



Software Safety Requirements and Architecture Lane Assistance

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Document history

Date	Version	Editor	Description
23 – May – 2018	1.0	Rajagopala Rao Srinadhuni	Software Requirements and Architecture for Functional Safety Project

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Purpose

The Software Requirements and Architecture document specifies how the Technical Requirements shall be implemented in the system, detailing how each safety requirement translates to a system functionality that shall be present within the Lane Assistance System.

Inputs to the Software Requirements and Architecture Document

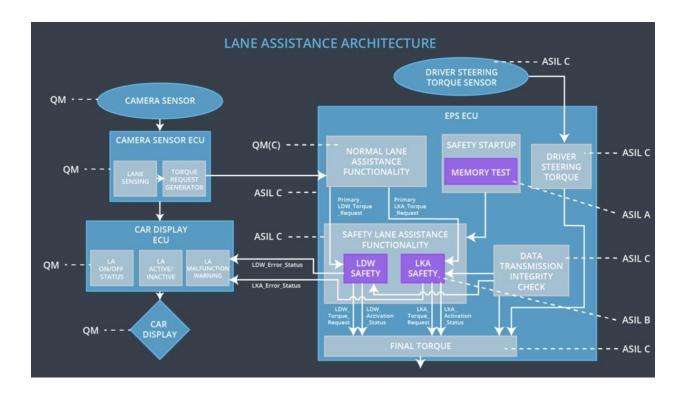
Technical safety requirements

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final EPS Torque' component is below Max_Torque_Amplitude	C	50ms	LDW Safety Block	Set LDW_Torque _Amplitude zero
Technical Safety Requirement 02	The validity and integrity of the LDW_Torque_Request signal shall be ensured	С	50ms	Data Transmission Integrity Block	Lane Assistance System is turned if Data_Validity is False
Technical Safety Requirement 03	As soon as failure is detected by the LDW function, the LDW_Torque_Request shall be set to zero	С	50ms	LDW Safety Block	Lane Assistance System is turned off

Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature, the software block shall send a signal to turn on a warning light	С	50ms	LA Malfunction Warning Block	Lane Assistance System is turned off with Error_Status True
Technical Safety Requirement 05	Memory tests shall be conducted at the start of EPS ECU to check for any faults in memory	A	Length of ignition cycle	Memory Test Block	Lane Assistance System is turned off

Refined Architecture Diagram from the Technical Safety Concept



Software Requirements

Lane Departure Warning (LDW) Amplitude Malfunction Software Requirements:

ID Technical Safety Requirement	A Fault Allocation to Safe State S Tolerant I Time L Interval	е
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Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	С	50ms	LDW Safety Block	Set LDW_Torqu e_Amplitud e zero
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ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
SoftwareSaf etyRequirem ent01-01	The input signal "Primary_LDW_Torq_Req" shall be read and pre-processed to determine the torque request coming from the "Basic/Main LAFunctionality" SW Component. Signal "processed_LDW_Torq_Req" shall be generated at the end of the processing.	С	LDW_SAFETY_INPUT_P ROCESSING	N/A
SoftwareSaf etyRequirem ent01-02	In case the "processed_LDW_Torq_Req" signal has a value greater than "Max_Torque_Amplitude_LDW" (maximum allowed safe torque), the torque signal "limited_LDW_Torq_Req" shall be set to 0, else "limited_LDW_Torq_Req" shall take the value of "processed_LDW_Torq_Req".	С	TORQUE_LIMITER	"limited_LDW_T orq_Req" = 0 (Nm=Newton- meter)
SoftwareSaf etyRequirem ent01-03	The "limited_LDW_Torq_Req" shall be transformed into a signal "LDW_Torq_Req" which is suitable to be transmitted outside of the LDW Safety component ("LDW Safety") to	С	LDW_SAFETY_OUTPUT _GENERATOR	LDW_Torq_Req = 0 (Nm)

the "Final EPS Torque"component. Also se SofSafReq02-01 and	e		
SofSafReq02-02			

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	С	50ms	Data Transmission Integrity Block	Lane Assistance System is turned if Data_Validit y is False

