

# 自编码器与Neural Transfer

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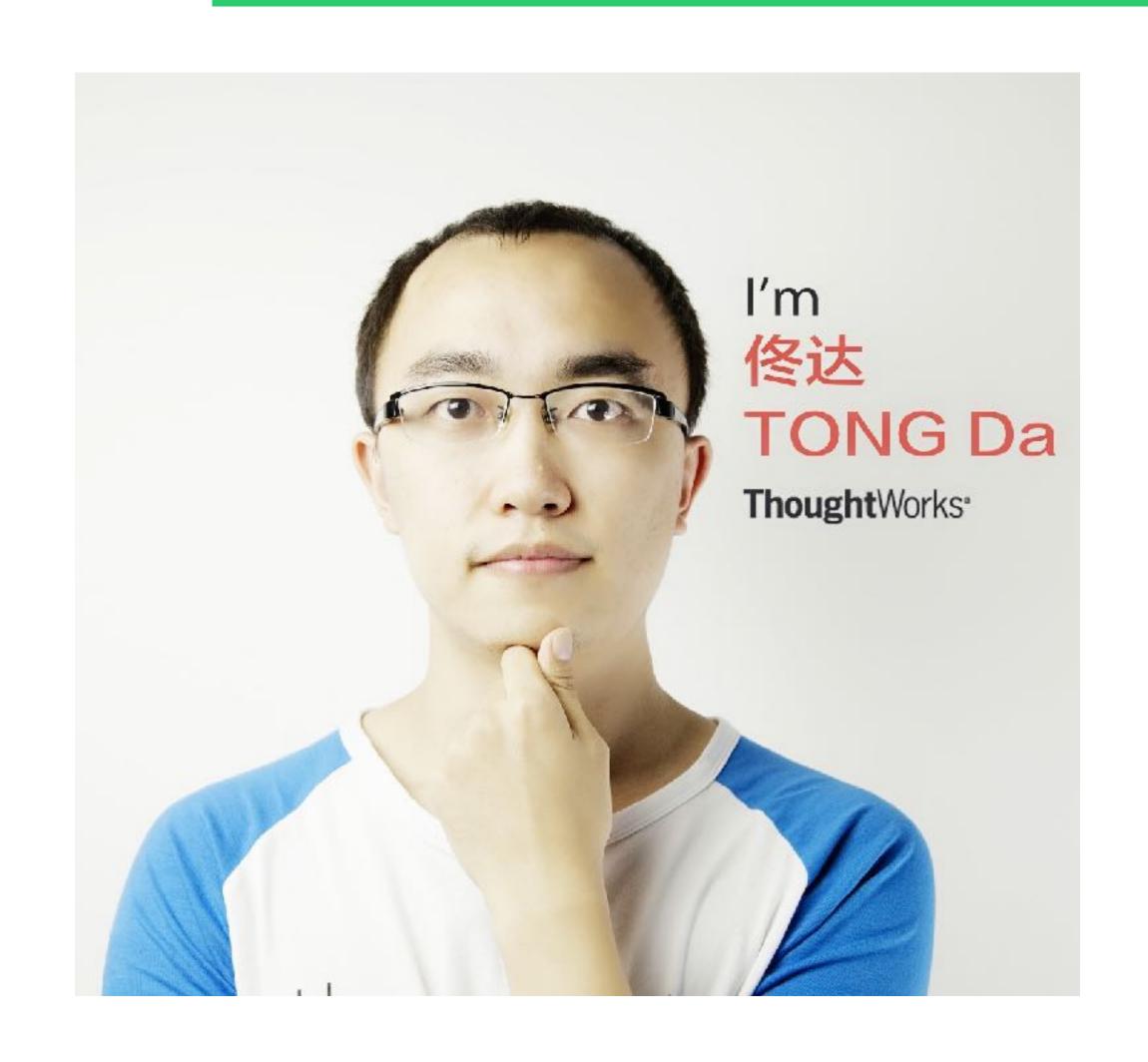


#### 学习目标:

- ■优化器
- ■自编码器
- ■反卷积
- Live Coding Autoencoder
- Regularization (L1/L2, Dropout, Batch Normalization)
- Neural Transfer



#### 讲师介绍:



会coding的科学家,懂数学的工程师,常年提 着酱油瓶游走在学术与工程之间,从云计算到 DevOps,从微服务到人工智能,不敢止步。



#### 回顾



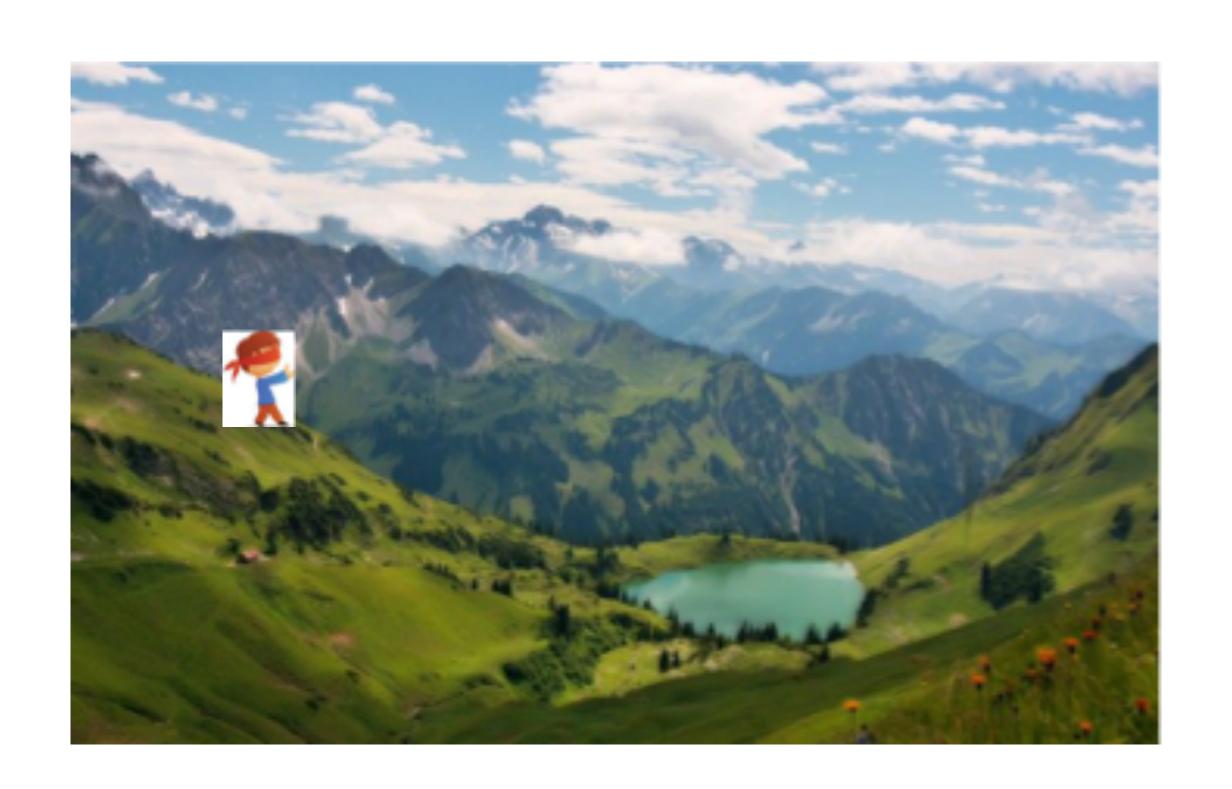
#### 卷积神经络(CNN)

