НАЦИОНАЛЬНЫЙ ИССЛЕДОВАТЕЛЬСКИЙ УНИВЕРСИТЕТ ИТМО

Факультет систем управления и робототехники

Прикладной искусственный интеллект Лабораторная работа № 3

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Классификация цветов с помощью свёрточных нейронных сетей.

В работе необходимо познакомится с различными архитектурами сверхточных нейронных сетей и их обучением на GPU (англ. graphics processing, графический процессор) на языке программирования Python 3 и фреймворка Torch (PyTorch). Для этого предлагается использовать ресурсы Google Colab - Colaboratory, для выполнения вычислений на GPU. После с ознакомления, выполнить практическое задане в конце данной тетради (notebook).

Рассмотрим <u>Датасет</u> содержащий 4242 изображения цветов размеченных по 5 видам (тюльпан, ромашка, подсолнух, роза, одуванчик). Данный набор данных можно скачать по ссылке с сайте kaggle.

Загрузите папку с картинками на гугл диск, чтобы не загружать ее каждый раз заново при перезапуске колаба. Структура файлов (можно посмотреть в меню слева) может быть такой: "/content/drive/My Drive/data/flowers". Обязательно подключите аппаратный ускоритель (GPU) к среде выполнения, чтобы вычисления были. В меню сверху: Среда выполнения -> Сменить среду выполнения

Первым делом разберите более детально код выполнив код ниже.

Подготовка

Загружаем библиотеки. Фиксируем random.seed для воспроизводимости

```
import numpy as np # linear algebra
import os
import torch
import torchvision
from torchvision.datasets.utils import download url
from torch.utils.data import random split
from torchvision.datasets import ImageFolder
from torchvision import transforms
from torchvision.transforms import ToTensor
from torch.utils.data.dataloader import DataLoader
import torch.nn as nn
import torch.nn.functional as F
import random
from tgdm import tgdm
import matplotlib.pyplot as plt
random.seed(0)
torch.manual seed(0)
```

```
<torch. C.Generator at 0x7f9f3cc9cab0>
Выбираем на чем будем делать вычисления - CPU или GPU (cuda)
device = 'cuda' if torch.cuda.is available() else 'cpu'
print(device)
cuda
from google.colab import drive
drive.mount('/content/drive', force remount=True)
FOLDERNAME = 'data/flowers'
assert FOLDERNAME is not None, "[!] Enter the foldername."
%cd drive/My\ Drive
#%cp -r $FOLDERNAME ../../
#%cd ../../
%cd data/flowers/
#!bash get datasets.sh
#%cd ../../
Mounted at /content/drive
/content/drive/My Drive
/content/drive/My Drive/data/flowers
prepare imgs = torchvision.transforms.Compose(
        torchvision.transforms.Resize((224, 224)), #приводим картинки
к одному размеру
        torchvision.transforms.ToTensor(), # упаковывем их в тензор
        torchvision.transforms.Normalize(
            mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225] #
нормализуем картинки по каналам
        ),
    1
)
# задаем датасет. Лейблы - имена папок:
dataset = ImageFolder('/content/drive/My Drive/data/flowers',
transform=prepare imgs)
dataset.imgs[2]
('/content/drive/My
Drive/data/flowers/daisy/10172379554 b296050f82 n.jpg', 0)
class ValueMeter(object):
  Вспомогательный класс, чтобы отслеживать loss и метрику
```

```
def init__(self):
      self.sum = 0
      self.total = 0
  def add(self, value, n):
      self.sum += value*n
      self.total += n
  def value(self):
      return self.sum/self.total
def log(mode, epoch, loss meter, accuracy meter, best perf=None):
  Вспомогательная функция, чтобы
  print(
      f"[{mode}] Epoch: {epoch:0.2f}. "
      f"Loss: {loss meter.value():.2f}. "
      f"Accuracy: {100*accuracy meter.value():.2f}% ", end="\n")
  if best perf:
      print(f"[best: {best perf:0.2f}]%", end="")
Сверточная нейросеть с нуля
Вручную прописываем слои
model = nn.Sequential(
            nn.Conv2d(in channels=3, out channels=32, kernel size=3,
stride=1, padding=1),
            nn.ReLU(),
            nn.Conv2d(32, 64, kernel size=3, stride=1, padding=1),
            nn.ReLU(),
            nn.MaxPool2d(2, 2), # output: 64 \times 16 \times 16
            nn.Conv2d(64, 128, kernel size=3, stride=1, padding=1),
            nn.ReLU(),
            nn.Conv2d(128, 128, kernel size=3, stride=1, padding=1),
            nn.ReLU(),
            nn.MaxPool2d(2, 2), # output: 128 x 8 x 8
            nn.Conv2d(128, 256, kernel size=3, stride=1, padding=1),
            nn.ReLU(),
            nn.Conv2d(256, 256, kernel size=3, stride=1, padding=1),
            nn.ReLU(),
            nn.MaxPool2d(2, 2), # output: 256 x 4 x 4
            nn.Flatten(),
```

nn.Linear(256*28*28, 1024),

```
nn.ReLU(),
            nn.Linear(1024, 512),
            nn.ReLU(),
            nn.Linear(512, 5))
model.to(device) # отправляем модель на девайс (GPU)
Sequential(
  (0): Conv2d(3, 32, kernel size=(3, 3), stride=(1, 1), padding=(1,
1))
  (1): ReLU()
  (2): Conv2d(32, 64, \text{kernel size}=(3, 3), \text{stride}=(1, 1), padding=(1, 1)
1))
  (3): ReLU()
  (4): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
ceil mode=False)
  (5): Conv2d(64, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1))
  (7): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
1))
  (8): ReLU()
  (9): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
ceil mode=False)
  (10): Conv2d(128, 256, \text{kernel size}=(3, 3), \text{stride}=(1, 1),
padding=(1, 1)
  (11): ReLU()
  (12): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1)
  (13): ReLU()
  (14): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
ceil mode=False)
  (15): Flatten(start dim=1, end dim=-1)
  (16): Linear(in features=200704, out features=1024, bias=True)
  (17): ReLU()
  (18): Linear(in features=1024, out features=512, bias=True)
  (19): ReLU()
  (20): Linear(in features=512, out features=5, bias=True)
)
```

