

PreOrder : Root → left child → Right child

$$1 \rightarrow 2 \rightarrow 4 \rightarrow 5 \rightarrow 3 \rightarrow 6 \rightarrow 7$$

InOrder : Left → Root → Right

~~16~~ 4 → 2 → 5 → 1 → 6 → 3 → 7

post-order : Left → Right → Root

4 → 5 → 2 → 6 → 7 → 3 → 1

② Dynamic

technique to solve a problem by solving overlapping subproblems

- subproblems are dependent

$$\begin{aligned} S_1 &= \{\text{VAGABOND}\} \\ S_2 &= \{\text{MIXTAPE}\} \end{aligned} \quad] \text{ LCS?}$$

Subproblems,

$$S_1' = \{\text{VAGA}\}$$

$$S_2' = \{\text{MIX}\}$$

$$\begin{aligned} \text{LCS}(S_1', S_2') + \text{LCS}(S_1 - S_1', S_2 - S_2') \\ \neq \\ \text{LCS}(S_1, S_2) \end{aligned}$$

Approx

- algorithm that runs in polynomial time and outputs a solution close to the optimal solution
- can guarantee global ^{some sort of} optimization
eg. 2-approx algos can guarantee not-bad-than-twice-the-optimal solution

Divide & Conquer

technique to solve a problem by dividing the problem into independent subproblems and solving them

- subproblems are independent

Example:

$$A_1 = [2, 1, 5, 3, 4] \text{ sorting?}$$

$$A_1' = [2, 1, 5]$$

$$A_1'' = [3, 4]$$

sort in A_1' and A_1'' and merging their solution gives same result as $\text{sort}(A_1)$.

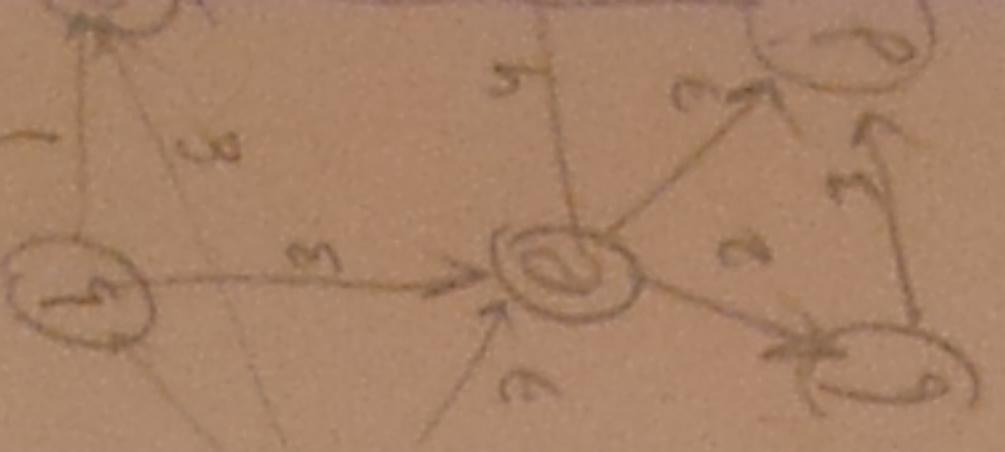
Greedy

- algorithm that produces an output by choosing locally optimal solution for each iteration

• Cannot guarantee any sort of global optimization
eg. local optimization might not lead to any sort of global optimization as it might miss solutions that are locally non-optimal but lead to global optimization.

③ ④ (3+2)

⑤ P7 (3, 4, 5, 6)
3+0



② Dynamic

technique to solve a problem by solving overlapping subproblems

- subproblems are dependent

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Approx

- algorithm that runs in polynomial time and outputs a solution close to the optimal solution
- can guarantee global optimization eg 2-approx algos can guarantee not-bad-than-twice-the-optimal solution

Divide & Conquer

technique to solve a problem by dividing the problem into independent subproblems and solving them

- subproblems are independent

Example:

$$A_1 = [2, 1, 5, 9, 4] \text{ sorting ?}$$

$$A_1' = [2, 1, 5]$$

$$A_1'' = [9, 4]$$

sort in A_1' and A_1'' and merging their solution gives same result as $\text{sort}(A_1)$.