- ■解卷积神经 络和相关概念
- ■学习如何在 TensorFlow 中创建、训练 CNN 模型



#### 优化器 (Optimizer)







- ■采样一批次(batch)数据
- ■前向通过计算图,计算Loss
- ■反向计算梯度
- 更新参数



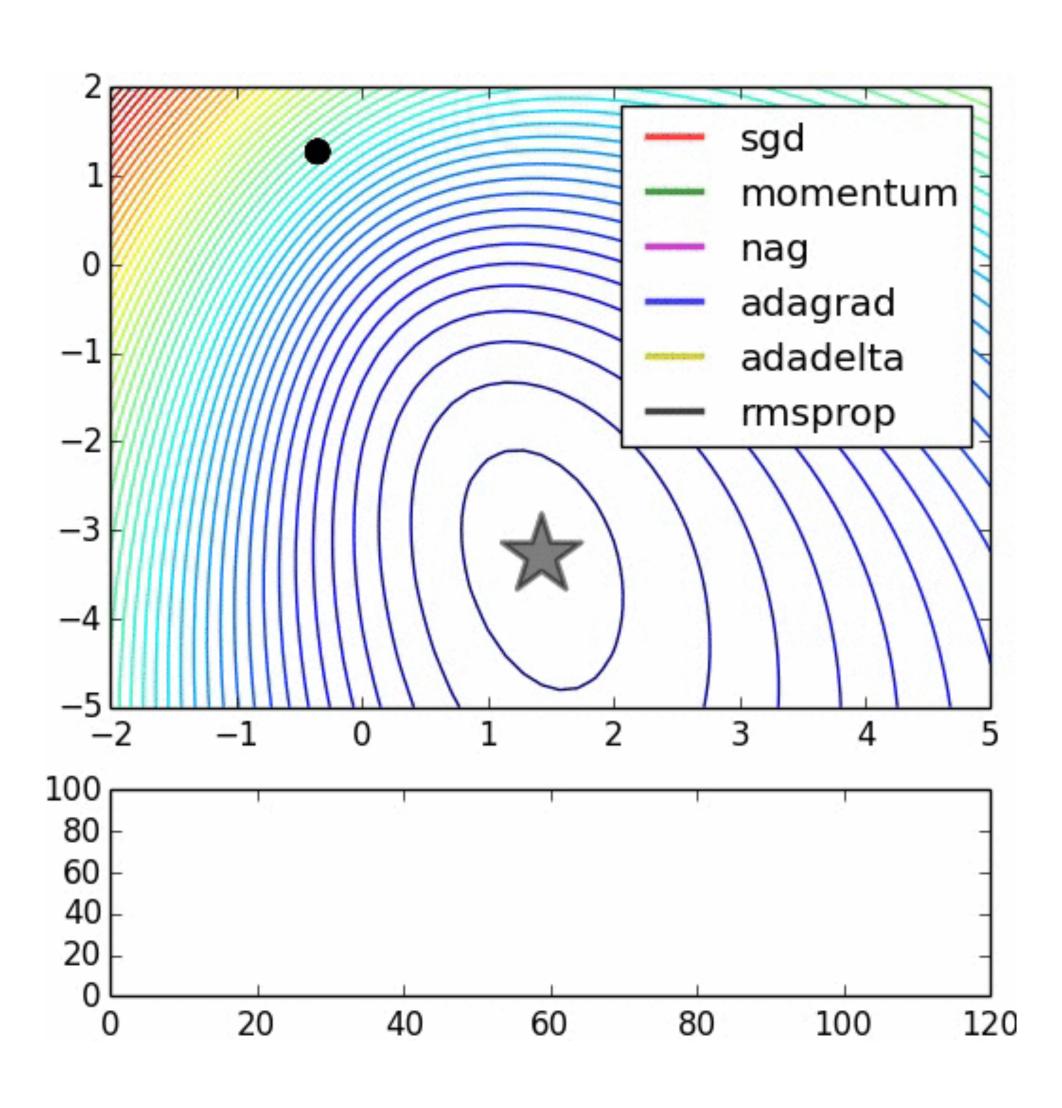
```
while True:
    data_batch = dataset.sample_data_batch()
    loss = network.forward(data_batch)
    dx = network.backward()
    x += - learning_rate * dx
```



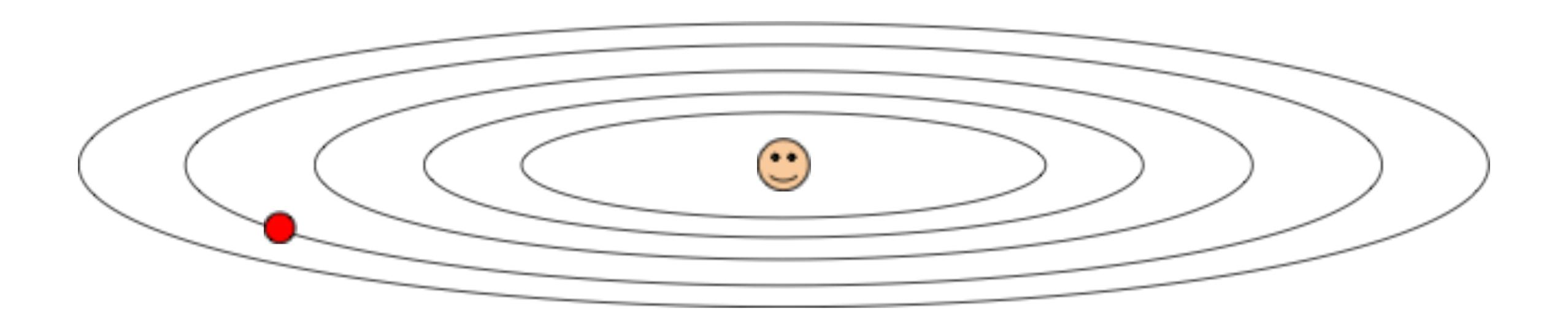
```
while True:
    data_batch = dataset.sample_data_batch()
    loss = network.forward(data_batch)
    dx = network.backward()
    x += - learning_rate * dx
```