Задаем гиперпараметры для обучения:

Задаем параметры и функцию для обучения. Разбиваем датасет на train/validation

```
batch_size = 32 # размер батча
optimizer = torch.optim.Adam(params = model.parameters()) # алгоритм
оптимизации
lr = 0.001 # learning rate
```

Разбиваем датасет на train и validation

```
Задаем dataloader'ы - объекты для итеративной загрузки данных и лейблов
для обучения и валидации
train set, val set = torch.utils.data.random split(dataset,
[len(\overline{d}ataset) - \overline{1000}, 1000])
print('Размер обучающего и валидационного датасета: ', len(train set),
len(val set))
loaders = {'training': DataLoader(train set, batch size,
pin memory=True,num workers=2, shuffle=True),
           'validation':DataLoader(val_set, batch_size,
pin memory=True,num workers=2, shuffle=False)}
Размер обучающего и валидационного датасета: 3317 1000
Функция для подсчета Accuracy
def accuracy(outputs, labels):
    _, preds = torch.max(outputs, dim=1)
    return torch.tensor(torch.sum(preds == labels).item() /
len(preds))
Функция для обучения и валидации модели
def trainval(model, loaders, optimizer, epochs=10):
    model: модель, которую собираемся обучать
    loaders: dict c dataloader'ами для обучения и валидации
    optimizer: оптимизатор
    epochs: число обучающих эпох (сколько раз пройдемся по всему
датасету)
    n n n
    loss meter = {'training': ValueMeter(), 'validation':
ValueMeter()}
    accuracy meter = {'training': ValueMeter(), 'validation':
ValueMeter()}
    loss track = {'training': [], 'validation': []}
    accuracy track = {'training': [], 'validation': []}
    for epoch in range(epochs): # итерации по эпохам
        for mode in ['training', 'validation']: # обучение - валидация
            # считаем градиаент только при обучении:
            with torch.set grad enabled(mode == 'training'):
                # в зависимоти от фазы переводим модель в нужный
ружим:
                model.train() if mode == 'training' else model.eval()
                for imgs, labels in tqdm(loaders[mode]):
                    imgs = imgs.to(device) # отправляем тензор на GPU
                    labels = labels.to(device)
                    bs = labels.shape[0] # размер батча (отличается
для последнего батча в лоадере)
```

```
preds = model(imgs) # forward pass - прогоняем
тензор с картинками через модель
                    loss = F.cross entropy(preds, labels) # считаем
функцию потерь
                    acc = accuracy(preds, labels) # считаем метрику
                    # xpaним loss и accuracy для батча
                    loss meter[mode].add(loss.item(), bs)
                    accuracy meter[mode].add(acc, bs)
                    # если мы в фазе обучения
                    if mode == 'training':
                        optimizer.zero grad() # обнуляем прошлый
градиент
                        loss.backward() # делаем backward pass
(считаем градиент)
                        optimizer.step() # обновляем веса
            # в конце фазы выводим значения loss и accuracy
            log(mode, epoch, loss meter[mode], accuracy meter[mode])
            # сохраняем результаты по всем эпохам
            loss track[mode].append(loss meter[mode].value())
            accuracy track[mode].append(accuracy meter[mode].value())
    return loss_track, accuracy track
```

