECTIONS

«to be completed»

5 DISCUSSION

«to be completed»

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