

Plan for today:

Finish 2.2

Start 2.3

Learning goals for the day:

1. Be able to construct a bifurcation diagram for a differential equation depending on a parameter
2. Be able to set up and solve a differential equation for the motion of a body under the influence of air resistance.

Reminders-Announcements

1. Ungraded Quiz 1.5 on Monday.
2. Quiz 2 on Thursday
3. Future quizzes are open book, see syllabus update
4. Read the textbook!

Last time: critical pts of an autonomous eqn.

$$\frac{dx}{dt} = f(x)$$

$c$  critical:  $f(c) = 0$

Logistic Model w/ harvesting

fish in a lake following a logistic model, harvest  $h$  every year.

$$\frac{dx}{dt} = \underbrace{x(100-x)}_{\text{logistic part}} - h$$

$x(t) \rightarrow \# \text{ of fish}$   
in year  $t$

depends on parameter

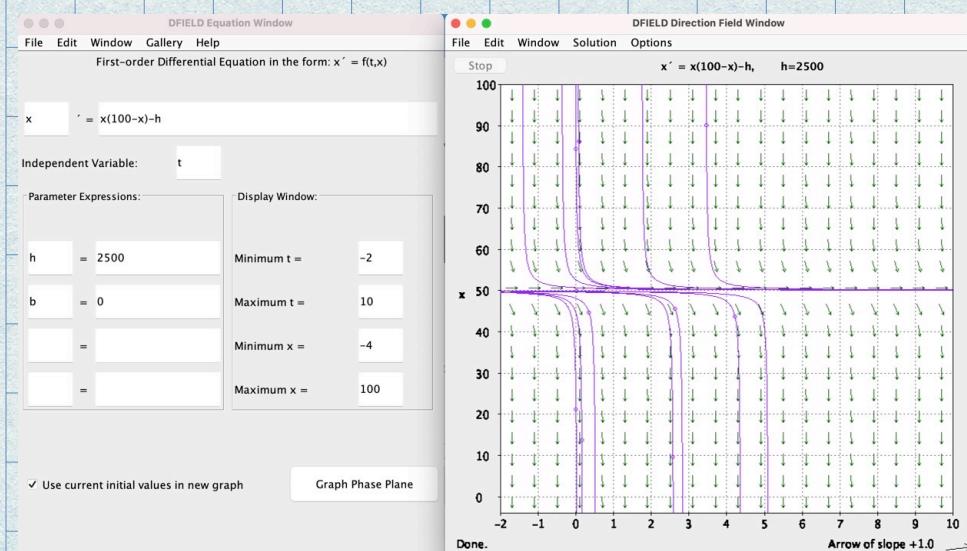
Crit pts? When is  $x(100-x)-h=0$ ?