Обучаем базовую модель

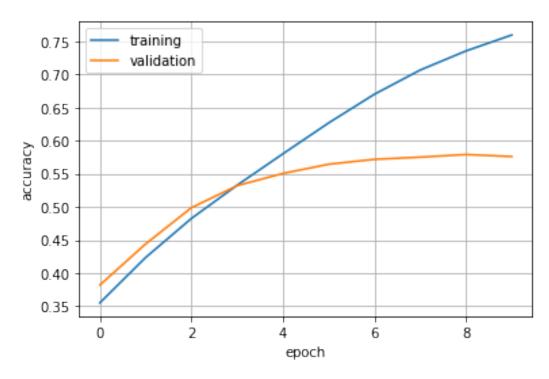
Проверим загрузку видеокарты, прежде чем запустить обучение:

```
66C
              P0
                   74W / 149W | 1321MiB / 11441MiB |
| N/A
                                                         0%
Default |
N/A |
 Processes:
  GPU
                      PID
                                                              GPU
        GΙ
            CI
                           Type
                                  Process name
Memory |
        ID
             ID
Usage
  No running processes found
Запускаем обучение на 10 эпох
loss track, accuracy track = trainval(model, loaders, optimizer,
epochs=10)
100%| 104/104 [04:07<00:00, 2.38s/it]
[training] Epoch: 0.00. Loss: 1.43. Accuracy: 35.51%
100%| 32/32 [01:08<00:00, 2.14s/it]
[validation] Epoch: 0.00. Loss: 1.39. Accuracy: 38.20%
100%| 104/104 [01:16<00:00, 1.36it/s]
[training] Epoch: 1.00. Loss: 1.31. Accuracy: 42.36%
100% | 32/32 [00:10<00:00, 2.93it/s]
[validation] Epoch: 1.00. Loss: 1.26. Accuracy: 44.40%
100%| 104/104 [01:16<00:00, 1.37it/s]
[training] Epoch: 2.00. Loss: 1.21. Accuracy: 48.25%
100%| 32/32 [00:11<00:00, 2.80it/s]
[validation] Epoch: 2.00. Loss: 1.17. Accuracy: 49.87%
```

```
100%| 104/104 [01:16<00:00, 1.37it/s]
[training] Epoch: 3.00. Loss: 1.11. Accuracy: 53.27%
            32/32 [00:11<00:00, 2.88it/s]
[validation] Epoch: 3.00. Loss: 1.12. Accuracy: 53.20%
100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 
[training] Epoch: 4.00. Loss: 1.01. Accuracy: 58.00%
100%| 32/32 [00:10<00:00, 3.07it/s]
[validation] Epoch: 4.00. Loss: 1.12. Accuracy: 55.04%
100%| 104/104 [01:16<00:00, 1.37it/s]
[training] Epoch: 5.00. Loss: 0.91. Accuracy: 62.67%
100%| 32/32 [00:10<00:00, 3.05it/s]
[validation] Epoch: 5.00. Loss: 1.17. Accuracy: 56.43%
100%| 104/104 [01:16<00:00, 1.37it/s]
[training] Epoch: 6.00. Loss: 0.81. Accuracy: 67.00%
100% | 32/32 [00:10<00:00, 3.02it/s]
[validation] Epoch: 6.00. Loss: 1.28. Accuracy: 57.17%
100%| 100%| 104/104 [01:16<00:00, 1.37it/s]
[training] Epoch: 7.00. Loss: 0.72. Accuracy: 70.65%
100%| 32/32 [00:11<00:00, 2.89it/s]
[validation] Epoch: 7.00. Loss: 1.42. Accuracy: 57.50%
100%| 104/104 [01:16<00:00, 1.36it/s]
[training] Epoch: 8.00. Loss: 0.66. Accuracy: 73.53%
100%| 32/32 [00:11<00:00, 2.88it/s]
[validation] Epoch: 8.00. Loss: 1.50. Accuracy: 57.90%
              | 104/104 [01:16<00:00, 1.36it/s]
[training] Epoch: 9.00. Loss: 0.60. Accuracy: 75.93%
100%| 32/32 [00:11<00:00, 2.83it/s]
[validation] Epoch: 9.00. Loss: 1.56. Accuracy: 57.59%
```

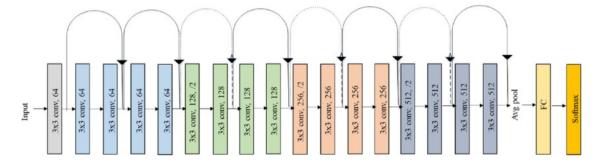
```
from matplotlib import pyplot as plt
%matplotlib inline
plt.plot(accuracy_track['training'], label='training')
plt.plot(accuracy_track['validation'], label='validation')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.grid()
plt.legend()
```

<matplotlib.legend.Legend at 0x7f9f33be8510>



Fine-tuning предобученной модели

Теперь попробуем поработать с предобученной сетью ResNet-18



```
resnet = torchvision.models.resnet18(pretrained=True) # инициализируем
модель
resnet
Downloading: "https://download.pytorch.org/models/resnet18-
f37072fd.pth" to /root/.cache/torch/hub/checkpoints/resnet18-
f37072fd.pth
{"version major":2,"version minor":0,"model id":"85880191086b49f99723e
e1c88aa1a4e"}
ResNet(
  (conv1): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2),
padding=(3, 3), bias=False)
  (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1,
ceil mode=False)
  (layer1): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    )
  (layer2): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(64, 128, kernel size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1),
```

```
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (downsample): Sequential(
        (0): Conv2d(64, 128, \text{kernel size}=(1, 1), \text{stride}=(2, 2),
bias=False)
        (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
  (layer3): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(128, 256, kernel size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (downsample): Sequential(
        (0): Conv2d(128, 256, kernel size=(1, 1), stride=(2, 2),
bias=False)
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
```

