

# Quick introduction to probability and statistics

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## 1 Probability theory

Probability theory studies randomness in a rigorous mathematical fashion. The following notions are the key concepts in probability theory:

- Probability space  $\Omega$  — describes possible outcomes we can expect while studying a random phenomena;
- Probability measure — describes how probable a specific random outcome;
- Random variable — a quantity whose value is random;
- Distribution function — a function that describes how probable a specific value is for a given random variable
- Expected value — an average value of a random variable;
- Variance — a quantity describing volatility of a random variable.

### 1.1 Probability space

We shall discuss all these notions, give definitions and list their properties.

**Definition 1.1.1** *Probability space is a triple  $(\Omega, \mathcal{F}, \mathbb{P})$ , where*

- $\Omega$  is a set of all elementary events;
- $\mathcal{F} \subset 2^\Omega$  is a family of set representing events we are interested in;
- $\mathbb{P}$  is a probability measure  $\mathbb{P} : \mathcal{F} \rightarrow [0, 1]$ .

*The family  $\mathcal{F}$  has the following properties*

- $\emptyset \in \mathcal{F}$ , that is we always can speak of the event that definitely will not happen;
- if  $A \in \mathcal{F}$ , then  $\Omega \setminus A \in \mathcal{F}$ , that is if an event  $A$  happens, then we can reason about the opposite event, that  $A$  didn't happen;
- if  $(A_n)_{n=1}^\infty \subset \mathcal{F}$ , then  $\bigcup_{i=1}^\infty A_n \in \mathcal{F}$ , that is if we have an infinite sequence of events  $(A_n)_{n=1}^\infty$  we can speak of the event that at least one event  $A_n$  happened.

*The function  $\mathbb{P}$  must satisfy equations*

- $\mathbb{P}(\Omega) = 1$
- for any family  $(A_n)_{n=1}^\infty \subset \mathcal{F}$  such that  $A_n \cap A_m = \emptyset$  for  $n \neq m$  holds

$$\mathbb{P}\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} \mathbb{P}(A_n)$$

Any single element  $\{\omega\} \in \Omega$  is called an elementary event.

**Remark 1.1.2** *As a consequence*

$$\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B)$$

whenever  $A, B \in \mathcal{F}$  and  $A \cap B = \emptyset$ . In general

$$\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B)$$

**Example 1.1.3** *Consider an experiment where we toss a dice once. Then  $\Omega = \{1, 2, 3, 4, 5, 6\}$ . Elementary events:  $\{1\}, \{2\}, \dots, \{6\}$ . An event — any subset of  $\Omega$ , e.g.  $\{1, 4, 5\}$ .*

**Example 1.1.4** *Consider an experiment where we toss a coin once. Then  $\Omega = \{H, T\}$ ,  $\mathcal{F}$  — all subsets of  $\Omega$  and  $\mathbb{P}(\{H\}) = 1/2$ ,  $\mathbb{P}(\{T\}) = 1/2$*

**Example 1.1.5** *Consider an experiment where we toss a coin twice. Then define we can define a probability space as follows  $\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$ ,  $\mathcal{F}$  — all subset of  $\Omega$  and*

$$\mathbb{P}(\{(H, H)\}) = \mathbb{P}(\{(H, T)\}) = \mathbb{P}(\{(T, H)\}) = \mathbb{P}(\{(T, T)\}) = 1/4.$$

**Example 1.1.6** *Throwing a dot on a segment. Let  $\Omega = [0, 1]$ ,  $\mathcal{F}$  is a set of Borel subset of  $\Omega$  (it is quite complicated, so you can think that  $\mathcal{F}$  contains almost any subset of  $\Omega$ ). Finally, let  $\mathbb{P}(A) = \text{length}(A)$ . If  $A = [0.2, 0.4]$ , then  $\mathbb{P}(A) = 0.2$ . If  $B = [0.7, 0.8]$ , then  $\mathbb{P}(B) = 0.1$  and  $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) = 0.3$*

**Definition 1.1.7** *Two events  $A, B \subset \Omega$  are called independent if*

$$\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B)$$

This mathematical definition of independent events is consistent with our usual understanding of independent events.

**Example 1.1.8** *Tossing a coin twice. Let  $A$  denote the event that first toss gave tails, and  $B$  denote the event that second toss gave heads. Then*

$$A = \{(T, H), (T, T)\}, \quad B = \{(T, H), (H, H)\}, \quad A \cap B = \{(T, H)\},$$

$$\mathbb{P}(A) = \frac{1}{4} + \frac{1}{4} = \frac{1}{2}, \quad \mathbb{P}(B) = \frac{1}{4} + \frac{1}{4} = \frac{1}{2}, \quad \mathbb{P}(A \cap B) = \frac{1}{4}$$

As we see  $A$  and  $B$  are independent in usual sense and  $\mathbb{P}(A \cap B) = \mathbb{P}(A) \cdot \mathbb{P}(B)$ .

**Definition 1.1.9** *Events  $A_1, \dots, A_n$  are called independent if*

$$\mathbb{P}(A_{i_1} \cap \dots \cap A_{i_m}) = \mathbb{P}(A_{i_1}) \cdot \dots \cdot \mathbb{P}(A_{i_m})$$

for any  $\{i_1, \dots, i_m\} \subset \{1, \dots, n\}$

**Definition 1.1.10** *Let  $A$  and  $B$  be two events and  $\mathbb{P}(B) \neq 0$ , then the conditional probability of  $A$  given  $B$  is defined by*

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}$$

**Example 1.1.11** *Conditional probability measures how probable the event  $A$  is given that event  $B$  already happened. For example, consider experiment where we toss a coin twice. Then  $\Omega = \{(H, H), (H, T), (T, H), (T, T)\}$ . Let  $A$  be the event that after two tosses we got two different outcomes, and let  $B$  be the event that there was at first toss we got head. In this case*

$$A = \{(H, T), (T, H)\} \quad B = \{(H, T), (H, H)\}$$

Then

$$\begin{aligned} \mathbb{P}(A) &= \mathbb{P}(\{(H, T), (T, H)\}) = \frac{1}{2} & \mathbb{P}(B) &= \mathbb{P}(\{(H, T), (H, H)\}) = \frac{1}{2} \\ \mathbb{P}(A \cap B) &= \mathbb{P}(\{(H, T)\}) = \frac{1}{4} & \mathbb{P}(A|B) &= \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{\frac{1}{4}}{\frac{1}{2}} = \frac{1}{2} \end{aligned}$$

**Remark 1.1.12** *If  $A$  and  $B$  are independent events and  $\mathbb{P}(B) \neq 0$ , then*

$$\mathbb{P}(A|B) = \mathbb{P}(A)$$

Indeed,

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(A)\mathbb{P}(B)}{\mathbb{P}(B)} = \mathbb{P}(A)$$

## 1.2 Random variables

**Definition 1.2.1** *A random variable is a function  $X : \Omega \rightarrow \mathbb{R}$  on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , such that for any  $c \in \mathbb{R}$ , the set  $\{\omega \in \Omega : X(\omega) < c\}$  lies in  $\mathcal{F}$ .*

**Example 1.2.2** *Let  $A$  be any event in a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . Then the function*

$$1_A : \Omega \rightarrow \mathbb{R} : \omega \rightarrow \begin{cases} 1 & \text{if } \omega \in A \\ 0 & \text{if } \omega \notin A \end{cases}$$

*is called the indicator function of  $A$ .*

**Example 1.2.3** *Consider an experiment where we toss a dice once. Then*

$$X : \Omega \rightarrow \mathbb{R} : \omega \rightarrow \omega + 10$$

*is a random variable.*

**Example 1.2.4** *Suppose we are tossing a coin. With probability  $p$  we get tails and we set  $X = 1$ , otherwise we set  $X = 0$ . This random variable is called the Bernoulli random variable. We denote this fact as  $X \sim \text{Ber}(p)$ .*

**Example 1.2.5** *Suppose we are tossing a coin  $n$  times. If  $X$  is the numbers of tails after  $n$  tosses, we say that  $X$  is binomial random variable. We write this fact as  $X \sim \text{Bin}(n, p)$ . Clearly  $X$  can be represented as a sum of  $n$  Bernoulli random variables  $X_1, \dots, X_n$ , i.e.  $X = X_1 + \dots + X_n$ . Indeed, just pick  $X_i = 1$  if we got tails at  $i$ -th toss and  $X_i = 0$  if we got head at  $i$ -th toss.*

**Example 1.2.6** Let  $\Omega$  be a unit square (i.e.  $\Omega = [0, 1] \times [0, 1]$ ), let  $\mathbb{P}(A) = \text{area}(A)$ . Then

$$X : \Omega \rightarrow \mathbb{R} : (x, y) \mapsto \sqrt{x^2 + y^2}$$

is a random variable.