$$-\frac{x^2 + 100x - h}{2} = 0$$
$$x = \frac{100 \pm \sqrt{10,000 - 4h}}{2}$$

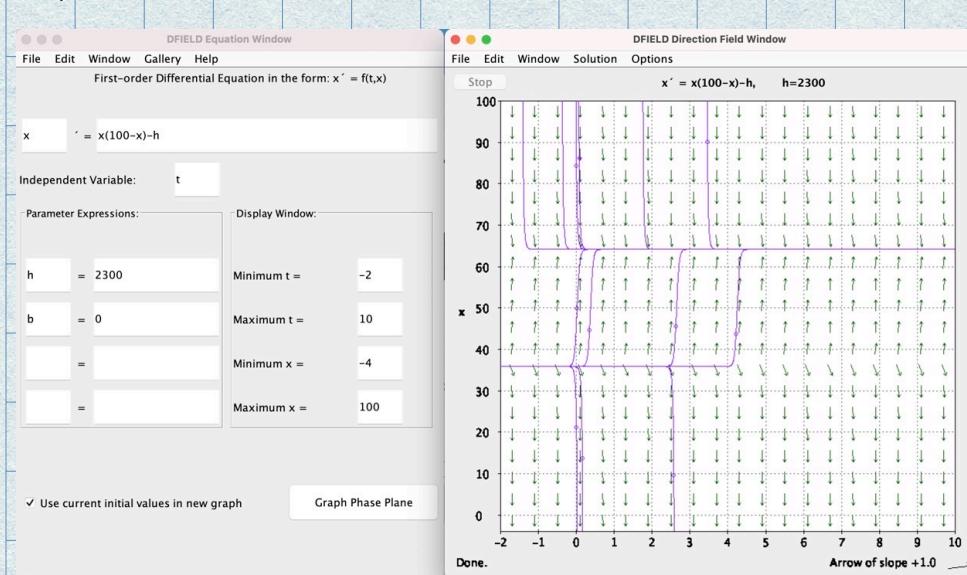


# of critical pts depends on  $h$ .

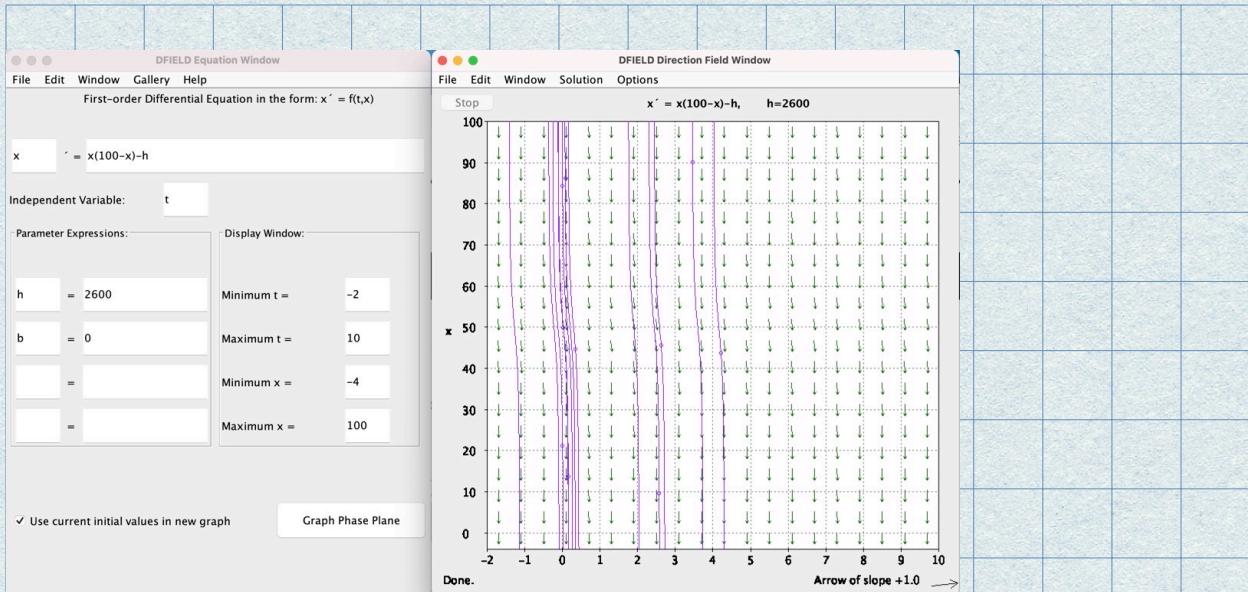
If  $h = 2500$  then  $10000 - 4h = 0$  and  
we have only 1 crit. pt.



If  $h < 2500$  then  $\Delta > 0$  and  $\rightarrow 2$  crit pts



If  $h > 2500$  then  $\Delta < 0$  and we have no crit pts.