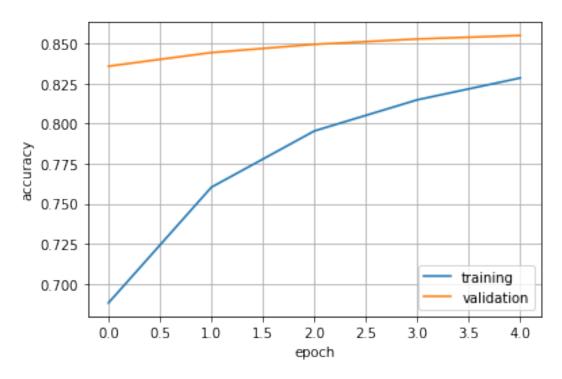
```
)
  (layer4): Sequential(
    (0): BasicBlock(
      (conv1): Conv2d(256, 512, kernel size=(3, 3), stride=(2, 2),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (downsample): Sequential(
        (0): Conv2d(256, 512, kernel size=(1, 1), stride=(2, 2),
bias=False)
        (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
    (1): BasicBlock(
      (conv1): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
  (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
  (fc): Linear(in features=512, out features=1000, bias=True)
)
def set parameter requires grad(model):
  Функция для заморозки весов модели
  for param in model.parameters():
    param.requires grad = False
set_parameter_requires_grad(resnet)
# Меняем последний слой модели, чтобы он предсказывал 5 классов, а не
1000
# Когда мы заново определяем слой, у него по умолчанию стоит аттрибут
requires grad = True
# То есть этот полносвязный слой будет обучаться
resnet.fc = nn.Linear(512, 5)
```

```
# Проверим все ли сработало правильно, выведем веса, которые будут
обучаться
for name, param in resnet.named parameters():
         if param.requires grad:
                  print(name)
fc.weight
fc.bias
Запустим функцию обучения модели. Внимание - необходимо заново
задать оптимизатор, чтобы он теперь работал с весами resnet
resnet.to(device)
optimizer = torch.optim.Adam(params = resnet.parameters()) # алгоритм
оптимизации
loss track, accuracy track = trainval(resnet, loaders, optimizer,
epochs=5)
100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 100%| 
[training] Epoch: 0.00. Loss: 0.89. Accuracy: 68.80%
100%| 32/32 [00:06<00:00, 4.81it/s]
[validation] Epoch: 0.00. Loss: 0.54. Accuracy: 83.60%
100%| 100%| 104/104 [00:21<00:00, 4.79it/s]
[training] Epoch: 1.00. Loss: 0.70. Accuracy: 76.03%
             | 32/32 [00:06<00:00, 4.83it/s]
[validation] Epoch: 1.00. Loss: 0.48. Accuracy: 84.45%
100%| 100%| 104/104 [00:21<00:00, 4.84it/s]
[training] Epoch: 2.00. Loss: 0.60. Accuracy: 79.55%
100%| 32/32 [00:06<00:00, 4.84it/s]
[validation] Epoch: 2.00. Loss: 0.46. Accuracy: 84.97%
100%| 104/104 [00:21<00:00, 4.85it/s]
[training] Epoch: 3.00. Loss: 0.54. Accuracy: 81.50%
100%| 32/32 [00:06<00:00, 4.79it/s]
[validation] Epoch: 3.00. Loss: 0.44. Accuracy: 85.30%
100%| 104/104 [00:21<00:00, 4.74it/s]
[training] Epoch: 4.00. Loss: 0.51. Accuracy: 82.86%
100%| 32/32 [00:06<00:00, 4.83it/s]
```

```
[validation] Epoch: 4.00. Loss: 0.42. Accuracy: 85.52%
```

```
plt.plot(accuracy_track['training'], label='training')
plt.plot(accuracy_track['validation'], label='validation')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.grid()
plt.legend()
```

<matplotlib.legend.Legend at 0x7fae3d184d10>



Сохраним веса модели:

```
weights_fname = '/content/drive/My Drive/data/flower-resnet.pth'
torch.save(resnet.state_dict(), weights_fname)
```

Смотрим результат

И посмотрим как модель предсказывает

```
import matplotlib.pyplot as plt
%matplotlib inline
import warnings
warnings.filterwarnings("ignore")

def predict_image(img, model):
    # Преобразование to a batch of 1
```

```
xb = img.unsqueeze(0).to(device)
# Получение прогнозов от модели
yb = model(xb)
# Выбираем индекс с наибольшей вероятностью
_, preds = torch.max(yb, dim=1)
# Получение метки класса
return dataset.classes[preds[0].item()]

for i in range(1,10):
img, label = val_set[i]
plt.imshow(img.clip(0,1).permute(1, 2, 0))
plt.axis('off')
plt.title('Label: {}, Predicted:
{}'.format(dataset.classes[label], predict_image(img, resnet)))
plt.show()
# print('Label:', dataset.classes[label], ', Predicted:',
predict_image(img, resnet))
```

Label: dandelion, Predicted: dandelion



Label: sunflower, Predicted: daisy



Label: sunflower, Predicted: sunflower



Label: dandelion, Predicted: dandelion



Label: sunflower, Predicted: sunflower



Label: rose, Predicted: rose



Label: daisy, Predicted: daisy



Label: sunflower, Predicted: sunflower



Label: rose, Predicted: tulip



Практическое задание

В пракическом задание необходимо обучить еще одну сверточную архитектуру для задач классификации цветов.

В выбранной Вами архитектуре также необходимо разобраться с основными её параметрами и принципами работы.

```
используя transfer learning до-обучите модель на классификацию цветов.
Чтобы это сделать замените ___ в ячейках ниже на работающий код.
# Выберите модель из списка доступных в PyTorch моделей
# Не забудьте указать, что она модель должна быть предобучена!
model =torchvision.models.densenet169(pretrained=True)
model
Downloading: "https://download.pytorch.org/models/densenet169-
b2777c0a.pth" to /root/.cache/torch/hub/checkpoints/densenet169-
b2777c0a.pth
{"version major":2, "version minor":0, "model id": "b2e2ea5997a643df8c119
316336ce371"}
DenseNet(
  (features): Sequential(
    (conv0): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2),
padding=(3, 3), bias=False)
    (norm0): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (relu0): ReLU(inplace=True)
    (pool0): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1,
ceil mode=False)
    (denseblock1): _DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(64, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(96, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(96, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
```

