

EMBEDDED SYSTEMS CMPE-453

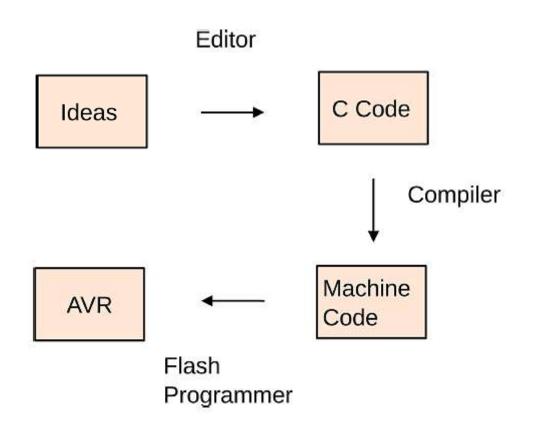
Department of Computer Engineering



Programming AVR Microcontroller

PROGRAMMING AVR MICROCONTOLLER

Tool-Chain



- Arduino IDE and board combines all these steps into one.
- Write the C code in Arduino IDE
- · Compile it.
- If no errors, upload the machine code to AVR microcontroller.



WHY TO CODE THE AVR IN C-LANGUAGE

- Easier and less time consuming to write in C than Assembly
- C is easier to modify and update
- Available state-of-the-art libraries
- Portable

But, what about the HEX Files?



FROM HEX TO MACHINE CODE

inside of an hex file

```
1:100000000C9434000C9446000C9446000C9446006A
3:100020000C9446000C9446000C9446000C94460038
    .00060000C9446000C94460011241FBECFEFD8E03C
8:10007000DEBFCDBF21E0A0E0B1E001C01D92A930FC
12:1000B0000E940000F9CF1E920E920EB60E921124E9
13:1000C0002F933F938F939F93AF93BF9380910101A1
```

```
cf 92
                        push
                                 r12
       df 92
                        push
1cc:
                                 r13
       ef 92
1ce:
                        push
                                 r14
                                               avr-objdump
1d0:
       ff 92
                        push
                                 r15
1d2:
       cf 93
                        push
                                 r28
       df 93
1d4:
                        push
                                 r29
                                 r12, r22
1d6:
       6b 01
                        movw
1d8:
       7c 01
                                 r14, r24
                        MOVW
```

```
> :107E000011E0A0E0B1E0E0E1F0E802C005900D92E1
```

- :[10] [7E00] [00] 11E0A0E0B1E0E0E1F0E802C005900D92 [E1]
- "" indicates the start of the record
- $[10] \rightarrow 0$ x10 indicating the number of bytes for the record.
- [7E00] or $0x7E00 \rightarrow Starting address$
- $[00] \rightarrow data (type).$
- [E1] is the checksum
- The string in the middle \rightarrow the actual data that gets programmed into the flash memory...
 - > 0x7E00 = 0x11
 - 0x7E01 = 0xE0
 - 0x7E02 = 0xA0
 - 0x7E03 = 0xE0

. . .

Atmega328p: address range 0x0000-0x3FFF

0x7E00/2 = 0x3F00

AVR is 'little endian' architecture. Instruction width is 16-bits

> 3F00 = 0xE011

3F01 = 0xE0A0

inc r22

0x9563

1001010101100011



RECALL!

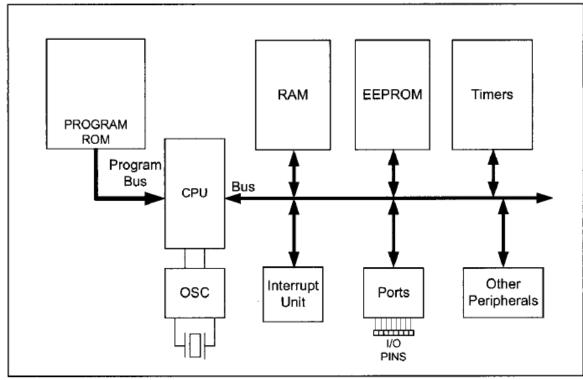


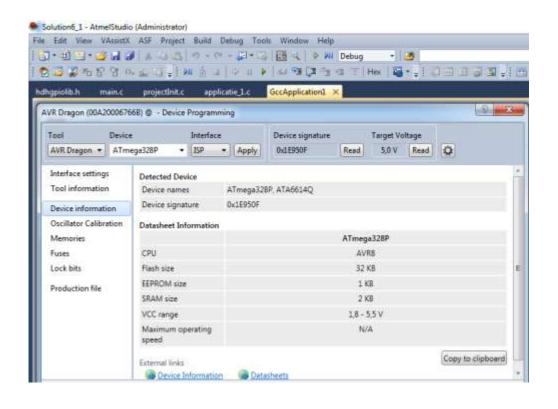
Figure 1-2. Simplified View of an AVR Microcontroller

