



Machine Learning

CS60050

Computational Learning Theory (The VC-Dimension)



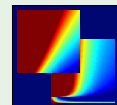
Learning From Data

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Lecture 7: The VC Dimension



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Outline

- The definition
- VC dimension of perceptrons
- Interpreting the VC dimension
- Generalization bounds

Definition of VC dimension

The VC dimension of a hypothesis set \mathcal{H} , denoted by $d_{\text{VC}}(\mathcal{H})$, is

the largest value of N for which $m_{\mathcal{H}}(N) = 2^N$

“the most points \mathcal{H} can shatter”

$N \leq d_{\text{VC}}(\mathcal{H}) \implies \mathcal{H}$ can shatter N points

$k > d_{\text{VC}}(\mathcal{H}) \implies k$ is a break point for \mathcal{H}

The growth function

In terms of a break point k :

$$m_{\mathcal{H}}(N) \leq \sum_{i=0}^{k-1} \binom{N}{i}$$

In terms of the VC dimension d_{VC} :

$$m_{\mathcal{H}}(N) \leq \underbrace{\sum_{i=0}^{d_{\text{VC}}} \binom{N}{i}}_{\text{maximum power is } N^{d_{\text{VC}}}}$$

Examples

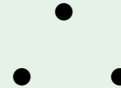
- \mathcal{H} is positive rays:

$$d_{VC} = 1$$



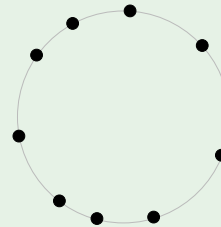
- \mathcal{H} is 2D perceptrons:

$$d_{VC} = 3$$



- \mathcal{H} is convex sets:

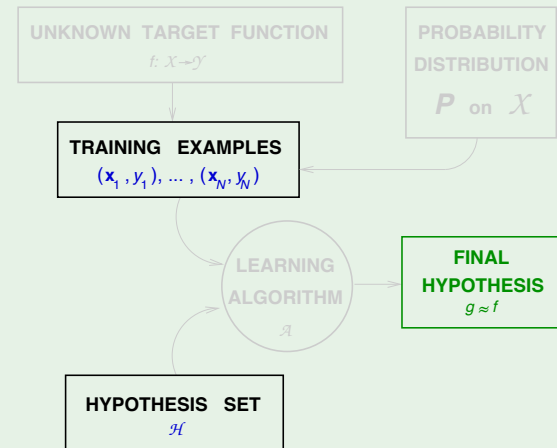
$$d_{VC} = \infty$$



VC dimension and learning

$d_{\text{VC}}(\mathcal{H})$ is finite $\implies g \in \mathcal{H}$ will generalize

- Independent of the **learning algorithm**
- Independent of the **input distribution**
- Independent of the **target function**



VC dimension of perceptrons

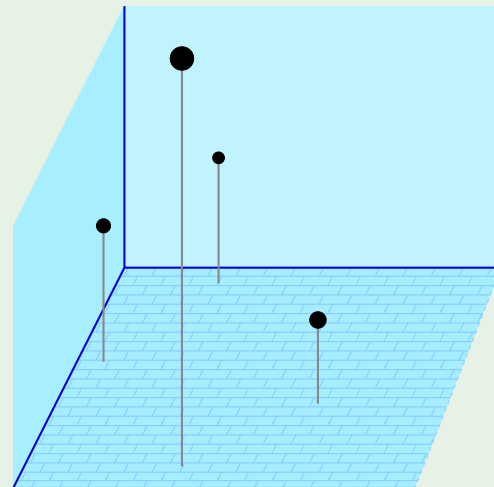
For $d = 2$, $d_{VC} = 3$

In general, $d_{VC} = d + 1$

We will prove two directions:

$$d_{VC} \leq d + 1$$

$$d_{VC} \geq d + 1$$



Here is one direction

A set of $N = d + 1$ points in \mathbb{R}^d shattered by the perceptron:

$$X = \begin{bmatrix} -\mathbf{x}_1^\top - \\ -\mathbf{x}_2^\top - \\ -\mathbf{x}_3^\top - \\ \vdots \\ -\mathbf{x}_{d+1}^\top - \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & 1 & 0 & \dots & 0 \\ 1 & 0 & 1 & & 0 \\ & \vdots & & \ddots & 0 \\ 1 & 0 & \dots & 0 & 1 \end{bmatrix}$$

X is invertible

Can we shatter this data set?

For any $\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_{d+1} \end{bmatrix} = \begin{bmatrix} \pm 1 \\ \pm 1 \\ \vdots \\ \pm 1 \end{bmatrix}$, can we find a vector \mathbf{w} satisfying

$$\text{sign}(\mathbf{X}\mathbf{w}) = \mathbf{y}$$

Easy! Just make $\mathbf{X}\mathbf{w} = \mathbf{y}$

which means $\mathbf{w} = \mathbf{X}^{-1}\mathbf{y}$

We can shatter these $d + 1$ points

This implies what?

[a] $d_{VC} = d + 1$

[b] $d_{VC} \geq d + 1$ ✓

[c] $d_{VC} \leq d + 1$

[d] No conclusion

Now, to show that $d_{vc} \leq d + 1$

We need to show that:

- [a] There are $d + 1$ points we cannot shatter
- [b] There are $d + 2$ points we cannot shatter
- [c] We cannot shatter *any* set of $d + 1$ points
- [d] We cannot shatter *any* set of $d + 2$ points ✓

Take any $d + 2$ points

For any $d + 2$ points,

$$\mathbf{x}_1, \dots, \mathbf{x}_{d+1}, \mathbf{x}_{d+2}$$

More points than dimensions \implies we must have

$$\mathbf{x}_j = \sum_{i \neq j} a_i \mathbf{x}_i$$

where not all the a_i 's are zeros

So?

$$\mathbf{x}_j = \sum_{i \neq j} a_i \mathbf{x}_i$$

Consider the following dichotomy:

\mathbf{x}_i 's with non-zero a_i get $y_i = \text{sign}(a_i)$

and \mathbf{x}_j gets $y_j = -1$

No perceptron can implement such dichotomy!