**Definition 1.2.7** If  $X : \Omega \rightarrow \mathbb{R}$  is a random variable and  $A$  is some subset of real numbers then

$$\{X \in A\} = \{\omega \in \Omega : X(\omega) \in A\}$$

In particular, for a real number  $a \in \mathbb{R}$  we have

$$\{X = a\} = \{\omega \in \Omega : X(\omega) = a\}$$

**Definition 1.2.8** Two random variables  $X : \Omega \rightarrow \mathbb{R}$  and  $Y : \Omega \rightarrow \mathbb{R}$  are called independent if events

$$\{X \in A\}, \quad \{Y \in B\}$$

are independent for any  $A, B \in \mathcal{F}$ .

This definition of independence is consistent with usual understanding of independent random quantities. Checking by definition that two random variables are independent is tedious. Usually it is clear from the context of the problem being solved that two random variables are independent.

**Definition 1.2.9** Random variables  $X_1, \dots, X_n$  are called independent if events

$$\{X_{i_1} \in A_1\}, \dots, \{X_{i_m} \in A_m\}$$

are independent for any  $\{i_1, \dots, i_m\} \subset \{1, \dots, n\}$  and any  $A_1, \dots, A_m \in \mathcal{F}$ .

### 1.3 Distributions of random variables

**Definition 1.3.1** Cumulative density function is a function defined by

$$F_X : \mathbb{R} \rightarrow [0, 1] : t \mapsto \mathbb{P}(X \leq t)$$

**Example 1.3.2** Tossing a coin twice. Again  $\Omega = \{(i, j), i, j \in \{1, \dots, 6\}\}$ ,  $\mathbb{P}((i, j)) = \frac{1}{36}$  for all  $(i, j) \in \Omega$ . Again consider random variable

$$X : \Omega \rightarrow \mathbb{R} : (i, j) \mapsto i + j$$

Now we shall compute  $F_X$  for all  $t \in \mathbb{R}$ .

$$F_X(t) = \begin{cases} 0 & \text{if } t < 2 \\ \mathbb{P}(X = 2) & \text{if } 2 \leq t < 3 \\ \mathbb{P}(X = 2) + \mathbb{P}(X = 3) & \text{if } 3 \leq t < 4 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 4) & \text{if } 4 \leq t < 5 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 5) & \text{if } 5 \leq t < 6 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 6) & \text{if } 6 \leq t < 7 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 7) & \text{if } 7 \leq t < 8 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 8) & \text{if } 8 \leq t < 9 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 9) & \text{if } 9 \leq t < 10 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 10) & \text{if } 10 \leq t < 11 \\ \mathbb{P}(X = 2) + \dots + \mathbb{P}(X = 11) & \text{if } 11 \leq t < 12 \\ 1 & \text{if } 12 \leq t \end{cases} = \begin{cases} 0 & \text{if } t < 2 \\ \frac{1}{36} & \text{if } 2 \leq t < 3 \\ \frac{3}{36} & \text{if } 3 \leq t < 4 \\ \frac{6}{36} & \text{if } 4 \leq t < 5 \\ \frac{10}{36} & \text{if } 5 \leq t < 6 \\ \frac{15}{36} & \text{if } 6 \leq t < 7 \\ \frac{21}{36} & \text{if } 7 \leq t < 8 \\ \frac{26}{36} & \text{if } 8 \leq t < 9 \\ \frac{30}{36} & \text{if } 9 \leq t < 10 \\ \frac{33}{36} & \text{if } 10 \leq t < 11 \\ \frac{35}{36} & \text{if } 11 \leq t < 12 \\ 1 & \text{if } 12 \leq t \end{cases}$$

**Example 1.3.3** Consider an experiment where we drop a dot on a line. Let  $\Omega = [0, 1]$ ,  $\mathbb{P}(A) = \text{length}(A)$  and

$$X : \Omega \rightarrow \mathbb{R} : \omega \mapsto \omega$$

We shall compute  $F_X$  for all  $t \in \mathbb{R}$

$$\begin{aligned} F_X(t) &= \mathbb{P}(X \leq t) = \mathbb{P}(\{\omega \in \Omega : X(\omega) \leq t\}) = \mathbb{P}(\{\omega \in [0, 1] : \omega \leq t\}) \\ &= \begin{cases} \text{length}(\emptyset) & t < 0 \\ \text{length}([0, t]) & 0 \leq t \leq 1 \\ \text{length}([0, 1]) & 1 < t \end{cases} = \begin{cases} 0 & t < 0 \\ t & 0 \leq t \leq 1 \\ 1 & 1 < t \end{cases} \end{aligned}$$

From these examples we see that  $F_X$  is always a non-decreasing function. If  $X$  attains only finitely many values, then  $F_X$  has discontinuities, and  $X$  is called a discrete random variable. If  $F_X$  is continuous, then  $X$  is called a continuous random variable.

**Definition 1.3.4** Probability density function is a function defined by

- $f_X : \mathbb{R} \rightarrow [0, 1] : t \mapsto \mathbb{P}(X = t)$  if  $X$  is discrete;
- $f_X : \mathbb{R} \rightarrow \mathbb{R} : t \mapsto F'_X(t)$  if  $X$  is continuous.

**Theorem 1.3.5** If  $X$  is a continuous random variable, then

$$F_X(t) = \int_{-\infty}^t f_X(s) ds$$

**Example 1.3.6** Consider an experiment where we toss a dice twice. Define  $\Omega = \{(i, j), i, j \in \{1, \dots, 6\}\}$ ,  $\mathbb{P}((i, j)) = \frac{1}{36}$  for all  $(i, j) \in \Omega$ . Consider a random variable

$$X : \Omega \rightarrow \mathbb{R} : (i, j) \mapsto i + j$$

Now we shall compute  $f_X$  for reasonable values of  $X$ . That is for  $t \in \{2, 3, \dots, 12\}$

$$f_X(2) = \mathbb{P}(X = 2) = \mathbb{P}(\{(1, 1)\}) = \frac{1}{36}$$

$$f_X(3) = \mathbb{P}(X = 3) = \mathbb{P}(\{(1, 2), (2, 1)\}) = \frac{2}{36}$$

$$f_X(4) = \mathbb{P}(X = 4) = \mathbb{P}(\{(1, 3), (3, 1), (2, 2)\}) = \frac{3}{36}$$

...

After careful gazing we get

$$f_X(k) = \begin{cases} \frac{6-|k-7|}{36} & \text{if } k \in \{2, \dots, 12\} \\ 0 & \text{otherwise} \end{cases}$$

**Example 1.3.7** Consider an experiment where we drop a dot on a line. Let  $\Omega = [0, 1]$ ,  $\mathbb{P}(A) = \text{length}(A)$  and

$$X : \Omega \rightarrow \mathbb{R} : \omega \mapsto \omega$$

We shall compute  $f_X$  for all  $t \in \mathbb{R}$

$$f_X(t) = F'_X(t) = \begin{cases} 0' & t < 0 \\ t' & 0 \leq t \leq 1 \\ 1' & 1 < t \end{cases} = \begin{cases} 0 & t < 0 \\ 1 & 0 \leq t \leq 1 \\ 0 & 1 < t \end{cases}$$

**Example 1.3.8 (Uniform distribution)** We say that a random variable is uniformly distributed on a segment  $[a, b]$  if it has probability density function of the form

$$f_X(t) = \begin{cases} \frac{1}{b-a} & \text{if } t \in [a, b] \\ 0 & \text{if } t \notin [a, b] \end{cases}$$

We express this fact as  $X \sim \text{Unif}(a, b)$

The following example is central to the whole theory

**Definition 1.3.9 (Normal distribution)** A random variable  $X$  is called normal if it has probability density function of the form

$$f_X(t) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(t-\mu)^2}{2\sigma^2}}$$

In this case we shall write  $X \sim \text{Norm}(\mu, \sigma^2)$ .

**Remark 1.3.10** Consider function

$$\Phi(t) = \int_{-\infty}^t \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt$$

then for any  $X$  with normal distribution with parameters  $\mu, \sigma$  we have

$$F_X(t) = \Phi\left(\frac{t-\mu}{\sigma}\right)$$

In other words  $\Phi$  is the cumulative density function of the normal random variable with parameters  $\mu = 0, \sigma^2 = 1$ . Normal random variables with such parameters are called standard normal random variables.

Later we shall discuss the meaning of parameters  $\mu$  and  $\sigma$ .

