## 임베디드 MCU 프로그래밍

# 초음파 센서 / Buzzer / 3색 LED 구동 / CCU61 Timer

Architecture and Compiler for Embedded System LAB.
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# 초음파 센서 모듈



VCC = +5VDC

Trig = Trigger input of Sensor

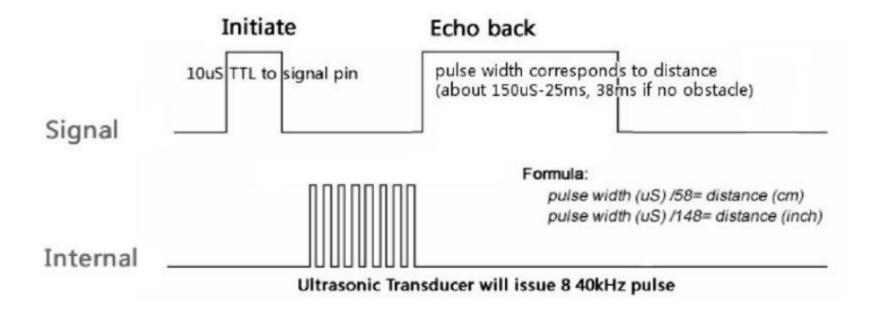
Echo = Echo output of Sensor

GND = GND

### 초음파 센서 모듈

Time = Width of Echo pulse, in uS (micro second)

- Distance in centimeters = Time / 58
- Distance in inches = Time / 148
- Or you can utilize the speed of sound, which is 340m/s



Hitex ShieldBuddy TC275

D15 4	(SCL0-3)	J403	
P15_5	(SDA0-3)	- 8	
P20_3	(RXD2)	7	
P20_0	(TXD2)	5	
P33_8	(RXD1)	4	1 /
P33_9	(TXD1)	3	,,,
P15_1	(RXD0)	2	,,,,
P15 0	(TXD0)	1	, , , , , , , , , , , , , , , , , , ,
Al-Almara Live		1	,,,,
	SS	W-108-0	1-G-S



**External Interrupt** 

Pin	Symbol	Ctrl	Type	Function		
138	P15.5	I	MP /	General-purpose input		
	TIN76		PU1 /	GTM input		
	ARX1B		VEXT	ASCLIN1 input		
	MTSR2A			QSPI2 input		
	REQ13			SCU input		
	SDA0C			I2C0 input		
	P15.5	00		General-purpose output		
	TOUT76	01		GTM output		
	ATX1	02		ASCLIN1 output		
	MTSR2	О3		QSPI2 output		
	END02	04		MSC0 output		
	EN00	05		MSC0 output		
	SDA0	06		I2C0 output		
	CC61	07		CCU60 output		
137	P15.4	I	MP/	General-purpose input		
	TIN75		PU1/	GTM input		
	MRST2A		VEXT	QSPI2 input		
	REQ0			SCU input		
	SCL0C			I2C0 input		
	P15.4	00		General-purpose output		
	TOUT75	01		GTM output		
	ATX1	02		ASCLIN1 output		
	MRST2	О3		QSPI2 output		
	_	04		Reserved		
	_	O5		Reserved		
	SCL0	06		I2C0 output		
	CC62	07		CCU60 output		

#### **Ultrasonic**

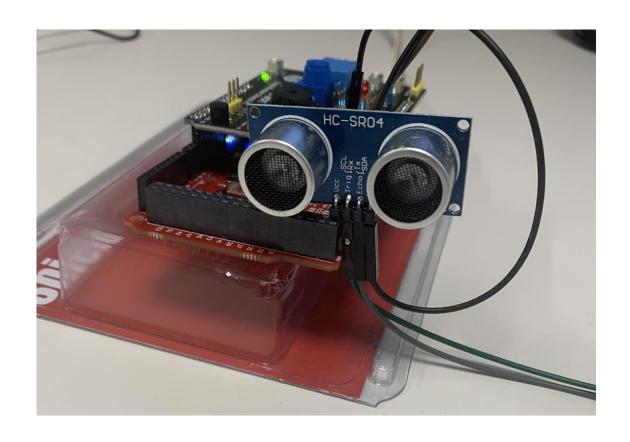
#### VDD(5V)

