

Face recognition with convoluted neural networks

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OT1-PJ12

FOSSART Alexis, RENAULT Benoit

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1 Introduction

2 Running the project

3 Description of the work

3.1 Setting up Caffe to be used through PyCaffe and Docker

3.2 Training the network

3.2.1 Code

```
import numpy as np
import matplotlib.pyplot as plt
from PIL import Image
import caffe

caffe.set_mode_cpu()
solver = caffe.SGDSolver('solver.prototxt')
solver.solve()
```

3.2.2 Adjusting the Docker image for better performances during training

3.3 Evaluating the detection performance of our NN

3.3.1 Code

Basic setup of neural network

```
import caffe

caffe.set_mode_cpu()

model_train = 'conv.prototxt'
model_test = 'deploy.prototxt'
weights = 'deep_iter_100000.caffemodel'

net_training = caffe.Net(model_train, weights, caffe.TEST)
net_testing = caffe.Net(model_test, weights, caffe.TEST)
```

Compute the accuracy of the previously trained neural network on the training dataset (see 01_CNN_Training notebook) by using the accuracy layer of the network (defined in conv.prototxt)

```
NUMBER_OF_IMAGES_ON_TRAINING_SET_WITHOUT_FACE = 26950
NUMBER_OF_IMAGES_ON_TRAINING_SET_WITH_A_FACE = 64770

TOTAL_NUMBER_OF_IMAGES_ON_TRAINING_SET = (NUMBER_OF_IMAGES_ON_TRAINING_SET_WITHOUT_FACE +
                                           NUMBER_OF_IMAGES_ON_TRAINING_SET_WITH_A_FACE)

total_accuracy = 0
batch_size = net_training.blobs['data'].num
test_iters = TOTAL_NUMBER_OF_IMAGES_ON_TRAINING_SET / batch_size
```

```

for i in range(test_iters):
    net_training.forward()
    batch_accuracy = net_training.blobs['accuracy'].data
    total_accuracy += batch_accuracy
accuracy = total_accuracy / test_iters

print "Accuracy of trained network on train data: {}".format(accuracy)
print "Number of well classified images on train data: {}".format(
    int(accuracy * TOTAL_NUMBER_OF_IMAGES_ON_TRAINING_SET))

```

Evaluate the accuracy of the previously trained neural network on the test dataset

```

NUMBER_OF_IMAGES_ON_GOOGLEFACE_TEST = 632
NUMBER_OF_IMAGES_ON_GOOGLE_IMAGES = 6831
NUMBER_OF_IMAGES_ON_YALEFACES_TEST = 165

TOTAL_NUMBER_OF_IMAGES_ON_TEST_SET = (NUMBER_OF_IMAGES_ON_YALEFACES_TEST +
    NUMBER_OF_IMAGES_ON_GOOGLE_IMAGES +
    NUMBER_OF_IMAGES_ON_GOOGLEFACE_TEST)

img_classified_as_faces = 0
img_classified = 0

total_accuracy = 0

batch_size = net_testing.blobs['data'].num
test_iters = TOTAL_NUMBER_OF_IMAGES_ON_TEST_SET / batch_size

for i in range(test_iters):
    net_testing.forward()
    batch_accuracy = net_testing.blobs['accuracy'].data
    total_accuracy += batch_accuracy
    for i in range(batch_size):
        img_classified += 1
        if net_testing.blobs['prob'].data[i].argmax():
            img_classified_as_faces += 1

accuracy = total_accuracy / test_iters

print "Number of faces found on test : {} / {} images".format(img_classified_as_faces,
    img_classified)
print "Accuracy of trained network on test data: {}".format(accuracy)
print "Number of well classified images on test data: {}".format(
    int(accuracy * TOTAL_NUMBER_OF_IMAGES_ON_TEST_SET))

```

3.4 Implementing a naive face detector

Basic setup of neural network

```

import numpy as np
import matplotlib.pyplot as plt
from PIL import Image

```

```

import cv2
import caffe
import os

caffe.set_mode_cpu()
model = 'deploy.prototxt'
weights = 'deep_iter_100000.caffemodel'
net = caffe.Net(model, weights, caffe.TEST)

try:
    os.mkdir("../data/results/")
except OSError: pass
try:
    os.mkdir("../data/results/1/")
except OSError: pass

```

Implementation of face detector Downscaling done by factor of 2 (using an integrated function of opencv which seems to be the only way to do pyramid scaling without destroying the quality of the images). Naive algorithm implementation, without heuristics : we simply use a shifting window of size 36*36px and offset 4px.

```

for id_img in range(1, 8):
    # Used on 7 images named 1.jpg to 7.jpg
    image_path = '../data/' + str(id_img) + '.jpg'

    # Open image and convert to gray scale
    im = cv2.imread(image_path)
    im = cv2.cvtColor(im, cv2.COLOR_BGR2GRAY)

    # Save base image for future comparison
    imbase = im

    scale = 1

    base_save_path = "../data/results/"
    img_base_name = str(id_img) + "_"

    # Used to batch save detected faces, and avoid writing to disk at every loop
    keep = dict()

    # Tuple with (width, height)
    shifting_window_size = 36, 36
    offset = 4

    min_probability_for_a_match = 0.99

    while len(im) >= shifting_window_size[0] * 2 and len(im[0]) > shifting_window_size[1] * 2:
        # Downscale of the image using opencv pyramid scaling
        im = cv2.pyrDown(im)
        scale*=2

        img_scale_name = img_base_name + str(scale) + "_"

```

```

showarray(im)

# Face detector
for x in range(0, len(im) - shifting_window_size[0], offset):
    for y in range(0, len(im[0]) - shifting_window_size[1], offset):
        img_name = img_scale_name + str(x) + "_" + str(y) + ".png"

        # Create the shift window image on the original scaled image
        imtmp = np.array(im [x:x + shifting_window_size[0], y:y + shifting_window_size[1]])

        # Transform the data to be compatible as an entry to the neural network
        im_input = imtmp[np.newaxis, np.newaxis, :, :] / 256.0

        # Input the data in the NN
        net.blobs['data'].reshape(*im_input.shape)
        net.blobs['data'].data[...] = imtmp

        # Run the NN
        output = net.forward()

        # If the probability that the image that is in the
        # shift window is a face is higher than 99%
        if output['prob'][0][1] > min_probability_for_a_match:
            # We add a bounding box in the original image
            white = 255
            for i in range(x * scale, (x + shifting_window_size[0]) * scale):
                imbase[i][y * scale] = white
                imbase[i][(y + shifting_window_size[1]) * scale] = white
            for j in range(y * scale, (y + shifting_window_size[1]) * scale):
                imbase[x * scale][j] = white
                imbase[(x + shifting_window_size[0]) * scale][j] = white

            # Save this in memory
            save_dir = "1/"
            save_path = base_save_path + save_dir + img_name
            keep[save_path] = imtmp

# When everything is done we show the original image
# with the bounding boxes and save it as a file
showarray(imbase)
save_results = "../data/results/" + str(id_img) + ".jpg"
cv2.imwrite(save_results, imbase)

# We also save the face subimages we found to improve the NN in the future
for path, img in keep.iteritems():
    cv2.imwrite(path, img)

```

4 Conclusion