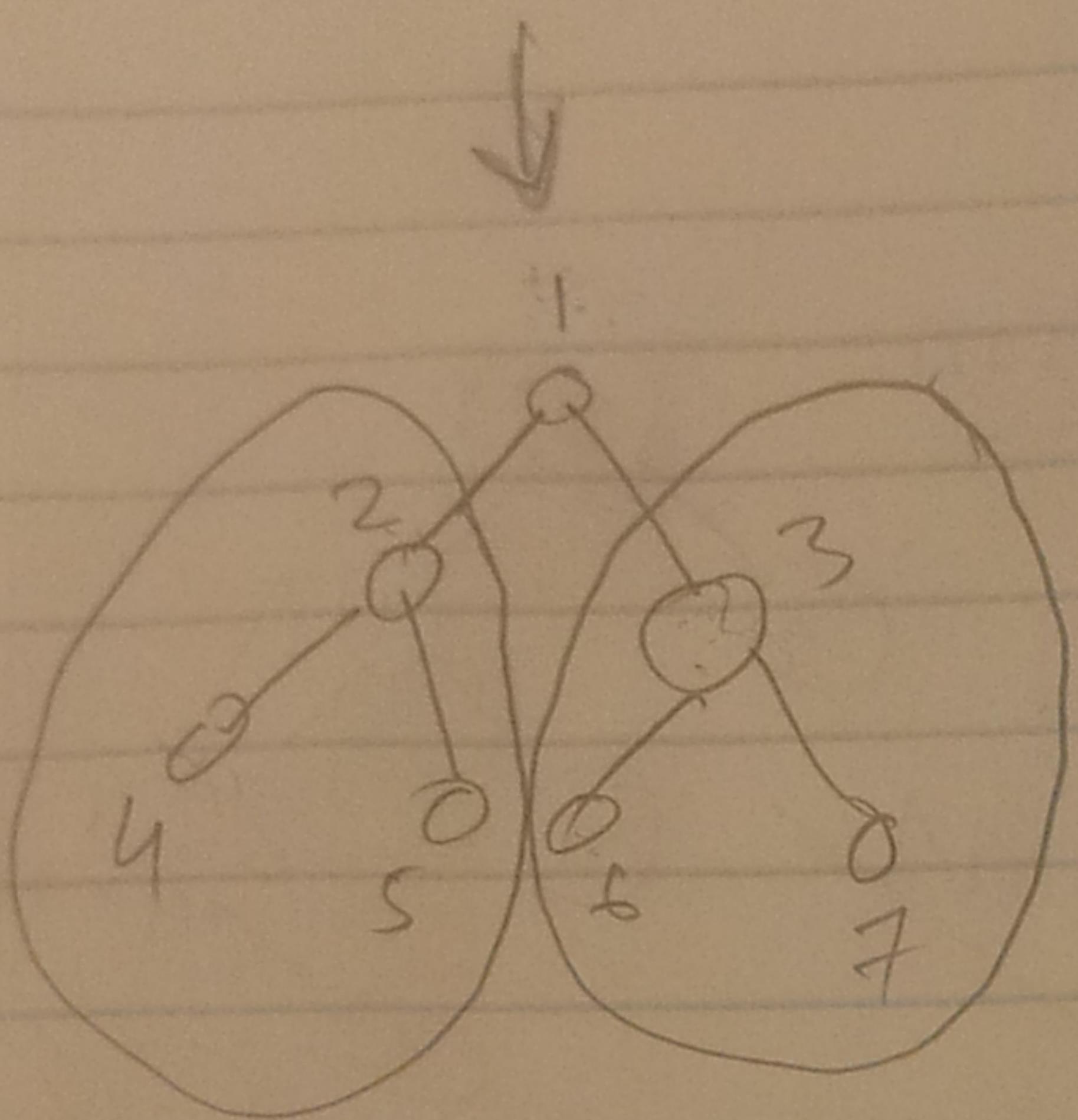
Greedy

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eg. local optimization might not lead to any sort of global optimization as it might miss solutions that are locally non-optimal but lead to global optimization

$$\begin{aligned} x_2 + x_4 &= 1 \\ x_1 + x_2 + x_3 &= 1 \\ x_3 + x_4 &= 1 \\ x_2 + x_3 + x_5 &= 1 \\ x_4 + x_5 &= 1 \end{aligned}$$

$$\begin{aligned} \textcircled{1} & (3+2) \\ f_1 & (3, 2) \\ 9 & (3, 6, 4, 6) \\ 3+0, & \dots \end{aligned}$$