Trig P15\_4

Echo P15\_5

GND GND

거리(cm) printf로 출력





### 초음파 센서 모듈

#### 1. 프로그래밍

- ① Trigger 출력.
- ② Timer Start.
- ③ External interrupt falling Edge Detection Interrupt → CNT Read
- ④ External interrupt rising Edge Detection Interrupt → CNT Read
- ⑤ CNT 차이를 이용하여 거리 계산
- ⑥ External Interrupt가 Timer Max나 정해진 시간까지 발생하지 않을 시 초음파 센서 초기 모드로 전환.
- 2. Github에 Rerence Source code 제공 예정

## Buzzer 구동

모듈	TC275 Shield Buddy Pin	TC275 Pin	TC275 관련기 능	
Buzzer	D5	P02_3	PWM	

)2	P02.3	1	I LP/	General-purpose input	
	TIN3		PU1 /	GTM input	
	ARX1G		VEXT	ASCLIN1 input	
	RXDCAN2B			CAN node 2 input	
	RXDB2			ERAY input	
	PSIRX0B			PSI5 input	
	DSCIN5B			DSADC channel 5 input B	
	SDI11			MSC1 input	
	CIFD3			CIF input	
	P02.3	00		General-purpose output	
	TOUT3	01		GTM output	
	ASLSO2	02		ASCLIN2 output	
	SLSO34	03		QSPI3 output	
	DSCOUT5	04		DSADC channel 5 output	
	_	05		Reserved	
	-	06		Reserved	
	COUT61	07		CCU60 output	

#### TOMO – Channel 11

Port	Input	Output	Input Timer Mapped		Output Timer Mapped				
			Α	В	Α	В	С	D	
P02.2	TIN2	TOUT2	TIM0_2	TIM1_2	TOM0_10	TOM1_10	ATOM 0_2	ATOM 1_2	
P02.3	TIN3	TOUT3	TIM0_3	TIM1_3	TOM0_11	TOM1_11	ATOM 0_3	ATOM 1_3	

// Buzzer ON
GTM\_CMU\_CLK\_EN |= ((0x2) << EN\_FXCLK);
// Buzzer Off

GTM\_CMU\_CLK\_EN &= ~((0x2) << EN\_FXCLK); // disable

#### github에 Reference code 제공예정

				옥타브((	Octaves)			
	1	2	3	4	5	6	7	8
C(도)	32.7	65.4 130.8 261.6		261.6	523.2	1046.5	2093.0	4186.0
C#	34.6	69.3	138.6 277.2	554.4	1108.7	2217.5	4434.9	
D(레)	36.7	73.4	146.8	293.7	587.3	1174.7	2349.3	4698.6
D#	38.9	77.8	77.8 155.6 311.1	311.1	.1 622.2 1244.5		2489.0	4978.0
E(0 )	41.2	82.4	164.8	329.6	659.3	1318.5	2637.0	5274.0
F(파)	43.7	87.3	174.6	349.2	698.5	1396.9	2793.8	5587.7
F#	46.2	92.5	185.0	370.0	740.0	1480.0	2960.0	5919.9
G(솔)	49.0	98.0	196.0	392.0	783.9	1568.0	3136.0	6271.9
G#	51.9	103.8	207.7	415.3	830.6	830.6 1661.2	3322.4	6644.9
A(라)	55.0	110.0	220.0	440.0	880.0	1760.0	3520.0	7040.0
<b>A</b> #	58.3	116.5	233.1	466.1	932.3	1864.7	3729.3	7458.6
B(시)	61.7	123.5	246.9	493.9	987.8	1975.5	3951.0	7902.1