**Example 1.3.11 (Binomial distribution)** Let  $X$  be a binomial random variable with parameters  $n$  and  $p$ . In other words  $X$  is a number of tails after  $n$  tosses of coin such that at each toss tails have probability  $p$ . Clearly  $X$  attains values  $\{0, \dots, n\}$ . We shall compute  $f_X(k)$  for  $k \in \{0, \dots, n\}$ . By definition  $f_X(k) = \mathbb{P}(X = k)$ . An event  $\{X = k\}$  consist of some number elementary events  $\{\omega_1, \dots, \omega_N\}$ . The number  $N$  of these elementary events equals the number of ways

to pick  $k$  tosses out of  $n$  tosses that will end up with tails. This is a standard fact from combinatorics, that the latter number is  $\binom{n}{k}$ . Each elementary event  $\omega_i$  corresponds to the series of tosses with exactly  $k$  tails and  $n - k$  heads, so  $\mathbb{P}(\{\omega_i\}) = p^k(1 - p)^{n-k}$ . Thus

$$\begin{aligned} f_X(k) &= \mathbb{P}(X = k) \\ &= \mathbb{P}(\{\omega_1, \dots, \omega_N\}) \\ &= \mathbb{P}(\{\omega_1\}) + \dots + \mathbb{P}(\{\omega_N\}) \\ &= p^k(1 - p)^{n-k} + \dots + p^k(1 - p)^{n-k} \\ &= \binom{n}{k} p^k(1 - p)^{n-k} \end{aligned}$$

**Definition 1.3.12 (Poisson distribution)** Let  $X$  be a discrete random variable with probability density function defined by

$$f_X(k) = \frac{\lambda^k}{k!} e^{-\lambda}$$

then we say that  $X$  is Poisson random variable with parameter  $\lambda$ . We denote this fact as  $X \sim \text{Pois}(\lambda)$ .

## 1.4 Quantiles of random variables

**Definition 1.4.1** An  $\alpha$ -quantile of a random variable  $X$  is the smallest number  $q$  such that

$$\mathbb{P}(X \leq q) \geq \alpha$$

In other words this is the smallest number  $q$  such that  $F_X(q) \geq \alpha$ . Notation:  $q_\alpha(X)$ .

Put differently  $q_\alpha(X)$  is the smallest value  $q$  such that at least  $100\alpha$  percent of the values of  $X$  are less than  $q$ .

**Example 1.4.2** Tossing a coin twice. Again  $\Omega = \{(i, j), i, j \in \{1, \dots, 6\}\}$ ,  $\mathbb{P}(\{(i, j)\}) = \frac{1}{36}$  for all  $(i, j) \in \Omega$ . Again consider a random variable

$$X : \Omega \rightarrow \mathbb{R} : (i, j) \mapsto i + j$$

Then  $q_{0.25}(X) = 4$  because 25 percent of the values are less than 4 and 4 is the smallest possible constant here.

Notation:

- $q_{0.25}(X)$  — first quartile of  $X$
- $q_{0.50}(X)$  — second quartile of  $X$  or median of  $X$
- $q_{0.75}(X)$  — third quartile of  $X$

Question: Find the median value of the total score after tossing two cubes. Find the 0.99 quantile.

**Remark 1.4.3** If  $X$  is a continuous random variable, then  $q_\alpha(X)$  is a (necessarily unique) root of the equation  $F_X(q) = \alpha$ .

**Example 1.4.4** *Dropping a dot on a line. Let  $\Omega = [0, 1]$ ,  $\mathbb{P}(A) = \text{length}(A)$  and*

$$X : \Omega \rightarrow \mathbb{R} : \omega \mapsto \omega$$

*As we already know*

$$F_X(t) = \begin{cases} 0 & t < 0 \\ t & 0 \leq t \leq 1 \\ 1 & 1 < t \end{cases}$$

*Since  $X$  is a continuous random variable  $q_{0.25}(X)$ , is a root of the equation  $F_X(q) = 0.25$ . Clearly,  $q=0.25$ , so  $q_{0.25}(X) = 0.25$ .*

## 1.5 Expected value of a random variable

**Definition 1.5.1** *Expected value of a random variable  $X$  is a number*

- $\mathbb{E}[X] = \sum_{k \in \mathcal{X}} k\mathbb{P}(X = k)$  if  $X$  is discrete ( $\mathcal{X}$  is the set of values attained by  $X$ );
- $\mathbb{E}[X] = \int_{-\infty}^{+\infty} t f_X(t) dt$  if  $X$  is continuous;

*Another notation for expected value is  $m_X$ .*

Simply speaking expected value of a random variable is an average value of that variable.

**Example 1.5.2** *Tossing a coin twice. Again  $\Omega = \{(i, j), i, j \in \{1, \dots, 6\}\}$ ,  $\mathbb{P}((i, j)) = \frac{1}{36}$  for all  $(i, j) \in \Omega$ . Again consider random variable*

$$X : \Omega \rightarrow \mathbb{R} : (i, j) \mapsto i + j$$

*Then  $\mathcal{X} = \{2, 3, \dots, 12\}$ . Therefore*

$$\mathbb{E}[X] = 2 \cdot \mathbb{P}(X = 2) + 3\mathbb{P}(X = 3) + \dots + 12\mathbb{P}(X = 12) = 7$$

**Example 1.5.3** *Let  $X$  be a Bernoulli random variable with parameter  $p$ . Then  $\mathcal{X} = \{0, 1\}$ , so*

$$\mathbb{E}[X] = 0 \cdot \mathbb{P}(X = 0) + 1 \cdot \mathbb{P}(X = 1) = 0 \cdot (1 - p) + 1 \cdot p = p$$

**Example 1.5.4** *Let  $X$  be a normal random variable with parameters  $\mu$  and  $\sigma$ . Then*

$$\mathbb{E}[X] = \int_{-\infty}^{+\infty} t f_X(t) dt = \int_{-\infty}^{+\infty} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(t-\mu)^2}{2\sigma^2}} dt = \dots = \mu$$

*Thus parameter  $\mu$  in the normal distribution is the average value of the random variable.*

**Theorem 1.5.5** *Suppose we are given two random variables  $X$  and  $Y$ , then*

$$\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y]$$

*Even more if  $a$  and  $b$  — real numbers, then*

$$\mathbb{E}[aX + bY] = a\mathbb{E}[X] + b\mathbb{E}[Y]$$



**Theorem 1.5.6** If  $X$  and  $Y$  are two independent random variables then

$$\mathbb{E}[XY] = \mathbb{E}[X] \cdot \mathbb{E}[Y]$$

**Example 1.5.7** Let  $X$  be a binomial random variable with parameters  $n$  and  $p$ . Then  $X$  can be represented as sum of  $n$  Bernoulli random variables  $X_1, \dots, X_n$ , i.e.  $X = X_1 + \dots + X_n$ . From previous example we know that  $\mathbb{E}[X_1] = \dots = \mathbb{E}[X_n] = p$ . Therefore

$$\mathbb{E}[X] = \mathbb{E}[X_1 + \dots + X_n] = \mathbb{E}[X_1] + \dots + \mathbb{E}[X_n] = p + \dots + p = np$$

**Theorem 1.5.8 (Law of the unconscious statistician, a.k.a. LOTUS)** Let  $X$  be a random variable and  $g : \mathbb{R} \rightarrow \mathbb{R}$  be any function, then

- $\mathbb{E}[g(X)] = \sum_{k \in \mathcal{X}} g(k) \mathbb{P}(X = k)$  if  $X$  is discrete ( $\mathcal{X}$  — values attained by  $X$ );
- $\mathbb{E}[g(X)] = \int_{-\infty}^{+\infty} g(t) f_X(t) dt$  if  $X$  is continuous.

**Example 1.5.9** Let  $X$  be a Bernoulli random variable with parameter  $p$ . Then  $\mathcal{X} = 0, 1$  and by the LOTUS

$$\mathbb{E}[X^2] = 0^2 \cdot \mathbb{P}(X = 0) + 1^2 \cdot \mathbb{P}(X = 1) = 0^2 \cdot (1 - p) + 1^2 \cdot p = p$$

## 1.6 Variance and standard deviation of a random variable

**Definition 1.6.1** Variance of a random variable  $X$  is the expected value of the random variable  $(X - \mathbb{E}[X])^2$ . In other words

$$\mathbb{V}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2]$$

**Remark 1.6.2** One can show that

$$\mathbb{V}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2$$

If  $X$  is a continuous random variable, then

$$\mathbb{V}[X] = \int_{-\infty}^{+\infty} (t - \mathbb{E}[X])^2 f_X(t) dt = \int_{-\infty}^{+\infty} t^2 f_X(t) dt - \left( \int_{-\infty}^{+\infty} t f_X(t) dt \right)^2$$

Variance shows how volatile values of  $X$  are. Variance shows how much they are different from the expected value. In practice it is more convenient to work with another quantity called the standard deviation. This characteristic has the advantage that it is measured in the same units as the expected value.

**Definition 1.6.3** The standard deviation of a random variable  $X$  is defined as

$$s_X = \sqrt{\mathbb{V}[X]}$$

**Example 1.6.4** Let  $X$  be a Bernoulli random variable with parameter  $p$ . As we showed earlier  $\mathbb{E}[X] = p$  and  $\mathbb{E}[X^2] = p$ , so

$$\mathbb{V}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2 = p - p^2 = p(1 - p)$$

$$s_X = \sqrt{p(1 - p)}$$

**Example 1.6.5** Let  $X$  be a normal random variable with parameters  $\mu$  and  $\sigma$ . As we already know  $\mathbb{E}[X] = \mu$ , so

$$\mathbb{V}[X] = \int_{-\infty}^{+\infty} (t - \mathbb{E}[X])^2 f_X(t) dt = \int_{-\infty}^{+\infty} (t - \mu)^2 \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(t-\mu)^2}{2\sigma^2}} dt = \dots = \sigma^2$$

$$s_X = \sqrt{\mathbb{V}[X]} = \sigma$$

Thus the parameter  $\sigma$  in the normal distribution is the standard deviation of the random variable.

