NUMERICAL MODELING OF INCOMPLETE COMBUSTION IN A LIQUID CHEMICAL ROCKET ENGINE

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INTRO

Reasons to pursue a model of a rocket engine:

• Numerical modeling is cool.

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- · Numerical modeling is cool.
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- · Liquid rocket engines are very cool.
- Industry standard software isn't free.
- A learning opportunity!

THE LIQUID ROCKET ENGINE

A rocket engine accelerates a rocket by expelling a reaction mass in the opposite direction of the rocket's motion.

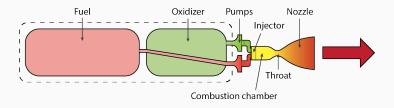


Figure 1: An idealized liquid rocket engine.

The reaction mass of a liquid rocket engine is the gaseous products of combustion. These gases are expelled by their expansion.

VARIABLES OF THE EQUATION OF STATE

- **Internal Energy** *U*, total energy stored in a system, related to the first law of thermodynamics.
 - **Entropy** *S*, a measure of microscopic randomness, related to the second law of thermodynamics.
 - **Volume** *V*, the amount of space a system is allowed to occupy.
- **Composition** N_i , the amount of each component (species) composing a system.
- **Temperature** *T*, a measure of the energy of the system, determines the flow of heat.
 - **Pressure** *P*, characterizes kinetic energy contained in collisions between the system and its surroundings.

[2, 3]

CHEMICAL EQUILIBRIUM

Internal Energy =
$$U(S, V, \{N_i\})$$

$$\frac{\partial U}{\partial S} = T$$
 $\frac{\partial U}{\partial V} = -P$

Minimum-energy principle

$$dU = T dS - P dV + \sum_{i} \frac{\partial U}{\partial N_{i}} dN_{i} = 0$$

Heads Up

Take note especially of the expressions defining T and -P.

[2, 3]

SUMMER WORK

Began with Gordon and McBride, 1994.

- First modern combustion modeling method.
- · Very brief-notoriously so!
- · Highly optimized.
- Had to work backwards through paper.

Halfway through semester–still unhappy with my understanding of the subject.



TOOLS

LEGENDRE TRANSFORMATIONS

The Legendre transformation changes the variables of a function to the associated partials.

$$f(x_1, \dots, x_n) \xrightarrow{\text{Leg.}} \theta\left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}\right)$$

How? The tangent line equation

$$f = df \cdot x + \theta$$

Gives us

$$\theta = f - df \cdot x$$

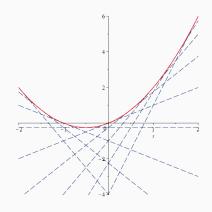


Figure 2: Tangent lines of $f(x) = x^2 + x$

Note

Unique partials are required to obtain a well-defined function.

LAGRANGE MULTIPLIERS

The method of Lagrange multipliers aids in finding extrema of a function subject to some constraints. Observe that:

- $\nabla f = \vec{0}$ at a global extremum.
- $\nabla f = \lambda \nabla c$ at a constrained extremum.
- $\nabla f = \sum_i \lambda_i \nabla c_i$ at a multiply-constrained extremum.

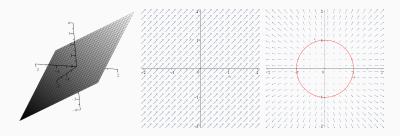


Figure 3: A function, f(x,y) = x + y, its gradient, and a constraint with the gradient of the function of which the constraint is a contour line.

MULTIVARIATE NEWTON'S

Continuously differentiable multivariate functions $f(\vec{x})$ may be linearly approximated for small (but not necessarily infinitesimal) changes of \vec{x} like so:

$$f(\vec{x} + \Delta \vec{x}) = f(\vec{x}) + \sum_{n} \frac{\partial f}{\partial x_{n}} \Delta x_{n} + O(\Delta \vec{x}^{2})$$

If we seek a root,

$$f(\vec{x} + \Delta \vec{x}) = 0$$

Implying that

$$\sum_{n} \frac{\partial f}{\partial x_n} \, \Delta x_n \approx -f(\vec{x})$$

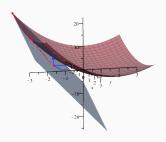


Figure 4: Multivariate
Newton's rootfinding method
descends most steeply along a
tangent plane each iteration.

DERIVATION

We transform internal energy to obtain *enthalphy*, *H*, and *Gibbs energy*, *G*. Minimizing the Gibbs, subject to constant *T*, *P*, is equivalent to minimizing *U* subject to constant *S*, *V*.

$$U(S, V, \{N_i\}) \xrightarrow{\text{Legendre}} H(S, V, \{N_i\}) \xrightarrow{\text{Legendre}} G(T, P, \{N_i\})$$

$$U = U \qquad H = U - PV \qquad G = H + TS$$

Internal Energy vs. Enthalpy

While it is difficult to measure U in a laboratory environment, it is feasible to acquire H data over a large range of temperatures.

[2, 3, 5]

Let us say we have a system of *i* elements and *j* species, some of which may be gaseous, and some of which may not be (condensed).