- Databus: 8-bit wide
- Program/instruction bus: 16-bits wide
- ALU: processes 8-bits data



WHICH COMPILER?

Atmel Studio

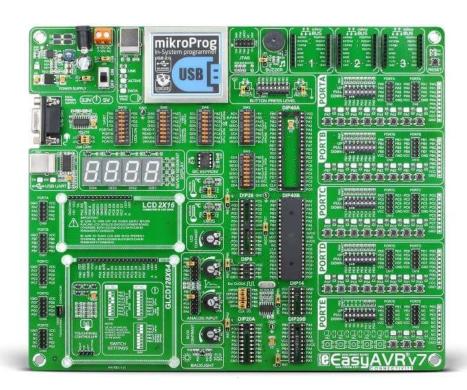


Arduino IDE

```
Blink | Arduino 1.8.5
  Blink 6
  This example code is in the public domain.
 http://www.arduino.cc/en/Tutorial/Blink
// the setup function runs once when you press reset or power the board
void setup() {
 // initialize digital pin LED_BUILTIN as an output.
  pirMode(LED_BUILTIN, OUTPUT);
// the loop function runs over and over again forever
void loop() {$
 digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)
                                     // wait for a second
 delay(1000);
 digitalWrite(LED_BUILTIN, LOW); // turn the LED off by making the voltage LOW
  delay(1000);
                                     // wait for a second
                                                                Arduino/Genuino Uno on COM1
```

WHICH BOARD?

The EasyAVR v7



Arduino Uno





WE WILL USE

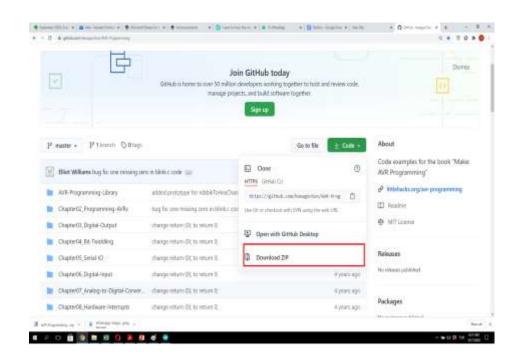


```
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  delay(1000);
                                     // wait for a second
                                                                Arduino/Genuino Uno on COM1
```



HOW TO WRITE C CODE ON ARDUINO IDE

- C library for AVR microcontroller.
 - Go to https://github.com/hexagon5un/AVR-Programming
 - Download the code.
 - Unzip the dowloaded folder and copy «AVR-Programming-Library» folder to
 - «Documents\Arduino\libraries» on Windows.





HOW TO WRITE C CODE ON ARDUINO IDE

- Replace portpins.h file in Arduino include folder with the newest version.
 - Copy the «portpins.h» file from downloaded «AVR-Programming-library»
 - Overwrite the already existing portpins.h file setup during installation of Arduino. In my machine, the location of this already existing file is «C:\Program Files (x86)\Arduino\hardware\tools\avr\avr\include\avr»

