

Plan for today:

§ 5.2

Learning goals/important concepts:

1. Be able to solve a 1st order system using the eigenvalue method when the characteristic equation has distinct real roots.
2. Eigenvalue, eigenvector of a matrix, Characteristic equation

Reminders/announcements

1. Quiz grades will be posted today
2. Computer Project 2 due Friday
3. Read the textbook!

Discussed linear systems (method of elimination)

Today: Eigenvalue method.

$$\frac{d\vec{x}}{dt} = A \vec{x} \quad (*), \quad A \text{ } n \times n \text{ matrix}$$

const. coef.

$$\text{Ex: } \frac{d\vec{x}}{dt} = \begin{bmatrix} 1 & 2 \\ 3 & -5 \end{bmatrix} \vec{x} \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Want: n lin. indep. sols. ^{for} Any other soln will be linear comb. of them.

Exploration: $y'' + py' + q = 0$ (*)

\uparrow \nearrow
const.

Set: $y = e^{\lambda t} \Rightarrow$ y is soln ex. when
 $\lambda^2 + p\lambda + q = 0$
found λ , found soln $y = e^{\lambda t}$.

Write \star as system:

$$\begin{aligned} y_1' &= y_1 \\ y_2' &= y_2 \end{aligned} \Rightarrow \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}' = \begin{bmatrix} 0 & 1 \\ -q & -p \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \quad \text{check!}$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2' \end{bmatrix}$$

Our educated guess $y = e^{\lambda t}$ becomes

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} e^{\lambda t} \\ \lambda e^{\lambda t} \end{bmatrix}. \quad \text{So if } e^{\lambda t} \text{ solves } \star \text{ then}$$

$$e^{\lambda t} \underbrace{\begin{bmatrix} 1 \\ \lambda \end{bmatrix}}_{\text{const. vector dep. on } \lambda} \text{ solves } \star$$

const. vector dep. on λ

Given $\underline{x}' = \underline{A} \underline{x}$, $\underline{A} = n \times n$.

Try: $\underline{x} = e^{\lambda t} \underline{v}$ for some λ .

$$\begin{aligned} \underline{x}' &= (e^{\lambda t} \underline{v})' = \lambda e^{\lambda t} \underline{v} \\ \underline{A} \underline{x} &= \underline{A} e^{\lambda t} \underline{v} \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\}$$

$$\Rightarrow \underline{A} \underline{v} = \lambda \underline{v} \Leftrightarrow \underline{A} \underline{v} - \lambda \underline{I} \underline{v} = 0 \quad \downarrow$$

$$\Leftrightarrow (\underline{A} - \lambda \underline{I}) \underline{v} = 0. \quad \begin{array}{l} \text{identity} \\ \text{matrix} \end{array}$$

So: if we can solve $(\underline{A} - \lambda \underline{I}) \underline{v} = 0$
for some λ and some $\underline{v} \neq 0$

$$\underline{I}^T = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \end{bmatrix}$$

then $e^{\lambda t} \underline{v}$ will solve $\underline{x}' = \underline{A} \underline{x}$.

Fact: Can solve $(\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0}$ for a $\underline{v} \neq \underline{0}$ exactly when $\det(\underline{A} - \lambda \underline{I}) = 0$, characteristic eq'n of \underline{A} .

Def'n: A number λ (real, cplx, 0) is an eigenvalue of \underline{A} ($n \times n$) if $\det(\underline{A} - \lambda \underline{I}) = 0$ polynomial of deg. n .