From physical experimentation, we know that:

$$h = \sum_{j} h_{j}^{\circ} n_{j} \qquad s = \sum_{j} s_{j} n_{j} \qquad s_{j} = \begin{cases} s_{j}^{\circ} & j \text{ cond.} \\ s_{j}^{\circ} - R \ln \left(P \cdot \frac{n_{j}}{n}\right) & j \text{ gas.} \end{cases}$$

Substitution obtains our fundamental expression for the Gibbs.

$$g = \sum_{j}^{\text{cond.}} \left(h_{j}^{\circ} - Ts_{j}^{\circ} \right) n_{j} + \sum_{j}^{\text{gas.}} \left(h_{j}^{\circ} - Ts_{j}^{\circ} + RT \ln \left(P \cdot \frac{n_{j}}{n} \right) \right) n_{j}$$

Here, lowercase thermodynamic symbols are the function specific to mass. $^{\circ}$ indicates a value at the standard pressure of 1 bar. n is the total number of specific mols of gas in the system.

[2, 3, 5]

Our system is subject to constant-temperature, constant-pressure, and atomic conservation constraints. Can be expressed as:

$$T = T_0$$
, or the function $t = 0$, where $t = T - T_0$

$$P = P_0$$
, or the function $p = 0$, where $p = P - P_0$

And the set of *i* atomic conservation constraints

$$\sum_{j} a_{ij} n_j = b_{0,i}$$
, or the functions $e_i = 0$ where $e_i = \sum_{j} a_{ij} n_j - b_{0,i}$

Here, a_{ij} is the number of atoms of element i in a molecule of species j and $b_{0,j}$ is the initial specific number of atoms j.

From this, we know we have the Lagrange equations:

$$t = 0$$

$$p = 0$$

$$e_i = 0, \ \forall i$$

To complete the Lagrange system, we must additionally find

$$\nabla g = \sum_{i} \lambda_{i} \nabla e_{i} + \lambda_{t} \nabla t + \lambda_{p} \nabla p = \begin{cases} \frac{\partial g}{\partial T} = \sum_{i} \lambda_{i} \frac{\partial e_{i}}{\partial T} + \lambda_{t} \frac{\partial t}{\partial T} + \lambda_{p} \frac{\partial p}{\partial T} \\ \frac{\partial g}{\partial P} = \sum_{i} \lambda_{i} \frac{\partial e_{i}}{\partial P} + \lambda_{t} \frac{\partial t}{\partial P} + \lambda_{p} \frac{\partial p}{\partial P} \\ \frac{\partial g}{\partial n_{j}} = \sum_{i} \lambda_{i} \frac{\partial e_{i}}{\partial n_{j}} + \lambda_{t} \frac{\partial t}{\partial n_{j}} + \lambda_{p} \frac{\partial p}{\partial n_{j}}, \ \forall j \end{cases}$$

This gives us the final system:

$$\begin{cases} T - T_0 = 0 \\ P - P_0 = 0 \\ \sum_j a_{ij} n_j - b_{0,i} = 0, \ \forall i \end{cases} & \& \begin{cases} nR - \sum_j s_j n_j = \lambda_t \\ \frac{nRT}{P} = \lambda_P \\ h_j^{\circ} - Ts_j^{\circ} = \sum_i \lambda_i a_{ij}, \ \forall \ \text{cond.} \ j \\ h_j^{\circ} - Ts_j^{\circ} + RT \ln\left(P \cdot \frac{n_j}{n}\right) = \sum_i \lambda_i a_{ij}, \ \forall \ \text{gas.} \ j \end{cases}$$

With a bit of rearranging, we can express this as a set of functions of which we seek the root. (These functions are named with a * to keep them distinct from previous functions.)

$$\begin{cases} T^*(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = T - T_0 \\ P^*(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = P - P_0 \\ E^*_i(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = \sum_j a_{ij} n_j - b_{0,i}, \ \forall \ \text{elements} \ i \\ t^*(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = nR - \sum_j s_j n_j - \lambda_t \\ p^*(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = \frac{nRT}{P} - \lambda_p \\ C^*_j(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = h^\circ_j - Ts^\circ_j - \sum_i \lambda_i a_{ij}, \ \forall \ \text{cond.} \ j \\ G^*_j(T, P, \{n_j\}, \{\lambda_i\}, \lambda_t, \lambda_p) = h^\circ_j - Ts^\circ_j + RT \ln\left(P \cdot \frac{n_j}{n}\right) - \sum_i \lambda_i a_{ij}, \ \forall \ \text{gas.} \ j \end{cases}$$

Note

 T^* and P^* should always be equal to 0. t^* and p^* are similarly worthless to us, as we have no need to find λ_t or λ_p .