Pre
P NLR
L NLR

PreOrder : Root → left child → Right child

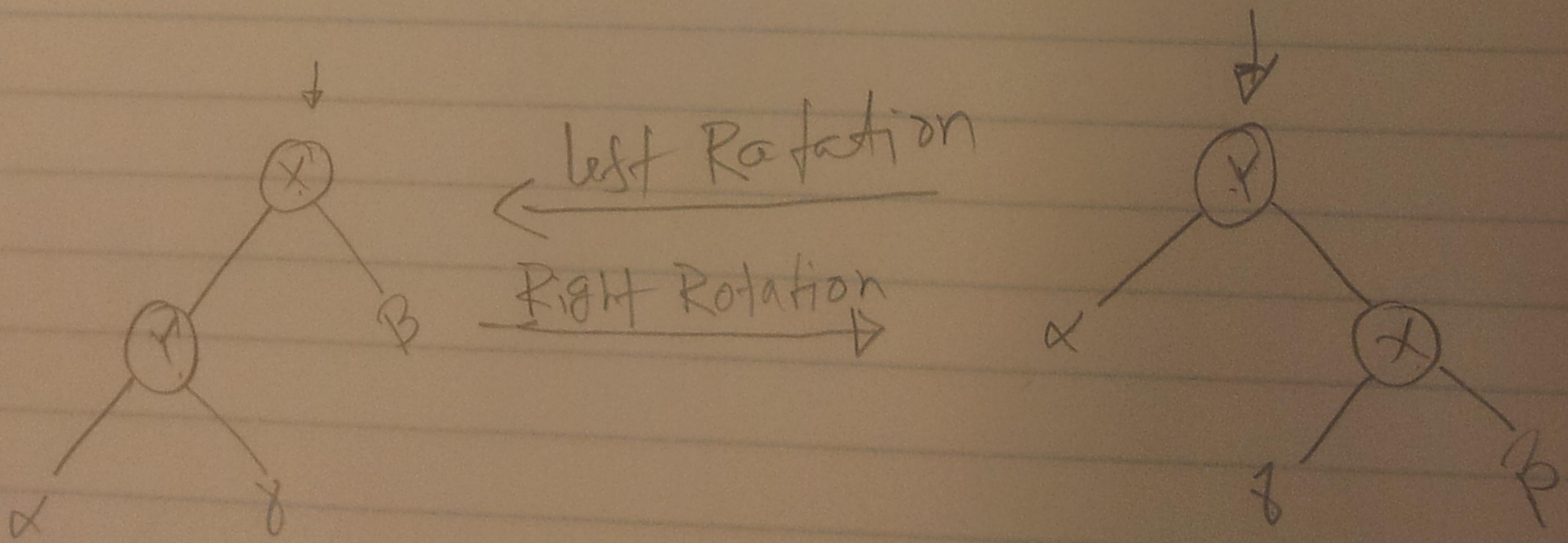