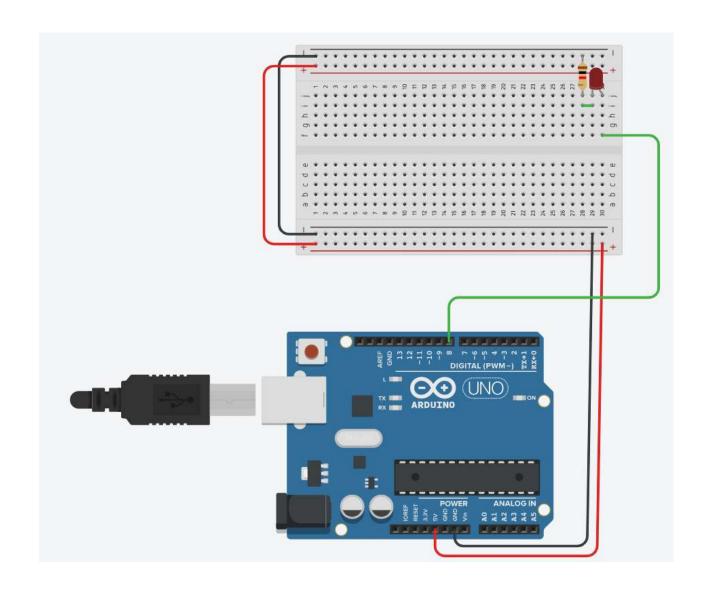


DEMO: C-PROGRAMMING ON ARDUINO IDE



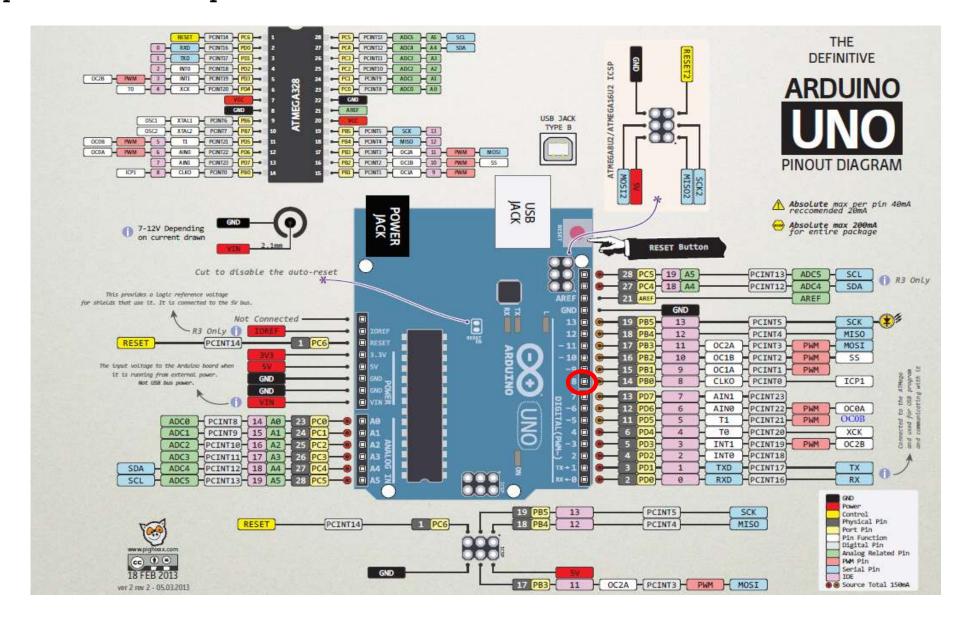
«BLINKER»