**Theorem 1.6.6** Suppose we are given two independent random variables  $X$  and  $Y$ , then

$$\mathbb{V}[X + Y] = \mathbb{V}[X] + \mathbb{V}[Y]$$

Even more if  $a$  and  $b$  are real numbers, then

$$\mathbb{V}[aX + bY] = a^2\mathbb{V}[X] + b^2\mathbb{V}[Y]$$

**Example 1.6.7** Let  $X$  be a binomial random variable, then  $X$  can be represented as a sum of  $n$  Bernoulli variables  $X = X_1 + \dots + X_n$ , where  $X_1, \dots, X_n \sim \text{Ber}(p)$ . As we showed earlier  $\mathbb{V}[X_1] = \dots = \mathbb{V}[X_n] = p(1-p)$ , so from independence of  $X_1, \dots, X_n$  and the previous remark we get

$$\mathbb{V}[X] = \mathbb{V}[X_1 + \dots + X_n] = \mathbb{V}[X_1] + \dots + \mathbb{V}[X_n] = p(1-p) + \dots + p(1-p) = np(1-p)$$

$$s_X = \sqrt{\mathbb{V}[X]} = \sqrt{np(1-p)}$$

## 1.7 De Moivre–Laplace theorem

The following theorem states informally that for big values of  $n$  binomial random variables behave like normal variables

**Theorem 1.7.1** Let  $X$  be a binomial random variable with parameters  $n$  and  $p$  where  $0 < p < 1$ . Then  $f_X(k) \approx f_Y(k)$  for the normal random variable  $Y$  with parameters  $\mu = np$  and  $\sigma^2 = np(1-p)$ . More explicitly

$$f_X(k) = \binom{n}{k} p^k (1-p)^{n-k} \xrightarrow{n \rightarrow \infty} \frac{1}{\sqrt{2\pi \cdot np(1-p)}} e^{-\frac{(k-np)^2}{2np(1-p)}}$$

This theorem has another form (the so called integral form).

**Theorem 1.7.2** Let  $X$  be a binomial random variable with parameters  $n$  and  $p$  where  $0 < p < 1$ . Then  $F_X(t) \approx F_Y(t)$  for the normal random variable  $Y$  with parameters  $\mu = np$  and  $\sigma = \sqrt{np(1-p)}$ . More explicitly

$$F_X(t) = \mathbb{P}(X \leq t) \xrightarrow{n \rightarrow \infty} \int_{-\infty}^t \frac{1}{\sqrt{2\pi \cdot np(1-p)}} e^{-\frac{(s-np)^2}{2np(1-p)}} ds = \Phi\left(\frac{k - np}{\sqrt{np(1-p)}}\right)$$

These theorems assume that  $n$  has to be big enough. How big should  $n$  be in practice?

**Remark 1.7.3** Let  $X$  be a binomial random variable with parameters  $n$  and  $p$  where  $np > 10$  and  $n(1-p) > 10$ . Then

$$F_X(k) \approx \Phi\left(\frac{k + \frac{1}{2} - np}{\sqrt{np(1-p)}}\right)$$

## 1.8 Law of large numbers

The following theorem states informally that average of a big number of equally distributed random variables approaches their expected value. This is one of the foundational theorems of probability theory which gives a firm basis for applications in real world problems.

**Definition 1.8.1** *We say that a sequence of random variables  $X_1, \dots, X_n$  is i.i.d. if its random variables are independent and identically distributed. In other words they are independent and have the same cumulative density function.*

Clearly, if  $X_1, \dots, X_n$  are i.i.d., then these random variables have equal characteristics like quantiles, mean, standard deviation and many others.

**Theorem 1.8.2 (Weak law of large numbers).** *Let  $X_1, \dots, X_n$  be i.i.d. with expected value  $\mu$ , then for all  $\epsilon > 0$  we have*

$$\mathbb{P} \left( \left| \frac{X_1 + \dots + X_n}{n} - \mu \right| < \epsilon \right) \xrightarrow{n \rightarrow \infty} 1$$

**Theorem 1.8.3 (Strong law of large numbers).** *Let  $X_1, \dots, X_n$  be i.i.d. with expected value  $\mu$ , then*

$$\mathbb{P} \left( \frac{X_1 + \dots + X_n}{n} = \mu \right) \xrightarrow{n \rightarrow \infty} 1$$

## 1.9 Central limit theorem

Central limit theorem is no doubt the most important theorem of probability theory. Most non-trivial results are based on this fact. It essentially says that the average of i.i.d. random variables behave like a normal random variable. Compare this with the law of large numbers.

Before stating the theorem we shall give a short remark on characteristics of the average of i.i.d. random variables.

**Remark 1.9.1** *Let  $X_1, \dots, X_n$  be i.i.d. random variables. Let  $Y = \frac{1}{n}(X_1 + \dots + X_n)$  be their average. Since  $X_1, \dots, X_n$  identically distributed, then they have the same expected value and variance*

$$\mathbb{E}[X_1] = \dots = \mathbb{E}[X_n] = \mu, \quad \mathbb{V}[X_1] = \dots = \mathbb{V}[X_n] = \sigma^2$$

*Then*

$$\mathbb{E}[Y] = \mathbb{E} \left[ \frac{1}{n}(X_1 + \dots + X_n) \right] = \frac{1}{n} \mathbb{E}[X_1 + \dots + X_n] = \frac{1}{n} (\mathbb{E}[X_1] + \dots + \mathbb{E}[X_n]) = \frac{1}{n} \cdot n\mu = \mu$$

$$\mathbb{V}[Y] = \mathbb{V} \left[ \frac{1}{n}(X_1 + \dots + X_n) \right] = \left( \frac{1}{n} \right)^2 \mathbb{V}[X_1 + \dots + X_n] = \frac{1}{n^2} (\mathbb{V}[X_1] + \dots + \mathbb{V}[X_n]) = \frac{1}{n^2} \cdot n\sigma^2 = \frac{\sigma^2}{n}$$

*Therefore*

$$m_Y = \mu, \quad s_Y = \frac{\sigma}{\sqrt{n}}$$

**Theorem 1.9.2** Let  $X_1, \dots, X_n$  be i.i.d. with expected value  $\mu$  and variance  $\sigma^2$ . Let  $Y = \frac{1}{n}(X_1 + \dots + X_n)$  be their average. Then the random variable  $Z_Y = \sqrt{n} \frac{Y - \mu}{\sigma}$  has cumulative density function approximately equal to the cumulative density function of the standard normal distribution:

$$F_{Z_Y}(t) \xrightarrow{n \rightarrow \infty} \Phi(t)$$

More explicitly

$$\mathbb{P} \left( \frac{\frac{1}{n}(X_1 + \dots + X_n) - \mu}{\frac{1}{\sqrt{n}}\sigma} < t \right) \xrightarrow{n \rightarrow \infty} \frac{1}{\sqrt{2\pi}} \int_{-\infty}^t e^{-\frac{s^2}{2}} ds$$

**Remark 1.9.3** One can note that De Moivre-Laplace theorem is nothing more than a central limit theorem applied to i.i.d. Bernoulli random variables.

## 2 Statistics

In probability theory we study characteristics and behaviour of random variables assuming that we know the probability space or at least the cumulative density functions. In real world it is not possible to get the exact description of a probability space for our problem or a precise formula for the densities of random variables.

The best we can do is to make a good guess about random variable distributions based on some numbers of observations. For example, tossing a coin 10000 times and observing heads in 5053 time we can be quite confident that this coin is described by a Bernoulli random variable with parameter  $p = 1/2$ . To be absolutely sure about distribution of the coin we had to make infinitely many tossing, which is impossible in practice. Therefore we need to study random variables given only finitely many observations.

The goal of statistics is to give us tools to

1. approximately recover distributions of random variables given finite number of observations;
2. approximately compute random variables characteristics given finite number of observations;
3. for a given level of confidence answer questions regarding random variable behaviour;
4. predict values of dependent random variables given finite number of observations of independent random variables.

These four big problems have their names: distribution estimation, point estimation, hypothesis testing and regression respectively.

### 2.1 Samples, observations, sample statistics

**Definition 2.1.1** A sample  $\mathcal{X}$  of size  $n$  is a sequence of random variables  $X_1, \dots, X_n$  defined on some probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

**Definition 2.1.2** Let  $X$  be a random variable. A sample  $\mathcal{X}$  from  $X$  of size  $n$  is a sequence  $X_1, \dots, X_n$  of i.i.d. random variables with the same distribution as  $X$ . We shall denote this fact as  $\mathcal{X} \sim X$ .

**Example 2.1.3** Assume we have a fair coin and we toss it  $n$  times. Outcomes of the tossed coin are described by a random variable  $X$ . Let  $X_i$  denote the random variable describing coin side on the  $i$ -th toss. Then  $\mathcal{X} = (X_1, \dots, X_n)$  is a sample of the size  $n$  of the random variable  $X$ , where  $X$  is a random variable representing outcome of the flipped coin.