Посмотрите как использовать модели в PyTorch, выберите одну и

```
(norm1): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(128, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(160, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(160, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(192, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(192, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(224, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(224, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (transition1): Transition(
      (norm): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
```

```
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock2): DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(128, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(160, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(160, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(192, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(192, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(224, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(224, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
```

```
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(256, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(288, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(288, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(320, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(320, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(352, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(352, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
```

```
(conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(384, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(384, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(416, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(416, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(448, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(448, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer12): DenseLayer(
        (norm1): Batch\overline{N}orm2d(480, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(480, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
)
    (transition2): Transition(
      (norm): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1),
bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock3): DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(256, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(288, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(288, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(320, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(320, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(352, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
```

```
(relu1): ReLU(inplace=True)
        (conv1): Conv2d(352, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(384, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(384, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(416, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(416, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(448, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(448, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(480, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(480, 128, kernel size=(1, 1), stride=(1, 1),
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bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(512, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(544, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(544, 128, kernel_size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(576, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(576, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(608, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(608, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
```

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affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer13): DenseLayer(
        (norm1): BatchNorm2d(640, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(640, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer14): DenseLayer(
        (norm1): BatchNorm2d(672, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(672, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer15): DenseLayer(
        (norm1): BatchNorm2d(704, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(704, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer16): DenseLayer(
        (norm1): BatchNorm2d(736, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(736, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
```

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(conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer17): DenseLayer(
        (norm1): BatchNorm2d(768, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer18): DenseLayer(
        (norm1): BatchNorm2d(800, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(800, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer19): DenseLayer(
        (norm1): BatchNorm2d(832, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(832, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer20): DenseLayer(
        (norm1): BatchNorm2d(864, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(864, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
(denselayer21): DenseLayer(
        (norm1): BatchNorm2d(896, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(896, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer22): DenseLayer(
        (norm1): BatchNorm2d(928, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(928, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer23): DenseLayer(
        (norm1): BatchNorm2d(960, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(960, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer24): DenseLayer(
        (norm1): BatchNorm2d(992, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(992, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer25): DenseLayer(
```

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(norm1): BatchNorm2d(1024, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1024, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer26): DenseLayer(
        (norm1): BatchNorm2d(1056, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1056, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer27): DenseLayer(
        (norm1): BatchNorm2d(1088, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1088, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer28): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1120, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1120, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer29): DenseLayer(
        (norm1): BatchNorm2d(1152, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
```

```
(relu1): ReLU(inplace=True)
        (conv1): Conv2d(1152, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer30): DenseLayer(
        (norm1): BatchNorm2d(1184, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1184, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer31): DenseLayer(
        (norm1): BatchNorm2d(1216, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1216, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer32): DenseLayer(
        (norm1): BatchNorm2d(1248, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1248, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (transition3): Transition(
      (norm): BatchNorm2d(1280, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
```

```
(conv): Conv2d(1280, 640, kernel size=(1, 1), stride=(1, 1),
bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock4): DenseBlock(
      (denselayer1): _DenseLayer(
        (norm1): BatchNorm2d(640, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(640, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): _DenseLayer(
        (norm1): BatchNorm2d(672, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(672, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(704, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(704, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(736, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(736, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
```

```
(conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(768, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(800, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(800, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(832, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(832, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(864, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(864, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
(denselayer9): DenseLayer(
        (norm1): BatchNorm2d(896, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(896, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(928, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(928, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(960, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(960, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(992, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(992, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer13): DenseLayer(
```

```
(norm1): BatchNorm2d(1024, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1024, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer14): DenseLayer(
        (norm1): BatchNorm2d(1056, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1056, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer15): DenseLayer(
        (norm1): BatchNorm2d(1088, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1088, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer16): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1120, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1120, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer17): DenseLayer(
        (norm1): BatchNorm2d(1152, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
```

```
(relu1): ReLU(inplace=True)
        (conv1): Conv2d(1152, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer18): DenseLayer(
        (norm1): BatchNorm2d(1184, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1184, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer19): DenseLayer(
        (norm1): BatchNorm2d(1216, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1216, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer20): DenseLayer(
        (norm1): BatchNorm2d(1248, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1248, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer21): DenseLayer(
        (norm1): BatchNorm2d(1280, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1280, 128, kernel size=(1, 1), stride=(1, 1),
```

```
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer22): DenseLayer(
        (norm1): BatchNorm2d(1312, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1312, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer23): DenseLayer(
        (norm1): BatchNorm2d(1344, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1344, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer24): DenseLayer(
        (norm1): BatchNorm2d(1376, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1376, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer25): DenseLayer(
        (norm1): BatchNorm2d(1408, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1408, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
```

```
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer26): DenseLayer(
        (norm1): BatchNorm2d(1440, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1440, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer27): DenseLayer(
        (norm1): BatchNorm2d(1472, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1472, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer28): DenseLayer(
        (norm1): BatchNorm2d(1504, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1504, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer29): DenseLayer(
        (norm1): BatchNorm2d(1536, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1536, 128, kernel_size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
```

```
(conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer30): DenseLayer(
        (norm1): BatchNorm2d(1568, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1568, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer31): DenseLayer(
        (norm1): BatchNorm2d(1600, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1600, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer32): DenseLayer(
        (norm1): BatchNorm2d(1632, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1632, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (norm5): BatchNorm2d(1664, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
  (classifier): Linear(in features=1664, out features=1000, bias=True)
set parameter requires grad(model) # передайте модель в функцию для
"заморозки" градиента
model.classifier = nn.Linear(1664,5) # Меняем последний слой модели
model
```

```
DenseNet(
  (features): Sequential(
    (conv0): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2),
padding=(3, 3), bias=False)
    (norm0): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (relu0): ReLU(inplace=True)
    (pool0): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1,
ceil mode=False)
    (denseblock1): DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(64, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(96, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(96, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(128, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(160, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
```