Make connections

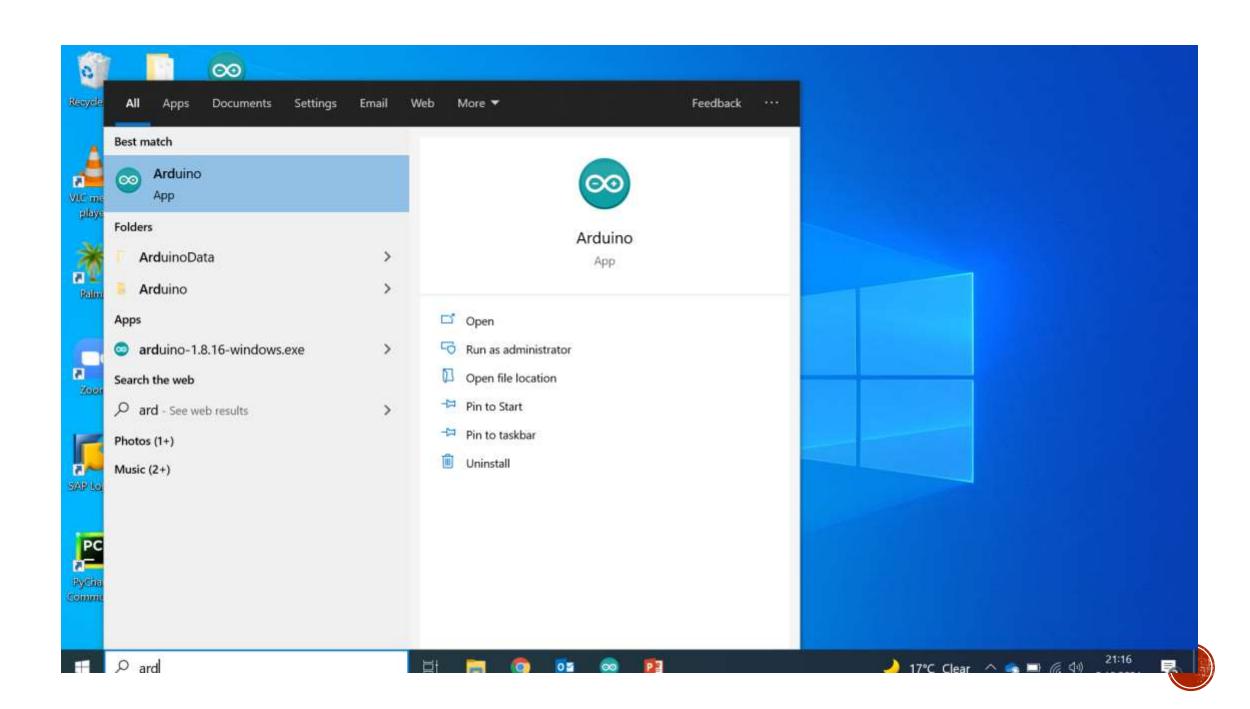




Before writing code, always check the pin mapping between Arduino board and AVR microcontroller. Digital pin 8 of Arduino is pin 0 of PortB on the microcontroller.