#### **RGB - PWM**

	모듈		TC275 Shield Buddy Pin TC275 Pin		TC275 관련기 능	
		Red	D9	P02_7	GPIO, PWM	
	RGB LED	Green	D10	P10_5	GPIO, PWM	
		Blue	D11	P10_3	GPIO, PWM	

Pin	Symbol	Ctrl	Туре	Function
F2	P02.7	1	MP/	General-purpose input
	TIN7		PU1/	GTM input
	SCLK3A		VEXT	QSPI3 input
	PSIRX2B			PSI5 input
	SENT1C			SENT input
	CC61INC			CCU60 input
	CCPOS1A			CCU60 input
	T13HRB			CCU61 input
	T3EUDA			GPT120 input
	CIFD7			CIF input
	DSCIN3B			DSADC channel 3 input B
	DSITR4E			DSADC channel 4 input E
	P02.7	00		General-purpose output
	TOUT7	01		GTM output
	-	02		Reserved
	SCLK3	О3		QSPI3 output
	DSCOUT3	04		DSADC channel 3 output
	VADCEMUX01	O5		VADC output
	SPC1	O6		SENT output
	CC61	07		CCU60 output

Pin	Symbol	Ctrl	Type	Function		
<b>46</b>	P10.3	I	MP/	General-purpose input		
	TIN105		PU1 /	GTM input		
	MTSR1A		VEXT	QSPI1 input		
	REQ3			SCU input		
	T5INB			GPT120 input		
	P10.3	00		General-purpose output		
	TOUT105	01		GTM output		
	VADCG6BFL3	02		VADC output		
	MTSR1	O3		QSPI1 output		
	EN00	04		MSC0 output		
	END02	O5		MSC0 output CAN node 2 output Reserved		
	TXDCAN2	O6				
	_	07				
<b>B</b> 5	P10.5	I	LP /	General-purpose input		
	TIN107		PU1 /	GTM input		
	HWCFG4		VEXT	SCU input		
	INJ01			MSC0 input		
	P10.5	00		General-purpose output		
	TOUT107	01		GTM output		
	ATX2	02		ASCLIN2 output		
	SLSO38	О3		QSPI3 output		
	SLSO19	04		QSPI1 output		
	T6OUT	O5		GPT120 output		
	ASLSO2	06		ASCLIN2 output		
	-	07		Reserved		

#### **RGB - PWM**

	Port	Input	Output	Input Timer Mapped		Output Timer Mapped			
				Α	В	Α	В	С	D
Red	P02.7	TIN7	TOUT7	TIM0_7	TIM1_7	TOM0_15	TOM1_15	ATOM 0_7	ATOM 1_7
	P02.8	TIN8	TOUT8	TIM2_0	TIM3_0	TOM0_8	TOM1_0	ATOM 0_0	ATOM 1_0
	P10.0	TIN102	TOUT102	TIM0_4	TIM1_4	TOM0_4	TOM2_12	ATOM 1_4	ATOM 4_4
	P10.1	TIN103	TOUT103	TIM0_1	TIM1_1	TOM0_1	TOM2_9	ATOM 1_1	ATOM 4_1
	P10.2	TIN104	TOUT104	TIM0_2	TIM1_2	TOM0_2	TOM2_10	ATOM 1_2	ATOM 4_2
Blue	P10.3	TIN105	TOUT105	TIM0_3	TIM1_3	TOM0_3	TOM2_11	ATOM 1_3	ATOM 4_3
	P10.4	TIN106	TOUT106	TIM0_6	TIM1_6	TOM0_6	TOM2_6	ATOM 0_6	ATOM 4_6
Green	P10.5	TIN107	TOUT107	TIM0_2	TIM1_2	TOM0_2	TOM2_10	ATOM 1_2	ATOM 4_2

github에 Reference code 제공예정

## Timer - CCU61 추가

- 1. CCU60 / CCU61의 T12를 사용하여 각각 Timer Interrupt 발생
- 2. Github에 Rerence Source code 제공 예정

# Q&A

## Thank you for your attention

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