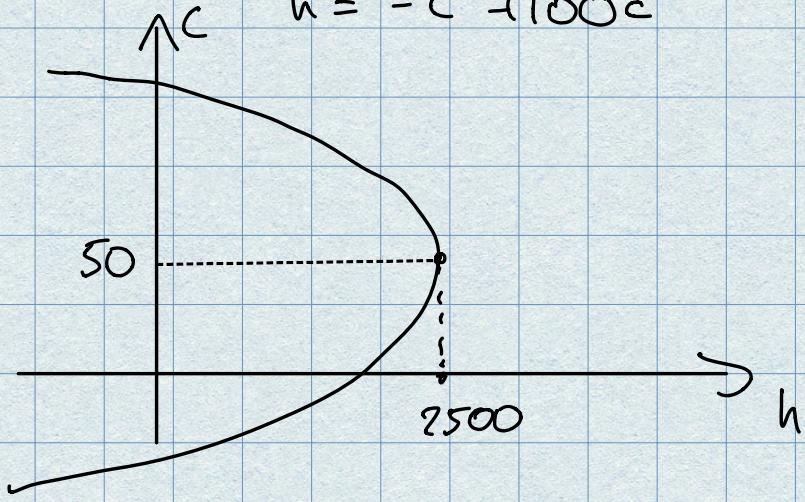
$h = 2500 \rightarrow$  bifurcation pt: qualitative behavior  
of eqn changes between  $h < 2500$  &  $h > 2500$

Bifurcation Diagram: sets of pts  $(h, c)$  so  
that  $c$  is a crit. pt.



$$c^2 - 100c + h = 0$$

$$h = -c^2 + 100c$$



## 2.3 Acceleration & velocity models.

In general: air resistance

$$F_R = k v^p \quad 1 \leq p \leq 2$$

↑                      ↑  
 resistance      a const.      velocity

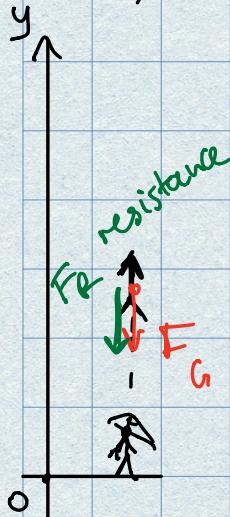
$F_R$  always in direction opposite to the motion

$k \rightarrow$  depends on viscosity / density of air & shape of body.

Ex: Arrow shot straight upwards, initial velocity  $v_0 = 160 \text{ ft/s}$ .

deceleration due to air resistance:  $\frac{v^2}{800} \frac{\text{ft}}{\text{s}^2}$

a) how high does it go?



maybe  $\frac{dy}{dt^2} = \dots$ ; easier to work w/ velocity directly.

$$\frac{dv}{dt} = - \underbrace{\frac{v^2}{800}}_{\substack{\uparrow \\ \text{acceleration}}} - \underbrace{32}_{\substack{\downarrow \\ \text{air resistance}}} \quad \rightarrow \text{gravitational acceleration}$$

autonomous, separable!

Exercise: solve! (solving at the end)

find:  $v(t) = 160 \tan \left( -\frac{t}{5} + c \right)$   $160 = 160 \tan(c)$

Know:  $v(0) = 160 \rightarrow c = \frac{\pi}{4}$

$\tan(c) = 1$

How do we find when it will be at its highest point?

$$\text{Want } v(t) = 0 \Leftrightarrow 160 \tan\left(-\frac{t}{5} + \frac{\pi}{4}\right) = 0 \\ \Rightarrow t = \frac{5\pi}{4}$$

$$y(t) = \int v(t) dt \\ = \int 160 \tan\left(-\frac{t}{5} + \frac{\pi}{4}\right) dt$$

$$y(t) = 800 \ln\left(\cos\left(\frac{\pi}{4} - \frac{t}{5}\right)\right) + C_2$$

$$\text{Find } C_2: \quad y(0) = 0$$

$$\Rightarrow C_2 = 400 \ln(2)$$

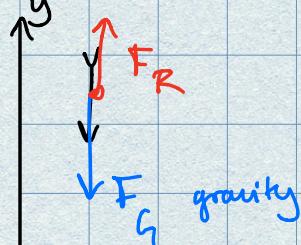
So: highest we reach

$$y\left(\frac{5\pi}{4}\right) = 800 \ln\left(\cos\left(\frac{\pi}{4} - \frac{\pi}{4}\right)\right) + 400 \ln(2)$$

$$\underbrace{\hspace{1cm}}_{1} \quad \underbrace{\hspace{1cm}}_{0}$$

$$= 400 \ln(2).$$

b) When arrow is going down.