更复杂的更新策略



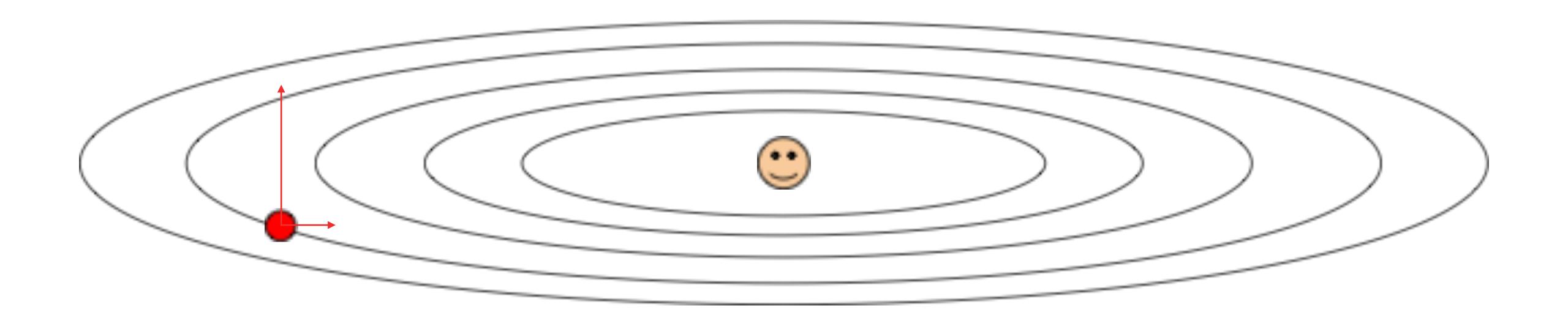






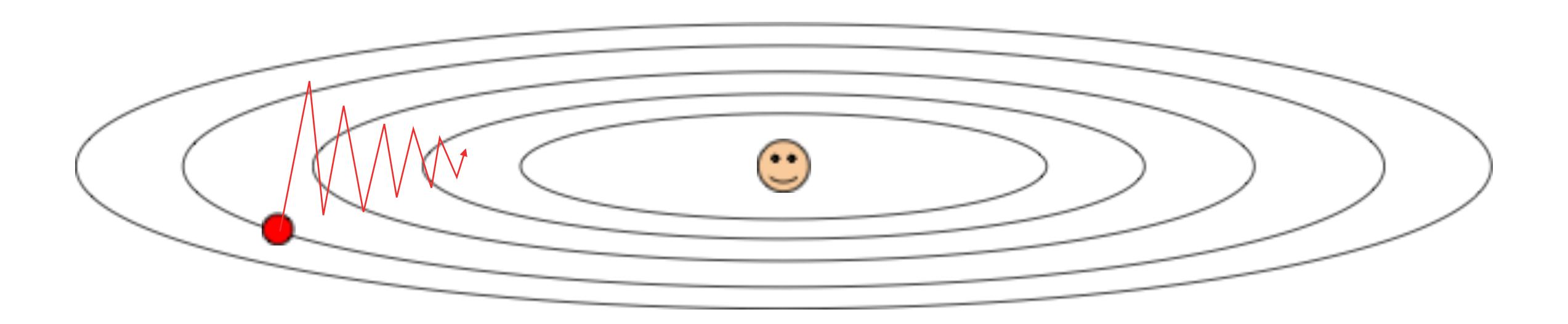
思考: 当前情况下, SGD策略的更新轨迹是什么样的。





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思考: 当前情况下,SGD策略的更新轨迹是什么样的。 在比较陡峭的方向会来回抖动,在平缓的方向缓慢趋向最低点。



#### Momentum (动量) Update

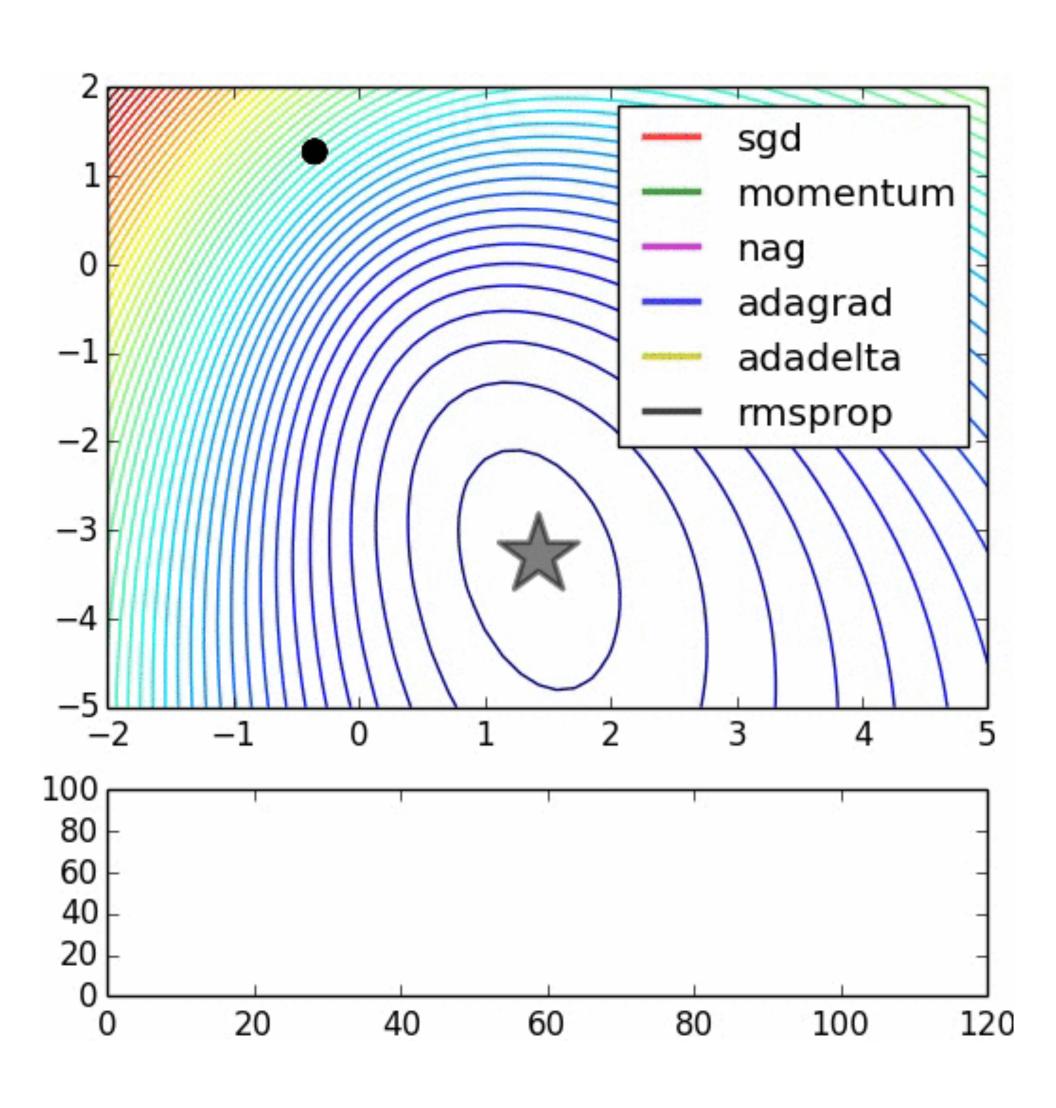
```
x += - learning_rate * dx
```

从物理的惯性角度思考 在平缓的方向上,不断累积速度, 在陡峭的方向上,由于不断变换符 号,速度会被抑制。

```
x = mu * v - learning_rate * dx
x += v
```