```
(conv1): Conv2d(160, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(192, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(192, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(224, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(224, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (transition1): Transition(
      (norm): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock2): DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(128, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
```

```
(relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(160, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(160, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(192, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(192, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(224, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(224, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(256, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
```

```
padding=(1, 1), bias=False)
      (denselayer6): DenseLayer(
        (norm1): BatchNorm2d(288, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(288, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(320, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(320, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(352, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(352, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(384, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(384, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
(denselayer10): DenseLayer(
        (norm1): BatchNorm2d(416, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(416, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(448, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(448, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(480, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(480, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (transition2): Transition(
      (norm): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1),
bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock3): _DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(256, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
```

```
(conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(288, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(288, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(320, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(320, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(352, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(352, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(384, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(384, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
```

```
(norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselaver6): DenseLaver(
        (norm1): BatchNorm2d(416, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(416, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(448, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(448, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(480, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(480, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(512, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
```

```
(relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselaver10): DenseLaver(
        (norm1): BatchNorm2d(544, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(544, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(576, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(576, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(608, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(608, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer13): DenseLayer(
        (norm1): BatchNorm2d(640, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(640, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
```

```
padding=(1, 1), bias=False)
      (denselayer14): DenseLayer(
        (norm1): BatchNorm2d(672, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(672, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer15): DenseLayer(
        (norm1): BatchNorm2d(704, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(704, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer16): DenseLayer(
        (norm1): BatchNorm2d(736, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(736, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer17): DenseLayer(
        (norm1): BatchNorm2d(768, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
(denselayer18): DenseLayer(
        (norm1): BatchNorm2d(800, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(800, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer19): DenseLayer(
        (norm1): BatchNorm2d(832, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(832, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer20): DenseLayer(
        (norm1): BatchNorm2d(864, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(864, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer21): DenseLayer(
        (norm1): BatchNorm2d(896, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(896, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer22): DenseLayer(
        (norm1): BatchNorm2d(928, eps=1e-05, momentum=0.1,
```

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affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(928, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer23): DenseLayer(
        (norm1): BatchNorm2d(960, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(960, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer24): DenseLayer(
        (norm1): BatchNorm2d(992, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(992, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer25): DenseLayer(
        (norm1): BatchNorm2d(1024, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1024, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer26): DenseLayer(
        (norm1): BatchNorm2d(1056, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
```

```
(conv1): Conv2d(1056, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer27): DenseLayer(
        (norm1): BatchNorm2d(1088, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1088, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer28): DenseLayer(
        (norm1): BatchNorm2d(1120, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1120, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer29): DenseLayer(
        (norm1): BatchNorm2d(1152, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1152, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer30): DenseLayer(
        (norm1): BatchNorm2d(1184, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1184, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
```

```
(norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer31): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1216, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1216, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer32): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1248, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1248, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (transition3): Transition(
      (norm): BatchNorm2d(1280, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (relu): ReLU(inplace=True)
      (conv): Conv2d(1280, 640, kernel size=(1, 1), stride=(1, 1),
bias=False)
      (pool): AvgPool2d(kernel size=2, stride=2, padding=0)
    (denseblock4): DenseBlock(
      (denselayer1): DenseLayer(
        (norm1): BatchNorm2d(640, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(640, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
```

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padding=(1, 1), bias=False)
      (denselayer2): DenseLayer(
        (norm1): BatchNorm2d(672, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(672, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer3): DenseLayer(
        (norm1): BatchNorm2d(704, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(704, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer4): DenseLayer(
        (norm1): BatchNorm2d(736, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(736, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer5): DenseLayer(
        (norm1): BatchNorm2d(768, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(768, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
(denselayer6): DenseLayer(
        (norm1): BatchNorm2d(800, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(800, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer7): DenseLayer(
        (norm1): BatchNorm2d(832, eps=1e-05, momentum=0.1,
affine=True, track running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(832, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer8): DenseLayer(
        (norm1): BatchNorm2d(864, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(864, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer9): DenseLayer(
        (norm1): BatchNorm2d(896, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(896, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer10): DenseLayer(
        (norm1): BatchNorm2d(928, eps=1e-05, momentum=0.1,
```

```
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(928, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer11): DenseLayer(
        (norm1): BatchNorm2d(960, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(960, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer12): DenseLayer(
        (norm1): BatchNorm2d(992, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(992, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer13): DenseLayer(
        (norm1): BatchNorm2d(1024, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1024, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer14): DenseLayer(
        (norm1): BatchNorm2d(1056, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
```

```
(conv1): Conv2d(1056, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer15): DenseLayer(
        (norm1): BatchNorm2d(1088, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1088, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer16): DenseLayer(
        (norm1): BatchNorm2d(1120, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1120, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer17): DenseLayer(
        (norm1): BatchNorm2d(1152, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1152, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer18): DenseLayer(
        (norm1): BatchNorm2d(1184, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1184, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
```

```
(norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer19): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1216, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1216, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer20): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1248, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1248, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer21): DenseLayer(
        (norm1): BatchNorm2d(1280, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1280, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer22): DenseLayer(
        (norm1): BatchNorm2d(1312, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1312, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
```