Each function f can have its root iteratively found by solving:

$$\frac{\partial f}{\partial T} \Delta T + \frac{\partial f}{\partial P} \Delta P + \sum_{j} \frac{\partial f}{\partial n_{j}} \Delta n_{j} + \sum_{i} \frac{\partial f}{\partial \lambda_{i}} \Delta \lambda_{i} + \frac{\partial f}{\partial \lambda_{t}} \Delta \lambda_{t} + \frac{\partial f}{\partial \lambda_{p}} \Delta \lambda_{p}$$

$$= -f(T, P, \{n_{j}\}, \{\lambda_{i}\}, \lambda_{t}, \lambda_{p})$$

And then adding each of the Δ values to each variable.

To solve our system, we can arrange the partials in a matrix and solve for a simultaneous solution to all equations. In the interest of both space and time, we will not show the massive matrix this derivation produces.

FINAL SYSTEM

After trimming trivial components of the system, we obtain the following reduced iteration matrix equation.

$$\begin{bmatrix}
a_{ij} & j & \vdots & \vdots & \vdots \\
0 & \begin{cases}
\frac{RT}{n_{ij}} - \frac{RT}{n} & \text{on diag.} \\
-\frac{RT}{n} & \text{off-diag.} \\
0 & 0 & -a_{ij}
\end{bmatrix} \} j \text{ (gas.)} \cdot \begin{bmatrix}
\Delta n_{j} \\
\Delta n_{j} \\
\Delta \lambda_{i}
\end{bmatrix} \} j \text{ (gas.)}$$

$$\begin{bmatrix}
\Delta n_{j} \\
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\end{bmatrix} \} j \text{ (gas.)}$$

$$\begin{bmatrix}
\lambda_{i} a_{ij} - h_{j}^{\circ} + Ts_{j}^{\circ} - RT \ln \left(P \cdot \frac{n_{j}}{n}\right) \\
\sum_{i} \lambda_{i} a_{ij} - h_{i}^{\circ} + Ts_{j}^{\circ}
\end{bmatrix} \} j \text{ (cond.)}$$

IMPLEMENTATION

We implement the solution in Python 3 by the following:

Algorithm 1 combustion.py

```
    Pull thermodynamic information from the online NIST database.
```

- 2: Initialize thermodynamic functions of each species.
- 3: Define constants, including precision.
- 4: Define initial (reactant) composition as $\{n_i\}$.
- 5: $\{\lambda_i\}$ \leftarrow a i-long array of zeros. These are our Lagrange multipliers.
- 6: {μ_j} ← a j-long array of ones. This will be used for damping non-physical leaps Newton's method may attempt.

```
7: proceed \leftarrow true
```

8: while proceed is true do

9: Build the matrix A and column vector \vec{b} .

10: Using GE-SPP algorithm, solve $A\vec{x} = \vec{b}$ for $\{\Delta n_i\}$ and $\{\Delta \lambda_i\}$.

11: for index j in species do

12: while
$$n_j + \Delta n_j \cdot \mu_j \leq 0$$
 do
13: $\mu_j \leftarrow 0.5\mu_j$

14:
$$n_j \leftarrow n_j + \Delta n_j \cdot \mu_j$$

15: **if** $\mu_i \neq 1$ **then**

16:
$$\mu_i \leftarrow 2\mu_i$$

17: for index i in elements do

18:
$$\lambda_i \leftarrow \lambda_i + \Delta \lambda_i$$

Let proceed be false iff all $\Delta n_j \leq precision$. return $\{n_i\}$

CONCLUSIONS

COMPARISON WITH CEA

	CEA	Our Method
H_2	4.9476000E-01	4.9506127E-01
N_2	2.5040000E-01	2.5040559E-01
CO	2.4750000E-01	2.4767425E-01
H_2O	3.1579000E-03	2.9432857E-03
CH_4	1.7431000E-03	1.6540116E-03
HCN	1.5955000E-03	1.5125876E-03
CO_2	3.4484000E-04	3.2292458E-04
NH_3	2.1157000E-04	2.1523088E-04
Н	1.4791000E-04	1.4791430E-04
HNC	8.0486000E-05	

Table 1: Hot, high pressure CHON system. 2000 K, 60 bar. 1 mols N_2O ; 1 mols CH_4 . Results in mol fractions. Results truncated for size.

ASSESSMENT VS. CEA

The majority of variation appears to be from our NIST-sourced data being more incomplete than the database CEA draws from.

Missing data: HCNO and most cyclic hydrocarbons

Worse data: e.g. HCN (hydrogen cyanide) is present. HNC (hydrogen

isocyanide) is not.

While the missing species are minor, their absence still slightly affects calculations for other major species.

SUMMARY

From first thermodynamic principles (equation of state), we:

- 1. Derive an expression for the Gibbs energy with respect to enthalphy and entropy of each species.
- 2. Re-express the function as a system of T, P, composition ($\{n_j\}$), and Lagrange multipliers, including expressions for isothermal, isobaric and elemental constraints.
- 3. Produce a matrix expression of the **simultaneous multivariate Newton iteration equation** for all the equations in our system.
- Obtain thermodynamic data from the National Institute of Standards and Technology (NIST) and solve the system in Python.

QUESTIONS?

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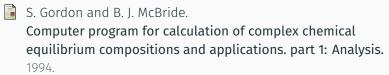
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