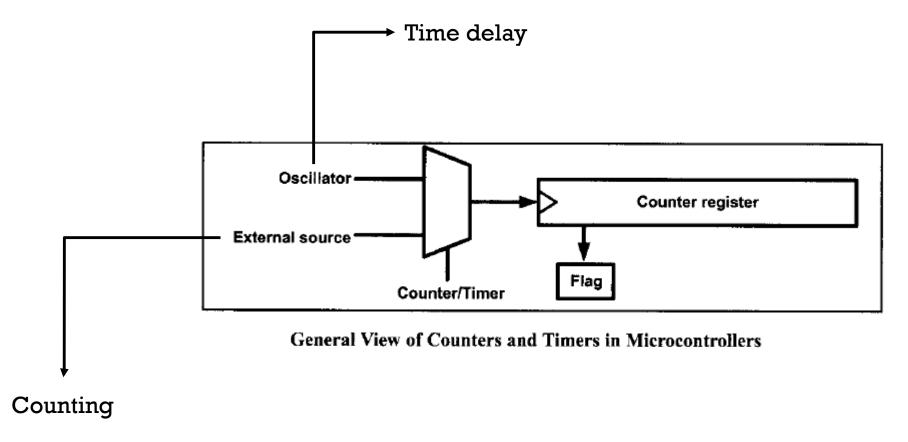


# EMBEDDED SYSTEMS CMPE-453

Department of Computer Engineering



**Timers/Counters** 



#### To generate a time delay

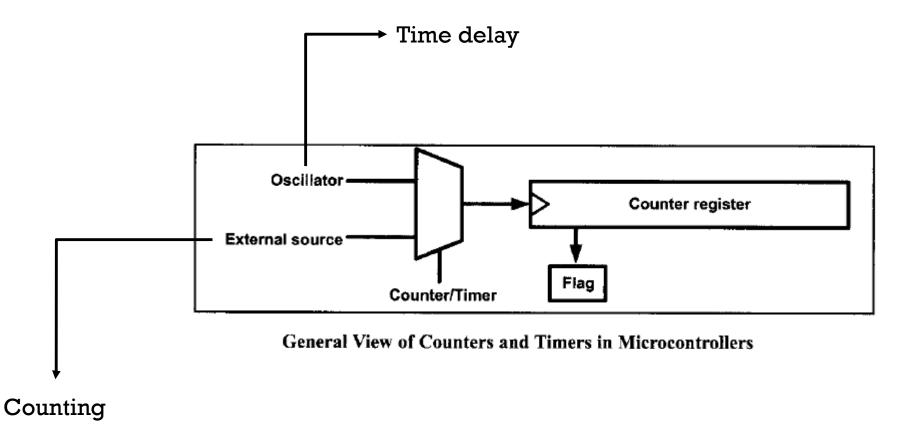
- Each osilator tick increases counter register
- How many ticks has occured in counter register
- Oscilator frequency→tick period
- A.O.Time = tick period x register content

#### Example

- Oscillator freq. = 1MHz
- 1 tick for each 1/10<sup>6</sup> secs.
- lsec delay, we need 10<sup>6</sup> ticks



Clear counter and wait it reaches upto a certain value



## Second way for a time delay

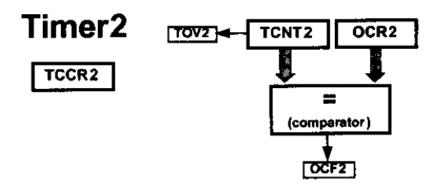
- Counter flag is cleared when it is overflow.
- Load counter register, wait upto it is cleared.

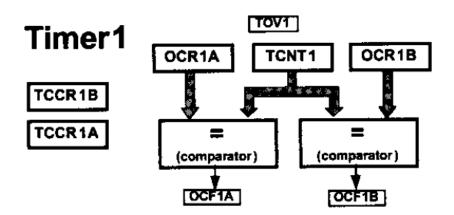
## Example

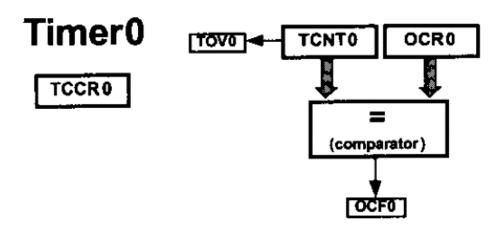
- Oscillator freq. = 1MHz
- 4µsec delay, we need 4 ticks
- Load counter register with FC