#### SGD vs Momentum

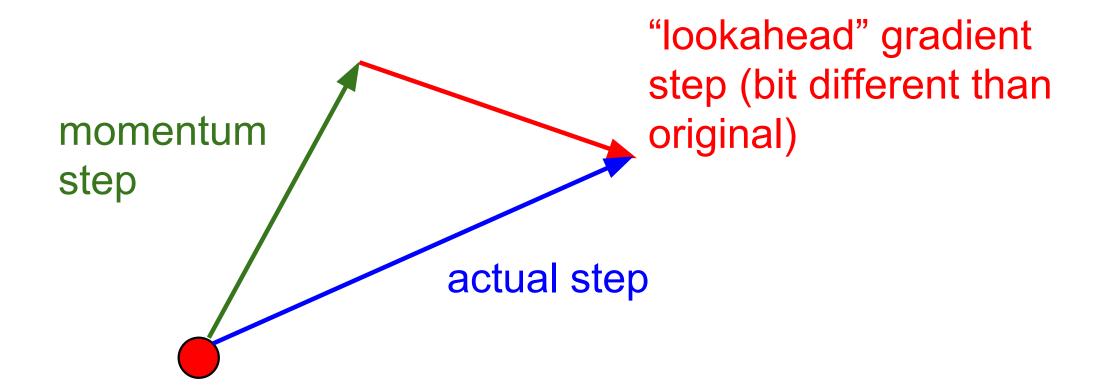




#### Nesterov Accelerated Gradient

# momentum update momentum step gradient step

#### Nesterov momentum update





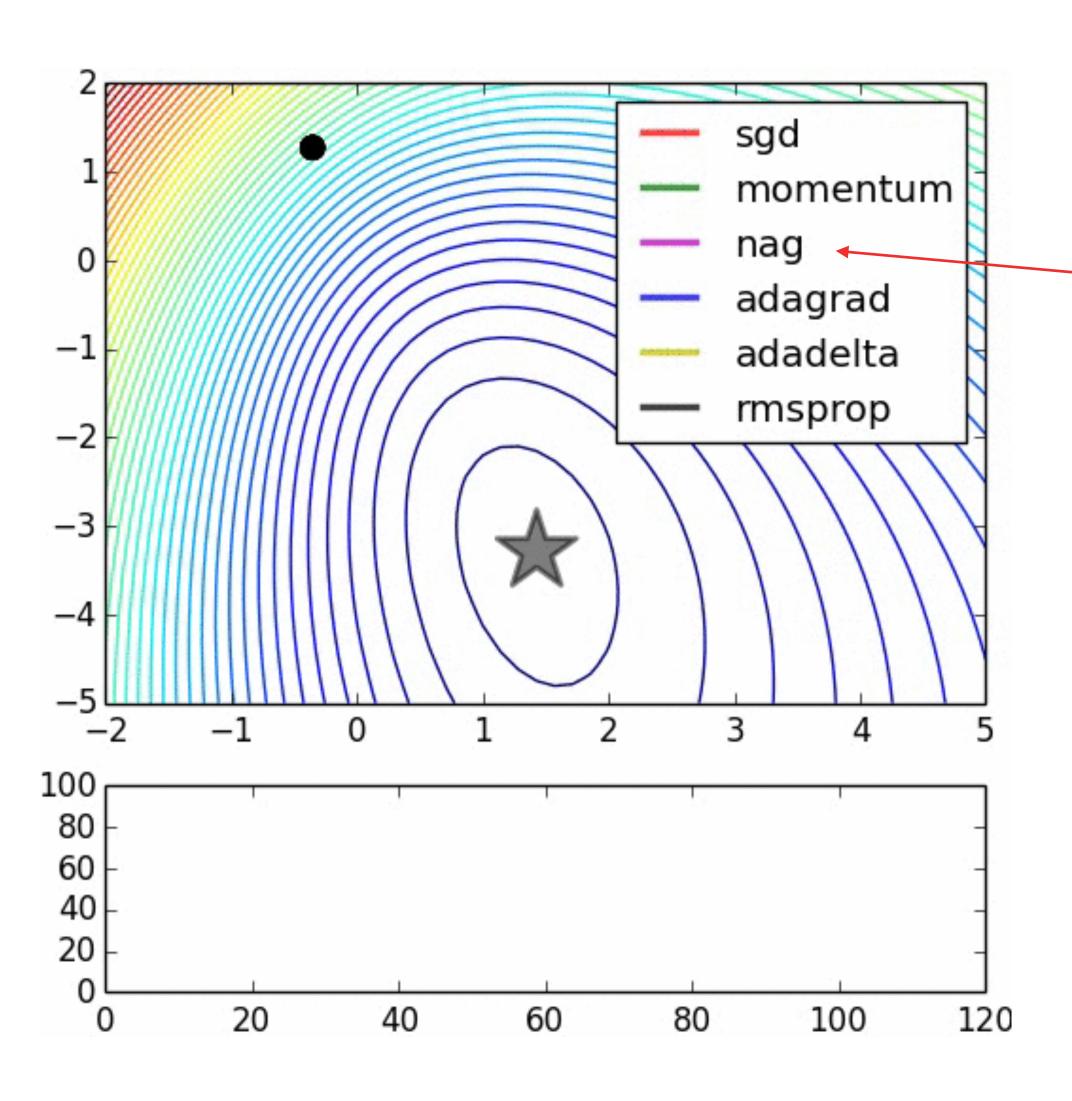
#### Nesterov Accelerated Gradient

```
x = mu * v - learning_rate * dx
x += v
```

```
v_prev = v
v = mu * v - learning_rate * dx
x += -mu * v_prev + (1 + mu) * v
```



#### NAG





#### AdaGrad

```
cache += dx**2
x += - learning_rate * dx / (np.sqrt(cache) + 1e-7)
```

基于每个维度每一个元素的历史平方和,计算learning\_rate的调整比例



#### AdaGrad

```
cache += dx**2
x += - learning_rate * dx / (np.sqrt(cache) + 1e-7)
```

基于每个维度每一个元素的历史平方和,计算learning\_rate的调整比例随着训练时间越来越长,每次更新的步长会越来越小。



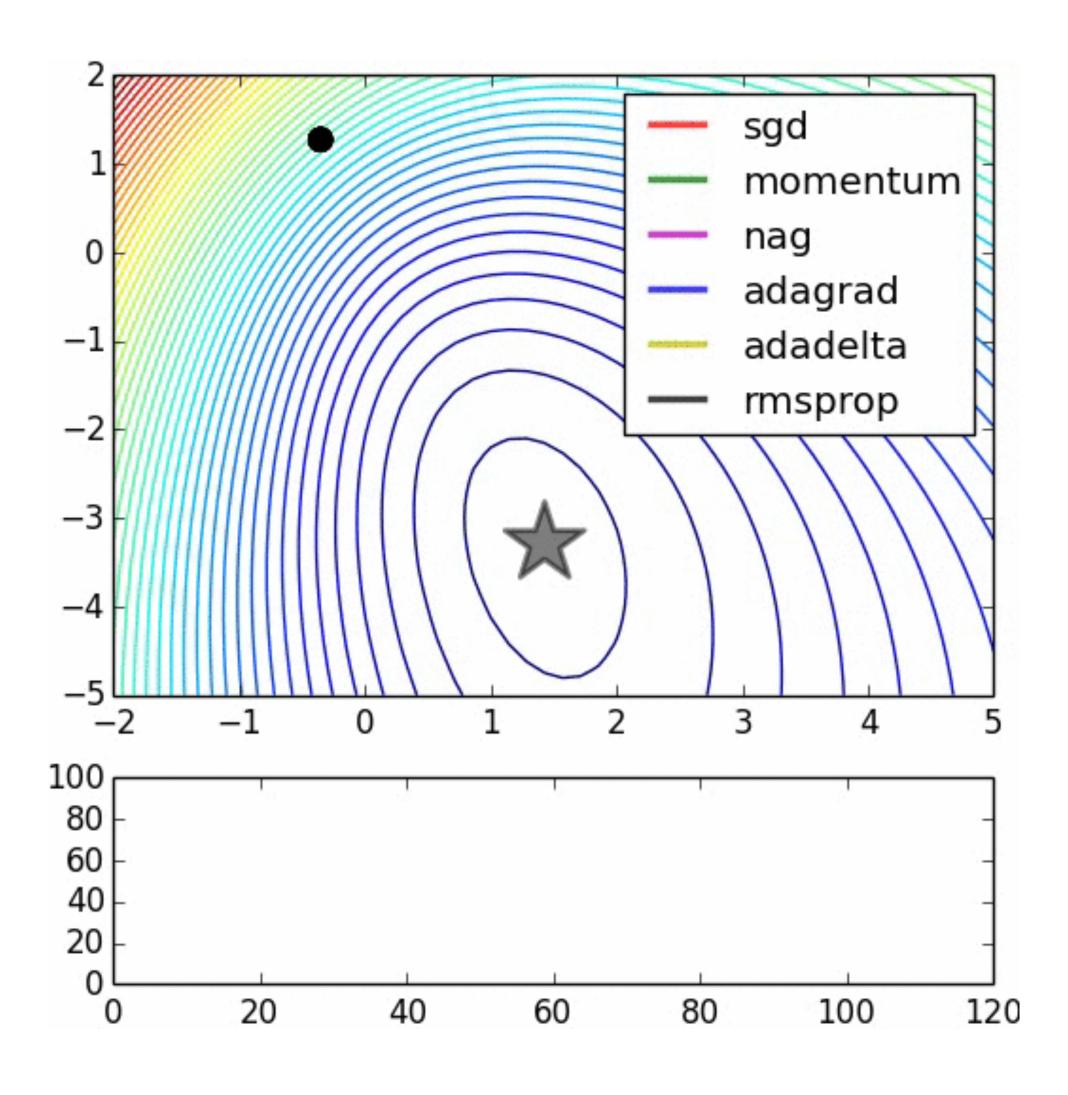
#### RMSProp

```
cache += dx**2
x += - learning_rate * dx / (np.sqrt(cache) + 1e-7)
```

```
cache += decay_rate * cache + (1 - decay_rate) * dx**2
x += - learning_rate * dx / (np.sqrt(cache) + 1e-7)
```



