

Quick Review of basic search

1) Linear search

arr = [3, 9, ..., 15]

$O(1)$ $\xrightarrow{\hspace{2cm}}$ $O(n)$

find x , $x=15$

iterate, if x , return T , else F

2) Binary search arr = [1, 3, ..., 15]

$\log(n)$

b/c it's a tree

has to be sorted

start at middle, find x

- if x , true

- if $> x$, go to middle of right

- if $< x$, go to middle of left

- repeat

Graph and Tree Traversal

- BFS and DFS

- $O(n)$ for tree

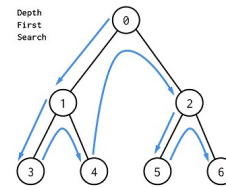
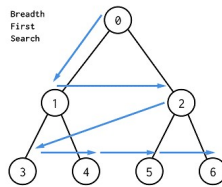
Breadth First Search (BFS)

1) start at root

2) move left to right on first level, then left to right on second level, to n level until node match or tree ends

- good on close targets, finding shortest path, more memory needed

- uses queue to keep track of children you want to traverse before jumping and a optional (for graphs) visited set to keep track of visited nodes



Depth First Search (DFS)

- 1) start at root

- 2) follow one branch down to leaf, pick ancestor with unexplored children

- good on far targets, finding if path exists, less memory

- uses stable recursion

BFS Implementation

needs:

- S:
- 1) Declare Queue, visited[], current node (temp traversal)

- 2) push root

- 3) while (queue.size != 0)

\hookleftarrow $current = queue.poll()$ // removes a node
 add curr to visited
 if (left child exists)
 add to queue
 if (right child exists)
 add to queue

```

graph TD
    N1(( )) --> N2(( ))
    N2 --> N3(( ))
    N3 --> N4(( ))
    N4 --> N5(( ))
    N5 --> N6(( ))
  
```



```
public void breadthFirstSearch(){
```

```
// Temp Node for traversal
Node currentNode = root;
```

```
// Optional, but mandatory for Graphs
```

```
ArrayList<Integer> visited = new ArrayList<Integer>();
```

```
Queue<Node> queue = new LinkedList<Node>();
queue.add(currentNode);
```

```
while (queue.size() != 0) {
    currentNode = queue.poll();
    visited.add(currentNode.data);
```

```
if (currentNode.left != null) {
    queue.add(currentNode.left);
}
if (currentNode.right != null) {
```

```

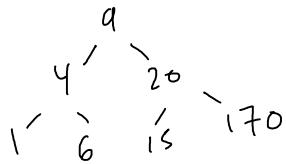
        queue.add(currentNode.right);
    }

}

System.out.println("bfs: " + visited);
}

```

DFS, 3 TYPES



In order (Left, root, right): [1, 4, 6, 9, 15, 20, 170]
 - In a BST, it gives nodes in order

Preorder (Root, Left, right): [9, 4, 1, 6, 20, 15, 170]
 - Good for copying a tree

Post order (Left, Right, root): [1, 6, 4, 15, 170, 20, 9]
 - Good for deleting a tree

DFS implementation

```

public static void dfsInOrder(Node root) {
    if (root.left != null) {
        dfsInOrder(root.left);
    }
    System.out.print(root.data + " "); // inOrder
    if (root.right != null) {
        dfsInOrder(root.right);
    }
}

```

```

public static void dfsPreOrder(Node root) {
    System.out.print(root.data + " "); // preOrder
    if (root.left != null) {
        dfsPreOrder(root.left);
    }
    if (root.right != null) {
        dfsPreOrder(root.right);
    }
}

```

Just move your operation around

tree height = deepest recursive function

memory = $O(\text{height})$

```

public static void dfsPostOrder(Node root) {
    if (root.left != null) {
        dfsPostOrder(root.left);
    }
    if (root.right != null) {
        dfsPostOrder(root.right);
    }
    System.out.print(root.data + " "); // postOrder
}

```

Graph Traversal

<https://visualgo.net/en/dfsdfs>

- needs boolean visited[] to mark all vertices as not visited
- default false
- For BFS and DFS
- O(V+E) for adjacency list

BFS : shortest path, closer nodes / cons: more memory

<https://www.geeksforgeeks.org/breadth-first-search-or-bfs-for-a-graph/>

```

// prints BFS traversal from a given source s
void BFS(int s)
{
    // Mark all the vertices as not visited (By default
    // set as false)
    boolean visited[] = new boolean[V];

    // Create a queue for BFS
    LinkedList<Integer> queue = new LinkedList<Integer>();

    // Mark the current node as visited and enqueue it
    visited[s]=true;
    queue.add(s);

    while (queue.size() != 0)
    {
        // Dequeue a vertex from queue and print it
        s = queue.poll();
        System.out.print(s+" ");

        // Get all adjacent vertices of the dequeued vertex s
        // If a adjacent has not been visited, then mark it
        // visited and enqueue it
        Iterator<Integer> i = adj[s].listIterator();
        while (i.hasNext())
        {
            int n = i.next();
            if (!visited[n])
            {
                visited[n] = true;
                queue.add(n);
            }
        }
    }
}

```

cons

cons: more backtracking after dead end | can get slow if

PODS
DFS: Solving a maze, backtracking after dead end
less memory
Does path Exist?

can get slow if
deep graph

```
void DFSUtil(int v, boolean visited[])
{
    // Mark the current node as visited and print it
    visited[v] = true;
    System.out.print(v + " ");

    // Recur for all the vertices adjacent to this
    // vertex
    Iterator<Integer> i = adj[v].listIterator();
    while (i.hasNext()) {
        int n = i.next();
        if (!visited[n])
            DFSUtil(n, visited);
    }
}

// The function to do DFS traversal. It uses recursive
// DFSUtil()
void DFS()
{
    // Mark all the vertices as not visited (set as
    // false by default in java)
    boolean visited[] = new boolean[V];

    // Call the recursive helper function to print DFS
    // traversal starting from all vertices one by one
    for (int i = 0; i < V; ++i)
        if (visited[i] == false)
            DFSUtil(i, visited);
}
```

for adjacency matrix

this are factors in
unconnected graphs
BFS can also do the same

Weighted Graphs (Shortest Path for Weighted graph)

<https://www.geeksforgeeks.org/what-are-the-differences-between-bellman-fords-and-dijkstras-algorithms/>

Dijkstra

<https://www.geeksforgeeks.org/dijkstras-shortest-path-algorithm-greedy-algo-7/>

- Greedy algorithm
- can only handle positive weights
- $O((V + E) \cdot \log(V))$, more efficient than Bellman

Bellman Ford

<https://www.geeksforgeeks.org/bellman-ford-algorithm-dp-23/>

- Dynamic Programming
- handles negative and positive weights
- than Dijkstra

- handles negative and positive
- $O(V, E)$, longer than Dijkstra