$$FC - FD - FE - FF - overflow (00)$$





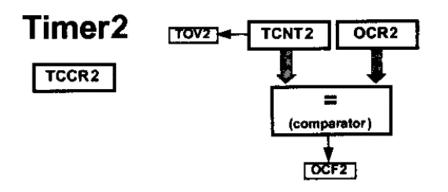


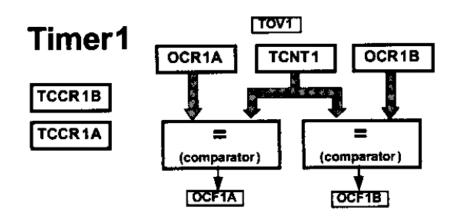


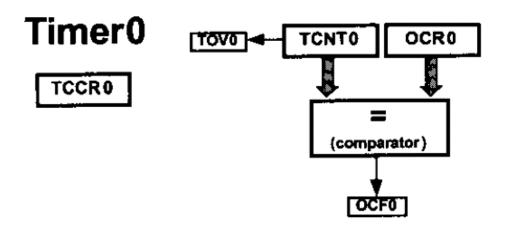
- TCNTn: 0 when reset, counts up for each pulse
- Load or read TCNTn

- TOVn: Timer overflow
- It is set when overflow









- TCCRn: 0 when reset, counts up for each pulse
- Specify to work as timer or counter
- OCRn: Timer overflow
- It is set when overflow
- OCFn: Output compare flag
- It is set when TCNTn and OCRn is equal



# PROGRAMMING TIMERO

TCNT0 D7 D6 D5 D4 D3 D2 D1 D0

## TCCR0 (Timer/Counter Control Register)

FOC0	WGM00	COM01	COM00	WGM01	CS02	CS01	CS00
------	-------	-------	-------	-------	------	------	------

CS02:00					WGM00, WGM01				
	0	0	0	No clock source (Timer/Counter stopped)		D6	D3	Timer0 mode selector bits	
	0	0	1	clk (No Prescaling)		0	0	Normal	
	0	1	0	clk / 8		0	1	CTC (Clear Timer on Compare Match)	
	0	1	1	clk / 64		U	1		
	1	0	0	clk / 256		1	0	PWM, phase correct	
	1	0	1	clk / 1024		1	1	Fast PWM	
	1	1	0	External clock source on T0 pin. Clock on falling edge					
	1	1	1	External clock source on T0 pin. Clock on rising edge.					

# EXAMPLES

#### Example 9-1

Find the value for TCCR0 if we want to program Timer0 in Normal mode, no prescaler. Use AVR's crystal oscillator for the clock source.

#### Solution:

TCCR0 =WGM00 COM01 COM00 FOC0 **CS01** WGM01 CS02 CS00

## Example 9-2

Find the timer's clock frequency and its period for various AVR-based systems, with the following crystal frequencies. Assume that no prescaler is used.

- (a) 10 MHz (b) 8 MHz (c) 1 MHz

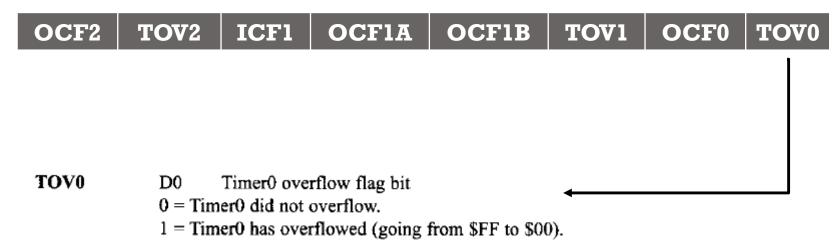
#### Solution:

- (a) F = 10 MHz and  $T = 1/10 \text{ MHz} = 0.1 \mu s$
- (b) F = 8 MHz and  $T = 1/8 \text{ MHz} = 0.125 \mu s$
- (c) F = 1 MHz and T = 1/1 MHz = 1  $\mu$ s



# PROGRAMMING TIMERO

TIFR (Timer/Counter Interrupt Flag Register)



#### WGM00, WGM01

D6	D3	Timer0 mode selector bits
0	0	Normal
0	1	CTC (Clear Timer on Compare Match)
1	0	PWM, phase correct
1	1	Fast PWM



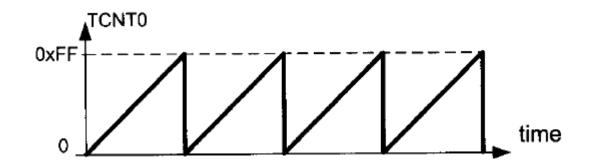
## NORMAL MODE

## TCCR0 (Timer/Counter Control Register)

$oxed{FOC0}$ $oxed{WGM00}$ $oxed{COM01}$ $oxed{COM00}$ $oxed{WGM01}$ $oxed{CS02}$ $oxed{CS01}$ $oxed{CS0}$
--

