# Iterative Approximate Cross Validation in High Dimensions

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 ${\sf Background}$ 

To set out the notation used throughout this seminar, we can define the Empirical Risk Minimisation (ERM) framework to solve a supervised learning problem.

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#### General Problem Setting

- $\bullet$  Input space  ${\mathcal X}$  and an output space  ${\mathcal Y}.$
- ullet Data is "generated" by a *true* distribution  $P(\mathcal{X},\mathcal{Y})$ .
- ullet Aim is to find a mapping  $h:\mathcal{X} o \mathcal{Y}$  (called a hypothesis).
- Denote all possible combinations of input and output space as  $\mathcal{D} = \{(X,Y) \in (\mathcal{X},\mathcal{Y})\}.$

To measure the error (or loss) we make on a data point, define a function  $\ell(h; D_i)$ ,

$$\ell(h; D) = \sum_{i=1}^{n} \ell(h; D_i)$$

as the loss for the dataset. Examples of  $\ell$  are 0-1 loss (for classification) and a squared error (for regression).

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#### Risk

Define the **risk** of a hypothesis for the complete space of inputs and outputs as,

$$R(h) = \mathbb{E}_{\mathcal{X},\mathcal{Y}}[\ell(h;\mathcal{D})]$$

The optimal hypothesis for the data is,

$$h_{\mathcal{H}} = \arg\min_{h \in \mathcal{H}} R(h)$$

# Empirical Risk

As we cannot measure **true** risk, we seek an approximation using the observed data D.

#### **Empirical Risk**

We define **empirical risk** of a hypothesis given data D as,

$$R_{\mathsf{emp}}(h;D) = \frac{1}{n} \sum_{i=1}^{n} \ell(h;D_i)$$

The optimal hypothesis given observed data D is,

$$h_D = \operatorname*{arg\,min}_{h \in \mathcal{H}} R_{\mathsf{emp}}(h; D)$$

where  $\mathcal{H}$  is a hypothesis space which a *learning algorithm* picks a hypothesis from. We will describe the parameters which describe h as  $\theta \in \mathbb{R}^p$ , assuming the case of a Generalised Linear Model (GLM).

By the (weak) law of large numbers  $R_{\text{emp}}(h;D) \to R(h;\mathcal{D})$  as  $n \to \infty$ , so it is reasonable to assume that  $h_D$  converges to a minimiser of true risk.

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#### Issues with ERM

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### Regularised Empirical Risk

To restrict the hypothesis space, we define the formulation of **regularised empirical risk** as,

$$R_{\mathsf{reg}}(h;D) = R_{\mathsf{emp}}(h;D) + \lambda \pi(\theta)$$

Here,  $\pi: \mathbb{R}^p \to \mathbb{R}$  is a regulariser and  $\lambda \in \mathbb{R}^+$  is a hyper-parameter to control the strength of regularisation. The solution becomes  $(h_D)_{\lambda} = \arg\min_{h \in \mathcal{H}_{\lambda}} R_{\mathsf{emp}}(h; D)$  where  $\mathcal{H}_{\lambda}$  is a restricted hypothesis space.

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#### **Cross Validation**

Background

To avoid "overfitting" to the observed data (i.e blindly minimising empirical risk), we can attempt to define an approximation of true risk to measure the efficacy of a learned hypothesis.

<sup>&</sup>lt;sup>2</sup>Arlot & Celisse (2008)

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The most common way to estimate the true risk of a hypothesis is to run Cross Validation (CV) for a hypothesis . This is where we break the observed data into small subsets to run multiple "validation" experiments (training the data on a subset and testing on an unseen subset).

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One of the most effective methods for risk approximation is Leave One Out Cross Validation (LOOCV)  $^2$ . This method is computationally expensive as we repeat the learning task n times (where n is the size of the observed data).

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Literature Review

# Approximate CV Methods

To reduce the computational cost of CV (specifically LOOCV), we turn to Approximate Cross Validation (ACV), which attempts to approximate (rather than solve) individual CV experiments.

#### **LOOCV**

The definition of leave-one-out (LOO) regularised empirical risk is,

$$R_{\mathsf{reg}}(\theta; D_{-j}) = \sum_{i=1, i \neq j}^{n} \ell(\theta; D_{i}) + \lambda \pi(\theta)$$

where we leave out a point with index j for this experiment.

Preliminary Work

# Future Plans