

10. Multi-objective Problem

Bi-criterion problems

multi-objective with two objectives

decision variable x lies in decision space X .
 feasible region F is a subset of X .
 objective space Y .

feasible region in objective space:
 $\{ (z_1(x), z_2(x), \dots, z_n(x)) : x \in X \} \subseteq Y$.

Non-inferior set

$$\max_{x \in F} \{ z_1(x), z_2(x) \}$$

↓

or $z_1(x) > z_1(x_2), z_2(x) \geq z_2(x_2)$ x_1 give a strictly better result than x_2 in at least one variable.
 $z_1(x) \geq z_1(x_2), z_2(x) > z_2(x_2)$

Then x_1 dominates x_2
 x_2 is inferior to x_1

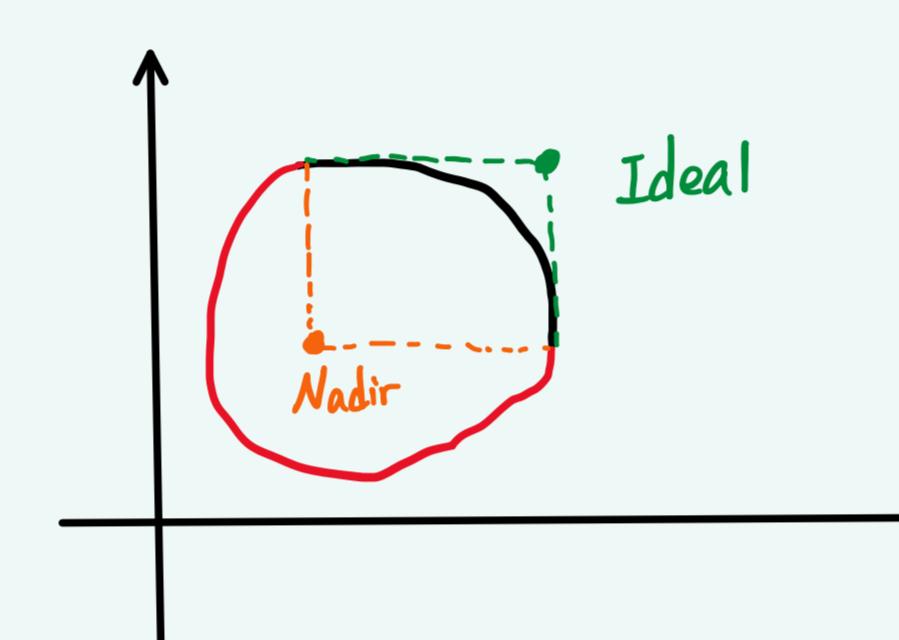
NIS (Non-inferior set): A set of points in the feasible region that are not inferior to any other point in F
 (points in set "Pareto-optimal")

Ideal and nadir solution

Suppose a multi-objective maximisation problem with feasible region $F \subseteq X$ and NIS NIS .

Ideal solution $Z^* = \max \{ z_i(x) : x \in F \}$
 $\frac{1}{k} \leq z_i \leq z^*$ ideal solution maximises each component over the given feasible region, regardless of feasibility.

Nadir solution $\hat{z}_i = \min \{ z_i(x) : x \in F \}$
 Nadir solution provides component-wise lower bound on the NIS.



Solution Method

The Weighting method

- Quantify the relative importance of different objectives.

$$Z(\gamma) = (1-\gamma)z_1 + \gamma z_2 \quad \text{with weighting variable } \gamma \in [0,1]$$

For $Z = (1-\gamma)z_1 + \gamma z_2 = \text{Const}$ is a line in objective space. (decision maker set γ)
 determines the slope. $\gamma \in [0,1]$

For $\gamma=0$, $Z(0)=z_1$

increase γ , B remains optimal until C .