#### AdaGrad vs RMSProp



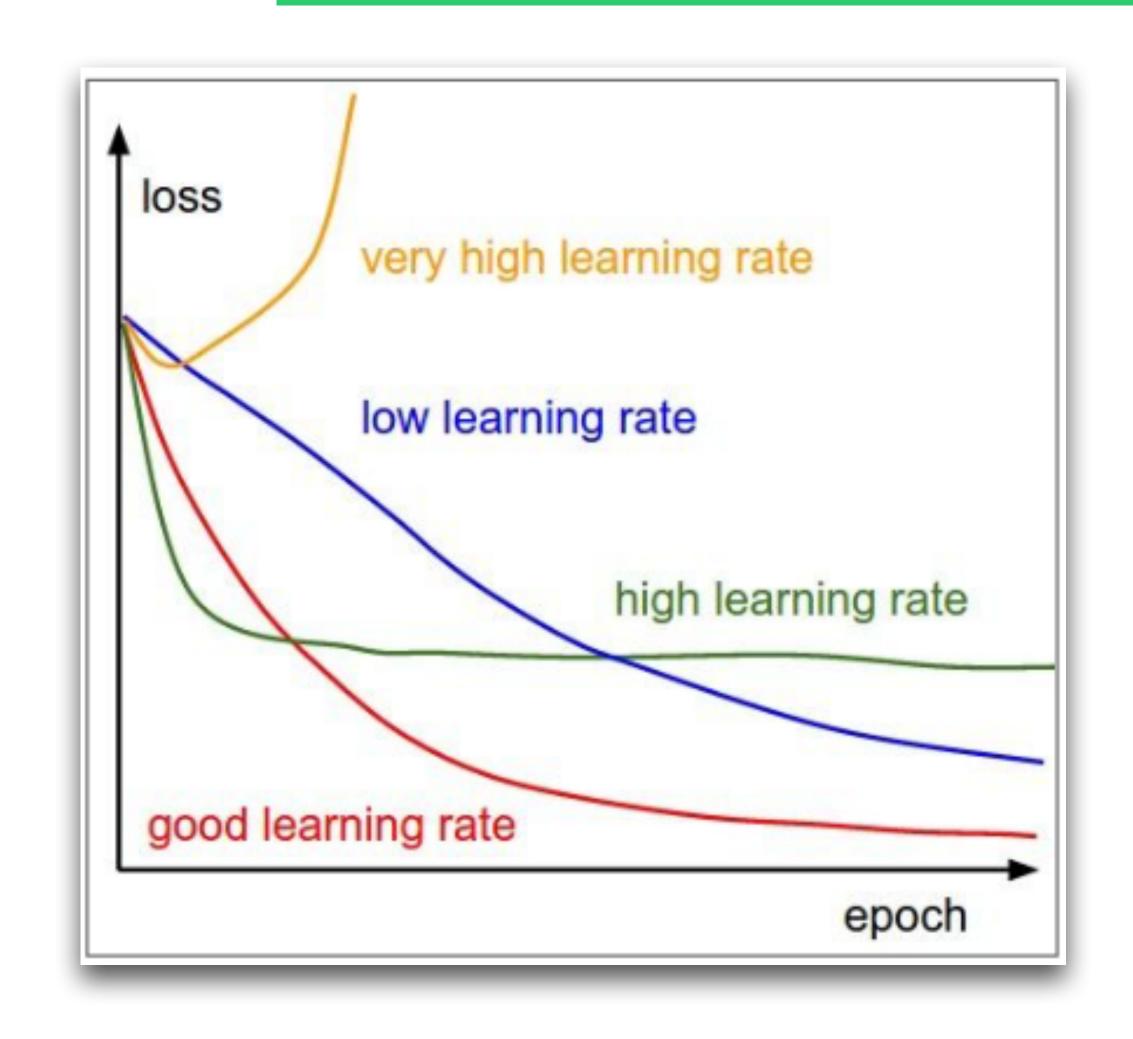


#### Adam Update

```
m = beta1 * m + (1 - beta1) * dx
v = beta2*v + (1 - beta2) * (dx**2)
mb = m / (1 - beta1**5)
vb = v / (1 - beta2**t)
x += - learning_rate * mb / (np.sqrt(vb) + 1e-7)
```



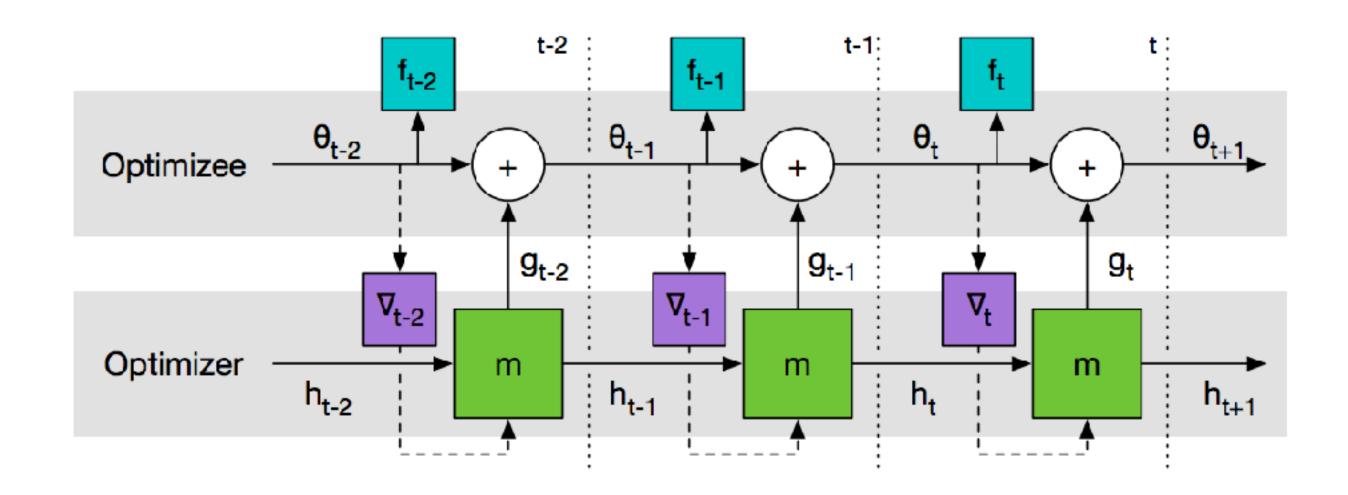
#### 如何选择?