**Definition 2.1.4** Let  $\mathcal{X}$  be a sample of the random variable  $X : \Omega \rightarrow \mathbb{R}$  defined on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . For any fixed elementary event  $\omega \in \Omega$  the sequence of numbers  $x = (X_1(\omega), \dots, X_n(\omega))$  is called an observation of  $X$  of size  $n$ .

**Example 2.1.5** Assume we have a fair coin and we toss it 5 times. Outcomes of the tossed coin are described by a random variable  $X$ . Suppose we got the following outcomes  $x = (H, H, T, T, H)$ . Then  $x$  is called the observations of the random variable  $X$ .

**Definition 2.1.6** Let  $\mathcal{X}$  be a sample of size  $n$ . A statistic  $T$  is a random variable which is a function of sample  $\mathcal{X}$ .

**Example 2.1.7** Let  $\mathcal{X}$  be a sample of size  $n$  of the random variable  $X$ . Then we define the following statistics

- sample mean

$$m(\mathcal{X}) = \frac{1}{n} \sum_{i=1}^n X_i$$

- sample  $k$ -th moment

$$m_k(\mathcal{X}) = \frac{1}{n} \sum_{i=1}^n X_i^k$$

- sample variance

$$s_b^2(\mathcal{X}) = \frac{1}{n} \sum_{i=1}^n (X_i - m(\mathcal{X}))^2$$

- unbiased sample variance

$$s^2(\mathcal{X}) = \frac{1}{n-1} \sum_{i=1}^n (X_i - m(\mathcal{X}))^2$$

**Remark 2.1.8** Clearly,

$$m(\mathcal{X}) = m_1(\mathcal{X}) \quad s^2(\mathcal{X}) = \frac{n}{n-1} s_b^2(\mathcal{X})$$

One can show that

$$s_b^2(\mathcal{X}) = \frac{1}{n} \sum_{i=1}^n X_i^2 - \left( \frac{1}{n} \sum_{i=1}^n X_i \right)^2 = m_2(\mathcal{X}) - m(\mathcal{X})^2$$

**Remark 2.1.9** Let  $\mathcal{X}$  be a sample from the random variable  $X$ , then

$$\mathbb{E}[m_k(\mathcal{X})] = \mathbb{E}[X^k]$$

Indeed,

$$\mathbb{E}[m_k(\mathcal{X})] = \mathbb{E}\left[\frac{1}{n} \sum_{i=1}^n X_i^k\right] = \frac{1}{n} \mathbb{E}\left[\sum_{i=1}^n X_i^k\right] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}[X_i^k] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}[X^k] = \frac{1}{n} \cdot n \mathbb{E}[X^k] = \mathbb{E}[X^k]$$

**Remark 2.1.10** Let  $\mathcal{X}$  be a sample from the random variable  $X$ , then

$$\mathbb{E}[m(\mathcal{X})] = m_X, \quad \mathbb{E}[s_b^2(\mathcal{X})] = \frac{n-1}{n} s_X^2, \quad \mathbb{E}[s^2(\mathcal{X})] = s_X^2$$

Indeed,

$$\mathbb{E}[m(\mathcal{X})] = \mathbb{E}[m_1(\mathcal{X})] = \mathbb{E}[X^1] = m_X$$

Now note that

$$\begin{aligned} \mathbb{E}\left[\left(\frac{1}{n} \sum_{i=1}^n X_i\right)^2\right] &= \frac{1}{n^2} \mathbb{E}\left[\left(\sum_{i=1}^n X_i\right)^2\right] \\ &= \frac{1}{n^2} \mathbb{E}\left[\sum_{i=1}^n \sum_{j=1}^n X_i X_j\right] \\ &= \frac{1}{n^2} \mathbb{E}\left[\sum_{i=1}^n X_i^2 + \sum_{i \neq j} X_i X_j\right] \\ &= \frac{1}{n^2} \left(\sum_{i=1}^n \mathbb{E}[X_i^2] + \sum_{i \neq j} \mathbb{E}[X_i X_j]\right) \\ &= \frac{1}{n^2} \left(\sum_{i=1}^n \mathbb{E}[X^2] + \sum_{i \neq j} \mathbb{E}[X_i] \mathbb{E}[X_j]\right) \\ &= \frac{1}{n^2} \left(n \mathbb{E}[X^2] + \sum_{i \neq j} \mathbb{E}[X] \mathbb{E}[X]\right) \\ &= \frac{1}{n^2} (n \mathbb{E}[X^2] + (n^2 - n) \mathbb{E}[X] \mathbb{E}[X]) \\ &= \frac{1}{n} (\mathbb{E}[X^2] + (n-1) \mathbb{E}[X]^2) \end{aligned}$$

So

$$\begin{aligned}
\mathbb{E}[s_b^2(\mathcal{X})] &= \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n X_i^2 - \left( \frac{1}{n} \sum_{i=1}^n X_i \right)^2 \right] \\
&= \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n X_i^2 \right] - \mathbb{E} \left[ \left( \frac{1}{n} \sum_{i=1}^n X_i \right)^2 \right] \\
&= \mathbb{E}[m_2(\mathcal{X})] - \frac{1}{n} (\mathbb{E}[X^2] + (n-1)\mathbb{E}[X]^2) \\
&= \mathbb{E}[X^2] - \frac{1}{n} (\mathbb{E}[X^2] + (n-1)\mathbb{E}[X]^2) \\
&= \frac{n-1}{n} (\mathbb{E}[X^2] - \mathbb{E}[X]^2) \\
&= \frac{n-1}{n} \mathbb{V}[X] \\
&= \frac{n-1}{n} s_X^2
\end{aligned}$$

and

$$\mathbb{E}[s^2(\mathcal{X})] = \mathbb{E} \left[ \frac{n}{n-1} s_b^2(\mathcal{X}) \right] = \frac{n}{n-1} \mathbb{E}[s_b^2(\mathcal{X})] = \frac{n}{n-1} \frac{n-1}{n} s_X^2 = s_X^2$$

## 2.2 Distribution estimates

As we have seen earlier the most single important characteristic of a random variable is its distribution function. Given a set of observations of a random variable one can construct an approximation of this distribution function. The construction is pretty straightforward.

**Definition 2.2.1** *Let  $\mathcal{X}$  be a sample from a random variable  $X$ . Then the parametric random variable*

$$F_{\mathcal{X}}(t) = \frac{1}{n} \sum_{i=1}^n 1_{\{X_i \leq t\}}$$

*is called the empirical cumulative distribution function.*

For every  $t$  this statistic gives a good approximation for  $F_X(t)$ .

**Theorem 2.2.2** *Let  $\mathcal{X}$  be a sample from a random variable  $X$ . Then for all  $t \in \mathbb{R}$  and  $\epsilon > 0$*

$$\mathbb{P}(|F_{\mathcal{X}}(t) - F_X(t)| > \epsilon) \xrightarrow{n \rightarrow \infty} 0$$

Even stronger result is true

**Theorem 2.2.3** *Let  $\mathcal{X}$  be a sample from a random variable  $X$ . Then for all  $\epsilon > 0$*

$$\mathbb{P} \left( \sup_{t \in \mathbb{R}} |F_{\mathcal{X}}(t) - F_X(t)| > \epsilon \right) \xrightarrow{n \rightarrow \infty} 0$$

**Example 2.2.4** Let  $x = (1, 2, 4, 2, 4, 1, 3, 1)$  be an observation of a random variable  $X$ . Find a function that approximates cumulative distribution function of  $X$ . The observation  $x$  corresponds to some elementary event  $\omega$ , that is  $(X_1(\omega), \dots, X_8(\omega)) = (1, 2, 4, 2, 4, 1, 3, 1)$ . The desired approximation will be

$$\begin{aligned} F_{\mathcal{X}}(t)(\omega) &= \frac{1}{n} \sum_{i=1}^n 1_{\{X_i(\omega) < t\}} \\ &= \frac{1}{8} \sum_{i=1}^8 1_{\{X_i(\omega) < t\}} \\ &= \frac{1}{8} (1_{1 < t} + 1_{2 < t} + 1_{4 < t} + 1_{2 < t} + 1_{4 < t} + 1_{1 < t} + 1_{3 < t} + 1_{1 < t}) \\ &= \frac{1}{8} (3 \cdot 1_{1 < t} + 2 \cdot 1_{2 < t} + 1_{3 < t} + 2 \cdot 1_{4 < t}) \end{aligned}$$

Therefore

$$F_{\mathcal{X}}(t)(\omega) = \begin{cases} 0 & < t \leq 1 \\ \frac{3}{8} & 1 < t \leq 2 \\ \frac{5}{8} & 2 < t \leq 3 \\ \frac{6}{8} & 3 < t \leq 4 \\ 1 & 4 < t \end{cases}$$

## 2.3 Point estimates

Suppose we study a random variable  $X$ . We have  $n$  observations  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$  and we want to know the distribution of  $X$ . In practice we usually have a good guess of what type of distribution  $X$  should have. It might be a normal distribution or a binomial distribution or a Poisson distribution. All these classes of distributions are parametric meaning that you need to specify some parameters to pick a concrete distribution of the class. For example you need to know exact values of  $\mu$  and  $\sigma^2$  to speak of the normal distribution  $Norm(\mu, \sigma^2)$ . Now given observations  $x \in \mathbb{R}^n$  and a class of distributions  $X$  belongs to we can hope to find parameters of the specific distribution of  $X$ . This is the primary goal of point estimations theory.