```
(relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer23): DenseLayer(
        (norm1): BatchNorm2d(1344, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1344, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer24): DenseLayer(
        (norm1): BatchNorm2d(1376, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1376, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer25): DenseLayer(
        (norm1): BatchNorm2d(1408, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1408, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer26): DenseLayer(
        (norm1): BatchNorm2d(1440, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1440, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
```

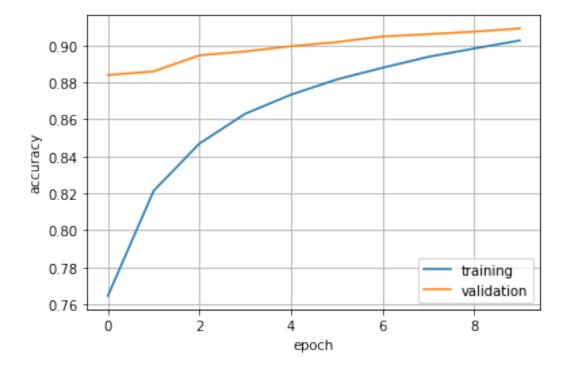
```
padding=(1, 1), bias=False)
      (denselayer27): DenseLayer(
        (norm1): BatchNorm2d(1472, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1472, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel_size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer28): DenseLayer(
        (norm1): BatchNorm2d(1504, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1504, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer29): DenseLayer(
        (norm1): BatchNorm2d(1536, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1536, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer30): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1568, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1568, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
```

```
(denselayer31): DenseLayer(
        (norm1): BatchNorm2d(1600, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1600, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
      (denselayer32): DenseLayer(
        (norm1): Batch\overline{N}orm2d(1632, eps=1e-05, momentum=0.1,
affine=True, track_running_stats=True)
        (relu1): ReLU(inplace=True)
        (conv1): Conv2d(1632, 128, kernel size=(1, 1), stride=(1, 1),
bias=False)
        (norm2): BatchNorm2d(128, eps=1e-05, momentum=0.1,
affine=True, track running stats=True)
        (relu2): ReLU(inplace=True)
        (conv2): Conv2d(128, 32, kernel size=(3, 3), stride=(1, 1),
padding=(1, 1), bias=False)
    (norm5): BatchNorm2d(1664, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
  (classifier): Linear(in features=1664, out features=5, bias=True)
# Проверим все ли сработало правильно, выведем веса, которые будут
обучаться
for name, param in model.named parameters():
   if param.requires grad:
        print(name)
classifier.weight
classifier.bias
model.to(device) # Отправляем модель на GPU
optimizer = torch.optim.Adam(params = model.parameters()) # алгоритм
оптимизации
loss_track, accuracy_track = trainval(model, loaders, optimizer,
epochs=10) # запускаем обучение
100%| 104/104 [00:33<00:00, 3.12it/s]
[training] Epoch: 0.00. Loss: 0.75. Accuracy: 76.45%
100%| 32/32 [00:09<00:00, 3.23it/s]
```

```
[validation] Epoch: 0.00. Loss: 0.42. Accuracy: 88.40%
100%| 104/104 [00:32<00:00, 3.15it/s]
[training] Epoch: 1.00. Loss: 0.57. Accuracy: 82.14%
100%| 32/32 [00:10<00:00, 3.20it/s]
[validation] Epoch: 1.00. Loss: 0.38. Accuracy: 88.60%
100%| 100%| 104/104 [00:32<00:00, 3.16it/s]
[training] Epoch: 2.00. Loss: 0.49. Accuracy: 84.70%
100%| 32/32 [00:09<00:00, 3.24it/s]
[validation] Epoch: 2.00. Loss: 0.35. Accuracy: 89.47%
100%| 104/104 [00:32<00:00, 3.17it/s]
[training] Epoch: 3.00. Loss: 0.44. Accuracy: 86.31%
     | 32/32 [00:09<00:00, 3.25it/s]
[validation] Epoch: 3.00. Loss: 0.34. Accuracy: 89.67%
100%| 104/104 [00:32<00:00, 3.17it/s]
[training] Epoch: 4.00. Loss: 0.40. Accuracy: 87.34%
100%| 32/32 [00:09<00:00, 3.25it/s]
[validation] Epoch: 4.00. Loss: 0.33. Accuracy: 89.96%
100%| 104/104 [00:32<00:00, 3.17it/s]
[training] Epoch: 5.00. Loss: 0.37. Accuracy: 88.16%
100%| 32/32 [00:09<00:00, 3.24it/s]
[validation] Epoch: 5.00. Loss: 0.32. Accuracy: 90.18%
100%| 104/104 [00:32<00:00, 3.16it/s]
[training] Epoch: 6.00. Loss: 0.35. Accuracy: 88.79%
     32/32 [00:09<00:00, 3.24it/s]
[validation] Epoch: 6.00. Loss: 0.31. Accuracy: 90.49%
100%| 100%| 104/104 [00:32<00:00, 3.16it/s]
[training] Epoch: 7.00. Loss: 0.33. Accuracy: 89.38%
100%| 32/32 [00:09<00:00, 3.25it/s]
```

```
[validation] Epoch: 7.00. Loss: 0.30. Accuracy: 90.61%
100%| 104/104 [00:32<00:00, 3.16it/s]
[training] Epoch: 8.00. Loss: 0.32. Accuracy: 89.83%
100%| 32/32 [00:09<00:00, 3.24it/s]
[validation] Epoch: 8.00. Loss: 0.30. Accuracy: 90.74%
100%|
         | 104/104 [00:32<00:00, 3.16it/s]
[training] Epoch: 9.00. Loss: 0.30. Accuracy: 90.27%
100%| 32/32 [00:09<00:00, 3.25it/s]
[validation] Epoch: 9.00. Loss: 0.29. Accuracy: 90.92%
plt.plot(accuracy_track['training'], label='training')
plt.plot(accuracy track['validation'], label='validation')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.grid()
plt.legend()
```

<matplotlib.legend.Legend at 0x7f9f1d275510>



import matplotlib.pyplot as plt
%matplotlib inline