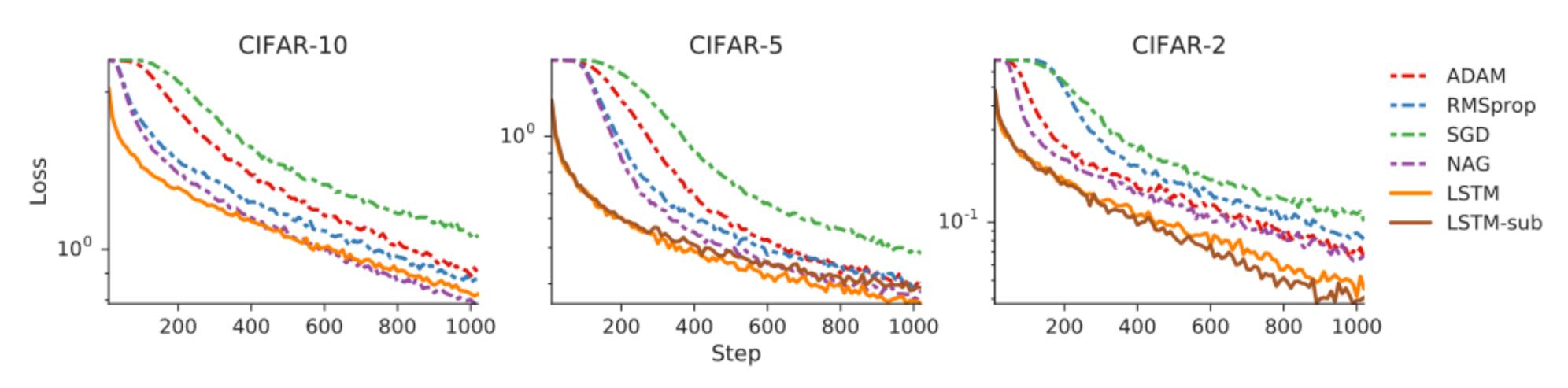


一个好的学习曲线,应该是一开始可以 让Loss快速下降,同时在最低点收敛。



#### Learning to Learn





#### Optimizer in TensorFlow

#### Optimizers

The Optimizer base class provides methods to compute gradients for a loss and apply gradients to variables. A collection of subclasses implement classic optimization algorithms such as GradientDescent and Adagrad.

You never instantiate the Optimizer class itself, but instead instantiate one of the subclasses.

- tf.train.Optimizer
- tf.train.GradientDescentOptimizer
- tf.train.AdadeltaOptimizer
- tf.train.AdagradOptimizer
- tf.train.AdagradDAOptimizer
- tf.train.MomentumOptimizer
- tf.train.AdamOptimizer
- tf.train.FtrlOptimizer
- tf.train.ProximalGradientDescentOptimizer
- tf.train.ProximalAdagradOptimizer
- tf.train.RMSPropOptimizer

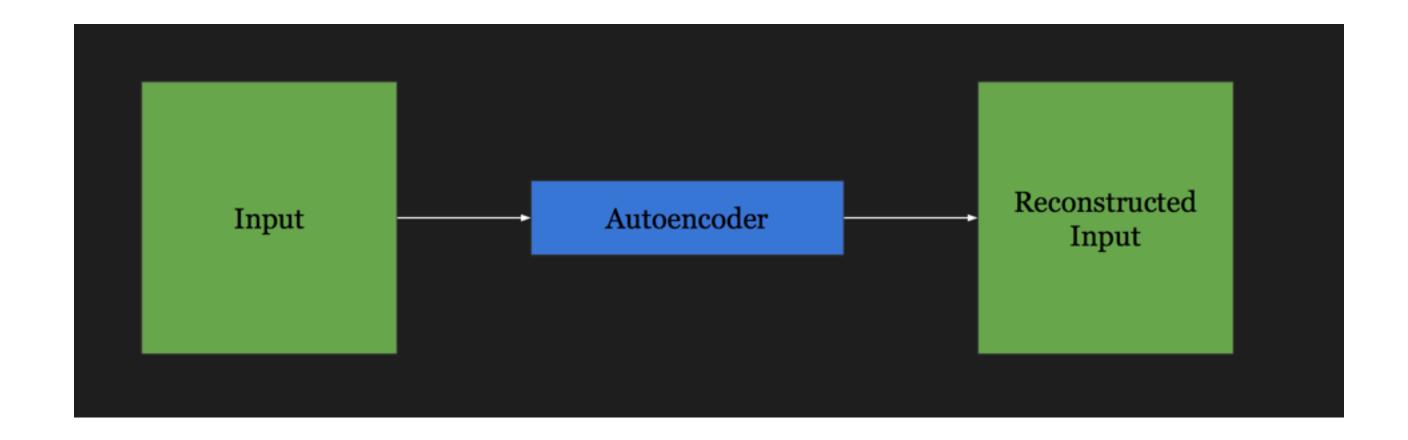
optimizer = tf.train.XXOptimizer(learning\_rate=0.1).minimize(loss)