**Definition 2.3.1** Let  $\mathcal{D}$  be a family of distributions. We say that  $\mathcal{D}$  is a parametric family if there is a set of parameters  $\Theta \subset \mathbb{R}^k$  such that any distribution  $D \in \mathcal{D}$  is uniquely determined by some group of parameters  $\theta \in \Theta$ . We write this fact as  $\mathcal{D} = \{D_\theta : \theta = (\theta_1, \dots, \theta_k) \in \Theta\}$ .

**Example 2.3.2** Let  $\Theta = \mathbb{R}_+$ . Then the class of Poisson distributions  $\mathcal{P}$  is a parametric family because

$$\mathcal{P} = \{Pois(\lambda) : \lambda \in \Theta\}$$

**Example 2.3.3** Let  $\Theta = \mathbb{R} \times \mathbb{R}_+$ . Then the class of normal distributions  $\mathcal{N}$  is a parametric family because

$$\mathcal{N} = \{Norm(\mu, \sigma^2) : (\mu, \sigma^2) \in \Theta\}$$

**Example 2.3.4** Let  $\Theta = \mathbb{N} \times [0, 1]$ . Then the class of binomial distributions  $\mathcal{B}$  is a parametric family

$$\mathcal{B} = \{Bin(n, p) : (n, p) \in \Theta\}$$



**Definition 2.3.5** Let  $X$  be a random variable with distribution from a parametric family  $\mathcal{D} = \{D_\theta : \theta = (\theta_1, \dots, \theta_k) \in \Theta\}$ . Let  $\mathcal{X}$  be a sample of  $X$ . A statistic  $T$  is called a point estimation of  $\theta_i \in \mathbb{R}$  if

$$\mathbb{E}[T(\mathcal{X})] = \theta_i$$

**Example 2.3.6** Let  $X \sim \text{Norm}(\mu, \sigma^2)$  be a normal random variable. Let  $\mathcal{X}$  be a sample from  $X$ . Then  $m(\mathcal{X})$  is a point estimation of  $\mu$  and  $s^2(\mathcal{X})$  is a point estimation of  $\sigma^2$ . Indeed, since  $X$  is normal, then  $m_X = \mu$  and  $s_X^2 = \sigma^2$ . Now using remark 2.1.10 we get

$$\mathbb{E}[m(\mathcal{X})] = m_X = \mu, \quad \mathbb{E}[s^2(\mathcal{X})] = s_X^2 = \sigma^2$$

**Example 2.3.7** Let  $X \sim \text{Unif}(a, b)$  be a random variable uniformly distributed on  $[a, b]$ . Let  $\mathcal{X}$  be a sample from  $X$ . Consider statistics  $L(\mathcal{X}) = \min(X_1, \dots, X_n)$  and  $U(\mathcal{X}) = \max(X_1, \dots, X_n)$  then one can show that

$$\mathbb{E}[L(\mathcal{X})] = a + \frac{1}{n+1}(b-a), \quad \mathbb{E}[U(\mathcal{X})] = a + \frac{n}{n+1}(b-a)$$

Therefore

$$\begin{aligned} a &= \frac{n\mathbb{E}[L(\mathcal{X})] - \mathbb{E}[U(\mathcal{X})]}{n-1} = \mathbb{E}\left[\frac{nL(\mathcal{X}) - U(\mathcal{X})}{n-1}\right], \\ b &= \frac{n\mathbb{E}[U(\mathcal{X})] - \mathbb{E}[L(\mathcal{X})]}{n-1} = \mathbb{E}\left[\frac{nU(\mathcal{X}) - L(\mathcal{X})}{n-1}\right] \end{aligned}$$

These equalities show that statistics

$$A(\mathcal{X}) = \frac{nL(\mathcal{X}) - U(\mathcal{X})}{n-1}, \quad B(\mathcal{X}) = \frac{nU(\mathcal{X}) - L(\mathcal{X})}{n-1}$$

are point estimates for  $a$  and  $b$ .

**Example 2.3.8** Let  $x = (1, 2, 3, 1, 3, 1, 4)$  be observations of the random variable  $X$  with uniform distribution on some segment  $[a, b]$ . Our observation corresponds to some elementary event  $\omega$ , so  $(X_1(\omega), \dots, X_n(\omega)) = (1, 2, 3, 1, 3, 1, 4)$  In our case  $n = 7$  and

$$\begin{aligned} L(\mathcal{X})(\omega) &= \min(1, 2, 3, 1, 3, 1, 4) = 1, & U(\mathcal{X})(\omega) &= \max(1, 2, 3, 1, 3, 1, 4) = 4 \\ A(\mathcal{X})(\omega) &= \frac{nL(\mathcal{X})(\omega) - U(\mathcal{X})(\omega)}{n-1} = \frac{1}{2}, & B(\mathcal{X})(\omega) &= \frac{nU(\mathcal{X})(\omega) - L(\mathcal{X})(\omega)}{n-1} = \frac{9}{2} \end{aligned}$$

Therefore  $a \approx 0.5$ ,  $b \approx 4.5$ .

## 2.4 Hypothesis testing

Given observation of a random variable  $X$  we can make several guesses about random variable distribution. These guesses are called hypotheses. Our goal is to construct a function that chooses one of the hypothesis given observations of  $X$ . Such functions are called a criteria. Since we can inspect only finitely many observations there is always a possibility that our criterion chooses a wrong hypothesis. We want this to happen as rarely as possible.

**Definition 2.4.1** Let  $\mathcal{X}$  be a sample. A hypothesis  $H$  is any proposition regarding  $\mathcal{X}$ .

**Example 2.4.2** Let  $\mathcal{X}$  be a sample. The following statements are hypotheses:

- all random variables  $X_1, \dots, X_n$  in  $\mathcal{X}$  are independent;
- all random variables  $X_1, \dots, X_n$  in  $\mathcal{X}$  are i.i.d.;
- $\mathcal{X}$  is a sample from Bernoulli random variable with  $p = 1/2$ ;
- $\mathcal{X}$  is a sample from normal random variable with  $\mu \in [0.25, 0.75]$  and  $\sigma^2 \in [1, 2]$ ;

**Definition 2.4.3** A hypothesis  $H$  is called simple if it has the form:  $\mathcal{X}$  is a sample from distribution  $D$ . Otherwise  $H$  is composite.

**Example 2.4.4** Here are a few examples of simple and composite hypotheses:

- $\mathcal{X} \sim \text{Norm}(1, 2^2)$  — simple hypothesis;
- $\mathcal{X} \sim \text{Unif}(1, 5)$  — simple hypothesis;
- $\mathcal{X} \sim \text{Norm}(\mu, 2^2)$  where  $\mu \in (-1, 1)$  — composite hypothesis;
- all random variables in  $\mathcal{X} = (X_1, \dots, X_n)$  are independent — composite hypothesis;
- all random variables in  $\mathcal{X} = (X_1, \dots, X_n)$  are i.i.d. — composite hypothesis.

Now we shall formalize the notion of criterion for hypotheses testing.

**Definition 2.4.5** Let  $H_1, \dots, H_k$  be a set of hypotheses. Then any function of the form

$$\delta : \mathbb{R}^n \rightarrow \{H_1, \dots, H_k\}$$

is called a criterion.

**Remark 2.4.6** In practice we usually consider criteria with two hypotheses  $\{H_1, H_2\}$ . The hypothesis  $H_1$  is called the null hypothesis, and  $H_2$  is called the alternative.

It is rarely possible to develop a criterion that does not make mistakes. In order to quantify mistakes that a criterion can make we give the following definition.