An eigenvector associated w/ λ is a non-zero vector \underline{v} such that

$$(\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0} \Leftrightarrow \underline{A} \underline{v} = \lambda \underline{v}$$

↑ ↑
matrix. scalar

Ex: $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

↓ ↓
 \underline{A} \underline{v}

special
numbers,
eigenvalues

Method: $\underline{x}' = \underline{A} \underline{x}$

1. Solve char. eqn $\det(\underline{A} - \lambda \underline{I}) = 0$.

→ n roots, n values for $\lambda, \lambda_1, \dots, \lambda_n$

2. For each λ_j find \underline{v}_j eigenvector assoc. to λ_j

3. If process gives n. lin. indep. \underline{v}_j
 Then $x_1 = e^{\lambda_1 t} \underline{v}_1, \dots, x_n = e^{\lambda_n t} \underline{v}_n$
 are n lin. indep. sol's for $\underline{x}' = A \underline{x}$

4. Any sol'n is

$$\begin{aligned} \underline{x} &= c_1 \underline{x}_1 + \dots + c_n \underline{x}_n \\ &= c_1 e^{\lambda_1 t} \underline{v}_1 + \dots + c_n e^{\lambda_n t} \underline{v}_n \end{aligned}$$

Fact?

If λ_j are all distinct then method works.

Ex:

$$\underline{x}'_1 = 5x_1 - 6x_3$$

$$\underline{x}'_2 = 2x_1 - x_2 - 2x_3$$

$$\underline{x}'_3 = 4x_1 - 2x_2 - 4x_3.$$

$$\underline{x}' = A \underline{x} \quad A = \begin{bmatrix} 5 & 0 & -6 \\ 2 & -1 & -2 \\ 4 & -2 & -4 \end{bmatrix}$$

1. Solve clear. eq'n.

$$\det(A - \lambda I) = 0$$

$$\det \left(\begin{bmatrix} 5 & 0 & -6 \\ 2 & -1 & -2 \\ 4 & -2 & -4 \end{bmatrix} - \underbrace{\begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}}_{\lambda I} \right) = 0$$

$$\det \left(\begin{bmatrix} 5-\lambda & 0 & -6 \\ 2 & -1-\lambda & -2 \\ 4 & -2 & -4-\lambda \end{bmatrix} \right) = 0$$

$$(5-\lambda) \begin{vmatrix} -1-\lambda & -2 \\ -2 & -4-\lambda \end{vmatrix} - 6 \begin{vmatrix} 2 & -1-\lambda \\ 4 & -2 \end{vmatrix} = 0$$

$$(5-\lambda)((1+\lambda)(4+\lambda)-4) - 6(-4+4\lambda+4) = 0$$

$$\lambda^3 - \lambda^2 = 0. \quad \leftarrow \text{char. eqn, poly. in } \lambda$$

Roots: $\lambda = 0, \pm 1$. 3 distinct real

roots,
 \Rightarrow Method works by
Fact 2.

2. Find Eigenvectors, for each root.

$$\rightarrow \lambda = 0.$$

Looking for: $\underline{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ so that

$$\underline{A} \underline{v} = \underbrace{0 \cdot \underline{v}}_{=0}$$

$$\begin{bmatrix} 5 & 0 & -6 \\ 2 & -1 & -2 \\ 4 & -2 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$\therefore 0 \cdot \underline{v}$

3rd line is const. multiple of 2nd.

$$\textcircled{1} \quad 5v_1 - 6v_3 = 0$$

$$\textcircled{2} \quad 2v_1 - v_2 - 2v_3 = 0$$

$$\textcircled{3} \quad 4v_1 - 2v_2 - 4v_3 = 0$$

$$\textcircled{1} \Rightarrow v_1 = \frac{6}{5}v_3$$

$$\textcircled{2} \Rightarrow v_2 = 2v_1 - 2v_3 = 2\frac{6}{5}v_3 - 2v_3 = \frac{2}{5}v_3$$

v_3 has no restrictions.

So for any v_3

$$\begin{bmatrix} \frac{6}{5}v_3 \\ \frac{2}{5}v_3 \\ v_3 \end{bmatrix}$$

is an eigenvector.

Can take $v_3 = 5 \Rightarrow \begin{bmatrix} 6 \\ 2 \\ 5 \end{bmatrix}$ eigenvector, so

$$C \begin{bmatrix} 6 \\ 2 \\ 5 \end{bmatrix} = C e^{0t} \begin{bmatrix} 6 \\ 2 \\ 5 \end{bmatrix} \text{ is a sol'n of } \underline{x}' = A \underline{x}$$

for any C .

Case $\lambda = 1$ will be discussed on Wednesday.