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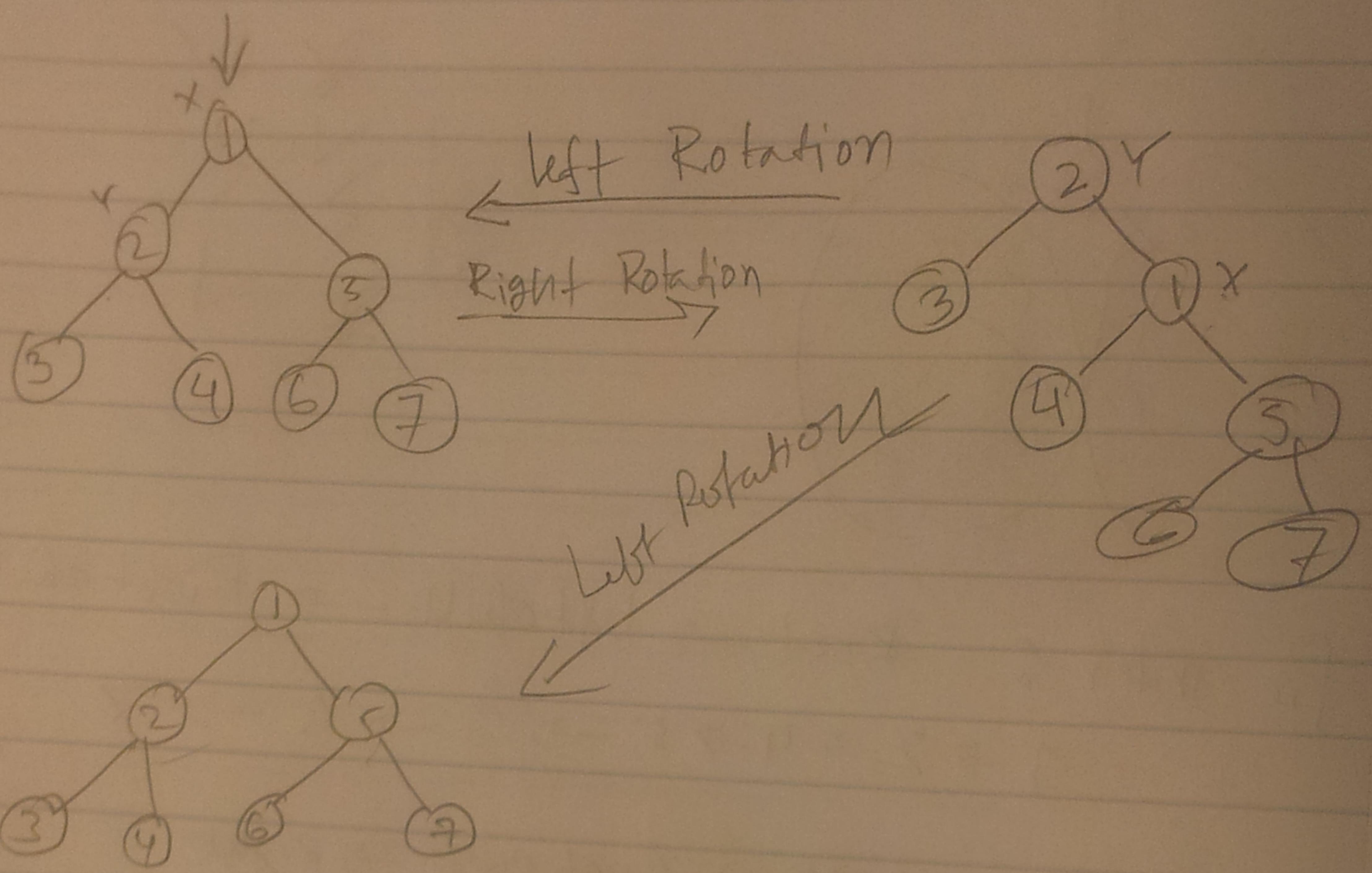
InOrder : Left → Root → Right