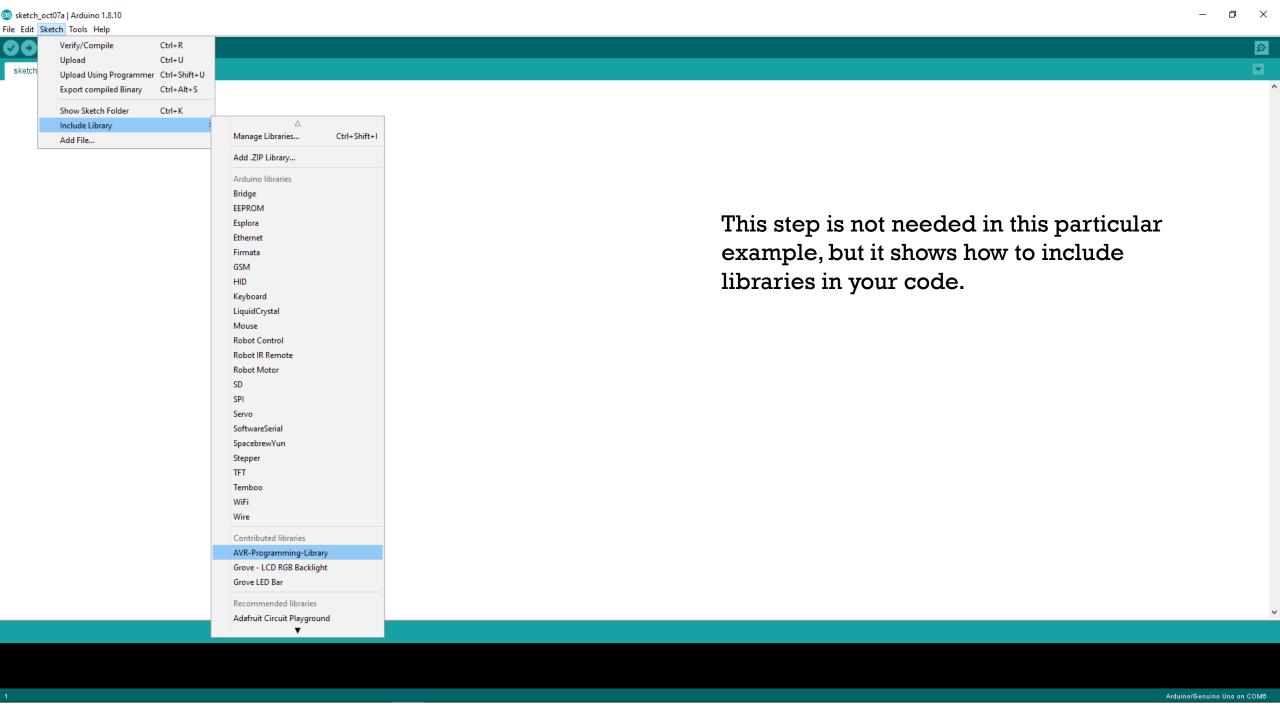


oo sketch_oct07a | Arduino 1.8.10 File Edit Sketch Tools Help

o ×



sketch_oct07a void setup() { // put your setup code here, to run once: void loop() { // put your main code here, to run repeatedly:



PASTE FOLLOWING CODE TO EMPTY FILE

```
/* Blinker Demo */
// ----- Preamble ----- //
#include <avr/io.h>
                                /* Defines pins, ports, etc */
#include <util/delay.h>
                                  /* Functions to waste time */
int main(void) {
// ----- Inits ----- //
                           /* Data Direction Register B: writing a one to the bit enables output. */
DDRB |= 0b00000001;
// ----- Event loop ----- //
while (1) {
        PORTB = 0b00000001;
                                   /* Turn on only pin 0 of PORTB */
                                                /* wait */
        _delay_ms(1000);
        PORTB = 0b000000000;
                                   /* Turn off all pins on PORT B */
                                                /* wait */
        _delay_ms(1000);
                                    /* End event loop */
                      /* This line is never reached */
return 0;
```

oo sketch_oct07a | Arduino 1.8.10

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sketch_oct07a§







```
// ----- Preamble ----- //
#include <avr/io.h>
                                        /* Defines pins, ports, etc */
#include <util/delay.h>
                                         /* Functions to waste time */
int main(void) {
 // ----- Inits ----- //
 DDRB |= 0b00000001;
                              /* Data Direction Register B:
                                 writing a one to the bit
                                 enables output. */
 // ----- Event loop ----- //
 while (1) {
   PORTB = 0b00000001;
                               /* Turn on first LED bit/pin in PORTB */
   _delay_ms(1000);
                                                           /* wait */
   PORTB = 0b00000000;
                               /* Turn off all B pins, including LED */
   _delay_ms(1000);
                                                           /* wait */
                                                 /* End event loop */
 return 0;
                                    /* This line is never reached */
```

/* Blinker Demo */

- Save file with name of «DemoExample», lets say, on Desktop.
- A folder with name of «DemoExample» will be created containing the arduino file named «DemoExample»



oo demoExample | Arduino 1.8.10

PORTB = 0b00000001;

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_delay_ms(1000);

_delay_ms(1000);

return 0;

