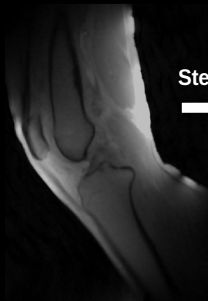


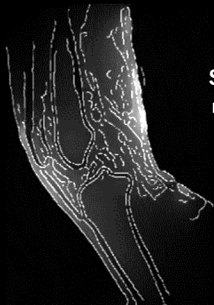
Single frame of
CINE data



Step I



Canny Edge
Detection



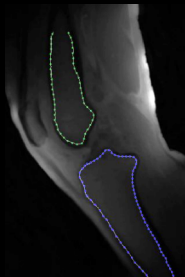
Step II



Connected Component
Labelling

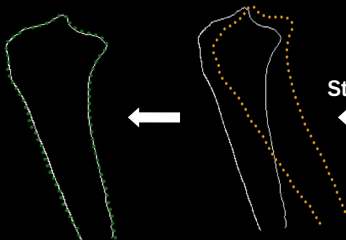


Step III



Establishment of
reference points

Step IV



Frame to frame matching of
reference points to labels