```
import warnings
warnings.filterwarnings("ignore")
def predict image(img, model):
    # Преобразование to a batch of 1
    xb = img.unsqueeze(0).to(device)
    # Получение прогнозов от модели
    yb = model(xb)
    # Выбираем индекс с наибольшей вероятностью
    _, preds = torch.max(yb, dim=1)
    # Получение метки класса
    return dataset.classes[preds[0].item()]
for i in range(1,10):
  img, label = val set[i]
  plt.imshow(img.clip(0,1).permute(1, 2, 0))
  plt.axis('off')
  plt.title('Label: {}, Predicted: {}'.format(dataset.classes[label],
predict image(img, model)))
  plt.show()
  # print('Label:', dataset.classes[label], ',Predicted:',
predict_image(img, ____))
```

Label: dandelion, Predicted: dandelion



Label: sunflower, Predicted: sunflower



Label: sunflower, Predicted: sunflower



Label: dandelion, Predicted: dandelion



Label: sunflower, Predicted: sunflower



Label: rose, Predicted: rose



Label: daisy, Predicted: daisy



Label: sunflower, Predicted: sunflower



Label: rose, Predicted: rose



По желанию, можно сохранить веса модели.

```
weights_fname = '/content/drive/My Drive/data/***___**.pth'
torch.save(model.state_dict(), weights_fname)
```

Вопросы.

Как работает выбранная вами модель сверточной нейронной сети? Какие параметры?

В чем основные отличия между сверточной нейронной сетью и "обычной" полносвязной нейронной сетью?

Что такое transfer learning?

Что такое функция для заморозки весов модели?

Ответы на вопросы:

- 1. Сначала объясню мотивацию выбора модели. Почитал про несколько из них на сайте руТогсh. Позже узнал, у друга, что тот использовал alexnet в сравнении с resnet, поэтому данные две модели решил не использовать, а попробовать другие. Выполнил лабу для модели vgg, результаты получились чуть хуже, чем у представленной в отчете модели. Связываю с тем, что документация по vgg предлагает ее использовать для крупномасштабных изображений, а наш датасет из 4000 картинов занимает всего ~300 мб, поэтому вряд ли их можно отнести к такой категории. Далее я наткнулся на модель DenseNet и увидел в описании следующие ее преимущества:
 - а) Сильный градиентный поток показалось полезным, так как функция градиента используется в лабе
 - b) Параметр и вычислительная эффективность показалось полезным лично для меня из-за жадности Google, который два дня урезал мне ресурсы для GPU или не давал подключиться вовсе. Практика показала, что без GPU успеть обучить сеть и уложиться в дедлайны невозможно. Кроме того, последний месяц стабильно пару раз в день прохожу reCaptcha когда просто что-то гуглю, поэтому хотелось обучить все скорее, пока GPU работает.
 - с) Разнообразие функций
 - d) Поддерживает функции низкой сложности

Перечисленные 4 преимущества убедили меня остановить выбор на данной сверточной сети. Принцип ее работы - в увеличении уровня абстракций (как и в целом у сверточных сетей). При проходе через каждый слой сеть выделяет наиболее значимые, на ее взгляд, характеристики, которые объядиняет в более крупные сущности, отсекая незначительные элементы (т.е. "сворачивает" сеть). Таким образом, с каждым слоем определить требуемую характеристику становится все проще. В DenseNet же каждый слой получает карту характеристик со всех предыдущих слоев, а не с 1 предыдущего, что позволяет сделать сеть тоньше и компактнее - слоев меньше, меньше кол-во каналов, быстрее обучится => более высокая вычислительная эффективность и эффективность памяти, что мне и понравилось. Традиционные сверточные сети с L слоями имеют L соединений между каждым слоем и

его последующими слоями, в то время как сеть DenseNet имеет L (L + 1)/ 2 прямых соединений. Для каждого слоя в качестве входных данных используются карты характеристик всех предыдущих слоев, а его собственные карты характеристик также используются в качестве входных данных для всех последующих слоев. Параметры схожи с описанными в примере выполнения лабораторной работы, однако менять последний слой нужно в атрибуте classifier. Почему именно в нем - видно из описания модели. Кроме того, количество входных параметров нужно подгонять под параметры модели, чтобы не возникло неприятных ошибок в виде того, что входной и выходной слой с разнымии параметрами не сочетаются. В этом была основная сложность работы.

- 1. Отличия частично уже описал, но можно сказать еще раз: отличие полносвязных нейросетей в том, что они не выделяют абстракции от слоя к слою, а прогоняют через себя данные "как есть".
- 2. Transfer Learning (трансферное обучение) это подраздел машинного обучения, целью которого является применение знаний, полученные из одной задачи, к другой целевой задаче.
- 3. Функция заморозки весов модели функция, позволяющая "зафиксировать" веса некоторых элементов и исключить эти элементы из общего перестроения всей модели в будущем. Поэтому она и используется в концепции предобучения нейросетей.

Выводы: в ходе проделанной работы я ознакомился с принципами работы сверточных нейронных сетей, а так же узнал, что выполнение лабораторной работы может зависеть не только от меня, но и от наличия снисхождения алгоритмов Google к выделению мне ресурсов видеокарты.