٠,

```
File Edit Sketch Tools Help
 demoExample
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```

/* Turn on first LED bit/pin in PORTB */

/* Turn off all B pins, including LED */

/* This line is never reached */

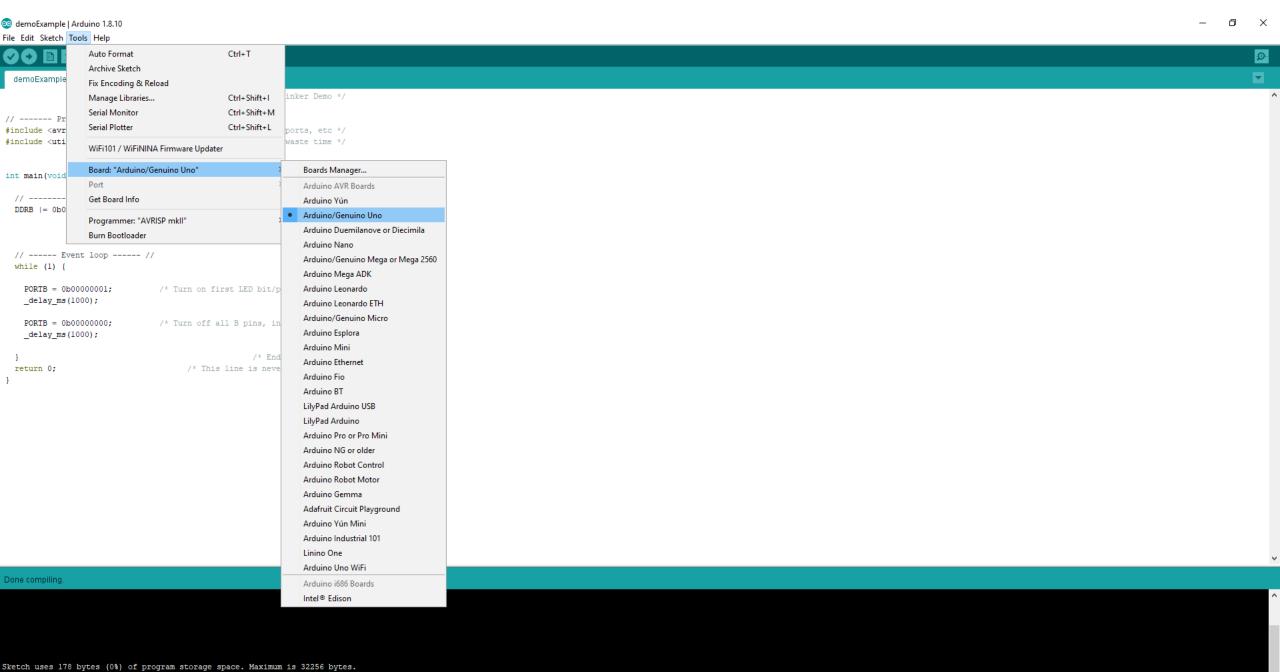
/* wait */

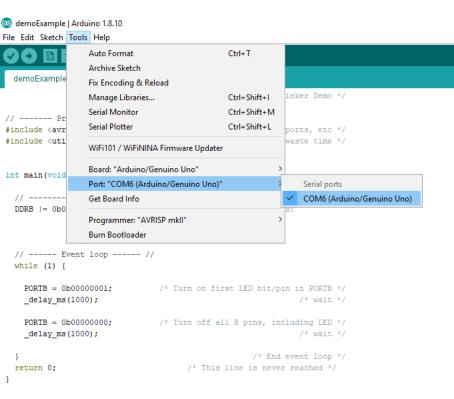
/* wait */

/* End event loop */

oo demoExample | Arduino 1.8.10 ð File Edit Sketch Tools Help demoExample /* Blinker Demo */ // ----- Preamble ----- // #include <avr/io.h> /* Defines pins, ports, etc */ #include <util/delay.h> /* Functions to waste time */ int main(void) { // ----- Inits ----- // DDRB |= 0b00000001; /* Data Direction Register B: writing a one to the bit enables output. */ // ----- Event loop ----- // while (1) { PORTB = 0b00000001; /* Turn on first LED bit/pin in PORTB */ _delay_ms(1000); /* wait */ PORTB = 0b00000000; /* Turn off all B pins, including LED */ _delay_ms(1000); /* wait */ /* End event loop */ return 0; /* This line is never reached */

Done compiling.





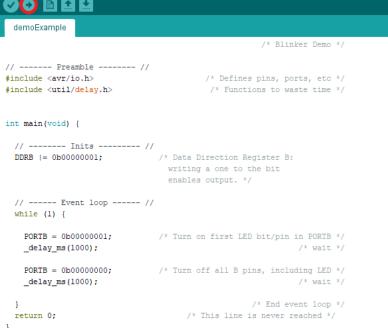
First connect your Arduino Uno board with your laptop/PC through USB cable.

Otherwise, the port will not appear in «Tools» menu.

Done compiling.

⊚ demoExample | Arduino 1.8.10

File Edit Sketch Tools Help



Done compiling.

oo demoExample | Arduino 1.8.10 File Edit Sketch Tools Help demoExample /* Blinker Demo */ // ----- Preamble ----- // #include <avr/io.h> /* Defines pins, ports, etc */ #include <util/delay.h> /* Functions to waste time */ int main(void) { // ----- Inits ----- // DDRB |= 0b00000001; /* Data Direction Register B: writing a one to the bit enables output. */ // ----- Event loop ----- // while (1) { PORTB = 0b00000001; /* Turn on first LED bit/pin in PORTB */ _delay_ms(1000); /* wait */ PORTB = 0b00000000; /* Turn off all B pins, including LED */ _delay_ms(1000); /* wait */ /* End event loop */ /* This line is never reached */ return 0;

Done uploading.

