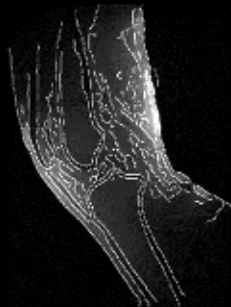


Single frame
of CINE data

Step I



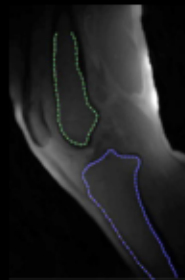
Canny edge
detection

Step II



Connected-component
labelling

Step III



Establishing
reference points

Step IV



Frame-to-frame transformation
of reference points