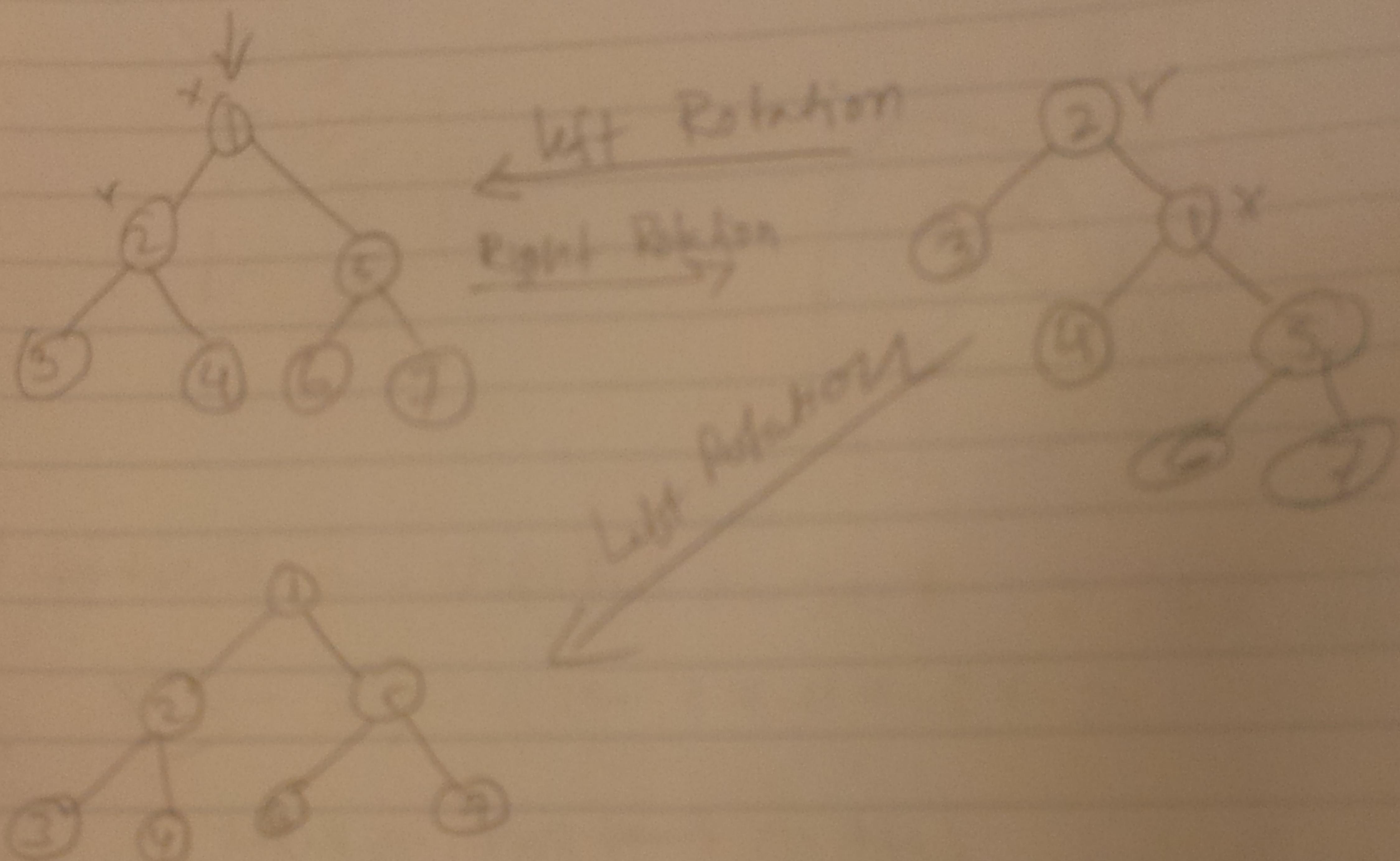
4 → 2 → 5 → 1 → 6 → 3 → 7

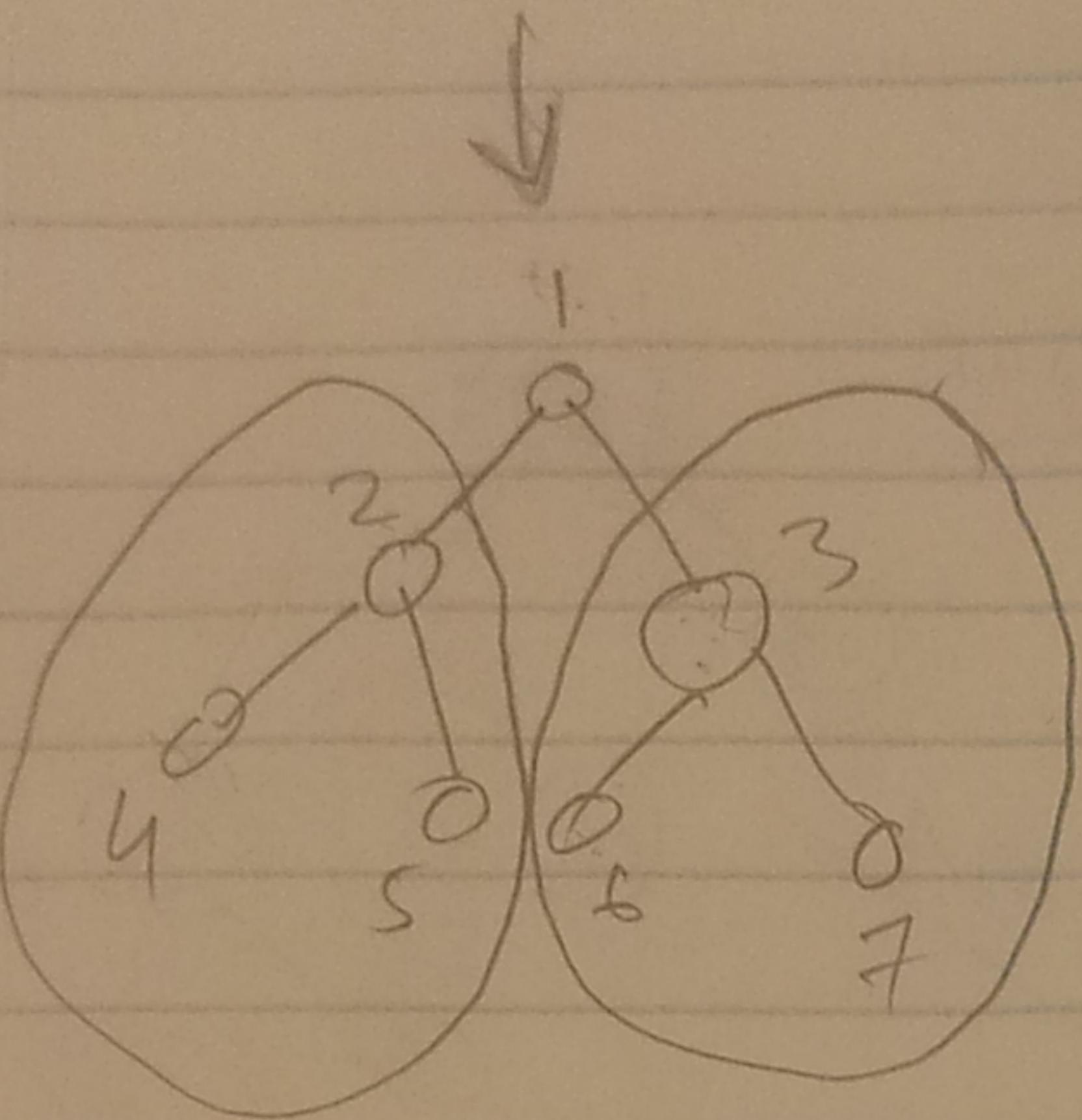
post-order : Left → Right → Root

4 → 5 → 2 → 6 → 7 → 3 → 1









Preorder