Why?

$$\mathbf{x}_j = \sum_{i \neq j} a_i \mathbf{x}_i \implies \mathbf{w}^\top \mathbf{x}_j = \sum_{i \neq j} a_i \mathbf{w}^\top \mathbf{x}_i$$

If $y_i = \text{sign}(\mathbf{w}^\top \mathbf{x}_i) = \text{sign}(a_i)$, then $a_i \mathbf{w}^\top \mathbf{x}_i > 0$

This forces
$$\mathbf{w}^\top \mathbf{x}_j = \sum_{i \neq j} a_i \mathbf{w}^\top \mathbf{x}_i > 0$$

Therefore, $y_j = \text{sign}(\mathbf{w}^\top \mathbf{x}_j) = +1$

Putting it together

We proved $d_{\text{VC}} \leq d + 1$ and $d_{\text{VC}} \geq d + 1$

$$d_{\text{VC}} = d + 1$$

What is $d + 1$ in the perceptron?

It is the number of parameters w_0, w_1, \dots, w_d

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1. Degrees of freedom

Parameters create degrees of freedom

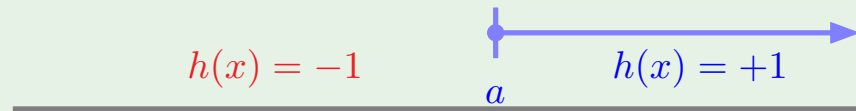
of parameters: **analog** degrees of freedom

d_{VC} : equivalent '**binary**' degrees of freedom

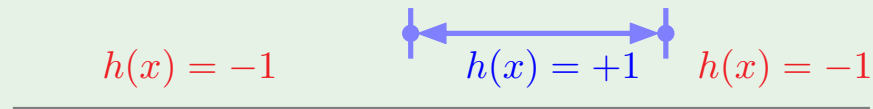


The usual suspects

Positive rays ($d_{VC} = 1$):

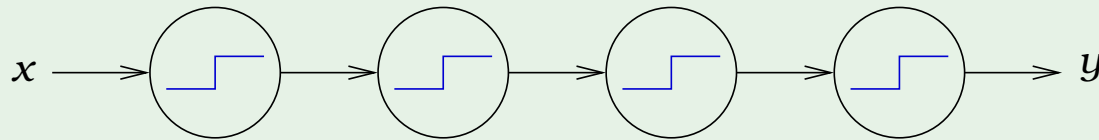


Positive intervals ($d_{VC} = 2$):



Not just parameters

Parameters may not contribute degrees of freedom:



d_{VC} measures the **effective** number of parameters

2. Number of data points needed

Two small quantities in the VC inequality:

$$\mathbb{P}[|E_{\text{in}}(g) - E_{\text{out}}(g)| > \epsilon] \leq \underbrace{4m_{\mathcal{H}}(2N)}_{\delta} e^{-\frac{1}{8}\epsilon^2 N}$$

If we want certain ϵ and δ , how does N depend on d_{VC} ?

Let us look at

$$N^d e^{-N}$$

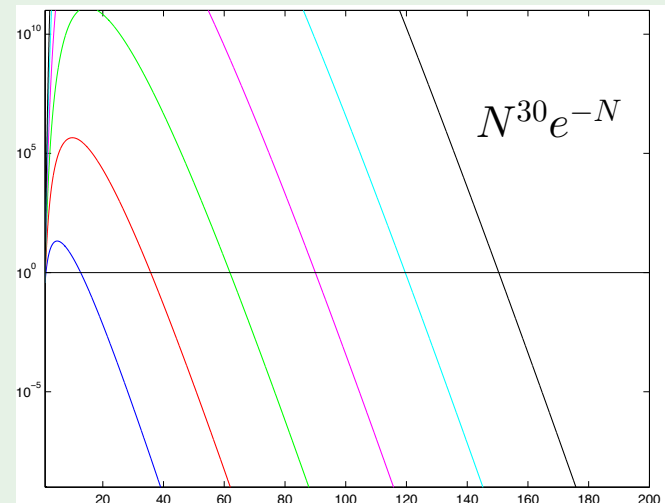
$$N^d e^{-N}$$

Fix $N^d e^{-N} = \text{small value}$

How does N change with d ?

Rule of thumb:

$$N \geq 10 d_{\text{VC}}$$



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Rearranging things

Start from the VC inequality:

$$\mathbb{P}[|E_{\text{out}} - E_{\text{in}}| > \epsilon] \leq \underbrace{4m_{\mathcal{H}}(2N)e^{-\frac{1}{8}\epsilon^2 N}}_{\delta}$$

Get ϵ in terms of δ :

$$\delta = 4m_{\mathcal{H}}(2N)e^{-\frac{1}{8}\epsilon^2 N} \implies \epsilon = \underbrace{\sqrt{\frac{8}{N} \ln \frac{4m_{\mathcal{H}}(2N)}{\delta}}}_{\Omega}$$

With probability $\geq 1 - \delta$, $|E_{\text{out}} - E_{\text{in}}| \leq \Omega(N, \mathcal{H}, \delta)$

Generalization bound

With probability $\geq 1 - \delta$, $E_{\text{out}} - E_{\text{in}} \leq \Omega$

\Rightarrow

With probability $\geq 1 - \delta$,

$$E_{\text{out}} \leq E_{\text{in}} + \Omega$$

Thank You!