#### 自编码器 (Autoencoder)



#### 什么是AUTOENCODER



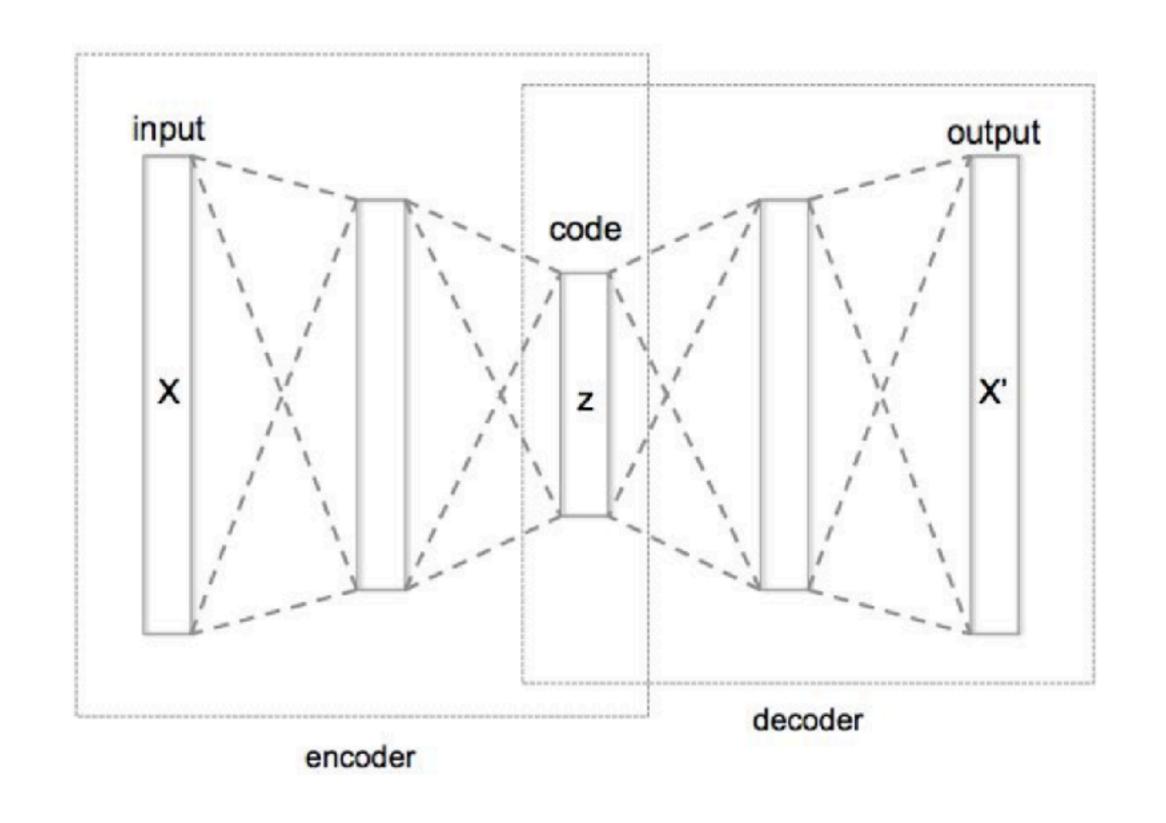


#### AUTOENCODER

autoencoder就是一种尽可能复现输入信号的神经网络, autoencoder是无监督学习



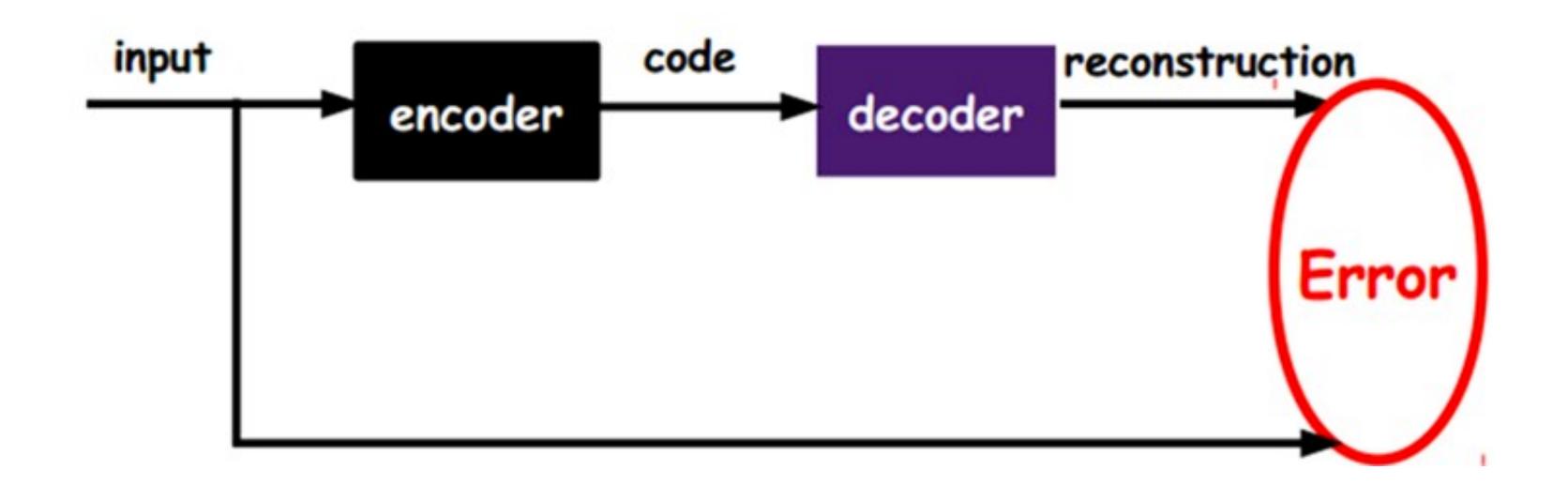
#### AUTOENCODER



输入和输出的维度应该相同输入和输出的范围应该相同



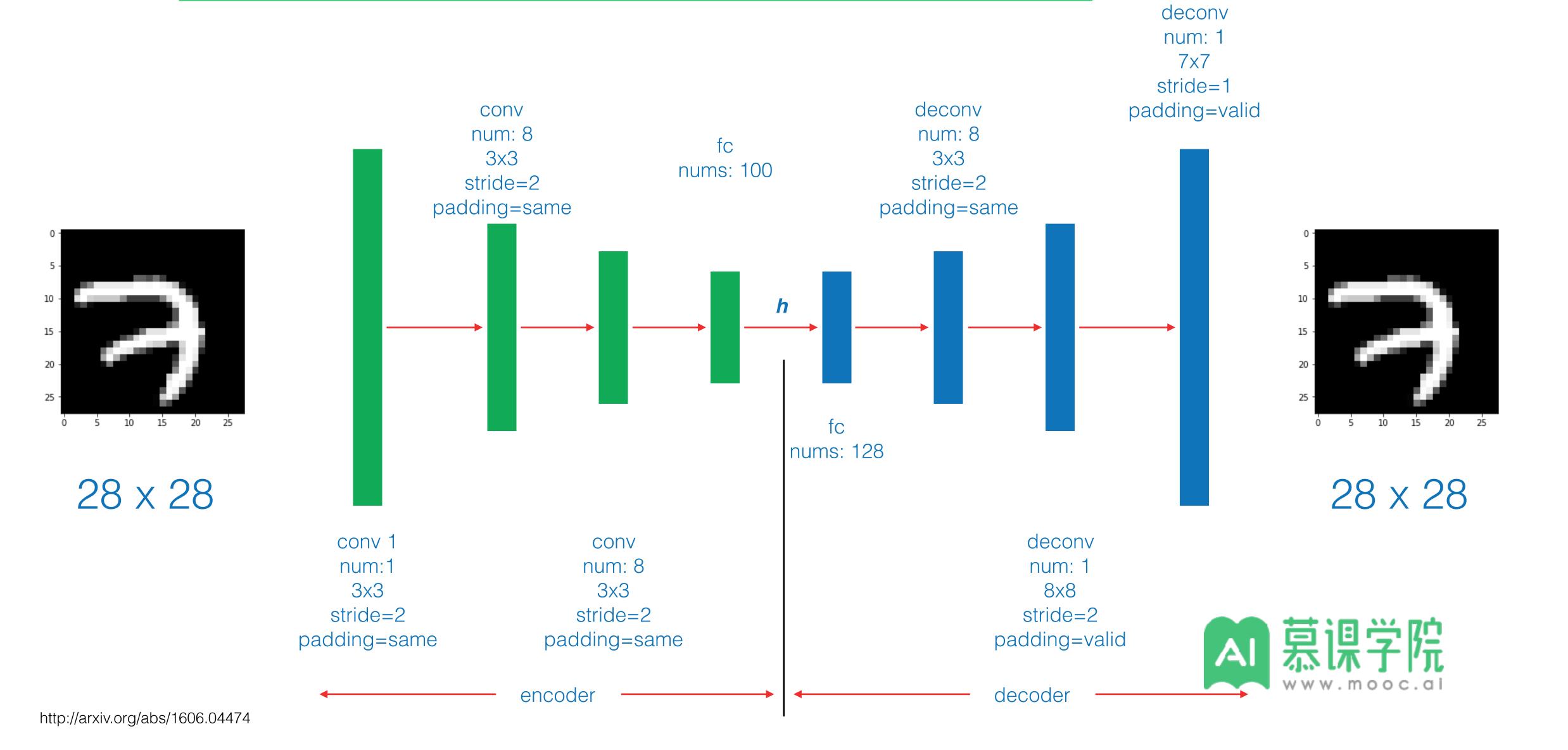
#### AUTOENCODER怎么求误差



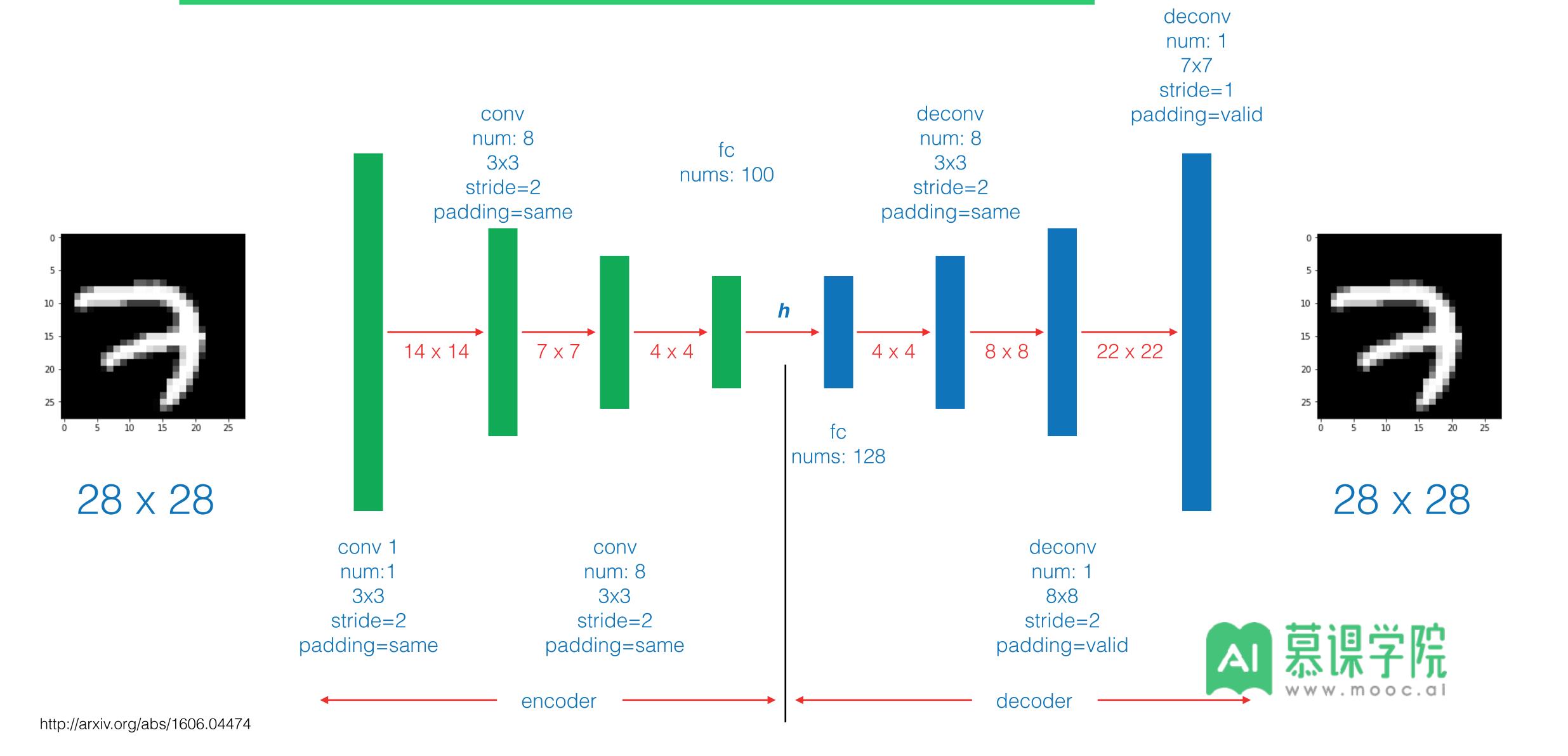
将input输入一个encoder编码器,就会得到一个code, code表示输入,加一个decoder解码器, decoder得到输出,通过通过调整encoder和decoder的参数,使得输入和输出的。



#### Autoencoder



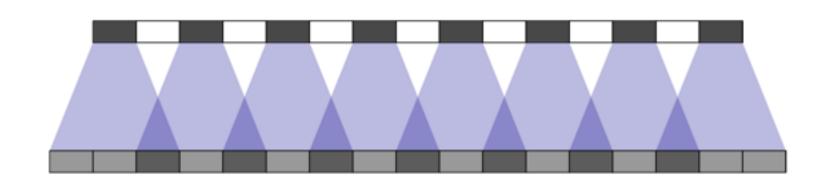
#### Autoencoder

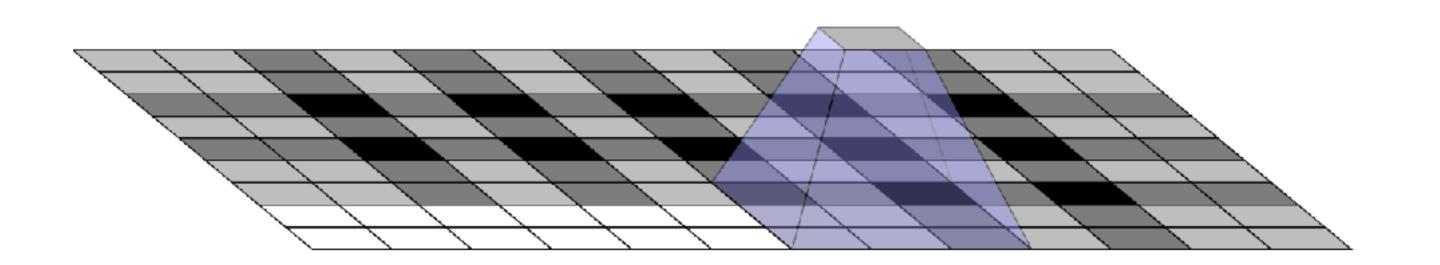


#### 反卷积 (Deconvolution)



### 反卷积







#### 反卷积

tf.nn.conv2d\_transpose(value, filter, output\_shape, strides, padding='SAME',
data\_format='NHWC', name=None)

The transpose of conv2d.

This operation is sometimes called "deconvolution" after Deconvolutional Networks, but is actually the transpose (gradient) of conv2d rather than an actual deconvolution.

#### Args:

- value: A 4-D Tensor of type float and shape [batch, height, width, in\_channels] for NHWC data format or [batch, in\_channels, height, width] for NCHW data format.
- filter: A 4-D Tensor with the same type as value and shape [height, width, output\_channels, in\_channels]. filter's in\_channels dimension must match that of value.