NLR
LNR

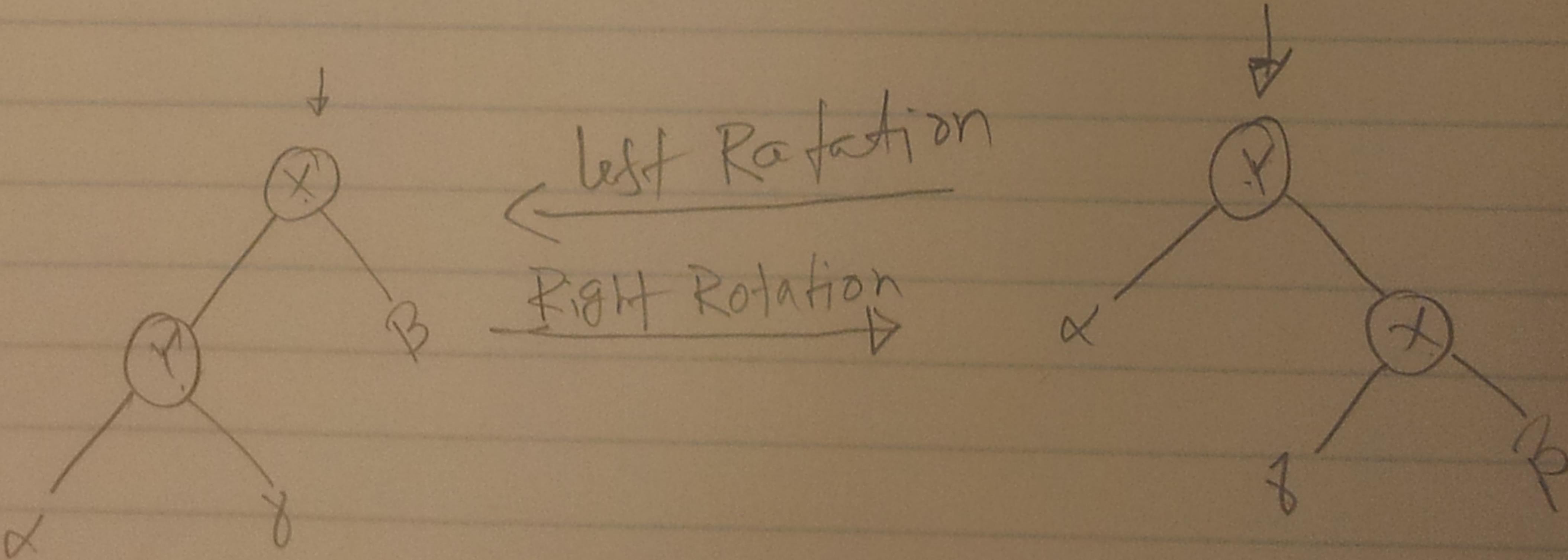
PreOrder : Root → left child → Right child
 $1 \rightarrow 2 \rightarrow 4 \rightarrow 5 \rightarrow 3 \rightarrow 6 \rightarrow 7$