#### WGM00, WGM01

D6	D3	Timer0 mode selector bits
0	0	Normal
0	1	CTC (Clear Timer on Compare Match)
1	0	PWM, phase correct
1	1	Fast PWM



TCNT0 D7 D6 D5 D4 D3 D2 D1 D0



# PROGRAMMING TIMERO IN NORMAL MODE

- 1. Load the TCNT0 register with the initial count value.
- Load the value into the TCCR0 register, indicating which mode (8-bit or 16-bit) is to be used and the prescaler option. When you select the clock source, the timer/counter starts to count, and each tick causes the content of the timer/counter to increment by 1.
- Keep monitoring the timer overflow flag (TOV0) to see if it is raised. Get out of the loop when TOV0 becomes high.
- 4. Stop the timer by disconnecting the clock source, using the following instructions:
- Clear the TOV0 flag for the next round.
- 6. Go back to Step 1 to load TCNT0 again.



Write C program to toggle all the bits of PORTB continuously with some delay. Use Timer0, Normal mode, and no prescaler options to generate the delay.

```
#include "avr/io.h"
void TODelay ( );
int main ( )
                        //PORTB output port
      DDRB = 0 \times FF;
      while (1)
                           //repeat forever
            PORTB \Rightarrow 0x55;
            TODelay ( ); //delay size unknown
                           //repeat forever
            PORTB = 0xAA;
            TODelay ();
void TODelay ( )
                                              Step-1
                             //load TCNT0
      TCNT0 = 0x20;
                           ·//Timer0, Normal mode, no prescaler Step-2
      TCCR0 = 0x01;
      while ((TIFR&Ox1)==0); //wait for Tovo to roll over Step-3
                    Step-4
                               //clear TOV0 Step-5
                                                        Be careful: to clear this flag, we write 1!!
                      Step-4
      TIFR = 0x1;
```

Write C program to toggle only bit 4 of PORTB continuously every 70µsec. Use Timer0, Normal mode, and 1:8 prescaler. Assume XTAL = 8MHz.

```
#include "avr/io.h"
void TODelay ( );
int main ( )
     DDRB = 0xFF;
                      //PORTB output port
     while (1)
           TODelay ();
                        //TimerO, Normal mode
           PORTB = PORTB ^ 0x10; //toggle PORTB.4
void TODelay ( )
     TCNT0 = 186; //load TCNT0
     TCCR0 = 0x02; //Timer0, Normal mode, 1:8 prescaler
     while ((TIFR&(1<<TOV0))==0); //wait for TOV0 to roll over
     TCCR0 = 0;
                    //turn off Timer0
     TIFR = 0x1;
                    //clear TOV0
```

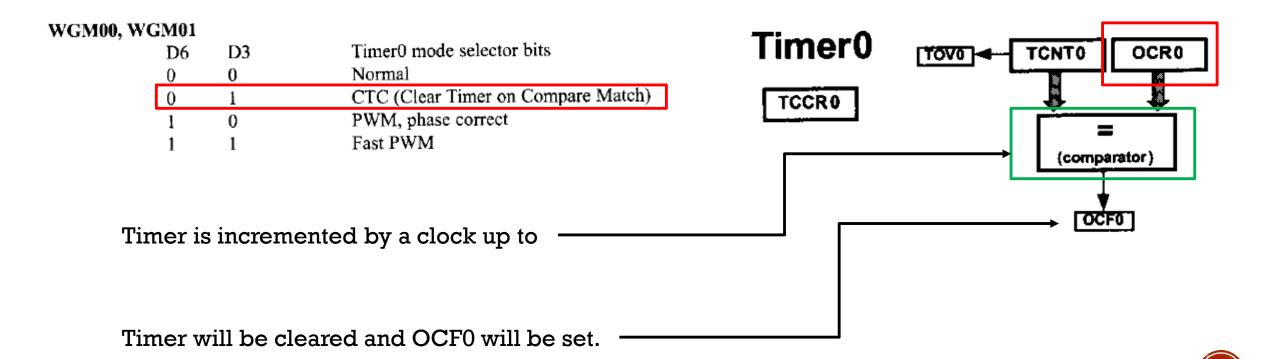
```
XTAL = 8MHz \rightarrow T<sub>machine cycle</sub> = 1/8 MHz
Prescaler = 1:8 \rightarrow T<sub>clock</sub> = 8 × 1/8 MHz = 1 \mus
70 \mus/1 \mus = 70 clocks \rightarrow 1 + 0xFF - 70 = 0x100 - 0x46 = 0xBA = 186
```