- output\_shape: A 1-D Tensor representing the output shape of the deconvolution op.
- strides: A list of ints. The stride of the sliding window for each dimension of the input tensor.
- padding: A string, either 'VALID' or 'SAME'. The padding algorithm. See the comment here
- data\_format: A string. 'NHWC' and 'NCHW' are supported.
- name: Optional name for the returned tensor.

```
def get_deconv2d_output_dims(input_dims, filter_dims, stride_dims, padding):
    # Returns the height and width of the output of a deconvolution layer.
    batch_size, input_h, input_w, num_channels_in = input_dims
    filter_h, filter_w, num_channels_out = filter_dims
    stride_h, stride_w = stride_dims
    # Compute the height in the output, based on the padding.
    if padding == 'SAME':
        out_h = input_h * stride_h
    elif padding == 'VALID':
        out_h = (input_h - 1) * stride_h + filter_h
    # Compute the width in the output, based on the padding.
    if padding == 'SAME':
        out_w = input_w * stride_w
    elif padding == 'VALID':
        out_w = (input_w - 1) * stride_w + filter_w
    return [batch_size, out_h, out_w, num_channels_out]
```



#### Live Coding



#### Q&A

https://github.com/tongda/leifeng\_tf\_course



# 場場

如果您有任何问题和建议

请联系 dtong@thoughtworks.com

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