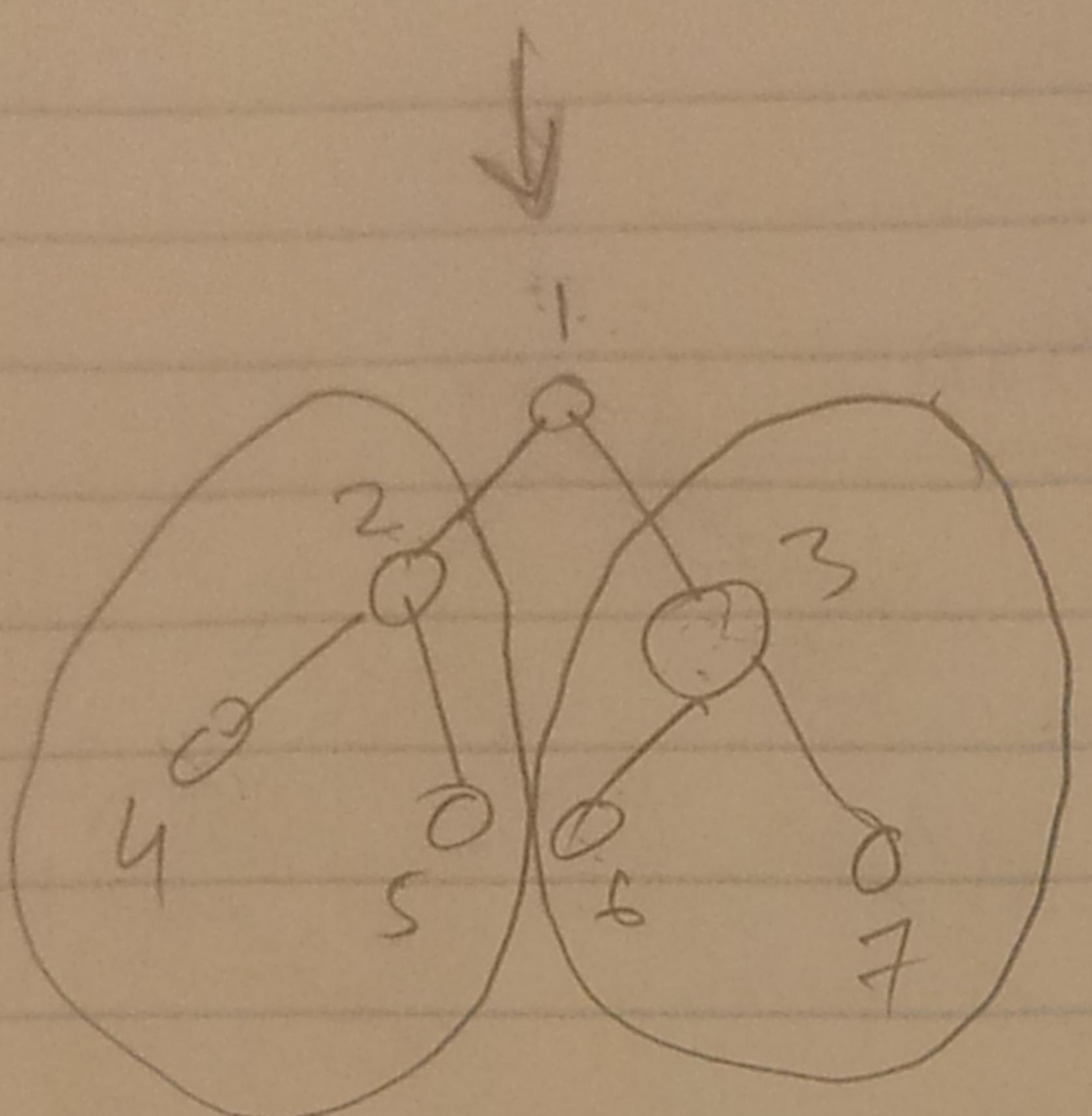
InOrder : Left → Root → Right

~~16~~ $4 \rightarrow 2 \rightarrow 5 \rightarrow 1 \rightarrow 6 \rightarrow 3 \rightarrow 7$