**Definition 2.4.7** Let  $\delta : \mathbb{R}^n \rightarrow \{H_1, \dots, H_k\}$  be a criterion. We say that  $\delta$  made an error of the  $i$ -th kind on the observation  $x = (x_1, \dots, x_n)$  if the hypothesis  $H_i$  is true but  $\delta(x_1, \dots, x_n) \neq H_i$ . The probability of the error of the  $i$ -th kind is defined by

$$\alpha_i(\delta) = \mathbb{P}(\delta(X_1, \dots, X_n) \neq H_i | H_i)$$

**Example 2.4.8** Let  $\mathcal{X}$  be a sample of size  $2n$  from Bernoulli random variable. Consider two hypotheses:

$$H_1 = \{\mathcal{X} \sim \text{Ber}(0.5)\} \quad H_2 = \{\mathcal{X} \sim \text{Ber}(p), p > 0.5\}$$

For example, for these two hypotheses we can define a criterion

$$\delta(x_1, \dots, x_{2n}) = \begin{cases} H_1 & \text{if } \bar{x} = 0.5 \\ H_2 & \text{otherwise} \end{cases}$$

where  $\bar{x} = \frac{1}{2n} \sum_{i=1}^{2n} x_i$ . Intuitively this criterion rarely chooses the null hypothesis and often makes the error of the first kind. We shall compute exact values for the errors of the first and second kind. For the beginning note that  $\mathbb{P}(\bar{x} \neq 0.5) = 1$ , so

$$\alpha_1(\delta) = \mathbb{P}(\delta(x) \neq H_1 | H_1) = \frac{\mathbb{P}(\delta(x) \neq H_1 \cap H_1)}{\mathbb{P}(H_1)} = \frac{\mathbb{P}(\bar{x} \neq 0.5 \cap H_1)}{\mathbb{P}(H_1)} = \frac{\mathbb{P}(H_1)}{\mathbb{P}(H_1)} = 1$$

$$\alpha_2(\delta) = \mathbb{P}(\delta(x) \neq H_2 | H_2) = \frac{\mathbb{P}(\delta(x) \neq H_2 \cap H_2)}{\mathbb{P}(H_2)} = \frac{\mathbb{P}(\bar{x} = 0.5 \cap H_2)}{\mathbb{P}(H_2)} = \frac{0}{\mathbb{P}(H_2)} = 0$$

Our criterion almost always makes the error of the first kind and never makes the error of the second kind.

Clearly the problem with this criterion is that it requires exact equality for the average rate of heads in Bernoulli trials. The better criterion would check that  $\bar{x}$  falls into some neighbourhood of 0.5. In this case the probability of the error of the first kind would fall dramatically but there would be a room for the errors of the second kind.

**Remark 2.4.9** In practice we usually consider criteria  $\delta$  with two hypotheses. In this case we denote  $\alpha_1(\delta)$  as  $\alpha(\delta)$  and  $\alpha_2(\delta)$  as  $\beta(\delta)$ . If the criterion in question is clear from the context, we denote probabilities of the errors as  $\alpha$  and  $\beta$ . Even more, the quantity  $1 - \beta$  is called the power of the criterion  $\delta$ .

Errors of the first and second kind are somewhat opposite to each other. If you minimize  $\alpha$ , the  $\beta$  grows bigger and if you try to make  $\beta$  smaller you get larger  $\alpha$ .

**Example 2.4.10** Let  $\mathcal{X}$  be a sample of size 1 from a normal random variable  $X$ . We have two simple hypotheses regarding distribution of  $X$ :

$$H_1 = \{\mathcal{X} \sim \text{Norm}(0, 1)\} \quad H_2 = \{\mathcal{X} \sim \text{Norm}(1, 1)\}$$

Consider criterion

$$\delta(x_1) = \begin{cases} H_1 & \text{if } x_1 \leq b \\ H_2 & \text{if } x_1 > b \end{cases}$$

Note, that this criterion depends on parameter  $b$ . By definition we have

$$\alpha = \mathbb{P}(\delta(x_1) \neq H_1 | H_1) = \mathbb{P}(x_1 > b | H_1) \quad \beta = \mathbb{P}(\delta(x_1) \neq H_2 | H_2) = \mathbb{P}(x_1 \leq b | H_2)$$

As  $b$  grows bigger we get smaller values of  $\alpha$  and larger values  $\beta$  and vice versa.

## 2.5 Statistical tests

From now on we shall build criteria for some specific but practically important problems. Suppose we have a sample  $\mathcal{X}$  from a random variable  $X$ . We consider only two hypotheses  $H_1$  and  $H_2 = \{H_1 \text{ is not true}\}$ . For these two hypotheses we shall build criteria of the form

$$\delta(x) = \begin{cases} H_1 & \text{if } |\rho(x)| \leq C \\ H_2 & \text{if } |\rho(x)| > C \end{cases}$$

Our goal is to invent a function  $\rho$  such that the criterion  $\delta$  ‘mostly’ gives correct answers. By ‘mostly’ we mean that we do not expect to make more than a specified percent (say  $\alpha$ ) of errors of the first kind. To tweak the error rate of our criterion we need to choose  $C$  such that  $\alpha(\delta) \leq \alpha$ .

**Definition 2.5.1** Let  $\mathcal{X}$  be a sample of size  $n$  from  $X$ . Consider two hypotheses  $H_1$  and  $H_2 = \{H_1 \text{ is not true}\}$ . Let  $\rho(\mathcal{X})$  be a statistic (called test statistic) such that

- if  $H_1$  is true, then cumulative density function of  $\rho(\mathcal{X})$  pointwise converges to cumulative density function of some continuous random variable  $\eta$

$$F_{\rho(\mathcal{X})}(t) \xrightarrow{n \rightarrow \infty} F_{\eta}(t) \quad \text{for all } t \in \mathbb{R}$$

- if  $H_1$  is not true, then

$$\mathbb{P}(|\rho(\mathcal{X})| > \epsilon) \xrightarrow{n \rightarrow \infty} 1 \quad \text{for all } \epsilon > 0.$$

Then a statistical test is a criterion of the form

$$\delta(x) = \begin{cases} H_1 & \text{if } |\rho(x)| \leq C \\ H_2 & \text{if } |\rho(x)| > C \end{cases}$$

where  $C > 0$ .

**Remark 2.5.2** One needs to clarify the requirements for the test statistic in the previous definition. The first requirement says that if  $H_1$  holds true, then  $\rho(\mathcal{X})$  attains the same values as  $\eta$ . If  $H_2$  holds true, then for  $n$  big enough  $\rho(\mathcal{X})$  will attain big values.

In the very definition of the criterion in statistical tests we assume that test statistic has distribution close to some distribution which does not depend on a sample being studied. Now we shall discuss typical distributions encountered in statistical tests.

**Definition 2.5.3** Let  $X_1, \dots, X_n \sim \text{Norm}(0, 1)$ . Consider random variable  $X = X_1^2 + \dots + X_n^2$ . Its distribution is called the  $\chi^2$  distribution with  $n$  degrees of freedom. Notation:  $X \sim \text{Chi}(n)$ .

**Definition 2.5.4** Let  $X_1 \sim \text{Norm}(0, 1)$  and  $X_2 \sim \text{Chi}(n)$ . Consider random variable  $X = \frac{X_1}{\sqrt{X_2/n}}$ . Its distribution is called the student distribution with  $n$  degrees of freedom. Notation:  $X \sim \text{St}(n)$ .

**Definition 2.5.5** Let  $X_1 \sim \text{Chi}(k)$  and  $X_2 \sim \text{Chi}(n)$ . Consider random variable  $X = \frac{X_1/k}{X_2/n}$ . Its distribution is called the Fisher distribution with parameters  $k$  and  $n$ . Notation  $X \sim F(k, n)$ .

**Definition 2.5.6** We say that a random variable  $X$  has Kolmogorov's distribution if its cumulative distribution function is

$$F_X(t) = \sum_{k=-\infty}^{+\infty} (-1)^k e^{-2k^2 t^2}.$$

Notation  $X \sim \text{Kolm}$

Now we shall list a few constructions that lead to these distributions

**Remark 2.5.7** Let  $\mathcal{X} = (X_1, \dots, X_n) \sim \text{Norm}(\mu, \sigma^2)$ . Then

- $\sqrt{n} \frac{m(\mathcal{X}) - \mu}{\sigma} \sim \text{Norm}(0, 1);$

- $\frac{(n-1)s^2(\mathcal{X})}{\sigma^2} \sim Chi(n-1);$
- $\sqrt{n} \frac{m(\mathcal{X}) - \mu}{s(\mathcal{X})} \sim St(n-1).$

Now we shall discuss statistical tests used in practice.

**Remark 2.5.8** Suppose we are given a statistical test. It must be used as follows:

- Choose a level of confidence  $\alpha$  (i.e. probability of errors of the first kind);
- Find  $C$  such that  $\mathbb{P}(|\eta| \geq C) = \alpha;$
- Given observations  $x$  compute  $\rho(x);$
- If  $|\rho(x)| > C$  we reject  $H_1$ , otherwise reject  $H_2$ .

**Example 2.5.9 (Kolmogorov's test)** This criterion tests if a given sample  $\mathcal{X}$  of size  $n$  was sampled from a continuous random variable  $X$  with cumulative distribution function  $F_X$ .

- hypotheses:

$$H_1 = \{\mathcal{X} \sim X\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}) = \sqrt{n} \sup_{t \in \mathbb{R}} |F_{\mathcal{X}}(t) - F_X(t)|$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim Kolm$

**Example 2.5.10 (z-test)** This criterion checks if a given sample  $\mathcal{X}$  of size  $n$  sampled from a normal random variable  $X \sim Norm(\mu, \sigma^2)$  (with unknown  $\mu$  and known  $\sigma$ ) has mean equal to  $\mu_0$ .