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 02-01	Any data to be transmitted outside of the LDW Safety component ("LDW Safety") including "LDW_Torque_Req" and "activation_status" (see SofSafReq03-02) shall be protected by an End2End(E2E) protection mechanism	С	E2ECalc	LDW_Torq_Req = 0 (Nm)
Software Safety Requirement 02-02	The E2E protection protocol shall contain and attach the control data: alive counter (SQC) and CRC to the data to be transmitted.	С	E2ECalc	LDW_Torq_Req = 0 (Nm)

		S I L	Tolerant Time Interval	Architecture	
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero	С	50ms	LDW Safety Block	Lane Assistance System is turned off

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 03-01	Each of the SW elements shall output a signal to indicate any error which is detected by the element. Error signal = error_status_input(LDW_SAFET Y_INPUT_PROCESSING), error_status_torque_limiter(TOR QUE_LIMITER), error_status_output_gen(LDW_SAFETY_OUTPUT_GENERAT OR)	С	All	N/A
Software Safety Requirement 03-02	A software element shall evaluate the error status of all the other software elements and in case any 1 of them indicates an error, it shall deactivate the LDW feature ("activation_status"=0)	С	LDW_SAFETY _ACTIVATION	Activation_status = 0 (LDW function deactivated)
Software Safety Requirement 03-03	In case of no errors from the software elements, the status of the LDW feature shall be set to activated ("activation_status"=1)	С	LDW_SAFETY _ACTIVATION	N/A
Software Safety Requirement 03-04	In case an error is detected by any of the software elements, it shall set the value of its corresponding torque to 0 so that "LDW_Torq_Req" is set to 0	С	All	LDW_Torq_Req = 0
Software Safety	Once the LDW functionality has been deactivated, it shall stay	С	LDW_SAFETY	Activation_status = 0

Requirement 03-05	deactivated till the time the ignition is switched from off to on again.		_ACTIVATION	(LDW function deactivated)
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ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light	eature, the lock shall r display	50ms	LA Malfunction Warning Block	Lane Assistance System is turned off with Error_Statu s True

ID	Software Safety Requirement	Safety Requirement A Software Elements	Software	Safe State
Software Safety Requirement 04-01	When the LDW function is deactivated (activation_status set to 0), the activation_status shall be sent to the car displayECU.	С	LDW_SAFET Y_ACTIVATIO N, CarDisplay ECU	N/A

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory	А	Length of ignition cycle	Memory Test Block	Lane Assistance System is turned off

ookware datety requirement. A Anocation date date		ID	Software Safety Requirement	Α	Allocation	Safe State
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		S I L	Software Elements	
Software Safety Requirement 05-01	A CRC verification check over the software code in the Flash memory shall be done every time the ignition is switched from off to on to check for any corruption of content.	Α	MEMORYTES T	Activation_status = 0
Software Safety Requirement 05-02	Standard RAM tests to check the data bus, address bus and device integrity shall be done every time the ignition is switched from off to on (E.g.walking 1s test, RAM pattern test. Refer RAM and processor vendor recommendations)	ess bus and shall be done gnition is off to on test, RAM fer RAM and or	MEMORYTES T	Activation_status = 0
Software Safety Requirement 05-03	The test result of the RAM or Flash memory shall be indicated to the LDW_Safety component via the "test_status" signal	Α	MEMORYTES T	Activation_status = 0
Software Safety Requirement 05-04	In case any fault is indicated via the "test_status" signal the INPUT_LDW_PROCESSING shall set an error on error_status_input (=1) so that the LDW functionality is deactivated and the LDWTorque is set to 0	Α	LDW_SAFET Y_INPUT_PR OCESSINGAc tivation_status = 0	LDW_SAFETY_INPUT_ PROCESSINGActivatio n_status = 0

Refined Architecture Diagram