## PROGRAMMING TIMERO IN CTC MODE

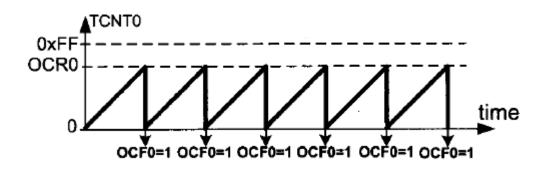
TCCR0 (Timer/Counter Control Register)

FOC0 WGM00 COM01 COM00 WGM01 CS02 CS01 CS00



# PROGRAMMING TIMERO IN CTC MODE

- 1. Load OCR0
- 2. Load TCCR0 to set the mode and to start the timer0
  - 1. As the timer (TCCR0) counts up:00,01,02,..... And reaches content of OCR0
  - 2. One more clock makes it 0 and OCF0 = 1
- 3. Stop timer0
- 4. OCF0 is set.



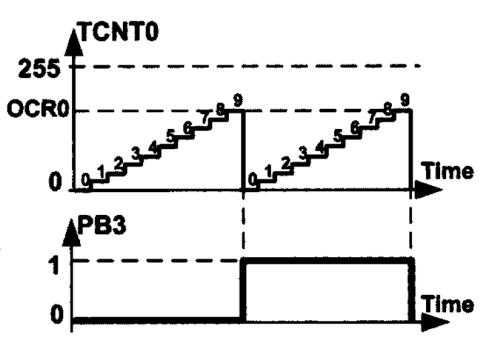


Find the delay generated by Timer0 when OCR0 is loaded with 9 in CNC mode. XTAL = 8MHz.

## **Solution:**

OCR0 is loaded with 9 and TCNT0 is cleared; ocro Thus, after 9 clocks TCNT0 becomes equal to OCR0. On the next clock, the OCF0 flag is set and the reset occurs. That means the TCNT0 is cleared after 9 + 1 = 10 clocks. Because XTAL = 8 MHz, the counter counts up every  $0.125 \,\mu s$ .

Therefore, we have  $10 \times 0.125 \,\mu s = 1.25 \,\mu s$ .





Due to prescaler = 1024 each timer clock lasts  $1024 \times 0.125 \,\mu s = 128 \,\mu s$ . Thus, in order to generate a delay of 25.6 ms we should wait 25.6 ms / 128  $\mu s = 200$  clocks. Therefore the OCR0 register should be loaded with 200 - 1 = 199.

Assuming XTAL = 8 MHz, write a program to generate a delay of 25.6 ms. Use Timer0, CTC mode, with prescaler = 1024.

## int main ()

## Void T0Delay()

TCCR0 (Timer/Counter Control Register)

		FOC0	WGM00	COM01	COM00	WGM01	CS02	CS01	CS00	//01001101
--	--	------	-------	-------	-------	-------	------	------	------	------------

CS02:00	D2	D1	D0	Timer0 clock selector	WGM00, WG	M01		
	0	0	0	No clock source (Timer/Counter stopped)		D6	D3	Timer0 mode selector bits
	0	0	1	clk (No Prescaling)	Г	0	0	Normal
	0	1	0	clk / 8	- 1	0	1	CTC (Clear Timer on Compare Match)
	0	1	1	clk / 64		•	0	
	1	0	0	clk / 256		1	U	PWM, phase correct
	1	0	1	clk / 1024		1	1	Fast PWM
	1	1	0	External clock source on T0 pin. Clock on falling edge.	•			
	1	1	1	External clock source on T0 pin. Clock on rising edge.				



## PROGRAMMING TIMERO AS COUNTER

- Timers can be used as counters if we provide pulses from outside the chip.
- T0 (PB0) and T1 (PB1) for Timer0 and Timer1



```
l Hz clocl #include "avr/io.h"
                                                                                              t counter
      And displint main ( )
                                                 //activate pull-up of PB0
                        PORTB = 0x01;
                        DDRC = 0xFF;
                                                 //PORTC as output
                        DDRD = 0xFF;
                                                  //PORTD as output
                                                  //output clock source
                        TCCR0 = 0x06;
                        TCNT0 = 0x00;
                        while (1)
                                                                                                //01001101
                               do
                                     PORTC = TCNT0:
       D2 D1 D0 Tir
CS02:00
                              \ while ((TIFR&(0x1<<TOV0))==0);//wait for TOV0 to roll over
                                                                                              ctor bits
                                                         //clear TOV0
                              TIFR = 0x1 << TOV0;
                                                                                               on Compare Match)
                                                         //increment PORTD
                               PORTD ++;
                   External clock source on T0 pin. Clock on rising edge.
```