↓ 因为 z_1 比 z_2 重， γ 越大， z_2 的比例越大

$$12(1-\gamma) + 7\gamma = 12(1-\gamma) + 9\gamma$$

$$\gamma = \frac{1}{2}, B, C \text{ are optimal}$$

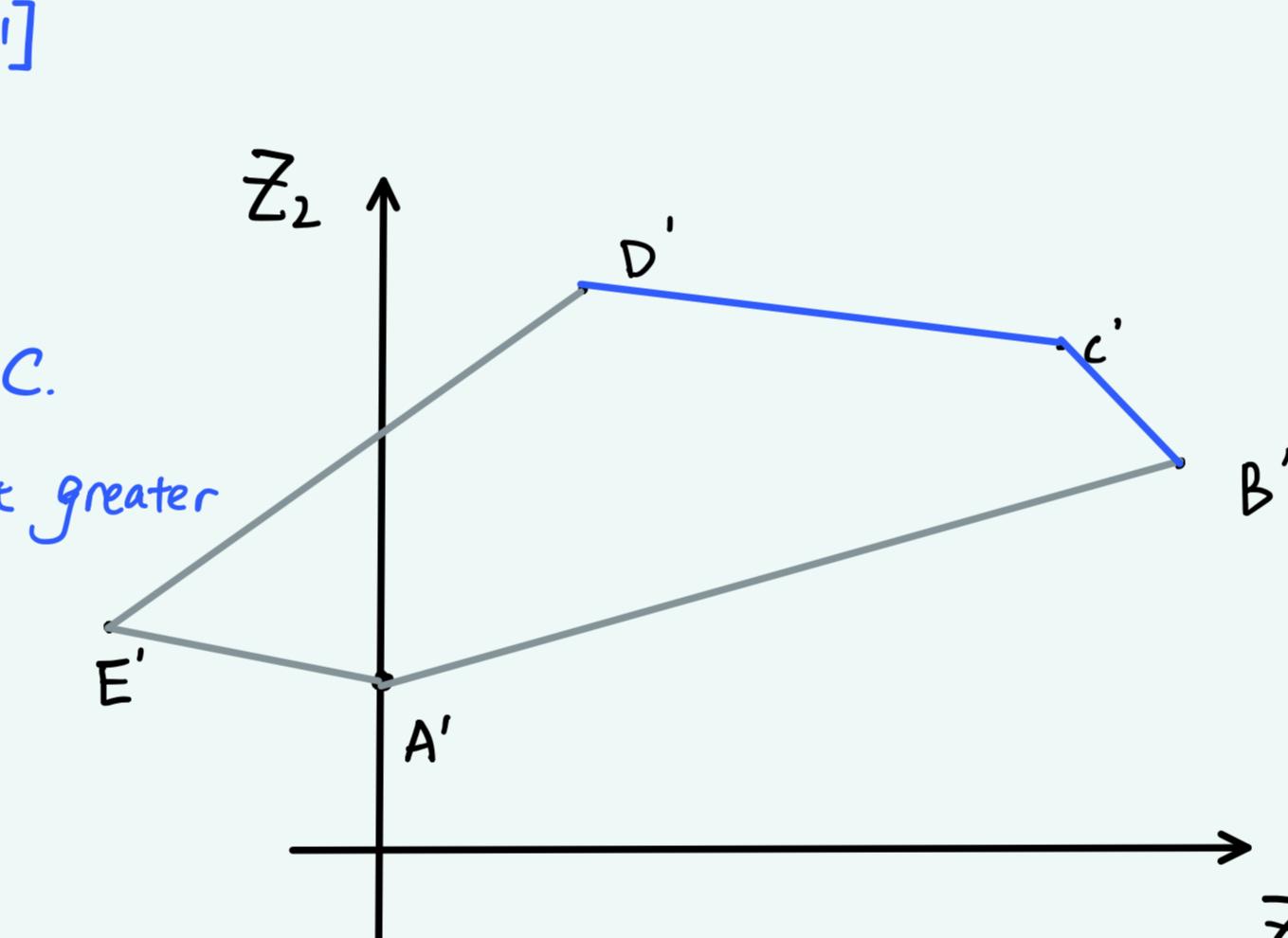
$$12(1-\gamma) + 9\gamma = 4(1-\gamma) + 11\gamma$$

$$\gamma = \frac{4}{5}, C, D \text{ are optimal}$$

$$B, \gamma \in [0, \frac{1}{2}]$$

$$C, \gamma \in [\frac{1}{2}, \frac{4}{5}]$$

$$D, \gamma \in [\frac{4}{5}, 1]$$



Generalize,

multi-objective with objective z_1, z_2, \dots, z_k and weights $\gamma_1, \dots, \gamma_k \in [0,1]^k$.

$$Z = \sum_{i=1}^k \gamma_i z_i$$

st. $\sum_{i=1}^k \gamma_i = 1$

γ 是 $k-1$ 维的。
 $\gamma_1, \gamma_2, \dots, \gamma_{k-1}$

 ϵ -constraints

for one or more of the objectives, there is a minimum acceptable value.

Consider a multi-objective problem:

$$\max_{x \in F} \{ z_1(x), \dots, z_k(x) \}$$

st. $\begin{array}{l} g_1(x) \leq b_1 \\ \vdots \\ g_m(x) \leq b_m \\ x \geq 0 \end{array}$

assign one objective a lower bound ϵ .
 the choice of ϵ may yield an infeasible LP.

$$\max_{x \in F_{\epsilon_1}} \{ z_k(x) \}$$

st. $\begin{array}{l} g_1(x) \leq b_1 \\ \vdots \\ g_{k-1}(x) \leq b_{k-1} \\ g_k(x) \geq \epsilon_1 \\ \vdots \\ g_m(x) \leq b_m \\ x \geq 0 \end{array}$

repeat until 仅剩一个变量

Goal programming

- Quantify the cost of an objective not meeting a particular value.

Consider a multi-objective problem:

$$\max_{x \in F} \{ z_1(x), \dots, z_k(x) \}$$

st. $\begin{array}{l} g_1(x) \leq b_1 \\ \vdots \\ g_m(x) \leq b_m \\ x \geq 0 \end{array}$

choose a target value for each z_i , called goal G_i . $Z_i(w) = G_i$.
 add slack and surplus variable.

$Z_i(x) = G_i + d_i^+ - d_i^-$

d_i^+ : how much greater the goal less than goal.
 d_i^- : penalty for overshooting
 d_i^- : penalty for undershooting

minimize the total penalty.

$$\min \left[\sum_{i=1}^k (\alpha_i^+ d_i^+ + \alpha_i^- d_i^-) \right]$$

st. $\begin{array}{l} Z_1(x) = G_1 + d_1^+ - d_1^- \\ \vdots \\ Z_k(x) = G_k + d_k^+ - d_k^- \\ g_1(x) \leq b_1 \\ \vdots \\ g_m(x) \leq b_m \\ x \geq 0 \end{array}$

当我们希望 $Z_i \geq G_i$ 时， $\alpha_i^+ = 0$