$$\frac{dv}{dt} = -32 + \frac{v^2}{800}, \quad v \text{ negative}$$

$$\frac{dv}{dt} = \frac{v^2}{800}$$

Solve (exercise)

$$\rightarrow \underline{\text{Find: }} v(t) = -160 \frac{1 - e^{-2t/5}}{1 + e^{-2t/5}} \xrightarrow[t \rightarrow \infty]{} -160$$

g

1

Reach limiting velocity.

time measured from the moment when  
arrow is at highest altitude

## Sols of examples

1.

$$\frac{dv}{dt} = -32 - \frac{v^2}{800}$$

$$\begin{aligned}\frac{dv}{dt} &= -32 \left(1 + \frac{v^2}{25600}\right) \\ &= -32 \left(1 + \left(\frac{v}{160}\right)^2\right)\end{aligned}$$

Separate variables:

$$32 \cdot 800 = 25600 = 160^2$$

$$\int \frac{dv}{1 + \left(\frac{v}{160}\right)^2} = -\int 32 dt, \text{ set } \frac{v}{160} = z$$

$$\int \frac{160 dz}{1 + z^2} = -\int 32 dt$$

$$\begin{aligned}\Rightarrow \arctan(z) &= -\frac{1}{5}t + C \\ \Rightarrow v &= 160 \tan\left(-\frac{t}{5} + C\right)\end{aligned}$$

$$2. \frac{dv}{dt} = -32 + \frac{v^2}{800} = -32 \left(1 - \frac{v^2}{25600}\right)$$

$$\Rightarrow \int \frac{dv}{1 - \left(\frac{v}{160}\right)^2} = \int -32 dt \Rightarrow$$

$$\begin{aligned}\Rightarrow \int \frac{160 dz}{1 - z^2} &= -32t + C \\ \Rightarrow 160 \int \frac{1}{2} \frac{1}{1-z} + \frac{1}{2} \frac{1}{1+z} dz &= -32t + C\end{aligned}$$

$$\Rightarrow 160 \left[ \frac{1}{2} \ln|1-z| + \frac{1}{2} \ln|1+z| \right] = -32t + C$$

$$\Rightarrow 160 \left( -\frac{1}{2} \ln|1-z| + \frac{1}{2} \ln|1+z| \right) = -32t + C$$

$$\Rightarrow 80 \ln \left| \frac{1+z}{1-z} \right| = -32t + C$$

$$\Rightarrow \ln \left| \frac{1+z}{1-z} \right| = -\frac{2}{5}t + C_1 \quad (C_1 = \frac{C}{80})$$

$$\Rightarrow \frac{1+z}{1-z} = \pm e^{C_1} e^{-\frac{2}{5}t}$$

$$\Rightarrow \frac{1+z}{1-z} = C_2 e^{-\frac{2}{5}t} \quad (C_2 = \pm e^{C_1})$$

$$\Rightarrow z \left( C_2 e^{-\frac{2}{5}t} + 1 \right) = C_2 e^{-\frac{2}{5}t} - 1$$

$$\Rightarrow v = 160 \frac{C_2 e^{-\frac{2}{5}t} - 1}{C_2 e^{-\frac{2}{5}t} + 1}$$

Starting to measure time from the moment when the arrow reaches its highest altitude,  $v(0) = 0$ .

$$\text{So } C_2 - 1 = 0 \Rightarrow C_2 = 1$$

$$v = 160 \frac{e^{-\frac{2}{5}t} - 1}{e^{-\frac{2}{5}t} + 1}$$