- hypotheses:

$$H_1 = \{\mu = \mu_0\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}) = \sqrt{n} \frac{m(\mathcal{X}) - \mu_0}{\sigma}$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim St(n-1)$

**Example 2.5.11 (t-test)** This criterion checks if a given sample  $\mathcal{X}$  of size  $n$  sampled from a normal random variable  $X \sim Norm(\mu, \sigma^2)$  (with unknown  $\mu$  and unknown  $\sigma$ ) has mean equal to  $\mu_0$ .

- hypotheses:

$$H_1 = \{\mu = \mu_0\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}) = \sqrt{n} \frac{m(\mathcal{X}) - \mu_0}{s(\mathcal{X})}$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim Norm(0, 1)$

**Example 2.5.12 (Pirson's test)** This criterion tests if a given sample  $\mathcal{X}$  of size  $n$  was sampled from a continuous random variable  $X$  satisfying certain restrictions on its distribution. Let  $A_1, \dots, A_k$  be a sequence of disjoint segments whose union contains all possible values of  $X$ . Let  $p_1, \dots, p_k$  be the expected probabilities that  $X$  fall into segments  $A_1, \dots, A_k$  respectively. Clearly  $p_1, \dots, p_k$  must sum up to 1.

- hypotheses:

$$H_1 = \{\mathbb{P}(X \in A_i) = p_i \text{ for all } i \in \{1, \dots, k\}\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}) = \sum_{i=1}^k \frac{(\nu_i(\mathcal{X}) - np_i)^2}{np_i}$$

where

$$\nu_i(\mathcal{X}) = \sum_{j=1}^n 1_{X_j \in A_i} \quad \text{the number of } X_j \text{ that fall into } A_i$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim \text{Chi}(k-1)$

In practice we do not explicitly specify probabilities  $p_1, \dots, p_k$ , but compute them from distribution of some random variable  $X$  using formulae

$$p_i = \mathbb{P}(X \in A_i)$$

This approach gives rise to the false belief that Pirson's test check that a sample  $\mathcal{X}$  was sampled from random variable  $X$ . This would be true if the number of segments  $A_1, \dots, A_k$  grew to infinity while their sizes would uniformly approach zero.

**Example 2.5.13 (Two-sample Kolmogorov's test)** This criterion tests if a given a sample  $\mathcal{X}$  of size  $n$  from a random variable  $X$  and a sample  $\mathcal{Y}$  of size  $m$  from a random variable  $Y$  have the same distribution.

- hypotheses:

$$H_1 = \{F_X = F_Y\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}, \mathcal{Y}) = \sqrt{\frac{mn}{m+n}} \sup_{t \in \mathbb{R}} |F_{\mathcal{X}}(t) - F_{\mathcal{Y}}(t)|$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim \text{Kolm}$

**Example 2.5.14 (Two-sample Fisher's test)** This criterion tests if a given sample  $\mathcal{X}$  of size  $n$  from a normal random variable  $X \sim \text{Norm}(\mu_X, \sigma_X^2)$  and a sample  $\mathcal{Y}$  of size  $m$  from a normal random variable  $Y \sim \text{Norm}(\mu_Y, \sigma_Y^2)$  have the same standard deviation.

- hypotheses:

$$H_1 = \{\sigma_X = \sigma_Y\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}, \mathcal{Y}) = \frac{s^2(\mathcal{X})}{s^2(\mathcal{Y})}$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim F(n-1, m-1)$

**Example 2.5.15 (Two-sample Student's test)** This criterion tests if a given sample  $\mathcal{X}$  of size  $n$  from a normal random variable  $X \sim \text{Norm}(\mu_X, \sigma^2)$  and a sample  $\mathcal{Y}$  of size  $m$  from a normal random variable  $Y \sim \text{Norm}(\mu_Y, \sigma^2)$  have the same mean.

- hypotheses:

$$H_1 = \{\mu_X = \mu_Y\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}, \mathcal{Y}) = \sqrt{\frac{mn(n+m-2)}{m+n}} \frac{m(\mathcal{X}) - m(\mathcal{Y})}{\sqrt{(n-1)s^2(\mathcal{X}) + (m-1)s^2(\mathcal{Y})}}$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim St(n-1, m-1)$

**Example 2.5.16 (Pirson's test)** This criterion tests if a given sample  $\mathcal{X}$  of size  $n$  of a random variable  $X$  and a sample  $\mathcal{Y}$  of size  $n$  from a random variable  $Y$  has the property that  $X$  and  $Y$  are independent. Let  $A_1, \dots, A_k$  be a sequence of disjoint segments whose union contains all possible values of  $X$ . Analogously, let  $B_1, \dots, B_l$  be a sequence of disjoint segments whose union contains all possible values of  $Y$ . Let  $p_{i,j}$  be the expected probability that  $X \in A_i$  and  $Y \in B_j$ . Clearly all  $p_{i,j}$  must sum up to 1.

- hypotheses:

$$H_1 = \{X \text{ and } Y \text{ are independent}\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- test statistic:

$$\rho(\mathcal{X}, \mathcal{Y}) = n \sum_{i=1}^k \sum_{j=1}^l \frac{(\nu_{i,j} - \frac{1}{n} \nu_{i,*} \nu_{*,j})^2}{\nu_{i,*} \nu_{*,j}}$$

where

$$\nu_{i,j} = \sum_{s=1}^n 1_{X_s \in A_i} 1_{Y_s \in B_j} \quad \text{number of pairs } (X_s, Y_s) \text{ that fall into } (A_i, B_j)$$

$$\nu_{i,*} = \sum_{j=1}^l \nu_{i,j} \quad \text{number of } X_s \text{ that fall into } A_i$$

$$\nu_{*,j} = \sum_{i=1}^k \nu_{i,j} \quad \text{number of } Y_s \text{ that fall into } B_j$$

- distribution of the test statistic if  $H_1$  is true:  $\eta \sim \text{Chi}((k-1) \cdot (l-1))$

**Example 2.5.17 (Bartlett test)** This criterion tests if samples from different normal random variables have the same variance. Let  $\mathcal{X}_1, \dots, \mathcal{X}_k$  be samples of sizes  $n_1, \dots, n_k$  respectively. Suppose  $\mathcal{X}_i \sim \text{Norm}(\mu_i, \sigma_i^2)$  and  $n_i > 3$ .

- hypotheses:

$$H_1 = \{\sigma_i = \sigma_j \text{ for all } i, j \in \{1, \dots, k\}\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- *test statistic:*

$$\rho(\mathcal{X}_1, \dots, \mathcal{X}_k) = \frac{(N - k) \ln(s_p^2(\mathcal{X}_1, \dots, \mathcal{X}_k)) - \sum_{i=1}^k (n_i - 1) \ln(s^2(\mathcal{X}_i))}{1 + \frac{1}{3(k-1)} \left( \sum_{i=1}^k \frac{1}{n_i - 1} - \frac{1}{N - k} \right)}$$

where

$$N = \sum_{i=1}^k n_i, \quad s_p^2(\mathcal{X}_1, \dots, \mathcal{X}_k) = \frac{1}{N - k} \sum_{i=1}^k (n_i - 1) s^2(\mathcal{X}_i)$$

- *distribution of the test statistic if  $H_1$  is true:  $\eta \sim \text{Chi}(k - 1)$*

**Example 2.5.18 (ANOVA test)** This criterion tests if samples from different normal variables have the same mean. Let  $\mathcal{X}_1, \dots, \mathcal{X}_k$  be samples of sizes  $n_1, \dots, n_k$  respectively. Suppose  $\mathcal{X}_i \sim \text{Norm}(\mu_i, \sigma^2)$ . Note: all samples must be sampled from normal variables with equal variances.

- *hypotheses:*

$$H_1 = \{\mu_i = \mu_j \text{ for all } i, j \in \{1, \dots, k\}\}, \quad H_2 = \{H_1 \text{ is not true}\}$$

- *test statistic:*

$$\rho(\mathcal{X}_1, \dots, \mathcal{X}_k) = \frac{s_i^2(\mathcal{X}_1, \dots, \mathcal{X}_k)}{s_p^2(\mathcal{X}_1, \dots, \mathcal{X}_k)}$$

where

$$N = \sum_{i=1}^k n_i,$$

$$M(\mathcal{X}_1, \dots, \mathcal{X}_k) = \frac{1}{N} \sum_{i=1}^k n_i m(\mathcal{X}_i) \quad \text{overall mean}$$

$$s_i^2(\mathcal{X}_1, \dots, \mathcal{X}_k) = \frac{1}{k - 1} \sum_{i=1}^k n_i (m(\mathcal{X}_i) - M(\mathcal{X}_1, \dots, \mathcal{X}_k))^2 \quad \text{inter sample variance}$$

$$s_p^2(\mathcal{X}_1, \dots, \mathcal{X}_k) = \frac{1}{N - k} \sum_{i=1}^k (n_i - 1) s^2(\mathcal{X}_i) \quad \text{pooled variance}$$

- *distribution of the test statistic if  $H_1$  is true:  $\eta \sim F(k - 1, n - k)$*