post-order : Left → Right → root

$4 \rightarrow 5 \rightarrow 2 \rightarrow 6 \rightarrow 7 \rightarrow 3 \rightarrow 1$





Pre
NLR
LNR

PreOrder : Root → left child → Right child
 $1 \rightarrow 2 \rightarrow 4 \rightarrow 5 \rightarrow 3 \rightarrow 6 \rightarrow 7$

InOrder : Left → Root → Right

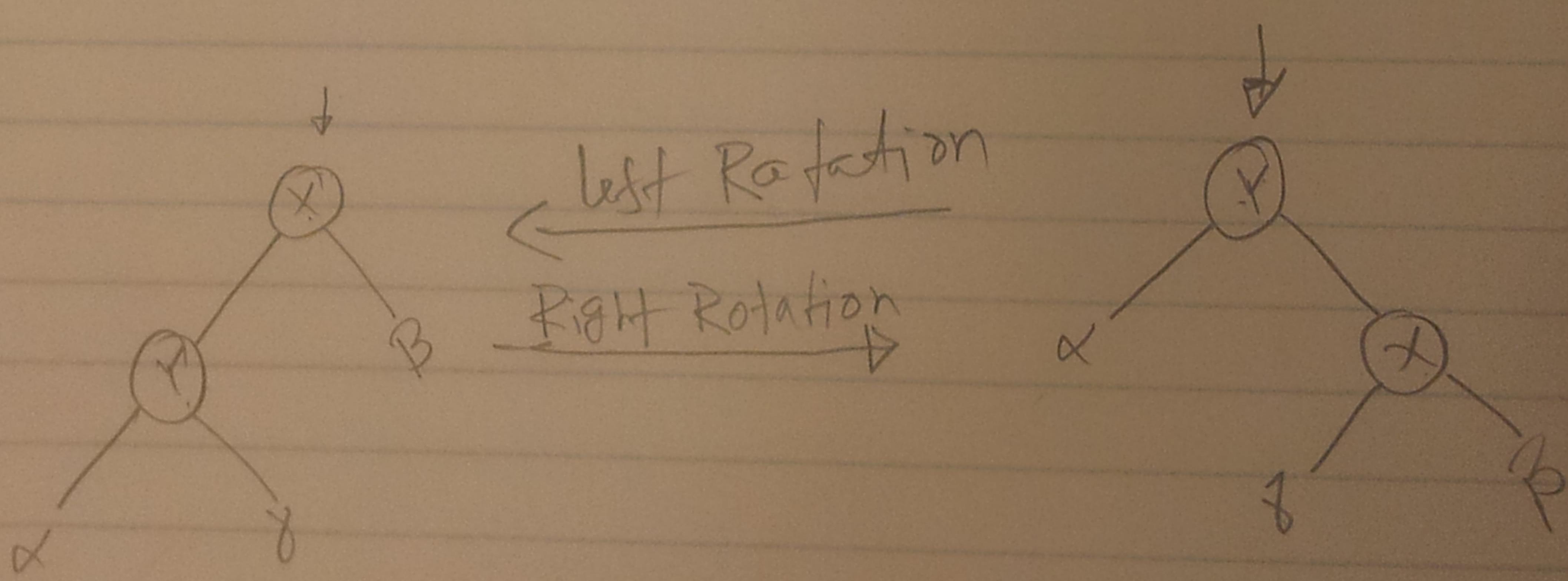
~~16~~ $4 \rightarrow 2 \rightarrow 5 \rightarrow 1 \rightarrow 6 \rightarrow 3 \rightarrow 7$

PostOrder : Left → Right → Root

$4 \rightarrow 5 \rightarrow 2 \rightarrow 6 \rightarrow 7 \rightarrow 3 \rightarrow 1$

Left Rotation

Right



Notes
about
AVL